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同转/对转双转子系统的动力学特性

Dynamic characteristics of co-rotating/counter-rotating dual-rotor system

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作者	单位
蒋云帆	西北工业大学 动力与能源学院, 西安 710007
廖明夫	西北工业大学 动力与能源学院, 西安 710007
刘永泉	中国航空工业集团公司 沈阳发动机设计研究所, 沈阳 110015
王德友	中国航空工业集团公司 沈阳发动机设计研究所, 沈阳 110015
金路	西北工业大学 动力与能源学院, 西安 710007
鲁鹏	西北工业大学 动力与能源学院, 西安 710007

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中文摘要:

建立了双转子动力学模型, 引入中介轴承刚度和高、低压转子陀螺力矩的影响, 利用数值分析和实验验证, 揭示了同转/对转双转子系统临界转速特性和不平衡响应存在的差异, 以及转速比对同转/对转双转子临界转速特性和不平衡响应的影响. 结果表明: 陀螺力矩是影响带有中介支承的双转子系统转子刚度的主要原因, 其刚度变化与内、外转子的转速比大小和相对旋转方向有关, 进而导致同转/对转双转子系统临界转速特性和不平衡响应发生改变; 相比同结构的同转双转子, 在相同的不平衡量作用下, 对转双转子的不平衡响应更为显著. 对转双转子进行动平衡时, 应更加严格的控制内、外转子的不平衡量.

A dynamic model of dual-rotor was set up. The influence of inter-shaft bearing stiffness and the gyroscopic moments of high and low pressure rotors were considered in this model. The difference of co-rotating or counter-rotating dual-rotor's critical speed characteristics and unbalance response and the influence of speed ratio on co-rotating or counter-rotating dual-rotor's critical speed characteristics and unbalance response were revealed by numerical analysis and experiments. The results show that, gyroscopic moment is a main influential factor to the rotor stiffness of dual-rotor system with inter-shaft bearing, and the changes of stiffness are related to the speed ratio and the relative rotating direction of inner and outer rotors, further causing the change of co-rotating or counter-rotating dual-rotor's critical speed characteristics and unbalance response. Compared with the co-rotating dual-rotor of the same structure with the counter-rotating dual-rotor, the counter-rotating dual-rotor's unbalance response is more obvious than the co-rotating dual-rotor's under the same unbalance mass, and for this reason the unbalance mass of counter-rotating dual-rotor's inner and outer rotors should be controlled more strictly during the dynamic balance.

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