## A NOTE ON CANONICAL RICCI FORMS ON 2-STEP NILMANIFOLDS

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ABSTRACT. In this note we prove that any left-invariant almost Hermitian structure on a 2-step nilmanifold is Ricci-flat with respect to the Chern connection and that it is Ricci-flat with respect to another canonical connection if and only if it is cosymplectic (i.e.  $d^*\omega = 0$ ).

## 1. INTRODUCTION

Let  $(M, g, J, \omega)$  be an almost Hermitian manifold. Gauduchon introduced in [13] a 1-parameter family  $\nabla^t$  of canonical Hermitian connections which can be distinguished by the properties of the torsion tensor T. In this family  $\nabla^1$  corresponds to so-called Chern connection which can be defined as the unique Hermitian connection whose (1,1)-part of the torsion vanishes. In the *quasi-Kähler* case (i.e. when  $\overline{\partial}\omega = 0$ ), the line  $\{\nabla^t\}$  degenerates to a single point and the Chern connection is the unique canonical connection.

Any canonical connection  $\nabla^t$  induces the so-called *Ricci form*  $\rho^t(X, Y) = 2 \operatorname{itr}_{\omega} R^t(X, Y)$ , where  $R^t$  denotes the curvature of  $\nabla^t$ . It turns out that  $\rho^t$  is always a closed form which can be locally written as the derivative of the 1-form  $\theta^t(X) = \sum_{r=1}^n g(\nabla^t_X Z_r, Z_{\overline{r}})$ , where  $\{Z_r\}$  is a (local) unitary frame. Moreover, in the cosymplectic case (i.e. when  $d\omega^{n-1} = 0$ ) the line  $\{\theta^t\}$  degenerates to a single point (see Corollary 3.3) and all the canonical connections have the same Ricci form.

The aim of this paper is to study the Ricci forms  $\rho^t$  on 2-step nilmanifolds equipped with a left-invariant almost Hermitian structure. We recall that by definition a *k*-step nilmanifold is a compact quotient of a *k*-step nilpotent Lie group G by lattice. Since we are considering *left-invariant* almost Hermitian structures, we can work on Lie algebras in an algebraic fashion. Our main result is the following

**Theorem 1.** Let  $(\mathfrak{g}, g, J, \omega)$  be a 2-step nilpotent Lie algebra with an almost Hermitian structure. Then (g, J) is Ricci-flat with respect to the Chern connection and it is Ricci-flat with respect to another canonical connection if and only if it is cosymplectic (i.e.  $d^*\omega = 0$ ).

This theorem has the following immediate consequence:

**Corollary 1.1.** Every left-invariant almost Hermitian structure on a nilmanifold associated to a 2-step Lie group is Ricci-flat with respect to the Chern connection.

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## 2. Preliminaries on canonical connections

Let  $(M, g, J, \omega)$  be an almost Hermitian manifold, where  $\omega$  is the fundamental form  $\omega(\cdot, \cdot) = g(J \cdot, \cdot)$ . The almost complex structure J extends to r-forms as

$$J\alpha(X_1,\ldots,X_n) = (-1)^r \alpha(JX_1,\ldots,JX_n)$$

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inducing the splittings

$$TM\otimes \mathbb{C}=T^{1,0}M\oplus T^{0,1}M\,,\quad \Lambda^r(M,\mathbb{C})=igoplus_{p+q=r}\Lambda^{p,q}M\,,$$

where  $\Lambda^r(M,\mathbb{C})$  is the vector bundle of complex r-forms on M. In particular  $\Lambda^3 M$  splits as

$$\Lambda^3 M = \Lambda^+ M \oplus \Lambda^- M$$

where  $\Lambda^+ M = (\Lambda^{2,1} M \oplus \Lambda^{1,2} M) \cap \Lambda^3 M$  and  $\Lambda^- M = (\Lambda^{3,0} M \oplus \Lambda^{0,3} M) \cap \Lambda^3 M$ . Given a 3-form  $\gamma$  we denote by  $\gamma^+$  and  $\gamma^-$  the projection onto  $\Lambda^+ M$  and  $\Lambda^- M$ , respectively. Moreover, denoting by  $\Omega^2(TM)$  the vector space of smooth sections of  $\Lambda^2 M \otimes TM$ , we have the splitting

$$\Omega^2(TM) = \Omega^{2,0}(TM) \oplus \Omega^{1,1}(TM) \oplus \Omega^{0,2}(TM)$$

where

$$\begin{split} \Omega^{2,0}(TM) &= \{ B \in \Omega^2(TM) \; : \; B(JX,Y) = JB(X,Y) \} \, ; \\ \Omega^{1,1}(TM) &= \{ B \in \Omega^2(TM) \; : \; B(JX,JY) = B(X,Y) \} \, ; \\ \Omega^{0,2}(TM) &= \{ B \in \Omega^2(TM) \; : \; B(JX,Y) = -JB(X,Y) \} \, . \end{split}$$

Hence any  $B \in \Omega^2(TM)$  can be written as  $B = B^{2,0} + B^{1,1} + B^{0,2}$ . Notice that in terms of complex vector fields of type (1,0) we have

$$B^{2,0}(Z_i, Z_j) = B(Z_i, Z_j) + B(Z_i, Z_j) - iJB(Z_i, Z_j) - iJB(Z_i, Z_j) = 2B(Z_i, Z_j) - 2iJB(Z_i, Z_j).$$

In particular the condition  $B^{2,0} = 0$  can be written in terms of (1,0) vector fields as  $B(Z_i, Z_j) \in T^{0,1}M$ . Furthermore  $\Omega^2(TM)$  splits as

$$\Omega^2(TM) = \Omega^2_b(TM) \oplus \Omega^2_c(TM)$$

where

$$g(B_b(X,Y),Z) = \frac{1}{2}(g(B(X,Y),Z) - g(B(Z,X),Y) - g(B(Y,Z),X))),$$
  
$$g(B_c(X,Y),Z) = \frac{1}{2}(g(B(X,Y),Z) + g(B(Z,X),Y) + g(B(Y,Z),X))).$$

Now we consider connections on  $\tilde{M}$ . A connection  $\nabla$  on M is called *Hermitian* if  $\nabla J = 0$ ,  $\nabla g = 0$ . It is well-known that every almost Hermitian manifold admits Hermitian connections. We denote by C the space of Hermitian connection on M. Gauduchon introduced in [13] the following special class of Hermitian connections:

**Definition 2.1.** A connection  $\nabla \in C$  is called canonical if its torsion T satisfies  $T_b^{1,1} = 0$ .

From [13] it follows that any canonical connection  $\nabla$  can be written as

(2.1) 
$$g(\nabla_X Y, Z) = g(D_X Y, Z) + \frac{t-1}{4} (d^c \omega)^+ (X, Y, Z) + \frac{t+1}{4} (d^c \omega)^+ (X, JY, JZ) - g(X, N(Y, Z)) + \frac{1}{2} (d^c \omega)^- (X, Y, Z).$$

for some  $t \in \mathbb{R}$ , where  $d^c$  is the operator acting on *r*-forms as  $d^c = (-1)^r J dJ$  and *N* denotes the Nijenhuis tensor N(X, Y) = [JX, JY] - [X, Y] - J([JX, Y] + [X, JY]).

For  $t \in \mathbb{R}$  we denote by  $\nabla^t$  the corresponding canonical connection. In the special case of a quasi-Kähler structure (i.e.  $\overline{\partial}\omega = 0$ ) the space of canonical connections reduces to a single point, while if J is integrable (i.e. N = 0) equation (2.1) reduces to

$$g(\nabla_X^t Y, Z) = g(D_X Y, Z) + \frac{t-1}{4} (d^c \omega)(X, Y, Z) + \frac{t+1}{4} (d^c \omega)(X, JY, JZ)$$

For the parameters t = 1, 0, -1, the family (2.1) gives the following remarkable cases

- t = 1. In this case  $\nabla^1$  is called the *Chern connection*. This connection can be defined as the unique Hermitian connection satisfying  $T^{1,1} = 0$ .
- t = 0. In this case  $\nabla^0$  is called the *first canonical connection*. This connection can be defined as the unique Hermitian connection whose torsion satisfies  $T^{2,0} = 0$ .

• t = -1. In this case the connection  $\nabla^{-1}$  is important in the complex case where it is known as the *Bismut connection*. Indeed, if J is integrable, then  $\nabla^{-1}$  can be defined as the unique Hermitian connection having totally skew-symmetric torsion (see [6]).

# 3. CANONICAL RICCI FORMS

Let  $(M^{2n}, g, J)$  be an almost Hermitian manifold and let  $\mathcal{C}$  the space of the associated Hermitian connections. For any  $\nabla \in \mathcal{C}$  it is defined the Ricci form  $\rho(X, Y) = 2 \operatorname{i} \operatorname{tr}_{\omega} R(X, Y)$ , where R is the curvature tensor  $R(X, Y) := [\nabla_X, \nabla_Y] - \nabla_{[X,Y]}$ . Such a form is always closed and it locally satisfies  $\rho = d\theta$ , where  $\theta(X) = \sum_{r=1}^n g(\nabla_X Z_r, Z_{\overline{r}})$  and  $\{Z_r\}$  is a local unitary frame. In the case of a canonical connection  $\nabla^t \in \mathcal{C}$  we use notation  $\rho^t$  and  $\theta^t$ . We denote by  $\natural$  the natural isomorphism between vector fields and 1-forms induced by g. Namely, if X a vector field, then we denote by  $X^{\natural}$  the 1-form  $X^{\natural}(Y) = g(X,Y)$ . We have the following

**Proposition 3.1.**  $\theta^t$  is locally defined by

(3.1) 
$$\theta^{t}(X) = \sum_{r=1}^{n} i \Im \mathfrak{m} \{ g([X + t \, \mathrm{i} \, JX, Z_{r}], Z_{\overline{r}}) \} + \frac{1}{2} \, \mathrm{i}(t-1)g(d^{*}\omega, X^{\natural})$$

for any vector field X.

*Proof.* First of all we note that if  $Z_r$  is a vector field of type (1,0), then

$$N(Z_r, Z_{\overline{r}}) = (d^c \omega)^- (X, Z_r, Z_{\overline{r}}) = 0, \quad (d^c \omega)^+ (X, Z_r, Z_{\overline{r}}) = d^c \omega(X, Z_r, Z_{\overline{r}}) = -d\omega(JX, Z_r, Z_{\overline{r}}) = -d\omega(JX,$$

Hence if  $\{Z_r\}$  is a local unitary frame using equation (2.1) we get

$$\theta^t(X) = \sum_{r=1}^n \left\{ g(D_X Z_r, Z_{\overline{r}}) + \frac{t-1}{4} (d^c \omega)(X, Z_r, Z_{\overline{r}}) + \frac{t+1}{4} (d^c \omega)(X, J Z_r, J Z_{\overline{r}}) \right\}$$
$$= \sum_{r=1}^n \left\{ g(D_X Z_r, Z_{\overline{r}}) - \frac{t}{2} d\omega (J X, Z_r, Z_{\overline{r}}) \right\}.$$

Now

$$2g(D_X Z_r, Z_{\overline{r}}) = Xg(Z_r, Z_{\overline{r}}) - Z_{\overline{r}}g(X, Z_r) + Z_rg(X, Z_{\overline{r}}) + g([X, Z_r], Z_{\overline{r}}) + g([Z_{\overline{r}}, X], Z_r) - g([Z_r, Z_{\overline{r}}], X)$$
$$= -Z_{\overline{r}}g(X, Z_r) + Z_rg(X, Z_{\overline{r}}) + g([X, Z_r], Z_{\overline{r}}) + g([Z_{\overline{r}}, X], Z_r) - g([Z_r, Z_{\overline{r}}], X)$$

and

$$\begin{aligned} d\omega(JX, Z_r, Z_{\overline{r}}) = & (JX)\omega(Z_r, Z_{\overline{r}}) - Z_r\omega(JX, Z_{\overline{r}}) + Z_{\overline{r}}\omega(JX, Z_r) - \omega([JX, Z_r], Z_{\overline{r}}) \\ & - \omega([Z_{\overline{r}}, JX], Z_r) - \omega([Z_r, Z_{\overline{r}}], JX) \\ = & Z_rg(X, Z_{\overline{r}}) - Z_{\overline{r}}g(X, Z_r) + ig([JX, Z_r], Z_{\overline{r}}) + ig([Z_{\overline{r}}, JX], Z_r) - g([Z_r, Z_{\overline{r}}], X) \,. \end{aligned}$$

Then we have

$$\begin{split} \theta^t(X) = &\frac{1}{2} \sum_{r=1}^n \left\{ g([X + t \,\mathrm{i}\, JX, Z_r], Z_{\overline{r}}) - g([X - t \,\mathrm{i}\, JX, Z_{\overline{r}}], Z_r) + g([Z_r, Z_{\overline{r}}], tX - X) \right. \\ &+ (1 - t) Z_r g(X, Z_{\overline{r}}) - (1 - t) Z_{\overline{r}} g(X, Z_r) \right\} \\ &= &\sum_{r=1}^n \left\{ \mathrm{i}\, \Im \mathfrak{m} \left\{ g([X + t \,\mathrm{i}\, JX, Z_r], Z_{\overline{r}}) + (1 - t) Z_r g(X, Z_{\overline{r}}) \right\} - \frac{1}{2} (1 - t) g([Z_r, Z_{\overline{r}}], X) \right\}. \end{split}$$

So in order to prove the statement we have to show that

(3.2) 
$$\sum_{r=1}^{n} \left\{ \Im \mathfrak{m} \left\{ Z_r g(X, Z_{\overline{r}}) \right\} + \mathrm{i} \frac{1}{2} g([Z_r, Z_{\overline{r}}], X) \right\} = -\frac{1}{2} g(\omega, dX^{\natural}) \,.$$

We can write  $X = \sum_{r=1}^{n} (X_r Z_r + X_{\overline{r}} Z_{\overline{r}})$  and  $X^{\natural} = \sum_{r=1}^{n} (X_r \zeta^r + X_{\overline{r}} \zeta^{\overline{r}})$ , where  $\{\zeta^r\}$  is the coframe dual to of  $\{Z_r\}$ . Then we get

$$\begin{split} g(\omega, dX^{\natural}) &= \mathrm{i} \sum_{k=1}^{n} g(\zeta^{k} \wedge \zeta^{\overline{k}}, dX^{\natural}) \\ &= \mathrm{i} \sum_{k,r=1}^{n} (Z_{r}(X_{\overline{r}}) - Z_{\overline{r}}(X_{r}) - X^{\natural}([Z_{r}, Z_{\overline{r}}]))g(\zeta^{k} \wedge \zeta^{\overline{k}}, \zeta^{r} \wedge \zeta^{\overline{r}}) \\ &= \mathrm{i} \sum_{k=1}^{n} Z_{k}(X_{\overline{k}}) - Z_{\overline{k}}(X_{k}) - X^{\natural}([Z_{k}, Z_{\overline{k}}])) \\ &= -2\sum_{k=1}^{n} \Im \mathfrak{m} \{Z_{k}(X_{\overline{k}})\} - \mathrm{i} \sum_{k,s=1}^{n} (B_{k\overline{k}}^{s}X_{s} + B_{k\overline{k}}^{\overline{s}}X_{\overline{s}}) \\ &= -\sum_{k=1}^{n} \left(2 \Im \mathfrak{m} \{Z_{k}(X_{\overline{k}})\} + \mathrm{i} g([Z_{k}, Z_{\overline{k}}], X)\right) \,, \end{split}$$

where with B we denote the components of the brackets.

Corollary 3.2. The following formulae hold

- $\theta^1(X) = 2 i \sum_{r=1}^n \Im \mathfrak{m} g([X^{0,1}, Z_r], Z_{\overline{r}});$
- $\theta^0(X) = i \sum_{r=1}^n \Im \mathfrak{m} \left\{ g([X, Z_r], Z_{\overline{r}}) \right\} i \frac{1}{2} g(d^* \omega, X^{\natural});$   $\theta^{-1}(X) = 2i \sum_{r=1}^n \Im \mathfrak{m} \left\{ g([X^{1,0}, Z_r], Z_{\overline{r}}) \right\} i g(d^* \omega, X^{\natural}).$

It is useful to write down formula (3.1) in real coordinates. In order to do this we write  $Z_r =$  $\frac{1}{\sqrt{2}}(e_r - i J e_r)$  for a suitable orthonormal frame  $\{e_1, \ldots, e_n, J e_1, \ldots, J e_n\}$ . Then a direct computation gives

$$\begin{split} 2\Im\mathfrak{m}\left\{g([X+\operatorname{ti} JX,Z_r],Z_{\overline{r}})\right\} &= \Im\mathfrak{m}\left\{g([X+\operatorname{ti} JX,e_r-\operatorname{i} Je_r],e_r+\operatorname{i} Je_r)\right\} \\ &= g([X,e_r],Je_r) - g([X,Je_r],e_r) + tg([JX,e_r],e_r) + tg([JX,Je_r],Je_r) \end{split}$$

and

(3.3) 
$$\theta^{t}(X) = \frac{1}{2} i \sum_{r=1}^{n} \{g([X, e_{r}], Je_{r}) - g([X, Je_{r}], e_{r}) + tg([JX, e_{r}], e_{r}) + tg([JX, Je_{r}], Je_{r})\} + \frac{1}{2} i(t-1)g(d^{*}\omega, X^{\natural}).$$

A remarkable consequence of formula (3.1) is the following

Corollary 3.3. All canonical connections of a cosymplectic structure have the same Ricci form. *Proof.* It is enough to show that  $\theta^1 = \theta^{-1}$ . Since the cosymplectic condition  $d^*\omega = 0$  implies

$$\theta^{-1}(X) = \sum_{r=1}^{n} 2i \Im \mathfrak{m} \left\{ g([X^{1,0}, Z_r], Z_{\overline{r}}) \right\}$$

we have

$$\begin{split} \theta^{-1}(X) &= -\sum_{r=1}^{n} 2\,\mathrm{i}\,\Im\mathfrak{m}\left\{g([X^{0,1}, Z_{\overline{r}}], Z_r)\right\} = -\sum_{r=1}^{n} 2\,\mathrm{i}\,\Im\mathfrak{m}\left\{g(D_{X^{0,1}} Z_{\overline{r}}, Z_r) - g(D_{Z_{\overline{r}}} X^{0,1}, Z_r)\right\} \\ &= \sum_{r=1}^{n} 2\,\mathrm{i}\,\Im\mathfrak{m}\left\{g(D_{X^{0,1}} Z_r, Z_{\overline{r}}) - g(D_{Z_{\overline{r}}} X^{0,1}, Z_r)\right\} \\ &= \theta^1(X) + \sum_{r=1}^{n} 2\,\mathrm{i}\,\Im\mathfrak{m}\left\{g(D_{Z_r} X^{0,1}, Z_{\overline{r}}) - g(D_{Z_{\overline{r}}} X^{0,1}, Z_r)\right\} \,. \end{split}$$

Now we observe that  $\sum g(D_{Z_r}X^{0,1}, Z_{\overline{r}}) = -\sum g(X^{0,1}, D_{Z_r}Z_{\overline{r}}) = 0$ , since the cosymplectic condition forces  $\sum D_{Z_{\overline{r}}}Z_r$  to be of type (1,0) (see e.g. [16]). The last step consists to show that  $\sum \Im \mathfrak{m} \{g(D_{Z_{\overline{r}}}X^{0,1}, Z_r)\} = 0$ . Here it is enough to consider the identity

$$\sum_{r=1}^{n} \left\{ \Im \mathfrak{m} \left\{ Z_r g(X, Z_{\overline{r}}) \right\} + \mathrm{i} \, \frac{1}{2} g([Z_r, Z_{\overline{r}}], X) \right\} = \sum_{r=1}^{n} \Im \mathfrak{m} \left\{ g(D_{Z_{\overline{r}}} X^{0,1}, Z_r) \right\}$$

which can be checked performing a direct computation. Then equation (3.2) implies the statement.  $\Box$ 

**Remark 3.4.** In the Hermitian case this last result was already known. In fact, it can be deduced from formula (8) of [14]. Another proof of this fact can be found in [17].

### 4. CANONICAL RICCI FORMS ON LIE ALGEBRAS

Now we restrict our attention to left-invariant almost Hermitian structures on Lie groups (or more generally on left-invariant almost Hermitian structures on quotient of Lie groups by lattices). Since here all the computations are purely algebraic, we may assume to work on a Lie algebra  $(\mathfrak{g}, [\cdot, \cdot])$  equipped with an almost Hermitian structure (g, J). An almost Hermitian structure on a Lie algebra is a pair (g, J), where J is an endomorphism of  $\mathfrak{g}$  satisfying  $J^2 = -\text{Id}$  and g is a J-Hermitian inner product. The bracket of  $\mathfrak{g}$  has not a priori any relation with J. The pair (g, J) induces as usual the fundamental form  $\omega(\cdot, \cdot) = g(J \cdot, \cdot)$ .

Proposition 3.1 implies the following

**Proposition 4.1.** Let  $(\mathfrak{g}, [\cdot, \cdot], g, J)$  be a Lie algebra with an almost Hermitian structure. For any  $t \in \mathbb{R}$  the following formula holds

(4.1) 
$$\theta^t(X) = \frac{1}{2} \operatorname{i} \left\{ -\operatorname{tr}(\operatorname{ad}_X \circ J) + t \operatorname{tr} \operatorname{ad}_{JX} + (t-1) g(d^*\omega, X^{\natural}) \right\} \,.$$

Moreover if  $(\mathfrak{g}, [\cdot, \cdot])$  is unimodular (i.e.  $\operatorname{tr} \operatorname{ad}_X = 0$  for any  $X \in \mathfrak{g}$ ); then

(4.2) 
$$\rho^{t}(X,Y) = \frac{1}{2} \operatorname{itr}(\operatorname{ad}_{[X,Y]} \circ J) - \frac{1}{2} \operatorname{i}(t-1) g(d^{*}\omega, [X,Y]^{\natural})$$

and  $\rho^t$  is the same for any t if and only if (g, J) cosymplectic.

*Proof.* The only non-trivial part of the statement is the last assertion. So we have just to show that condition  $g(\omega, d[X, Y]^{\natural}) = 0$  is equivalent to  $d^*\omega = 0$ . We can write  $\mathfrak{g} = [\mathfrak{g}, \mathfrak{g}] \oplus [\mathfrak{g}, \mathfrak{g}]^{\perp}$ . Let  $X \in [\mathfrak{g}, \mathfrak{g}]^{\perp}$ , then

$$dX^{\natural}(Z,W) = -g(X,[Z,W]) = 0.$$

Hence for every  $X \in [\mathfrak{g}, \mathfrak{g}]^{\perp}$ ,  $dX^{\natural} = 0$ . This implies that  $d\mathfrak{g}^* = d([\mathfrak{g}, \mathfrak{g}]^{\natural})$  and the claim follows.  $\Box$ 

Now we can prove Theorem 1:

Proof of Theorem 1. Let  $(\mathfrak{g}, [\cdot, \cdot], g, J)$  is a 2-step nilpotent Lie algebra with an almost Hermitian structure. Then, taking into account that  $\mathfrak{g}$  is unimodular, the 2-step condition implies that  $[\mathfrak{g}, \mathfrak{g}]$  is contained in the center of  $\mathfrak{g}$  and tr $(\mathrm{ad}_{[X,Y]} \circ J) = 0$  for every  $X, Y \in \mathfrak{g}$ . Then formula (4.2) reduces to

(4.3) 
$$\rho^{t}(X,Y) = \frac{1}{2} \operatorname{i}(1-t) g(d^{*}\omega, [X,Y]^{\natural})$$

and first claim follows.

Proposition 4.1 allows us to describe the behavior of  $\{\rho^t\}$  for some special almost Hermitian structures:

**Proposition 4.2.** Let  $(\mathfrak{g}[\cdot, \cdot], g, J)$  be an almost Hermitian Lie algebra.

• If J is bi-invariant (i.e.  $[J \cdot, \cdot] = J[\cdot, \cdot]$ ), then

$$\theta^t(X) = (t-1)\operatorname{itr}(\operatorname{ad}_{JX}), \quad \rho^t(X,Y) = \operatorname{i}(1-t)\operatorname{tr}(\operatorname{ad}_{[JX,Y]}).$$

• If J is anti-bi-invariant (i.e.  $[J \cdot, \cdot] = -J[\cdot, \cdot])$ , then

$$\theta^t = 0, \quad \rho^t = 0.$$

• If J is abelian (i.e.  $[J \cdot, J \cdot] = [\cdot, \cdot]$ ), then

$$\theta^{t}(X) = \frac{1}{2} i \left\{ (1+t) \operatorname{tr}(\operatorname{ad}_{JX}) + (t-1) g(d^{*}\omega, X^{\natural}) \right\},$$
  
$$\rho^{t}(X) = \frac{1}{2} i \left\{ -(1+t) \operatorname{tr}(\operatorname{ad}_{J[X,Y]}) + (1-t) g(d^{*}\omega, [X,Y]^{\natural}) \right\}.$$

• If J is anti-abelian (i.e.  $[J, J] = -[\cdot, \cdot]$ ), then

$$\theta^t(X) = \frac{1}{2} \operatorname{i}(1+t) \operatorname{tr}(\operatorname{ad}_{JX}), \quad \rho^t(X,Y) = -\frac{1}{2} \operatorname{i}(1+t) \operatorname{tr}(\operatorname{ad}_{J[X,Y]}).$$

In particular in the unimodular case bi-invariant, anti-bi-invariant and anti-abelian almost Hermitian structures are Ricci-flat with respect to any canonical connection, while in the abelian case  $\rho^t$  is given by the following formula

$$\rho^{t}(X,Y) = \frac{1}{2} \operatorname{i}(1-t) g(d^{*}\omega, [X,Y]^{\natural}).$$

and  $\rho^t = 0$  for  $t \neq 0$  if and only if (g, J) is a cosymplectic structure.

# **Remark 4.3.** We remark the following facts:

- The bi-invariant condition  $[J, \cdot] = J[\cdot, \cdot]$  is equivalent to require that the simply-connected Lie group associated to  $(\mathfrak{g}, J)$  is a complex Lie group. The fact that a bi-invariant almost Hermitian structure on an unimodular Lie algebra is Ricci-flat with respect any canonical connection has been already proved by Grantcharov in [15].
- The anti-bi-invariant condition  $[J, \cdot] = -J[\cdot, \cdot]$  is equivalent to require that any *J*-compatible inner product on  $\mathfrak{g}$  is quasi-Kähler and flat with respect to the Chern connection  $\nabla^1$  (see [9]).
- The abelian condition  $[J \cdot, J \cdot] = [\cdot, \cdot]$  was introduced in [4] and was intensely studied in [3, 5, 12, 8, 18]. This condition is equivalent to require that  $\mathfrak{g}^{1,0}$  is an abelian Lie algebra.
- Finally, the anti-abelian condition  $[J, J] = -[\cdot, \cdot]$  was studied in [11].

**Remark 4.4.** Theorem 1 can be applied to the Heisenberg Lie algebras  $\mathfrak{h}_n(\mathbb{R})$  and  $\mathfrak{h}_n(\mathbb{C})$ . That accords to Theorem 4.1 of [20] and Proposition 4.10 and 4.11 of [10]. Moreover things work differently either in the 3-step nilpotent case or in the 2-step solvable case (see [10]).

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