

Home > Research > Browse Publications

Education

# Calibration Method for Determining the Physical Location of the Ultrasound Image Plane

Devin Amin, Takeo Kanade, Branislav Jaramaz, Anthony M. Di Gioia, Constantinos Nikou, Richard LaBarca, and James E. Moody

Proceedings of the 4th International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI 2001), October, 2001.

## Download

Research

About RI

People

Adobe portable document format (pdf ) (712KB)

**Copyright notice**: This material is presented to ensure timely dissemination of scholarly and technical work. Copyright and all rights therein are retained by authors or by other copyright holders. All persons copying this information are expected to adhere to the terms and constraints invoked by each author's copyright. These works may not be reposted without the explicit permission of the copyright holder.

#### Abstract

This paper describes a calibration method for determining the physical location of the ultrasound (US) image plane relative to a rigidly attached 3D position sensor. A calibrated US probe can measure the 3D spatial location of anatomic structures relative to a global coordinate system. The calibration is performed by aiming the US probe at a calibration target containing a known point (1 mm diameter sphere) in physical space. This point is repeatedly collected at various locations in the US image plane to produce the calibration dataset. An idealized model of the collection process is used to eliminate outliers from the calibration dataset and also to examine the theoretical accuracy limits of this method. The results demonstrate accurate and robust calibration of the 3D spatial relationship between the US image plane and the 3D position sensor.

#### Notes

- Associated Center(s) / Consortia: Medical Robotics Technology Center
- Associated Lab(s) / Group(s): <u>Medical Robotics and Computer Assisted Surgery</u>
- Number of pages: 8

## Text Reference

Devin Amin, Takeo Kanade, Branislav Jaramaz, Anthony M. Di Gioia, Constantinos Nikou, Richard LaBarca, and James E. Moody, "Calibration Method for Determining the Physical Location of the Ultrasound Image Plane," *Proceedings of the 4th International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI 2001)*, October, 2001.

## **BibTeX Reference**

@inproceedings{Amin\_2001\_4604,

author = "Devin Amin and Takeo Kanade and Branislav Jaramaz and Anthony M. Di Gioia and Constantinos Nikou and Richard LaBarca and James E. Moody",

title = "Calibration Method for Determining the Physical Location of the Ultrasound Image Plane",

booktitle = "Proceedings of the 4th International Conference on Medical Image Computing and Computer-Assisted Intervention (MICCAI 2001)",

month = "October", year = "2001",

}

The <u>Robotics Institute</u> is part of the <u>School of Computer Science</u>, <u>Carnegie Mellon University</u>. <u>Contact Us</u>