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Research Article

**Damage Detection from SAR Imagery: A
to the 2003 Algeria and 2007 Peru Earth**

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Abstract

This paper is focused on the improvement and further validation of SAR radar satellite imagery of an area affected by a major disaster. We analyze different sites on imagery of two different earthquakes occurred in 2003 and 2007. The combination of different radar-extracted features and ancillary data provide enough detail and precision to achieve a damage level at the block level is achieved at enough detail using SAR data.

1. Introduction

One of the most important issues in disaster damage detection is the precision. As a consequence of that, every kind of data available is used by operators [1]. To this aim, remotely sensed imagery can be instrumental in the creation of GIS layers, printed maps, and historical datasets. However,

constantly growing in the past few years, image interpretation is accurate, are still not used in many applications.

Damage assessment is actually a big challenge, being impossible reason, the organizations such as the International Charter on "S wide range of sources. The need of rapid damage pattern estimation using quick and possibly efficient approaches suited to the decision at which the analysis can be carried out is determined by the space while SAR data can be useful to extract damage information only the single collapsed buildings from HR images.

The aim of this work is to understand the viability of radar satellite many different disasters all around the world, looking also at different available with more and more fine spatial resolution, and thus with improvement actually allows a better match between the growing (the concentration of population) with the enhanced availability of in urban areas using SAR data are very limited, due to the problem or semiautomated tools.

2. Damage Pattern Estimate FROM Sar Data

In recent technical literature, some works have already suggested proper temporal and spatial scale, interesting information about works concerning earthquakes need data coming from ground surface information extraction. For this reason, these strategies are very ground displacements and soil properties [2, 3], or to provide precise very poor results in terms of damage assessment and rapid damage important to say that classification and change detection methods usable results to the final user. Instead, these methods integrate more precise and understandable results. Moreover, damage analysis human settlements in general, where it is often easily feasible to (GIS) data.

In this work, we apply a technique recently proposed in [5] for the Golcük (Turkey) earthquakes. The first aim of this work is indeed to situations and produces useful results for damage assessment in this paper reports the results of an investigation about the robust features originally used in the cited papers.

The overall methodology of the data analysis is proposed in Figure here all the details of the algorithm. The procedure involves first of the original multitemporal dataset comprising pre- and postevent SAR is then input to a multiband supervised classifier, whose output is postclassification fusion step is performed at the end of the process ancillary data.

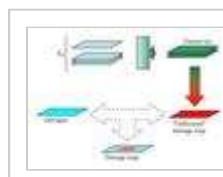


Figure 1: Overall structure of the damage mapping

The set of feature extracted from the multitemporal SAR image is based on the assumption that radar returns in damaged areas are quite different from the buildings. There are studies showing that urban areas show different values and correlation in amplitude/intensity values during time. In this paper, the change in the complex coherence and in the intensity correlation are tested in technical literature for the Hyogoken-nambu (Japan) earthquake where this was originally proposed [2], each (complex) SAR image is prefiltered with a Lee filter, and intensity correlation r_i between two images in the sequence is computed according to the formula

$$r_i = \frac{\sum_W x_i x_{i-1} - N \bar{x}_i \bar{x}_{i-1}}{\sqrt{(\sum_W x_i^2 - N \bar{x}_i^2)(\sum_W x_{i-1}^2 - N \bar{x}_{i-1}^2)}}$$

where $x_i = \|X_i\|$ (recall that SAR data are complex values), the \sum is over each image element in a window $W = N \times N$ around it, and finally the

Along with intensity correlation, another valuable input feature is the mean prefiltered data intensity $d_i = 10 \log_{10}(\bar{x}_i) - 10 \log_{10}(\bar{x}_{i-1})$, and the postevent pointwise intensities.

Of course, according to the dimension of the window W and thus the number of features, multiple scales of analysis of the data can be enhanced. In our past experience, this depends on the ground spatial resolution of the block of buildings in the human settlement under test. In all the cases, the features are equally valuable, when the SAR images have spatial resolution in the order of the block size.

The second step of the approach, as shown in Figure 1, is a comparison of two different approaches: a neuro-fuzzy per-pixel fuzzy classifier based on the assumption of a Markov random field (MRF) and a fuzzy classifier. The fuzzy classifier has been chosen because of its proven capability to perform per pixel classification, while the MRF approach allows a spatially global analysis as such a minimal knowledge about the damages on the ground, the

After classification, and due to the complex interactions between damaged or undamaged areas, it is very likely that the damage class will appear in a block. To improve the results, and to meaningfully focus the final user, a fusion step between the map results and ancillary GIS information is used. The fusion of the two classification methods is used to make a decision on each of the areas detailed by the GIS ancillary information. This fusion step, which has been detailed in [5] and in this work will be degraded to a single class. This basically means that the most voted damage class in each block is considered representative of the whole block.

Following this procedure, in the next section two different test cases are presented in different parts of the world. Moreover, different SAR images are used to analyze the damage patterns in different situations, and the results of the following procedure presented here can be helpful in real situations, and compare the input feature set can highlight the damage patterns in the test areas. The results are compared with the originally studied Bam (Iran) and Golcük (Turkey) earthquakes (if any) for all of them.

3. Applicative Test Cases

In order to test the proposed methodology, the aim of our tests was to use different sensors on board of different satellites. The combination of different information, availability or not of phase information was meant to test the proposed approach and find where it has to be adapted. Moreover, the very specific spatial urban patterns and the effect of the earthquake, make the 2003 Bam test case in [5] and the 1999 Turkey case in [6] :

3.1. First Test Site: Boumerdes (2003 Algeria Earthquake)

The first results refer to the magnitude 6.8 earthquake occurred in the Boumerdes province (Figure 2) some 50 km east of Algiers, the Boumerdes, Zemmouri, Thenia, Belouizdad, Rouiba, and Reghaia data are available; in this work the analysis will be concentrated in Boumerdes. We have been acquired, one pre-event acquired on July 27th, 2002, and one post-event acquired on August 15th, 2003.

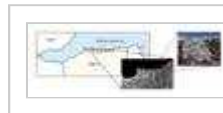


Figure 2: Location of the urban area of Boumerdes

3.2. Second Test Site: Pisco (2007 Peru Earthquake)

The second example refers to the test case of Peru, whose central coast was affected by an earthquake on August 15th, 2007. Among the affected cities, the city of Pisco was the most affected. The data used in this work are the ALOS/PALSAR fine beam double polarization (HH/HV) Precision Beam mode images with a resolution of 10 meters posting. The two images were acquired before (on August 1st, 2007) and after (on August 15th, 2007) the earthquake. Ancillary data consist of a GIS layer depicting the built-up areas of Pisco obtained by manual digitalization of the information in [9], and a SAR image of the city of Pisco before the event image used in that paper. From the same paper, also the in situ measurements was extracted (see Figure 5).

Since the data have been provided as amplitude images, no phase information is available. This prevents us from using the bands which were considered as the most sensitive for damage detection, that is, pre- and postevent intensity, pre-post coherence, and phase change. Instead, from the available images only some intensity and coherence features are used. The intensity correlation r and the backscattering coefficient d and the phase change $\Delta\phi$ are the features used in the ALOS/PALSAR scene than the ERS and JERS data used in [9]. The features considered are the pre- and postevent intensities, computed using a 3×3 Gamma filter. As in the first test case the first classification step is performed using a maximum likelihood classifier or the context-aware MRF classifier is followed by a fusion step. The final class is assigned to the class to which the majority of mapped pixels belong.

For this test case, a wider range of classification maps is proposed to test the proposed methodology, as well as to appreciate the effect of the different combinations of features and classifiers, as well as to appreciate the effect of the data fusion final step. The need for this extended resolution of ALOS/PALSAR with respect to the ERS/JERS data is to have a more precise at the per-pixel level and allows defining spatial units smaller than the resolution of the data (see Figure 3(b)). Moreover, the lack of original complex data does not prevent the use of the most important bands for the multiband/multitemporal damage detection. The features thus intend to analyze which, among the computed features, are the most sensitive for damage detection.

this situation.



Figure 3: Postevent SAR image (left) and a damage map (right) showing highly damaged areas, orange to medium damaged areas, yellow.



Figure 4: Damage maps for the Boumerdes area. (a) shows a damage map generated by a detection algorithm; (b) introducing the GIS information.



Figure 5: Postevent pan-sharpened image of Boumerdes. (a) shows the original image, (b) shows the image with damage detection, and (c) shows the image with damage classification (untouched), yellow (light damage), and orange (medium damage).

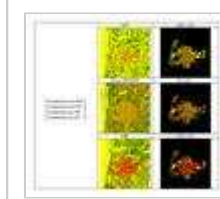


Figure 6: Per-pixel damage maps and focused images for the MRF and FA case. The input multiband/multiresolution image is shown on the left, followed by damage maps and focused images for MRF and FA.



Figure 7: Per-pixel damage maps and focused images for the MRF and FA case. The input multiband/multiresolution image is shown on the left, followed by damage maps and focused images for MRF and FA.

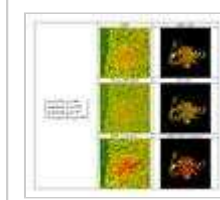


Figure 8: Per-pixel damage maps and focused images for the MRF and FA case. The input multiband/multiresolution image is shown on the left, followed by damage maps and focused images for MRF and FA.

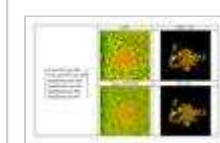


Figure 9: Per-pixel damage maps and focused images for the MRF and FA case. The input multiband/multiresolution image is shown on the left, followed by damage maps and focused images for MRF and FA.

Finally, Table 1 reports the overall accuracy for the maps in the improved visual comparison with a quantitative assessment.

Table 1: Overall accuracy for maps in Figures

A first comment to the results is that the information fusion step is decent mapping accuracy, but also understandable to anyone looking at the accuracy values are in the same range as the one reported for the ground truth in the present case is more detailed, the higher the accuracy values obtained from Boumerdes' images.

According to the maps and the accuracy values, the best result is pre-event image (both polarizations HH and HV) and the amplitude and the second best approach is the use of the backscattering an image (HH polarization) and the postevent image (HV polarization)

Since the ALOS/PALSAR image pre- and postevent image pairs are possible to compare the effect of polarization with respect to damage. However, it was found that no particular choice can be made, and to some extent in some portion of the area are equally in place using on combination of both.

A last comment is driven by the fact that the damage maps in [9] are not our validation. In Figure 9, in fact, medium and high damages are not shown. The reason is that previous trials attempting to obtain maps with high accuracy values, as reported in Table 1 for sake of completeness, are not shown, where a high level of damage is depicted in red, are reported. There are limits inherent to the structure of the artificial elements and the spatial resolution that prevent the 7 m ALOS/PALSAR to be effective.

4. Conclusions

In this paper, a rapid damage mapping approach is proposed, based on SAR data. The approach proves to be robust and useful to detect damage with respect to accuracy and needs improvements.

More specifically, although semiautomatic SAR data interpretation shows that a combination (fusion) of remotely sensed data and SAR data shows an improvement in this interpretation, making the data more useful for damage detection. The procedure, together with its affordability, were proved by the analysis of many different parts of the world.

There are some commonalities among the choices of input feature combination of the pre- and postevent intensity data with the logarithmic means achieves always better results. The possibility to use coherence, not exploited in this work but proposed in the original paper, could be a multiple possible choices.

Very interesting and still open issues are those connected to the correlation between the maps and the features itself to the actual, damage.

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