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On Stability and Trajectory Boundedness in Mean-square Sense for ARMA Processes

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摘要 For the multidimensional ARMA system $A(z)y_k = C(z)w_k$ it is shown that stability ($\det A(z) \neq 0, \forall z: |z| \leq 1$) of $A(z)$ is equivalent to the trajectory boundedness in the mean square sense (MSS) $\limsup_{n \rightarrow \infty} \|y_k\|_2 < \infty$ a.s., which, as a rule, is a consequence of a successful stochastic adaptive control leading the closed-loop of an ARMAX system to a steady state ARMA system. In comparison with existing results the stability condition imposed on $C(z)$ is no longer needed. The only structural requirement on the system is that $\det A(z)$ and $\det C(z)$ have no unstable common factor.

关键词 [ARMA](#) [stability](#) [boundedness in MSS](#) [equivalence](#)

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Key words [ARMA](#) [stability](#) [boundedness in MSS](#) [equivalence](#)

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