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### 个人简述

(限300字)

高向东, 博士, 教授, 博士(硕士)生导师。1985年毕业于郑州大学计算机与自动化系, 获工学学士学位; 1988年毕业于中南大学自动化系, 获工学硕士学位; 1997年毕业于华南理工大学机电工程学院, 获工学博士学位(与日本九州大学联合培养)。2002年: 韩国先进科技研究院(KAIST)客座教授; 2008年: 日本大阪大学访问教授, 中国政府派遣研究员; 2014年: 日本学术振兴会(JSPS)特邀研究员及日本大阪大学访问教授; 2018年: 美国哈佛大学访问教授。先后主持完成国家自然科学基金、广东省自然科学基金、广东省科技攻关、广州市科技攻关、留学回国人员科研基金和教育部高等学校博士学科点专项科研基金(博士生导师类)等科研项目40余项, 在国内外期刊和学术会议发表论文270余篇, 获国家专利20多件。与美国、日本、韩国等国外重点大学有长期学术合作, 联合培养研究生多名。现为广东省焊接工程技术研究中心主任、广东省机械工程学会焊接分会副理事长、中国机械工程学会高级会员、中国自动化学会高级会员、中国图像学会高级会员、国家科学技术奖励评审专家。主要研究领域包括: 光机电先进传感与控制, 机器人自动焊接, 机器视觉与模式识别, 车辆自动识别与跟踪。

### 学科领域

科学学位: 机械电子工程, 机械制造及其自动化, 车辆工程, 机械工程  
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### 教育背景

1994.03-1997.07, 华南理工大学焊接自动控制专业学习, 获博士学位  
1985.09-1988.06, 中南大学工业自动化专业学习, 获硕士学位  
1981.09-1985.07, 郑州大学工业自动化专业学习, 获学士学位

### 工作经历

2018, 美国哈佛大学访问教授  
2014, 日本学术振兴会(JSPS)特邀研究员及日本大阪大学访问教授  
2008, 日本大阪大学, 中国政府派遣研究员  
2002, 韩国先进科技研究院(KAIST), 客座教授  
2002-广东工业大学教授

### 学术兼职

广东省焊接工程技术研究中心主任  
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#### 主要荣誉

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 “广东工业大学先进科技工作者”称号  
 美国罗克韦尔自动化(Rockwell Automation)优秀教师奖  
 《火箭体用新型焊接设备的研制》获国家教育部科技进步奖  
 《基于北斗 / GPS双模进口汽车可视化检验监管平台》获卫星导航定位科学技术奖  
 《新能源汽车行车状态智能采集系统设计与开发》获中国检验检疫学会科技奖  
 《互联网+进出口电动汽车物流仓储智能平台设计与实现》获中国物流与采购联合会科学技术奖  
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#### 主要论文

Lin Wang, Xiangdong Gao\*, Zinqin Chen. Status analysis of keyhole bottom in laser-MAG hybrid welding process. *Optics Express*, 2018, 26(1): 347-355

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发明人：高向东、杨雪荣、陈章兰，发明专利授权号：ZL200410015240.5，结构光视觉传感步进驱动型轮对测量方法及测量装置

发明人：高向东，蓝重洲，发明专利授权号：ZL201610681729.9，激光电弧复合焊3D增材修补装置及修补方法

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**科研项目**

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高向东 (主持), 广东省科技计划项目2007B010400069, JCOE直缝双面埋弧焊管焊缝跟踪机的研制, 2007.01-2009.12

高向东 (主持), 广州市科技计划项目2001-Z-097-01, 铁路车辆轮对自动检测装置的研制, 2001.01-2003.12

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