

# Null scrolls in the 3-dimensional Lorentzian space

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## Abstract

In this study, a timelike ruled surface in the 3 - dimensional Lorentzian space  $\mathbb{R}_1^3$  which is called null scroll is generated by a null straight line which moves along a null curve with respect to the null frame. In a null scroll, the central point, the curve of striction, pseudo-orthogonal trajectory and some theorems related to these structures are obtained in the 3-dimensional Lorentzian space  $\mathbb{R}_1^3$ . Results about developable null scrolls are provided as well.

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**Key words:** null curve, null scroll, Lorentzian space

## §1. Introduction

$\mathbb{R}_1^3$  is by definition the 3-dimensional vector space  $\mathbb{R}^3$  with the inner product of signature (1, 2) given by

$$\langle x, y \rangle = -x_1y_1 + x_2y_2 + x_3y_3$$

for any column vectors  $x = {}^t(x_1, x_2, x_3)$ ,  $y = {}^t(y_1, y_2, y_3) \in \mathbb{R}^3$ . Let  $\{e_1, e_2, e_3\}$  be the standart orthonormal basis of  $\mathbb{R}_1^3$  given by

$$e_1 = {}^t(1, 0, 0), \quad e_2 = {}^t(0, 1, 0), \quad e_3 = {}^t(0, 0, 1).$$

A basis  $F = \{X, Y, Z\}$  of  $\mathbb{R}_1^3$  is called a (*proper*) *null frame* if it satisfies the following conditions

$$\langle X, X \rangle = \langle Y, Y \rangle = 0, \quad \langle X, Y \rangle = -1,$$

$$Z = X \wedge Y = \sum_{i=1}^3 \varepsilon_i \det [X, Y, e_i] e_i,$$

where  $\varepsilon_1 = -1$ ,  $\varepsilon_2 = \varepsilon_3 = 1$ . Hence we obtain that

$$\langle X, Z \rangle = \langle Y, Z \rangle = 0, \quad \langle Z, Z \rangle = 1.$$

A vector  $V$  in  $\mathbb{R}_1^3$  is said to be null if  $\langle V, V \rangle = 0$ , [2, 4]. A surface in the 3-dimensional Lorentzian space  $\mathbb{R}_1^3$  is called a timelike surface if the induced metric on the surface

is a Lorentzian metric. A ruled surface is a surface swept out by a straight line  $Y$  moving along a curve  $\alpha$ . The various positions of the generating line  $Y$  are called the rulings of the surface. Such a surface, thus has a parametrization in ruled form as follows:

$$\varphi(t, v) = \alpha(t) + vY(t).$$

We call  $\alpha$  to be the base curve and  $Y$  to be the director curve. If the tangent plane is constant along a fixed ruling, then the ruled surface is called a developable surface. The remaining ruled surfaces are called skew surfaces. If there exists a common perpendicular to two preceding rulings in the skew surface, then the foot of the common perpendicular on the main ruling is called a central point. The locus of the central points is called the curve of striction [1, 5].

## §2. Null Scrolls in $\mathbb{R}_1^3$

Let  $\alpha : M \rightarrow \mathbb{R}_1^3$  be a null curve, namely, a smooth curve whose tangent vectors  $\alpha'(t)$ ,  $\forall t \in I$  are null. For a given smooth positive function  $d = d(t)$  let us put

$$(2.1) \quad X = X(t) = d^{-1}\alpha'.$$

Then  $X$  is a null vector field along  $\alpha$ . Moreover, there exists a null vector field  $Y$  along  $\alpha$  satisfying  $\langle X, Y \rangle = -1$ . Here if we put  $Z = X \wedge Y$  then we can obtain a (proper) null frame field  $F = \{X, Y, Z\}$  along  $\alpha$ . In this case the pair  $(\alpha, F)$  is said to be a (proper) framed null curve.

If the null vector  $Y$  moves along  $\alpha$ , then the ruled surface is given by the parametrization  $(I \times \mathbb{R}, \varphi)$  where

$$\varphi : I \times \mathbb{R} \rightarrow \mathbb{R}_1^3$$

is given by

$$(t, v) \rightarrow \varphi(t, v) = \alpha(t) + vY(t), \quad t \in I, \quad v \in J,$$

which can be obtained in the 3-dimensional Lorentzian space  $\mathbb{R}_1^3$ . Then the ruled surface is called a *null scroll* and denoted by  $M$ . It is a timelike surface.

Let  $\alpha$  be a (proper) framed null curve and  $\nabla$  be Levi-Civita connection on  $\mathbb{R}_1^3$ . Then a framed null curve  $\alpha$  satisfies the following Frenet equations

$$(2.2) \quad \begin{cases} \nabla_X X = aX + bZ \\ \nabla_X Y = -aY + cZ \\ \nabla_X Z = cX + bY, \end{cases}$$

where

$$(2.3) \quad \begin{cases} a = -\langle \nabla_X X, Y \rangle \\ b = \langle \nabla_X X, Z \rangle \\ c = \langle \nabla_X Y, Z \rangle \end{cases}$$

are smooth functions [3, 4].

If we fix the parameter  $v$ , then the curve  $\varphi_v : I \times \{v\} \rightarrow M$  sending  $(t, v)$  to  $\alpha(t) + vY(t)$  can be obtained on  $M$ , the tangent vector field of which is given by

$$A = dX - avY + cvZ.$$

**Theorem 2.1.** *Let  $M$  be a null scroll. Then the tangent planes along a ruling of  $M$  coincide if and only if  $a = c = 0$ .*

*Proof.* Straightforward computation.  $\square$

Then we have following:

**Corollary 2.2.** *The null scroll  $M$  is developable if and only if  $a = c = 0$ .*

**Lemma 2.3.** *For the null scroll  $M$  we have*

$$(2.4) \quad a = -\det(Y, Z, \nabla_X X)$$

$$(2.5) \quad c = -\det(X, Y, \nabla_X Y).$$

*Proof.* The equations (2.2) infer the two equalities.  $\square$

### §3. Position vector of a central point and pseudo-orthogonal trajectory for the null scrolls

If the distance between the central point and the base curve of a null scroll (which is a skew timelike surface), is  $\bar{u}$ , then the position vector  $\bar{\alpha}(t)$  can be expressed by  $\bar{\alpha}(t, \bar{u}) = \alpha(t) + \bar{u}Y(t)$ , where  $\alpha(t)$  is the position vector of the base curve and  $Y(t)$  is the directed vector belonging to the ruling. The parameter  $\bar{u}$  can be expressed in terms of position vector of the base curve and directed vector of the ruling. Consider three preceding rulings of a null scroll such that the first one is  $Y(t)$ , and the second one is  $Y(t) + dY(t)$ . Let  $P, P'$  and  $Q, Q'$  be the feet on the rulings of the common perpendicular to the two preceding rulings. The common perpendicular to  $Y(t)$  and  $Y(t) + dY(t)$  is  $Y(t) \wedge dY(t)$ .

The vector  $\overrightarrow{PQ}$  coincides with the vector  $\overrightarrow{PP'}$  in the limiting position, and  $\overrightarrow{PQ}$  will be the tangent vector of the curve of striction. Thus, we have

$$\langle \nabla_X Y, \overrightarrow{PQ} \rangle = 0.$$

Therefore, we get

$$(3.6) \quad \bar{u} = -ad/c^2.$$

Hence the curve of striction is given by

$$(3.7) \quad \bar{\alpha}(t) = \alpha(t) - \frac{\langle \nabla_X Y, dX \rangle}{\langle \nabla_X Y, \nabla_X Y \rangle} Y(t),$$

where  $\langle \nabla_X Y, \nabla_X Y \rangle \neq 0$  and  $ad/c^2$  is constant.

**Theorem 3.1.** *The curve of striction  $\bar{\alpha}$  is independent on the choice of the base curve  $\alpha$  for the non-developable null scroll  $M$ .*

*Proof.* Let  $\beta$  be a another base curve of the null scroll  $M$ , that is, let

$$\varphi(t, v) = \alpha(t) + vY(t)$$

and

$$\varphi(t, s) = \beta(t) + sY(t)$$

be two different base curve for the null scroll  $M$ . Then from (3.7) we obtain

$$\bar{\alpha}(t) - \bar{\beta}(t) = 0,$$

thus the proof is complete.

**Theorem 3.2.** *Let  $M$  be a nondevelopable null scroll. Then  $\varphi(t, v_0)$  on the ruling through the point  $\alpha(t)$  is a central point if and only if  $\nabla_X Y$  is a normal vector of the tangent plane at  $\varphi(t, v_0)$ .*

*Proof.* Let  $M$  be a nondevelopable null scroll and  $\nabla_X Y$  be a normal of the tangent plane at  $\varphi(t, v_0)$  on the ruling through  $\alpha(t)$ . The tangent vector field of the curve

$$\varphi_{v_0} : I \times \{v_0\} \rightarrow M$$

is  $A = dX - av_0Y + cv_0Z$ . Thus  $\langle \nabla_X Y, A \rangle = 0$ . Then we get  $v_0 = -ad/c^2$ . Therefore  $\varphi(t, v_0)$  is a central point of  $M$ .

Conversely, let  $\varphi(t, v_0)$  be a central point on the ruling through  $\alpha(t)$ . Then we obtain  $\langle \nabla_X Y, Y \rangle = 0$  and  $\langle \nabla_X Y, A \rangle = ad + c^2v = 0$ .

Thus  $\nabla_X Y$  is a normal vector of the tangent plane at  $\varphi(t, v_0)$ .

**Theorem 3.3.** *Let  $M$  be a nondevelopable null scroll. The curve of striction*

$$(3.8) \quad \bar{\alpha}(t) = \alpha(t) - \frac{ad}{c^2}Y(t)$$

*is a timelike curve in a null scroll  $M$ .*

*Proof.* If we use the equation (3.8), we can show easily that the tangent vector field of the curve of striction is a timelike vector field.  $\square$

We know that, if there is a curve which meets perpendicularly each of the rulings, then this curve is called an *orthogonal trajectory* of a ruled surface which base curve is non-null. Hence we have

**Definition 3.1.** Let  $M$  be a null scroll in  $\mathbb{R}_1^3$ . If there exists a curve which makes constant angle with each one of the rulings, the this curve is called a *pseudo-orthogonal trajectory* of  $M$ .

**Theorem 3.4.** *Let  $M$  be a null scroll in  $\mathbb{R}_1^3$ . Then there exists a unique pseudo-orthogonal trajectory of  $M$  through each point of  $M$ .*

*Proof.* Let  $\varphi : I \times J \rightarrow \mathbb{R}_1^3$ , defined by

$$\varphi(t, v) = \alpha(t) + vY(t)$$

be a parametrization of  $M$ . A pseudo-orthogonal trajectory of  $M$  is given by  $\beta : \tilde{I} \rightarrow M$ , where

$$\beta(t) = \alpha(t) + f(t)Y(t), \quad t \in \tilde{I}$$

and  $\langle \beta', Y \rangle = \text{const}$ . We may assume that  $\tilde{I} \subset I$ .

Now we want to get a curve which passes through the point  $p_0 = \varphi(t_0, v_0)$ . Thus we can write

$$p = \alpha(t) + f(t)Y(t), \quad p_0 = \alpha(t_0) + v_0Y(t_0).$$

Therefore we get  $\alpha(t) = \alpha(t_0)$  and  $f(t) = v_0$ .

If we choose  $I$  such that it is one to one, then we have  $t = t_0$ . Therefore the pseudo-orthogonal trajectory of  $M$  through the point  $p_0$  is unique. Since this pseudo-orthogonal trajectory of  $M$  makes a constant angle with each of the rulings of  $M$ , we have  $I = I$ . Thus the proof is complete.  $\square$

**Theorem 3.5.** *Let  $M$  be a null scroll in  $\mathbb{R}_1^3$ . The shortest distance between two rulings is measured only on the curve of striction which is one of the pseudo-orthogonal trajectories.*

*Proof.* We consider two rulings which pass through the points  $\alpha(t_1)$  and  $\alpha(t_2)$ , where  $t_1, t_2 \in I$  and  $t_1 < t_2$ . We compute the length  $\ell(v)$  of an pseudo-orthogonal trajectory between these two rulings

$$\ell(v) = \int_{t_1}^{t_2} \|A\| dt = \int_{t_1}^{t_2} (2adv + c^2v^2)^{\frac{1}{2}} dt.$$

To find the value of  $t$  which minimizes  $\ell(v)$ , we notice that

$$\frac{\partial \ell(v)}{\partial v} = 0,$$

which infers  $v = -ad/c^2$ . This completes the proof.  $\square$

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