A Newly Designed Resonance Frequency Analysis Device for Dental Implant Stability Detection

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Resonance frequency (RF) analysis technology was used to design a new dental implant stability detector. To calibrate and test the performance of this novel apparatus, *in vitro* and *in vivo* models, respectively, were used. The RF values of the test implants detected using our new device and a commercially available analogous device (Osstell) were compared. Further, implant stability status was also detected clinically using our device at 2, 4, 8, and 12 weeks after surgery. A high correlation was demonstrated between the values measured with the two devices (y=0.31x-12.45; R²=0.98, p<0.05). In our clinical tests, an initial RF value above 10.0 kHz indicated that the implant was ready to accept functional loading, while values in the 4.0–10.0 kHz range reflected the need for further ossecintegration. In conclusion, these results indicated that our new device might be useful in a clinical setting for evaluating the healing status of a placed implant.

Keywords: Resonance frequency, Dental implant, Device

INTRODUCTION

Presently, development and research pertaining to root form dental implants have advanced to the mature stage. However, the multi-step process of implant treatment is time-consuming and limited in terms of patient acceptance. Although the one-stage implant system provides a partial solution to these problems, the issue of immediate loading is the next logical step to execute¹⁾ — and hence the next logical decision to contend with when considering implant stability. Immediate loading refers to a restoration placed in occlusion with the opposing dentition within 48 hours of implant placement². When the appropriate implant conditions are present, most implants can be immediately loaded. Indeed, many research studies have indicated that the success rate of immediate loading is good³⁻⁴⁾. However, primary implant stability is one of the principal factors that governs a dentist's decision on whether a given implant is suitable for accepting immediate loading. Presently, few devices and methods are available for the accurate detection of implant stability immediately after placement.

The use of resonance frequency (RF) to evaluate the extent of bone healing with orthopedic treatment has been studied by many scholars. However, due to the effects of soft tissue, such techniques remain unavailable clinically⁵. In dental research, several recent studies have examined this issue. The results showed that, in principle, RF can be used to monitor the process of osseointegration after dental implant emplacement⁶⁻⁸⁾.

Osstell (Integration Diagnostics, Göteborgsvängen, Sweden), an RF device based on utilizing harmonic response for monitoring dental implant status, became commercially available in the year 2000. In clinical applications, a transducer is attached to the dental implant fixture and triggered to vibrate by means of sinusoidal waves. The resonance frequency value thus obtained is converted to give an Implant Stability Quotient (ISQ) for analyzing implant stability⁹⁻¹²⁾. Recently, this device has been used in implant research to perform the following tasks: compare the success rates between conventional and early loading of implants¹³⁻¹⁴, evaluate the survival rates of transmucosal implants immediately restored with single crowns¹⁵, monitor the differences between immediate and standard delayed loading of implants¹⁶⁻¹⁸⁾, profile physiological and geometric factors affecting immediate loaded $\operatorname{implants}^{19-20)}$, and measure stability achieved with one-stage surgical procedures²¹⁻²²⁾. However, clinical investigation has indicated that temporary attachment, removal, and sterilization of the transducer are time-consuming and far from being cost-effective¹⁷. In addition, the ISQ value is often influenced by the orientation of the Osstell's L-shaped transducer to the alveolar ridge^{19,23)}.

Another type of RF analysis, based on impulse force triggering, has proven useful in terms of detecting dental implant stability in a series of *in vivo* and *in vitro* experiments²⁴⁻²⁰. In this study, therefore, the capability of a novel RF detection device based on impulse force triggering for monitoring dental implant stability was tested. To reduce measurement operation time, a minimum contact device that did not require additional installation and/or disassembly was designed. To validate the device in terms of implant stability determination, a series of *in vitro* and *in vivo* tests was performed. Finally, the standard value for this novel technique, which was to be an indicator of a test implant's readiness for immediate loading, was determined by means of clinical data analysis.

MATERIALS AND METHODS

Device design

As shown in Fig. 1, our new device incorporated a minimum contact transducer and an attached handpiece. The handle could be rotated to improve access in the limited space of the oral cavity (Fig. 1(a)). The device consisted of two sections of an electromagnetic coil to provide driving feedback for the demagnetized iron impact head (Fig. 1(b)). When the impulse current passed through the first coil section, the generated electromagnetic field attracted the impact head and drove it to strike against the healing abutment. An impact force of 0.18 N was thereby delivered, as determined by a pressuresensitive film (Prescale Pressure Series, Fuji Photo Film, Tokyo, Japan). The second section then generated an electromagnetic field in the opposite direction, retracting the impact head to its original position. When the impact head strike the test implant, the resultant vibration was detected via a piezoelectric microphone and the vibration signal sent to a spectrum analyzer (resolution: 50 Hz; Implomates System, Biotech One, Taipei, Taiwan). The specific resonance frequency of the test implant was determined from the relatively highest point with a peak value for vibration amplitude. This device was used throughout the entire research.

In vitro testing

To validate the experimental device, a series of *in vitro* tests was carried out. A commercial pure titanium dental implant ($@3.75 \times 10$ mm; 3i Innovation, FL) with a 6-mm healing abutment was fixed using a metal clamp stand. RF values for the test implant were recorded while the clamp torque was varied (2 to 10 N·cm in 2 N·cm increments). In addition, the clamping level was altered to expose the implant and alter the vibrational length (0.8 mm in 2 mm steps upward from the base of the implant). Accuracy of the experimental device was tested by comparing the results with those obtained using a conventional excitation method (Osstell). Before RF detection with Osstell, a piezoelectric transducer was connected to the dental implant fixture. Transducer

vibration was triggered by 1-V sinusoidal waves in the 5 - 15 kHz range. The first RF value detected by the device was used for implant stability analysis.

Animal study

Five healthy adult beagles (weighing 8 - 12 kg) were used as test subjects in the animal study. Three months prior to implantation, the mandibular first premolars were bilaterally removed under general (intravenous injection of 0.5 mg/kg ketamine, followed by intramuscular injection of 25 mg/kg pentobarbital) and local anesthesia (2% lidocaine) (Showa Co., Tokyo, Japan). Prior to dental implant surgery, the animals were again anesthetized as described above. Crestal incisions were followed by flap reflection to expose the alveolar crest. The





surgical sites were prepared using the standard procedures specified by the dental implant manufacturer.

Test implants (Ø3.75 × 10 mm; 3i Innovation, FL) were placed into the drilled holes at the left first premolar of each animal until their collar margin reached the boundary of the cortical bone. Rightside surgical sites without implant placement were treated as controls. In other words, a total of five implants were used for the entire experiment. After implant placement, the flaps were repositioned and sutured. Profuse cooling with cold normal saline solution was used throughout the surgical procedure. After surgery, the animals were fed a soft diet (Quaker Oats, Peterborough, Ontario, Canada) for the first two weeks, and long-acting penicillin was also administered (Penlong XL, Rogar STB, London, Ontario, Canada) at appropriate intervals during this period.

Immediately after placement of the implants, RF was measured using both Osstell and our experimental device. Test setup was identical to that used for the *in vitro* tests above. Measurements were obtained on the implant samples along the buccolingual direction at 0, 2, 4, 8, and 12 weeks after implant surgery. All samples were subjected to five continuous tests, with results reported as the mean and standard deviation of the RF values. Oneway analysis of variance was used to test statistical differences between the test parameters. The experimental design was approved by the Laboratory Animal Research Committee, College of Oral Medicine, Taipei Medical University.

Clinical data collection

Data for continuous RF measurement of 11 implants were collected from seven patients (one female and six male patients). All of whom (mean age of 31.4 years, range of 25 - 48 years at time of surgery) were fully informed of the study protocol before signing written agreements. The recruitment criteria were: no history of oral disease or dental implant surgery. Edentulous areas were located at the mandibular premolar or first molar (Fig. 2(a)). The 3i implants (3i Innovation, FL) were placed in the mandible according to the manufacturer's guidelines for a onestage procedure (Fig. 2(b)). All the implants were covered with a 4-mm healing abutment to avoid oral fluid contamination. Resonance frequencies were measured using our newly designed apparatus immediately after the implants were placed (week 0) and at weeks 2, 4, 8, and 12 after the implantation surgery (Fig. 2(c)). Detection was performed in the buccolingual direction. After a healing period of 12 weeks, the patients received their prostheses using the classic procedure.









Fig. 2 Surgical and test procedures: (a) location of edentulous area; (b) general procedure for implant placement; and (c) resonance frequencies of test implants detected using the new device.

RESULTS

Table 1 shows the RF and ISQ values, as measured in vitro using our novel device and Osstell respectively, for a dental implant with various clamping torques. The mean experimental RF value increased from 14.76 ± 0.02 to 15.11 ± 0.02 kHz in the torque range 2 - 10 N·cm. Similarly, under the same test

(a)

Torque (N·cm) 2 4 6 8 10 Device Osstell (ISQ) 85.67 ± 0.58 88.00 ± 0.00 88.00 ± 0.00 89.00 ± 0.00 89.00 ± 0.00 Newly designed device (kHz) 14.76 ± 0.02 14.90 ± 0.00 15.01 ± 0.02 15.10 ± 0.00 15.11 ± 0.02

Table 1 Comparison of implant measurement data generated by Osstell and new RFA device for different clamping torques

Data are presented as mean \pm SD.

Table 2 Comparison of implant measurement data from Osstell and new RFA device for different clamping levels

Exposed height (mm) 0	2	4	6	8
Device	_				
Osstell (ISQ)	88.00 ± 0.00	77.67 ± 0.00	70.00 ± 0.00	64.67 ± 0.58	56.33 ± 1.53
Newly designed device (kHz)	16.10 ± 0.00	12.31 ± 0.02	9.16 ± 0.02	7.01 ± 0.02	5.29 ± 0.02

Data are presented as mean \pm SD.



Fig. 3 Relationship of data measured *in vitro* for the two devices.

conditions using the Osstell device, the ISQ value also increased from 85.67 ± 0.58 to 89.00 ± 0.00 . However, no differences in ISQ value were detected when clamping torque was increased from 4 to 6 N· cm (ISQ = 88), and from 8 to 10 N·cm (ISQ = 89). Table 2 lists the measurement data for the various clamping levels. When the exposed height of the test implant was increased from 0 to 8 mm, the mean experimental RF value decreased from 16.10 ± 0.00 to 5.29 ± 0.02 kHz. Similarly, the measured ISQ value decreased from 88.00 ± 0.00 to 56.33 ± 1.53 for the same test conditions. Replotting the measurement data from Tables 1 and 2 in Fig. 3, a linear correlation was obtained between the RF values of our newly designed device and ISQ values derived from Osstell (r = 0.991; P<0.01).

All animals used in the *in vivo* study remained in excellent health throughout the course of the experiment. The *in vivo* data, in the form of continuous measurements obtained using our novel device, are plotted in Fig. 4(a). There was a mean significant decrease of 1.45 kHz between initial placement and two weeks post surgery (P<0.05), but a mean significant increase of 2.45 kHz between weeks 2 and 12 (P<0.01). More importantly, when the same implants were tested using the Osstell device, no significant differences were detected between the ISQ values across the experimental period (Fig. 4(b)).

Figure 5 shows the results of the clinical investigation, whereby test implants were divided into three groups. In Group I, the initial RF values were above 9 kHz, remaining high and plateauing at 11 kHz or more by week 12. In Group II, the initial RF values of the implants ranged between 3.58 and 5.3 kHz. These implants remained in excellent health throughout the course of the experiment and completed the osseointegration process. By week 12, the RF values for all the Group II implants were above 9.8 kHz. In Group III, one implant with an initial RF value of 3.56 kHz did not demonstrate an increasing trend in RF value after the first two weeks of healing. Osseointegration of the implant failed, and by week 12 it loosened with a finial RF value of 3.85 kHz. Our short-term results demonstrated a 91% success rate during the first 12 weeks.

To assess the relationship between the RF values of immediate and delayed loaded implants in this study, the resonance frequency increase ratio (RFIR) was defined as the ratio between the initial RF value and the analogous value at week 4. The mean RFIR of Group II implants (1.98 ± 0.31) was significantly higher than that of Group I analog $(1.09 \pm 0.11;$ P<0.005). The plot in Fig. 6 revealed a linear relationship between the RFIR of each test implant and its initial RF (y = - 0.126x + 2.50, R² = 0.811, p<0.05).



Fig. 4 Healing curves generated using RF values obtained from test implants in experimental animals with (a) experimental device and (b) Osstell. The data are presented as mean ± SD.



Fig. 5 RF healing curves from test implants in patients during the 12 weeks post implantation. Solid, short-dashed, and long-dashed lines denote Groups I, II, and III (initial RF values >9, 3.5 - 6, and <4 kHz, respectively).



Fig. 6 Relationship between the initial RF value and RF increase ratio of the successful implants at four weeks post surgery. Open and closed circles denote Group I and Group II implants respectively.

DISCUSSION

Osstell was the first commercially available RF device to test dental implant stability, and the efficacy of this method for monitoring implant status has been proven¹⁰⁻¹²⁾. However, it is somewhat inconvenient and time-consuming¹⁷⁾, and it may even affect the implant-bone interface at the early healing stage. This is because the Osstell transducer must be screwed into the test implant with a torque of 10 $N \cdot cm$, almost half the force used to place an implant. In this light, the mechanical effect of disassembling the healing abutment on the interface in the early stages of osseointegration should be taken into consideration. Against this background, our novel transducer was designed as a minimum contact device with no torque force required during transducer application.

In the development of a medical device, accuracy of the measuring instrument should be an utmost priority for the engineers involved. To validate the effectiveness of our newly designed apparatus, in vitro tests were performed with a view to reducing the physiological effects of measurement. According to previous studies, resonance frequency was affected by bone-implant contact percentage and height of the exposed implant above the marginal bone^{624,25)}. In this study, therefore, both factors were simulated and tested in vitro as in our previous work²⁴⁾. As shown in Fig. 3, a close relationship was demonstrated for the data obtained using Osstell and our device. Thus, it seemed reasonable to suggest that our novel device may be used to monitor changes in implant RF with various boundary conditions, while offering significant functional advantages and without adversely affecting the healing process.

In the present study, the mean RF of the implants placed in animals decreased during the first

two weeks and then increased progressively with time (Fig. 4). These results were consistent with other animal RFA^{14,26)} and reverse torque studies^{16,27)}. This initial reduction in stability might correspond to the remodeling and neo-apposition phases of the necrotized bone¹⁶. However, the stability-return phenomenon was not borne out in our clinical data (Fig. 5). In fact, demonstrating this phenomenon using resonance frequency analysis (RFA) remains controversial. Although a tendency for ISQ to decrease in the initial stage followed by a stable increase has been demonstrated in some clinical studies^{14,18-19,28)}, many RFA-based investigations have not confirmed this phenomenon^{16,23)}. After testing 276 immediate loaded implants using RFA, Balshi et al. suggested that bone types II and III were more consistent in term of stability return, while bone types I and IV were not^{19} .

Primary stability, a function of bone quality, implant design, and surgical procedure, is one of the important factors that influences the survival rate of implants^{17,20,27)}. It has been reported that primary stability can serve as a useful predictor of osseointegration¹⁶. Further, it has been demonstrated that good primary implant stability, as measured by RFA, did not increase significantly during the osseointegration period^{15,16,29}. In this study, it was found that implants with higher stability indeed had relatively stable RF during the whole healing period with a mean RFIR of 1.09 ± 0.112 (Figs. 5 and 6). As constant or slightly increased RF values for immediate loaded implants during the first 4 - 6 weeks have been reported¹⁶, it seemed reasonable to suggest that for implants with initial RF values exceeding 10 kHz (as measured by our device), these implants are ready for immediate loading.

A number of researches have proposed that where the initial ISQ value is above 60, the implant is ready for immediate loading¹⁷⁻¹⁹. However, for implants with ISQ values below 40, this should serve as a warning of early failure¹⁸. Interestingly, this proposed functional threshold of ISQ 60 is equivalent to an RF of 6.10 kHz¹⁸, much lower than our experimentally determined limit of 10 kHz. А negative relationship has been reported between RF value and effective vibrational length above bone level^{8,16,24-25)}. Since the Osstell transducer is an Lshaped device that must be attached to the top of the test implant, the effective vibrational length of test implant would thus be greater than that tested using our device. Accordingly, to compare and exchange measurement data generated using the Osstell system (ISQ) and the analogous information from our own device (in kHz), a transfer function was derived.

As shown in Fig. 3, the relationship between the two parameters was linear with a ratio of 0.3. As the relationship formula in Fig. 3 was obtained from

in vitro tests, the constant in the formula should be modified based on our clinical data. After substituting 10 kHz and 60 ISQ for y and x in Fig. 3 respectively, a new transfer function was derived: y = 0.3x. 8, where y and x are kHz and ISQ values respectively. Based on this function, the early failure threshold of ISQ 40 for Osstell was 4 kHz using our novel device. From Fig. 5, the initial and final RF values of the failed implant (3.56 kHz and 3.85 kHz, respectively) fit the hypothesis well.

The initial RF values of our test implants varied (Fig. 5), probably reflecting the marked interindividual variations in distributions of cortical and trabecular bone, as well as differences between various locations within bone³⁰. After analyzing the RFA data of 120 one-stage implants, Zix *et al.* suggested that a single RFA measurement for an implant at a given time point could not qualify being a full predictor of its future performance²². Repeated measurements of an implant over a period would provide a more credible prognosis of its future status. In this connection, Glauser *et al.* suggested that low RFA levels after one and two months implied risk for future failure¹⁸.

In the current study, implants with lower initial RF values revealed significantly higher RFIR values (Fig. 6). At this juncture, it must be clarified that RFIR was defined in this study for early diagnosis but not for determining the optimal time point for functional loading. However, it seemed reasonable to suggest that the time for functional loading of these implants is when their RF value plateaus or exceeds 9 kHz. Nedir et al. also reported that implants with lower initial ISQ values demonstrated a larger ISQ increase during the healing period¹⁷⁾. In contrast, higher initial stability was associated with a more stable ISQ value. In addition, only the implant with highest stability revealed stability decrease during the first four weeks before remaining stable. These results substantially agreed with our own findings.

Based on the results obtained in the present study, it was therefore reasonable to suggest that our novel RF detection device was suitable for evaluating the integrity of bone union during the osseointegration process. At the same time, our novel device provided functional superiority without adversely affecting the restorative process. Amongst which, the greatest advantage of this new device was its ergonomic superiority. Thus, we proposed that our newly designed RFA apparatus had the potential of delivering substantial benefits to advanced experiments in the future, as well as holding out significant promise for future clinical use.

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