论文

A MECHANIZATION METHOD OF GEOMETRY AND ITS APPLICATIONS IV. SOME THEOREMS IN PLANAR KINEMATICS

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摘要 Let a moving plane MP over a fixed plane FP occupy four different positions. Eachpair of such positions is associated with a center of rotation called pole so that we have a 6-pole configuration. As an illustration of our general method of mechanical theorem proving and discovering, we discuss in the present paper in some derails certain theorems connected with such a configuration.

关键词

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Key words <u>Mathematics mechanization</u> <u>Mechanical theorem proving</u> <u>Kinematics</u> <u>Linkages</u> <u>Mechanical design</u>

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