论文

ASYMPTOTIC ANALYSIS OF THE OPTIMAL CONTROL OF AN ELASTODYNAMIC SYSTEM

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摘要   Based on the idea of the reduction of optimal control systems in singular perturbations of Lions and a priori estimates in [4], we prove the convergence of the optimal control, state and the cost function between a singular linear elastodynamic systemand a limit system. Our asymptotic analysis is applicable to the optimal control of flexible robotic manipulators.

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Key words   Asymptotic analysis   the reduction of systems   a priori estimates   convergence between the singular and

DOI:

通讯作者