# KERNEL ESTIMATORS FOR SEMI-MARKOV PROCESSES 

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## Summary

In this article we define kernel estimator of sojourn time distribution for Semi Markov processes and prove its consistency and asymptotic normality. We use techniques of regenerative processes to prove the results.

Key words: Kernel estimator; semi-Markov processes; sojourn time distribution.

## 1 Introduction and preliminaries

In this paper, sojourn time distributions for semi-Markov processes are studied. A semi - Markov process is a continuous - time stochastic process $\left\{Y_{t}: t \geq 0\right\}$, which makes transitions from state to state in accordance with a Markov chain, but the amount of time spent in each state before a transition occurs is a random variable depending on the transitions. So $\left\{Y_{t}: t \geq 0\right\}$ can be described as a marked process $\left(T_{1}, Y_{1}\right),\left(T_{2}, Y_{2}\right), \ldots$, where $\left\{Y_{n}\right\}$ is the embedded Markov process and $\left\{T_{1}, T_{2}, \ldots\right\}$ are the sojourn times. As an example, consider a Shock model, a failure model where a system is studied in a random environment. The system is subject to a sequence of randomly occurring shocks and each shock causes a random amount of damage which accumulate over time. Let $\left\{T_{n}\right\}$ be the time points at which shocks occur and let $Y_{t}$ be the accumulated damage level at time $\mathrm{t}\left(Y_{n}=Y\left(T_{n}\right)\right)$. An interesting problem is related to the distribution time for the next shock when the damage is at level $y$.

Let $\mathbf{X}=\left\{X_{n}: n=0,1, \ldots\right\}$ be a Markov chain with state space $(S, \Sigma)$. In what follows we assume S the set $\Re$ of real numbers and $\Sigma=B(\Re)$, the Borel $\sigma$-algebra. Assume that there exists a point $\Delta \in \Re$ such that
$P_{x}\left(T_{\Delta}<\infty\right)=1$ and $E_{\Delta} T_{\Delta}<\infty$. It can be seen in Atuncar (1994) that if $\left\{X_{n}: n=0,1, \ldots\right\}$ is a Harris chain then for some $n_{0} \geq 1,\left\{X_{n n_{0}}\right.$ : $n=0,1, \ldots\}$ is a Markov chain for which a distinguished point $\Delta$ can be constructed by enlarging the state space. Thus the results of this study apply to Harris chains.

Let $\{G(x,):. x \in \Re\}$ be a family of distribution functions such that $G(x, 0)=0$ for all $x \in \Re$. Let $\left\{T_{n}: n=0,1, \ldots\right\}$ be a sequence of independent random variables such that, given $\left\{X_{n}: n=0,1, \ldots\right\}$,

$$
P\left(T_{n} \leq t \mid\left\{X_{n}: n=0,1, \ldots\right\}\right)=G\left(X_{n}, t\right) \quad \text { for all } t \geq 0
$$

These $\left\{T_{n}: n=0,1, \ldots\right\}$ are called sojourn times. Let $S_{0}=0, S_{n}=$ $\sum_{i=0}^{n-1} T_{i}$ for $n \geq 1$ and let

$$
Y_{t}=X_{n} \quad S_{n} \leq t<S_{n+1}, n=0,1,2, \ldots
$$

Since $P_{x}\left(X_{n}=\Delta\right.$ for some $\left.n \geq 1\right)=1,\left\{X_{n}: n=0,1, \ldots\right\}$ hits $\Delta$ infinitely often, say at $N_{1}, N_{2}, \ldots$ and so by the strong law of large numbers, $\sum_{i} T_{N_{i}}=\infty$ with probability 1 and hence $S_{n} \rightarrow \infty$ with probability 1 and so $Y_{t}$ is well defined for all $t$. The process $\left\{Y_{t}: t \geq 0\right\}$ has state space $\Re$ and is not Markovian unless $G(x,$.$) is exponential for all x$. However, $\left\{Y_{S_{n}}=X_{n}: n=0,1, \ldots\right\}$ is still a Markov chain. Thus $\left\{Y_{t}: t \geq 0\right\}$ sampled at $t=S_{n}, n=0,1,2, \ldots$ is Markov but not for all $t \geq 0$. For this reason it is called a semi-Markov process.

Results for kernel estimators for the stationary density $f$ and the transition density $t$ of the Markov chain $\left\{X_{n}: n=0,1, \ldots\right\}$ were established in Atuncar (1994).

The main goals in this paper will be to propose estimator for $G(x, t)$ and prove its properties. We observe the process up to time $n$. Besides the information $\left\{X_{0}, X_{1}, \ldots, X_{n}\right\}$, we have $\left\{T_{0}, T_{1}, \ldots, T_{n-1}\right\}$ where, for $i=0,1, \ldots, n-1, T_{i}$ is the sojourn time in $X_{i}$.

Fix $x \in \Re \backslash\{\Delta\}$, the set of the real numbers different than $\Delta$ and take $A_{n}=\left(x-\delta_{n}, x+\delta_{n}\right)$. During $\{0,1, \ldots, n\}$ let $N_{1}, N_{2}, \ldots, N_{L_{n}}$ be the times of visits by the process to $A_{n}$; i.e., for $i=1,2, \ldots, L_{n}, X_{N_{i}} \in A_{n}$; and let $T_{N_{i}}$ be the corresponding sojourn times. Given $X_{0}, X_{1}, \ldots, X_{n}$; $T_{N_{i}}: i=1,2, \ldots, L_{n}$ are independent, but not identically distributed.

Define

$$
G_{n}(x, t)=\frac{1}{L_{n}} \sum_{i=1}^{L_{n}} I\left(T_{N_{i}} \leq t\right)
$$

We propose $G_{n}(x, t)$ as an estimator of $G(x, t)$. Using the techniques of regenerative processes, introduced by Athreya and Ney (1978), we will prove consistency of $G_{n}(x, t)$ in Section 2 and asymptotic normality in Section 3. We finish this section with the formal definition of Harris recurrence and establishing, without proofs, some results from the literature.

Definition 1.1 A Markov chain $\left\{X_{n}: \mathrm{n}=0,1,2, \ldots\right\}$ is called Harris recurrent if there exist a set $A \in \Sigma$, a probability measure $\phi$ on $A$, a real number $\epsilon>0$, and an integer $n_{0}>0$ such that

$$
\begin{gather*}
P_{x}\left(\tau_{A}<\infty\right)=P_{x}\left(X_{n} \in A \text { for some } n \geq 1\right)=1 \forall x \in S  \tag{1.1}\\
P_{x}\left(X_{n_{0}} \in E\right)=P^{\left(n_{0}\right)}(x, E) \geq \epsilon \phi(E) \forall x \in A . \text { and } \forall E \subset A \tag{1.2}
\end{gather*}
$$

In what follows, we assume $n_{0}=1$ and will say $(A, \epsilon, \phi, 1)$ recurrent instead of Harris recurrent.

Lemma 1.2 (Regeneration Lemma) If $\mathbf{X}$ is $(A, \epsilon, \phi, 1)$ recurrent, then there exists a random time $N$ such that $P_{x}(N<\infty)=1$ and

$$
\begin{aligned}
a(x, n, k) & \stackrel{\text { def }}{=} P_{x}\left(X_{n} \in A, X_{n+1} \in A_{1}, \ldots, X_{n+k} \in A_{k}, N=n\right) \\
& =P_{x}(N=n) \int_{A} P_{y}\left(X_{1} \in A_{1}, \ldots, X_{k} \in A_{k}\right) \phi(d y) .
\end{aligned}
$$

That is, the evolution of the process for $n \geq N$ is independent of $X_{1}, X_{2}$, $\ldots, X_{N-1}$ and $N$ and has the same distribution as $\mathbf{X}$ where $X_{0}$ is distributed according to $\phi$. Thus $N$ is a random time such that the pre- $N$ and post- $N$ evolution are independent and the post- $N$ process has a distribution independent of $X_{0}, \ldots, X_{N-1}$.

Corollary 1.3 If $\mathbf{X}$ is $(A, \epsilon, \phi, 1)$ recurrent, then there exists a sequence of random times $\left\{N_{i} ; i=1,2, \ldots\right\}$ such that for any $x$, under $P_{x}, X_{N_{i}}$ have distribution $\phi$ on $A$, and the random tours $\left\{X_{N_{i}+j}: j=0,1,2, \ldots, N_{i+1}-\right.$ $\left.N_{i}-1 ; N_{i+1}-N_{i}\right\}$ are independent, identically distributed, and independent of $N_{1}$.

The regeneration lemma can be used to show the existence of a stationary measure for Harris recurrent chains.

Theorem 1.4 Let $N_{1}$ be the regeneration time as in Lemma 1.2. Define

$$
\begin{equation*}
\nu(E)=E_{\phi} \Sigma_{i=0}^{N_{1}-1} I\left(X_{i} \in E\right) . \tag{1.3}
\end{equation*}
$$

Then $\nu$ is a stationary measure for $\mathbf{X}$, and it is unique up to a multiplicative constant.
Since $\nu(S)=E_{\phi} N_{1}, \nu$ is finite if and only if $E_{\phi} N_{1}<\infty$.
Corollary 1.5 A stationary probability distribution $\pi($.$) for \mathbf{X}$ exists if and only if $E_{\phi} N_{1}<\infty$, and in this case, $\pi(E)=\frac{\nu(E)}{\nu(S)}$.

Proofs are in Athreya and Ney (1978).
Another characterization of the stationary measure $\nu$ is given by the following theorem.

Theorem 1.6 Let $g$ be any bounded measurable function.
(a) For a Harris recurrent chain, a measure $\nu$ satisfies (1.3) if and only if

$$
\begin{equation*}
\int_{S} g d \nu=E_{\phi} \Sigma_{i=0}^{N_{1}-1} g\left(X_{i}\right) \tag{1.4}
\end{equation*}
$$

(b) Define $\operatorname{Tg}(x)=E_{x} \Sigma_{j=1}^{N_{1}-1} g\left(X_{j}\right)$. Then

$$
E_{\phi}\left(\Sigma_{j=0}^{N_{1}-1} g\left(X_{j}\right)\right)^{2}=\int_{S} g^{2}(x) \nu(d x)+2 \int_{S} g(x)(T g)(x) \nu\left(d x x_{1} .5\right)
$$

Let $\Delta$ be a real number. For Theorems 1.7 and 1.8, define

$$
\begin{aligned}
& T_{\Delta}^{(1)}=\inf \left\{k>0: X_{k}=\Delta\right\} \\
& T_{\Delta}^{(2)}=\inf \left\{k>T_{\Delta}^{(1)}: X_{k}=\Delta\right\}
\end{aligned}
$$

Suppose $T_{\Delta}^{(i-1)}$ defined and define

$$
T_{\Delta}^{(i)}=\inf \left\{k>T_{\Delta}^{(i-1)}: X_{k}=\Delta\right\}
$$

Theorem 1.7 Let $\left\{X_{n}: n=0,1, \ldots\right\}$ be a real-valued Markov chain with stationary transition function. Assume that for any $x \in \Re, P_{x}\left(T_{\Delta}^{(1)}<\right.$ $\infty)=1$ and $\operatorname{Var}_{\Delta}\left(T_{\Delta}^{(1)}\right)<\infty$.
Let $\pi(A)=\frac{E_{\Delta} \sum_{j=0}^{T_{j}^{(1)}-1} I_{A}\left(X_{j}\right)}{E_{\Delta} T_{\Delta}^{(1)}}$ for any Borel set $A$ in $R$. Assume that $\pi$ is absolutely continuous w.r.t Lebesgue measure on $\Re \backslash\{\Delta\}$. Let $f$ be the corresponding density. Let $\delta_{n}>0$ and $p_{n}(x)=\frac{1}{2 n \delta_{n}} \sum_{j=0}^{n} I_{A_{n}}\left(X_{j}\right)$ where $A_{n}=\left(x-\delta_{n}, x+\delta_{n}\right)$. If $\delta_{n} \rightarrow 0$ and $n \delta_{n} \rightarrow \infty$, then for almost all $x$ and for every initial distribution,

$$
p_{n}(x) \rightarrow f(x) \quad \text { in probability. }
$$

Proofs are in Atuncar (1994).
Theorem 1.8 Let $\left\{X_{n}: n=0,1, \ldots\right\}$ be a Harris chain with a recurrence point $\Delta$. Let $\lambda=E_{\Delta} T_{\Delta}$ and $\sigma^{2}=\operatorname{Var}_{\Delta}\left(T_{\Delta}\right)$. Let $K_{n}$ be the random number of visits to $\Delta$ by the chain during $\{0,1,2, \ldots, n\}$. That is $K_{n}=$
$\sum_{j=0}^{n} I\left(X_{j}=\Delta\right)$. Then the family
$\left\{n-T_{\Delta}^{\left(K_{n}\right)}: n=1,2, \ldots\right\}$ is tight and

$$
\begin{gather*}
\frac{K_{n}}{n} \rightarrow \frac{1}{\lambda} \text { a.e. as } n \rightarrow \infty  \tag{1.6}\\
\sqrt{n}\left(\frac{K_{n}}{n}-\frac{1}{\lambda}\right) \xrightarrow{d} N\left(0, \frac{\sigma^{2}}{\lambda^{3}}\right) . \tag{1.7}
\end{gather*}
$$

Assertions (1.6) and (1.7) follow from the discrete version of Proposition 1.4, Chapter IV and Proposition 4.3, Chapter VI in Asmussen (1987). The first assertion is also derivable from the same material.

## 2 Consistency of $G_{n}(x, t)$

The main result of this section is Theorem 2.3 establishing weak consistency of $G_{n}(x, t)$.

Lemma 2.1 Let $\left\{k_{n}: n=1,2, \ldots\right\}$ be a sequence of integers such that $\frac{k_{n}}{n} \rightarrow \alpha, 0<\alpha<\infty$. For $i=1,2, \ldots, k_{n}$, define

$$
\begin{gathered}
\xi_{n i}=\sum_{j=T_{\Delta}^{(i)}}^{T_{\Delta}^{(i+1)}-1} \frac{1}{2 \delta_{n}}\left|G\left(X_{j}, t\right)-G(x, t)\right| I\left(X_{j} \in A_{n}\right) \\
\text { If } \lim _{\delta_{n} \rightarrow 0} \int_{|x-y|<\delta_{n}} \frac{1}{2 \delta_{n}}|G(y, t)-G(x, t)| f(y) d y=0 \text {, then } \\
\bar{\xi}_{n} \equiv \frac{1}{k_{n}} \sum_{i=1}^{k_{n}} \xi_{n i} \rightarrow 0 \text { in probability. }
\end{gathered}
$$

Proof: Since $\left\{\xi_{n i}: i=1,2, \ldots\right\}$ are i.i.d, see for example Asmussen (1987), and $E_{\Delta} \xi_{n 1} \rightarrow 0$ by hypothesis, $E_{\Delta} \bar{\xi}_{n} \rightarrow 0$ and since $\bar{\xi}_{n} \geq 0$, the result follows.

Lemma 2.2 Let $\left\{K_{n}: n=1,2, \ldots\right\}$ be a sequence of integer random variables such that $\frac{K_{n}}{n} \rightarrow \alpha$ with probability 1 for some $0<\alpha<\infty$. Under the hypothesis of Lemma 2.1,

$$
\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i} \quad \rightarrow \quad 0 \quad \text { in probability }
$$

Proof: Let $\epsilon>0, \theta>0$ and let $A(n, \alpha, \epsilon)=\left\{n(\alpha-\epsilon)<K_{n}<n(\alpha+\epsilon)\right\}$

$$
\begin{aligned}
& P_{\Delta}\left[\left|\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}\right|>\theta\right]=P_{\Delta}\left[\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}>\theta\right]+P_{\Delta}\left[\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}<-\theta\right] \\
&=\alpha_{n 1}+\alpha_{n 2} \quad \text { (say). } \\
& \alpha_{n 1}=P_{\Delta}\left[\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}>\theta, A(n, \alpha, \epsilon)\right]+P_{\Delta}\left[\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}>\theta, A^{c}(n, \alpha, \epsilon)\right] .
\end{aligned}
$$

Since $\frac{K_{n}}{n} \rightarrow \alpha$ w.p. 1; the second term converges to zero. Now,

$$
\begin{aligned}
& P_{\Delta}\left[\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}>\theta, A(n, \alpha, \epsilon)\right] \\
\leq & P_{\Delta}\left[\frac{1}{[n(\alpha-\epsilon)]} \sum_{i=1}^{[n(\alpha+\epsilon)]+1} \xi_{n i}>\theta, A(n, \alpha, \epsilon)\right] \\
= & P_{\Delta}\left[\frac{[n(\alpha+\epsilon)]+1}{[n(\alpha-\epsilon]} \frac{1}{[n(\alpha+\epsilon)]+1} \sum_{i=1}^{[n(\alpha+\epsilon)]+1} \xi_{n i}>\theta, A(n, \alpha, \epsilon)\right] .
\end{aligned}
$$

Since $\lim _{\epsilon \rightarrow 0} \lim _{n \rightarrow \infty} \frac{[n(\alpha+\epsilon)]+1}{[n(\alpha-\epsilon)]}=1$ as $n \rightarrow \infty$, the last probability converges to zero by Lemma 2.1. Similarly it is proved that $\alpha_{n 2} \rightarrow 0$.

Theorem 2.3 Fix $x \in R \backslash\{\Delta\}$. Let $f(x)>0$. Let $\delta_{n} \rightarrow 0$. If

$$
\begin{array}{r}
\lim _{\delta_{n} \rightarrow 0} \int_{|x-y|<\delta_{n}} \frac{1}{2 \delta_{n}}|G(y, t)-G(x, t)| f(y) d y=0, \\
\frac{1}{2 \delta_{n}} \int_{A_{n}} f(y) d y \rightarrow f(x) \text {, and } n \delta_{n} \rightarrow \infty \text { as } n \rightarrow \infty \text {, then } \\
G_{n}(x, t) \rightarrow G(x, t) \quad \text { in probability. }
\end{array}
$$

Remark 2.4 The first condition means that the averages of $\mid G(y, t)-$ $G(x, t)$, weighted by $f$, are small on small intervals centered at $x . x$ is a kind of Lebesgue point. In particular, if $G(., t)$ is continuous at $x$ this condition holds. If f is locally integrable in $(\Re, B(\Re))$ with respect to Lebesgue measure, the second condition holds by Lebesgue density theorem.

Proof: Recall that $N_{1}, N_{2}, \ldots, N_{L_{n}}$ are times of visits to $A_{n}$ and

$$
\begin{aligned}
G_{n}(x, t)= & \frac{1}{L_{n}} \sum_{j=1}^{L_{n}} I\left(T_{N_{j}} \leq t\right) \\
= & \frac{1}{L_{n}} \sum_{j=1}^{L_{n}}\left[I\left(T_{N_{j}} \leq t\right)-G\left(X_{N_{j}}, t\right)\right] \\
& +\frac{1}{L_{n}} \sum_{j=1}^{L_{n}}\left[G\left(X_{N_{j}}, t\right)-G(x, t)\right]+G(x, t) \\
= & \beta_{n 1}+\beta_{n 2}+G(x, t) .
\end{aligned}
$$

It was proved in Atuncar (1994) that if $\frac{1}{2 \delta_{n}} \int_{A_{n}} f(y) d y \rightarrow f(x)$ then $p_{n}(x)=\frac{L_{n}}{2 n \delta_{n}} \rightarrow f(x)$ in probability. So, $L_{n} \rightarrow \infty$ in probability if $f(x)>0$. Besides that, conditioned on $\left\{X_{n}: n=0,1, \ldots\right\},\left(I\left(T_{N_{j}} \leq t\right)-G\left(X_{N_{j}}, t\right)\right)$ are independent random variables with mean zero. Then $\beta_{n 1}$ converges to zero in probability. Next we will prove that $\beta_{n 2}$ converges to zero in probability:

$$
\begin{aligned}
& \frac{1}{L_{n}} \sum_{j=1}^{L_{n}}\left[G\left(X_{N_{j}}, t\right)-G(x, t)\right] \leq \frac{1}{L_{n}} \sum_{j=0}^{n}\left|G\left(X_{j}, t\right)-G(x, t)\right| I\left(X_{j} \in A_{n}\right) \\
& =\frac{1}{L_{n}} \sum_{j=0}^{T_{\Delta}^{(1)}-1}\left|G\left(X_{j}, t\right)-G(x, t)\right| I\left(X_{j} \in A_{n}\right) \\
& \quad+\frac{1}{L_{n}} \sum_{T_{\Delta}^{(1)}}^{T_{\Delta}^{\left(K_{n}\right)}-1}\left|G\left(X_{j}, t\right)-G(x, t)\right| I\left(X_{j} \in A_{n}\right) \\
& \quad+\frac{1}{L_{n}} \sum_{T_{\Delta}^{\left(K_{n}\right)}}^{n}\left|G\left(X_{j}, t\right)-G(x, t)\right| I\left(X_{j} \in A_{n}\right) \\
& =\beta_{n 21}+\beta_{n 22}+\beta_{n 23} \quad \text { (say). }
\end{aligned}
$$

Since $L_{n} \rightarrow \infty$ in probability, $\beta_{n 21}$ converges to zero in probability. Also $\beta_{n 23}$ converges to zero in probability because $\frac{n-T_{\Delta}^{\left(K_{n}\right)}}{L_{n}}$ does by tightness of $\left(n-T_{\Delta}^{\left(K_{n}\right)}\right)$.

Now,

$$
\begin{aligned}
\beta_{n 22} & =\frac{K_{n}}{n} \frac{2 n \delta_{n}}{L_{n}} \frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \sum_{j=T_{\Delta}^{(i)}}^{T_{\Delta}^{(i+1)}-1} \frac{1}{2 \delta_{n}}\left|G\left(X_{j}, t\right)-G(x, t)\right| I\left(X_{j} \in A_{n}\right) \\
& =\frac{K_{n}}{n} \frac{2 n \delta_{n}}{L_{n}} \frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i} .
\end{aligned}
$$

Therefore, by Theorem 1.8, Theorem 1.7, and Lemma 2.2, $\beta_{n 22}$ converges to zero in probability.

## 3 Asymptotic normality of $G_{n}(x, t)$

The main result of this section is Theorem 3.5.

Lemma 3.1 For $i=1,2, \ldots$; define

$$
\Psi_{n i}=\frac{1}{2 \delta_{n}} \sum_{j=T_{\Delta}^{(i)}}^{T_{\Delta}^{(i+1)}-1} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) I\left(X_{j} \in A_{n}\right) .
$$

Let $\frac{1}{\delta_{n}} \int_{A_{n}} E_{u} T_{\Delta} f(u) d u$ and $\frac{1}{\delta_{n}} \int_{A_{n}} f(u) d u$ be bounded in $n$. Then

$$
E_{\Delta}\left(\Psi_{n 1}-E_{\Delta} \Psi_{n 1}\right)^{2}=O\left(\frac{1}{\delta_{n}}\right) .
$$

Proof: Consider $\Psi_{n_{1}}$ as defined above.

$$
\begin{aligned}
& E_{\Delta} \Psi_{n 1}^{2}= \frac{1}{4 \delta_{n}^{2}} E_{\Delta} \sum_{j=0}^{T_{\Delta}^{(1)}-1} G^{2}\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right)^{2} I\left(X_{j} \in A_{n}\right) \\
&+\frac{1}{2 \delta_{n}^{2}} E_{\Delta} \sum_{j=0}^{T_{\Delta}^{(1)}-1} \sum_{k=j+1}^{T_{\Delta}^{(1)}-1} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) G\left(X_{k}, t\right) \\
&= u_{n}+v_{n} \quad\left(1-G\left(X_{k}, t\right)\right) I\left(X_{j} \in A_{n}\right) I\left(X_{k} \in A_{n}\right) \\
& \text { (say). }
\end{aligned}
$$

$$
\begin{aligned}
u_{n} & =\frac{\lambda}{2 \delta_{n}} \int_{A_{n}} \frac{1}{2 \delta_{n}} G^{2}(u, t)(1-G(u, t))^{2} f(u) d u \\
& \leq \frac{\lambda}{64 \delta_{n}} \int_{A_{n}} \frac{1}{\delta_{n}} f(u) d u \\
& =O\left(\frac{1}{\delta_{n}}\right)
\end{aligned}
$$

Next,

$$
\begin{aligned}
v_{n} & =\frac{1}{\delta_{n}} E_{\Delta} \sum_{j=0}^{T_{\Delta}^{(1)}-1} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) I\left(X_{j} \in A_{n}\right) \\
& E_{X_{j}} \sum_{K=1}^{T_{\Delta}^{(1)}-1} \frac{1}{2 \delta_{n}} G\left(X_{k}, t\right)\left(1-G\left(X_{k}, t\right)\right) I\left(X_{k} \in A_{n}\right) \\
& \leq \frac{\lambda}{\delta_{n}} \int_{A_{n}} \frac{1}{2 \delta_{n}} G(u, t)(1-G(u, t)) E_{u}\left(T_{\Delta}^{(1)}-1\right) f(u) d u \\
& \leq \frac{\lambda}{8 \delta_{n}} \int_{A_{n}} \frac{1}{\delta_{n}} E_{u} T_{\Delta} f(u) d u \\
& =O\left(\frac{1}{\delta_{n}}\right)
\end{aligned}
$$

Lemma 3.2 Assume the hypotheses of Theorem 2.3. Let $\left\{k_{n}: n=1,2\right.$, $\ldots\}$ be a sequence of integers such that $\frac{k_{n}}{n} \rightarrow \alpha$ with $0<\alpha<\infty$. Let $\delta_{n} \rightarrow 0$ and $n \delta_{n} \rightarrow \infty$. Then,

$$
\frac{1}{k_{n}} \sum_{i=1}^{k_{n}} \Psi_{n i} \quad \rightarrow \quad \lambda f(x) G(x, t)(1-G(x, t)) \quad \text { in probability. }
$$

## Proof:

$$
\frac{1}{k_{n}} \sum_{i=1}^{k_{n}} \Psi_{n i}=\frac{1}{k_{n}} \sum_{i=1}^{k_{n}}\left(\Psi_{n i}-E_{\Delta} \Psi_{n i}\right)+E_{\Delta} \Psi_{n 1}
$$

By Theorem 1.6, $E_{\Delta} \Psi_{n 1}=\lambda \int_{A_{n}} \frac{1}{2 \delta_{n}} G(y, t)(1-G(y, t)) f(y) d y$ and under the hypotheses of Theorem 2.3, this integral converges to $\lambda f(x) G(x, t)(1-$
$G(x, t))$. So, it is enough to prove that $\frac{1}{k_{n}} \sum_{i=1}^{k_{n}}\left(\Psi_{n i}-E_{\Delta} \Psi_{n i}\right) \rightarrow 0$ in probability:

$$
\begin{aligned}
P_{\Delta}\left(\frac{1}{k_{n}} \sum_{i=1}^{k_{n}}\left(\Psi-E_{\Delta} \Psi_{n i}\right)>\epsilon\right) & \leq \frac{1}{\epsilon^{2} k_{n}} E_{\Delta}\left(\Psi_{n 1}-E_{\Delta} \Psi_{n 1}\right)^{2} \\
& =O\left(\frac{1}{k_{n} \delta_{n}}\right)
\end{aligned}
$$

Similarly, it is proved that $P_{\Delta}\left(\frac{1}{k_{n}} \sum_{i=1}^{k_{n}}\left(\Psi-E_{\Delta} \Psi_{n i}\right)<-\epsilon\right)=O\left(\frac{1}{k_{n} \delta_{n}}\right)$. Since $k_{n} \delta_{n} \rightarrow \infty$, the proof is complete.

Lemma 3.3 Consider $\left\{K_{n}: n=1,2, \ldots\right\}$ a sequence of integer random variables such that $\frac{K_{n}}{n} \rightarrow \alpha$ with probability 1 for some $0<\alpha<\infty$ and assume the hypotheses of Lemma 3.2. Then,

$$
\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \Psi_{n i} \quad \rightarrow \quad \lambda f(x) G(x, t)(1-G(x, t)) \quad \text { in probability }
$$

The proof is similar to the proof of Lemma 2.2.
Lemma 3.4 Under hypotheses of Lemma 3.1 and Lemma 3.2,

$$
\frac{1}{L_{n}} \sum_{j=0}^{L_{n}} G\left(X_{N_{j}}, t\right)\left(1-G\left(X_{N_{j}}, t\right)\right) \rightarrow G(x, t)(1-G(x, t))
$$

in probability.
Proof: Notice that

$$
\begin{aligned}
& \frac{1}{L_{n}} \sum_{j=0}^{L_{n}} G\left(X_{N_{j}}, t\right)\left(1-G\left(X_{N_{j}}, t\right)\right) \\
= & \frac{1}{L_{n}} \sum_{j=0}^{n} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) I\left(X_{j} \in A_{n}\right) \\
= & \frac{2 n \delta_{n}}{L_{n}} \frac{K_{n}}{n} \frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \frac{1}{2 \delta_{n}} \sum_{j=T_{\Delta}^{(i)}}^{T_{\Delta}^{(1+1)}-1} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) I\left(X_{j} \in A_{n}\right) \\
& +\frac{1}{L_{n}} \sum_{j=0}^{T_{\Delta}^{(1)}-1} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) I\left(X_{j} \in A_{n}\right)
\end{aligned}
$$

$$
\begin{aligned}
& +\frac{1}{L_{n}} \sum_{j=T_{\Delta}^{\left(K_{n}\right)}}^{n} G\left(X_{j}, t\right)\left(1-G\left(X_{j}, t\right)\right) I\left(X_{j} \in A_{n}\right) \\
= & \gamma_{n 1}+\gamma_{n 2}+\gamma_{n 3} .
\end{aligned}
$$

By earlier arguments, $\gamma_{n 2}$ and $\gamma_{n 3}$ converge to zero in probability. Also, by Theorem 1.7, Theorem 1.8, and Lemma 3.3 it follows that $\gamma_{n 1}$ converges to $G(x, t)(1-G(x, t))$ in probability, concluding the proof.

Now we establish asymptotic normality of $G_{n}(x, t)$
Theorem 3.5 Assume the following hypotheses:
(i) $\frac{1}{\delta_{n}} \int_{A_{n}} f(y) d y$ is bounded in $n$,
(ii) $\frac{1}{2 \delta_{n}} \int_{A_{n}}|G(y, t)-G(x, t)| f(y) d y \rightarrow 0$,
(iii) $\frac{1}{\delta_{n}} \int_{A_{n}} E_{u} T_{\Delta} f(u) d u$ bounded in $n$,
(iv) $\delta_{n} \rightarrow 0, n \delta_{n} \rightarrow \infty$ as $n \rightarrow \infty$. Assume also that:
(v) There exist $\alpha>0$ and for each $t$, a $C_{t}$ such that $|G(y, t)-G(x, t)| \leq$ $C_{t}|x-y|^{2+\alpha}$ for $y$ near $x$,
(vi) $n \delta_{n}^{p} \rightarrow 0$ for some $1<p \leq 5+2 \alpha$.

Let

$$
Z_{n}=\frac{\frac{1}{L_{n}} \sum_{j=1}^{L_{n}}\left(I\left(T_{X_{N_{j}}} \leq t\right)-G(x, t)\right)}{\sqrt{\frac{1}{L_{n}^{2}} \sum_{j=1}^{L_{n}} G\left(X_{N_{j}}, t\right)\left(1-G\left(X_{N_{j}}, t\right)\right)}}
$$

Then, $Z_{n} \xrightarrow{d} N(0,1)$.
We write

$$
\begin{aligned}
Z_{n}= & \frac{\frac{1}{L_{n}} \sum_{j=1}^{L_{n}}\left(I\left(T_{X_{N_{j}}} \leq t\right)-G\left(X_{N_{j}}, t\right)\right)}{\sqrt{\frac{1}{L_{n}^{2}} \sum_{j=1}^{L_{n}} G\left(X_{N_{j}}, t\right)\left(1-G\left(X_{N_{j}}, t\right)\right)}} \\
& +\frac{\frac{1}{L_{n}} \sum_{j=1}^{L_{n}}\left(G\left(X_{N_{j}}, t\right)-G(x, t)\right)}{\sqrt{\frac{1}{L_{n}^{2}} \sum_{j=1}^{L_{n}} G\left(X_{N_{j}}, t\right)\left(1-G\left(X_{N_{j}}, t\right)\right)}} \\
= & \left.Z_{n 1}+Z_{n 2} \quad \text { (say }\right) .
\end{aligned}
$$

To prove Theorem 3.5, first we will prove Lemma 3.7 and Lemma 3.8 below. For Lemma 3.7 we need the following result from Chung (1974), pp. 199.

Lemma 3.6 Let $\left\{\theta_{n j}, 1 \leq j \leq k_{n}, 1 \leq n\right\}$ be a double array of complex numbers satisfying the following conditions as $n \rightarrow \infty$ :
(i) $\max \left\{\left|\theta_{n j}\right|: 1 \leq j \leq k_{n}\right\} \rightarrow 0$;
(ii) $\sum_{j=1}^{k_{n}}\left|\theta_{n j}\right| \leq M<\infty$, where $M$ does not depend on $n$;
(iii) $\sum_{j=1}^{k_{n}} \theta_{n j} \rightarrow \theta$, where $\theta$ is a (finite)complex number.

Then we have

$$
\prod_{j=1}^{k_{n}}\left(1+\theta_{n j}\right) \rightarrow \exp (\theta)
$$

Lemma 3.7 Let $D=\sigma\left(X_{0}, X_{1}, \ldots\right)$ be the $\sigma$-algebra generated by $\left\{X_{0}\right.$, $\left.X_{1}, \ldots\right\}$. Let $\phi_{n}(\theta)=E_{\Delta}\left[\exp \left(i \theta Z_{n 1}\right) \mid D\right]$. Then for each $\theta$ in $\Re, \phi_{n}(\theta) \rightarrow$ $\exp \left(-\frac{1}{2} \theta^{2}\right)$ in probability.

Proof: Let $\delta_{n j}=I\left(T_{X_{N_{j}}} \leq t\right), p_{n j}=G\left(X_{N_{j}}, t\right), w_{n}=\sqrt{\sum_{j=1}^{L_{n}} p_{n j}\left(1-p_{n j}\right)}$.
For every $\theta$ in $\Re$,

$$
\begin{aligned}
\phi_{n}(\theta) & =E_{\Delta}\left[\left.\exp \left(\frac{i \theta}{w_{n}} \sum_{j=1}^{L_{n}}\left(\delta_{n j}-p_{n j}\right)\right) \right\rvert\, D\right] \\
& =\prod_{j=1}^{L_{n}} E_{\Delta}\left[\left.\exp \left(\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right) \right\rvert\, D\right]
\end{aligned}
$$

(by conditional independence of $\delta_{n j}$ ). Let $a(\theta, n, j)=1+\theta_{n j}$ where $\theta_{n j}=$ $E_{\Delta}\left[\left.\exp \left(\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right)-1 \right\rvert\, D\right]$.

Since $E_{\Delta}\left[\left(\delta_{n j}-p_{n j}\right) \mid D\right]=0$,

$$
\begin{aligned}
\theta_{n j}= & E_{\Delta}\left[\left.\left\{\exp \left(\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right)-1-\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right\} \right\rvert\, D\right] \\
= & E_{\Delta}\left[\left\{\exp \left(\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right)-1-\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right.\right. \\
& \left.\left.-\frac{1}{2}\left(\frac{i \theta}{w_{n}}\right)^{2}\left(\delta_{n j}-p_{n j}\right)^{2}\right\} \mid D\right]-\frac{\theta^{2}}{2 w_{n}^{2}} p_{n j}\left(1-p_{n j}\right) .
\end{aligned}
$$

Since $|\exp (i t)-1-i t| \leq \frac{t^{2}}{2!}$ and $\left|\exp (i t)-1-i t-\frac{(i t)^{2}}{2!}\right| \leq \frac{|t|^{3}}{3!}$ for t real (See Feller (1971), pp 512), we have that

$$
\left|\theta_{n j}\right| \leq \frac{\theta^{2} p_{n j}\left(1-p_{n j}\right)}{2 w_{n}^{2}}
$$

Thus $\sum_{j=1}^{L_{n}}\left|\theta_{n j}\right| \leq \frac{\theta^{2}}{2}$ and $\max \left\{\left|\theta_{n j}\right|: 1 \leq j \leq L_{n}\right\} \leq \frac{\theta^{2}}{8 w_{n}^{2}}$.
From Lemma 3.4, $\frac{w_{n}^{2}}{L_{n}} \rightarrow G(x, t)(1-G(x, t)$ in probability and since $L_{n} \rightarrow \infty$ in probability as well, $\max \left\{\left|\theta_{n j}\right|: 1 \leq j \leq L_{n}\right\} \rightarrow 0$ in probability under conditioning by $D$.

Also

$$
\begin{aligned}
\sum_{j=1}^{L_{n}} \theta_{n j}+\frac{\theta^{2}}{2}= & \sum_{j=1}^{L_{n}} E_{\Delta}\left[\left\{\operatorname { e x p } \left(\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)-1-\frac{i \theta}{w_{n}}\left(\delta_{n j}-p_{n j}\right)\right.\right.\right. \\
& \left.\left.-\frac{1}{2}\left(\frac{i \theta}{w_{n}}\right)^{2}\left(\delta_{n j}-p_{n j}\right)^{2}\right\} \mid D\right]
\end{aligned}
$$

Then

$$
\begin{aligned}
\left|\sum_{j=1}^{L_{n}} \theta_{n j}+\frac{\theta^{2}}{2}\right| \leq & \frac{1}{3!} \sum_{j=1}^{L_{n}}\left(\frac{|\theta|}{w_{n}}\right)^{3} E_{\Delta}\left[\left(\delta_{n j}-p_{n j}\right)^{3} \mid D\right] \\
\leq & 2 \frac{|\theta|^{3}}{3!w_{n}^{3}} \sum_{j=1}^{L_{n}} E_{\Delta}\left[\left(\delta_{n j}-p_{n j}\right)^{2} \mid D\right] \\
& \left(\text { since }\left|\delta_{n j}-p_{n j}\right|^{2} \leq 2\right) \\
\leq & \frac{1}{3} \frac{|\theta|^{3}}{w_{n}}
\end{aligned}
$$

Since $w_{n} \rightarrow \infty$ in probability, $\left|\sum_{j=1}^{L_{n}} \theta_{n j}+\frac{\theta^{2}}{2}\right| \rightarrow 0$ in probability under conditioning by $D$.

For any subsequence $n^{\prime}$ there exists a further subsequence $n^{\prime \prime}$ such that along that, with probability one: $\max \left\{\left|\theta_{n j}\right|: 1 \leq j \leq L_{n}\right\} \rightarrow 0, \sum_{j=1}^{L_{n}} \theta_{n j}+$ $\frac{\theta^{2}}{2} \rightarrow 0$, and $\sum_{j=1}^{L_{n}}\left|\theta_{n j}\right| \leq \frac{\theta^{2}}{2} ;$ and so by Lemma 3.6, $\phi_{n}(\theta) \rightarrow \exp \left(-\frac{\theta^{2}}{2}\right)$ w.p. 1 along that subsequence $n^{\prime \prime}$. This being true for every subsequence $n^{\prime}$, the result follows.

Lemma 3.8 Assume conditions (v) and (vi) in Theorem 3.5. Then $Z_{n 2} \rightarrow$ 0 in probability, where $Z_{n 2}$, defined in Theorem 3.5, is

$$
Z_{n 2}=\frac{\frac{1}{\sqrt{L_{n}}} \sum_{j=1}^{L_{n}}\left(G\left(X_{N_{j}}, t\right)-G(x, t)\right)}{\sqrt{\frac{1}{L_{n}} \sum_{j=1}^{L_{n}} G\left(X_{N_{j}}, t\right)\left(1-G\left(X_{N_{j}}, t\right)\right)}}
$$

Proof: By Lemma 3.4, it is enough to prove that the numerator converges to zero in probability. To do this observe that

$$
\begin{aligned}
& \frac{1}{\sqrt{L_{n}}} \sum_{j=1}^{L_{n}}\left(G\left(X_{N_{j}}, t\right)-G(x, t)\right)=\frac{1}{\sqrt{L_{n}}} \sum_{j=0}^{n}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) \\
& =\frac{1}{\sqrt{L_{n}}} \sum_{j=0}^{T_{\Delta}^{(1)}-1}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) \\
& \quad+\frac{1}{\sqrt{L_{n}}} \sum_{j=T_{\Delta}^{K_{n}}}^{n}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) \\
& \quad+\frac{1}{\sqrt{L_{n}}} \sum_{j=T_{\Delta}^{(1)}}^{T_{\Delta}^{\left(K_{n}\right)}-1}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) \\
& =b_{n 1}+b_{n 2}+b_{n 3} \quad \text { (say). }
\end{aligned}
$$

By earlier arguments, $b_{n 1}+b_{n 2}$ converges to zero in probability. Next,

$$
\begin{aligned}
b_{n 3}= & \frac{1}{\sqrt{L_{n}}} \sum_{j=T_{\Delta}^{(1)}}^{T_{\Delta}^{\left(K_{n}\right)}-1}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) \\
= & \frac{\sqrt{2 n \delta_{n} f(x)}}{\sqrt{L_{n}}} \frac{\sqrt{2 n \delta_{n} f(x)}}{f(x)} \frac{K_{n}}{n} \frac{1}{K_{n}} \sum_{j=T_{\Delta}^{(1)}}^{T_{\Delta}^{\left(K_{n}\right)}-1} \frac{1}{2 \delta_{n}}\left(G\left(X_{j}, t\right)\right. \\
& -G(x, t)) I\left(X_{j} \in A_{n}\right) .
\end{aligned}
$$

By Theorem 1.7 and Theorem 1.8, it is enough to prove that

$$
\sqrt{2 n \delta_{n}} \frac{1}{K_{n}} \sum_{j=T_{\Delta}^{(1)}}^{T_{\Delta}^{\left(K_{n}\right)}-1} \frac{1}{2 \delta_{n}}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) \rightarrow 0
$$

in probability.
Consider first $K_{n}$ as non random. To go to the case in which $K_{n}$ is random we follow the procedure used earlier. Let

$$
\xi_{n i}=\sum_{j=T_{\Delta}^{(i)}}^{T_{\Delta}^{(i+1)}-1} \frac{1}{2 \delta_{n}}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) .
$$

Then,

$$
\begin{aligned}
& P_{\Delta}\left[\sqrt{2 n \delta_{n}}\left|\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}\right|>\epsilon\right] \\
& \leq \frac{2 n \delta_{n} E_{\Delta}\left(\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}\right)^{2}}{\epsilon^{2}} \\
& =\frac{2 n \delta_{n}}{\epsilon^{2}}\left[\frac{1}{K_{n}} E_{\Delta} \xi_{n 1}^{2}+\frac{K_{n}\left(K_{n}-1\right)}{2 K_{n}^{2}} E_{\Delta} \xi_{n 1} E_{\Delta} \xi_{n 2}\right] \\
& =O\left(\delta_{n} E_{\Delta} \xi_{n 1}^{2}\right)+O\left(n \delta_{n}\left(E_{\Delta} \xi_{n 1}\right)^{2}\right)
\end{aligned}
$$

where

$$
\begin{aligned}
E_{\Delta} \xi_{n 1}^{2}= & \frac{1}{4 \delta_{n}^{2}} E_{\Delta} \sum_{j=0}^{T_{\Delta}^{(1)}-1}\left(G\left(X_{j}, t\right)-G(x, t)\right)^{2} I\left(X_{j} \in A_{n}\right) \\
& +\frac{1}{4 \delta_{n}^{2}} E_{\Delta} \sum_{j=0}^{T_{\Delta}^{(1)}-1} \sum_{k=j+1}^{T_{\Delta}^{(1)}-1}\left(G\left(X_{j}, t\right)-G(x, t)\right)\left(G\left(X_{k}, t\right)-G(x, t)\right) \\
& I\left(X_{j} \in A_{n}\right) I\left(X_{k} \in A_{n}\right) \\
= & b_{n 31}+b_{n 32} \quad \text { (say) }
\end{aligned}
$$

Notice that

$$
\begin{aligned}
b_{n 31} & =\frac{1}{2 \delta_{n}} \lambda \int_{|x-y|<\delta_{n}} \frac{1}{2 \delta_{n}}(G(y, t)-G(x, t))^{2} f(y) d y \\
& \leq \frac{\lambda C_{t}}{2 \delta_{n}} \delta_{n}^{4+2 \alpha} \int_{|x-y|<\delta_{n}} f(y) d y \\
& =O\left(\delta_{n}^{4+2 \alpha}\right)
\end{aligned}
$$

By Theorem 1.6,

$$
\begin{aligned}
b_{n 32}= & E_{\Delta} \sum_{j=0}^{T_{\Delta}^{(1)}-1} \frac{1}{2 \delta_{n}}\left(G\left(X_{j}, t\right)-G(x, t)\right) I\left(X_{j} \in A_{n}\right) E_{X_{j}} \\
& \sum_{k=1}^{T_{\Delta}^{(1)}-1} \frac{1}{2 \delta_{n}}\left(G\left(X_{k}, t\right)-G(x, t)\right) I\left(X_{k} \in A_{n}\right) \\
= & \lambda \int_{|x-y|<\delta_{n}} \frac{1}{2 \delta_{n}}\left[( G ( y , t ) - G ( x , t ) ) E _ { y } \sum _ { k = 1 } ^ { T _ { \Delta } ^ { ( 1 ) } - 1 } \frac { 1 } { 2 \delta _ { n } } \left(G\left(X_{k}, t\right)\right.\right.
\end{aligned}
$$

$$
\begin{aligned}
& \left.-G(x, t)) I\left(X_{k} \in A_{n}\right)\right] f(y) d y \\
\leq & \frac{\lambda C_{t}}{2} \delta_{n}^{3+2 \alpha} \int_{|x-y|<\delta_{n}} \frac{1}{2 \delta_{n}} E_{y}\left(T_{\Delta}^{(1)}-1\right) f(y) d y \\
= & O\left(\delta_{n}^{3+2 \alpha}\right) .
\end{aligned}
$$

Hence, $E_{\Delta} \xi_{n 1}^{2}=O\left(\delta_{n}^{3+2 \alpha}\right)$. Also we have that

$$
\begin{aligned}
\left|E_{\Delta} \xi_{n 1}\right| & =\lambda \int_{|x-y|<\delta_{n}} \frac{1}{2 \delta_{n}}|G(y, t)-G(x, t)| f(y) d y \\
& \leq \frac{\lambda C_{t}}{2 \delta_{n}} \int_{|x-y|<\delta_{n}} \delta_{n}^{2+\alpha} f(y) d y \\
& =O\left(\delta_{n}^{2+\alpha}\right) \quad \text { (since } f \text { is bounded) } .
\end{aligned}
$$

Therefore, $P_{\Delta}\left[\sqrt{2 n \delta_{n}}\left|\frac{1}{K_{n}} \sum_{i=1}^{K_{n}} \xi_{n i}\right|>\epsilon\right]=O\left(n \delta_{n}^{5+2 \alpha}\right)$.
Proof of Theorem 3.5: For $\theta$ in $R$,

$$
\begin{aligned}
E\left(\exp \left(i \theta Z_{n 1}\right)\right) & =E\left(E_{\Delta}\left(\exp \left(i \theta Z_{n 1} \mid D\right)\right)\right. \\
& =E\left(\phi_{n}(\theta)\right)
\end{aligned}
$$

By Lemma 3.7 and the bounded convergence theorem, the last expectation converges to $\exp \left(-\frac{\theta^{2}}{2}\right)$. Thus $Z_{n 1} \xrightarrow{d} N(0,1)$.

By Lemma 3.8, $Z_{n 2} \rightarrow 0$ in probability. So by Slutsky's theorem, $Z_{n}=Z_{n 1}+Z_{n 2} \xrightarrow{d} N(0,1)$.

Remark 3.9 Notice that $Z_{n}$ is pivotal for $G(x, t)$ since the limit law of $Z_{n}$ is $N(0,1)$ and is independent of all parameters. Thus, $Z_{n}$ could be used to obtain confidence intervals for $G(x, t)$.

Remark 3.10 In the hypotheses of Theorem 3.5 (i), (ii), and (iii) hold for almost all $x$ by Lebesgue density theorem. $E_{\Delta} T_{\Delta}^{2}<\infty$ is necessary for (iii).

## 4 Conclusions and further research

We have proved Consistency and Asymptotic Normality of $G_{n}(x, t)$, the naive estimator of the sojourn time distribution for Semi - Markov processes. As we know, the naive estimator for the density function in the i. i. d. case it can be improved defining a more general kernel estimator. We believe that the estimator defined in this paper can also be improved following the ideas from the i.i.d. case and we are working in that direction.

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