Efficient tomography of quantum processes

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We show with explicit formulas that one can completely identify an unknown quantum process with only one weakly entangled state; and identify a quantum optical Gaussian process with either one two-mode squeezed state or a few different coherent states. In tomography of a multi-mode process, our method reduces the number of different test states exponentially compared with existing methods.

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Introduction.— One of the basic problems of quantum physics is to predict the evolution of a quantum system under certain conditions. For an isolated system with a known Hamiltonian, the evolution is characterized by a unitary operator determined by the Schrödinger equation. However, the system may interact with its environment, and the total Hamiltonian of the system plus the environment is in general not completely known. The evolution can then be regarded as a "black-box process" [1] which maps the input state into an output state. An important problem here is how to characterize an unknown process by testing the black-box with some specific input states, i.e., quantum process tomography (QPT) [1].

Any physical process can be described by a completely positive map ε . Such a process is fully characterized if the evolution of any input state ρ_{in} is predictable: $\rho_{out} = \varepsilon(\rho_{in})$. In general, QPT is very difficult to implement in high dimensional spaces, and, more challengingly, in an infinite dimensional space, such as a Fock space. Recently, Ref. [2] showed QPT in Fock space, for Continuous Variable (CV) states. Two conclusions [2] are: (*i*) If the output states of *all* coherent input states are known, then one can predict the output state of any input state; (*ii*) By taking the "photon-number-cut-off approximation", one can then characterize an unknown process with a finite number of different input coherent states (CSs).

Here we study QPT using a different approach. Based on the idea of isomorphism [3], and using the standard *Q*representation in quantum optics, we show, with explicit formulas, that one can complete QPT with either only one weakly entangled state for any quantum process, or only a few CSs for quantum optical Gaussian processes. The method described here has several advantages. First, it presents explicit formulas *without* any approximation, such as the photon-number-cut-off approximation. Second, it requires only one or a few different states to characterize a process, rather than *all* CSs. Third, for multimode Gaussian process tomography, the number of input CSs increases *polynomially* with the number of modes, rather than exponentially. Fourth, it uses Q-functions only, which is always well-defined for any state without any higher order singularities in the calculation.

Isomorphism and process tomography with one weakly entangled state. — Define $|\Phi^+\rangle = \sum_{k=0}^{s-1} |kk\rangle$ as the slevel maximally entangled state in the composite space of modes a and b. (Here $|\Phi^+\rangle$ is not normalized, because this simplifies the calculations below). Assume now that the process ε acts on mode b. Using isomorphism [3], if the state $\rho_{\varepsilon} = I \otimes \varepsilon(|\Phi^+\rangle \langle \Phi^+|)$ is known, we shall know $\varepsilon(\rho_{\rm in})$ for any single-mode input state $\rho_{\rm in}$ on mode b. Consider a single-mode input state on mode b, $|\psi(\{c_k\})\rangle = \sum_k c_k |k\rangle$. Obviously it can be written as

$$(|\psi\rangle\langle\psi|)_{b} = {}_{a}\langle\psi^{*}|\Phi^{+}\rangle\langle\Phi^{+}|\psi^{*}\rangle_{a}$$
$$= \operatorname{tr}_{a}\left(|\psi^{*}\rangle\langle\psi^{*}|\otimes I\cdot|\Phi^{+}\rangle\langle\Phi^{+}|\right)$$
(1)

and $|\psi^*\rangle_a = \sum_k c_k^* |k\rangle_a$, is a single-mode state on mode *a* (sometimes we omit the subscript *a* or *b* for simplicity). The output for any initial state $\rho_{\rm in} = (|\psi\rangle\langle\psi|)_b$ is

$$\rho_{\text{out}} = \varepsilon \left\{ \text{tr}_{a} \left[(|\psi^*\rangle \langle \psi^*|)_a \otimes I_b \cdot (|\Phi^+\rangle \langle \Phi^+|)_{ab} \right] \right\}$$
(2)

Since the partial trace and the map ε are taken in different subspaces, their orders can be exchanged. Thus

$$\rho_{\text{out}} = {}_a \langle \psi^* | I \otimes \varepsilon (|\Phi^+\rangle \langle \Phi^+|) | \psi^* \rangle_a = {}_a \langle \psi^* | \rho_\varepsilon | \psi^* \rangle_a = \operatorname{tr}_a (|\psi^*\rangle \langle \psi^*| \otimes I \cdot \rho_\varepsilon) . \quad (3)$$

Equation (3) predicts the output state of any input state of an unknown process, given ρ_{ε} . However, generating the maximum entangled state $|\Phi^+\rangle$ is technologically difficult, especially when *s* is large. Moreover, for the case of CV states in Fock space, *s* is infinite and the maximum entanglement does not physically exist. Therefore, we cannot really test a process with $|\Phi^+\rangle$ in Fock space. However, we can first test a process with some other easy-to-manipulate states, and then deduce the state ρ_{ε} . For example, one can test the one-sided map $I \otimes \varepsilon$ with an arbitrary non-maximally entangled state $|\phi(\{r_k\})\rangle = \sum_{k=0}^{s-1} r_k |kk\rangle$, if $r_0 \cdot r_1 \cdots r_{s-1} \neq 0$. Denoting the output state as $\Omega_{\{r_k\}}$, we have

$$\Omega_{\{r_k\}} = I \otimes \varepsilon(|\phi(\{r_k\})\langle \phi(\{r_k\})|). \tag{4}$$

On the other hand, we know that $|\phi(r_k)\rangle = \hat{T}(\{r_k\}) \otimes I|\Phi^+\rangle$; and $\hat{T}(\{r_k\})$ is a projection operator defined as $\hat{T}(\{r_k\}) = \sum_{k=0}^{s-1} r_k |k\rangle \langle k|$. Since $\hat{T} \otimes I$ and the one-sided map $I \otimes \varepsilon$ commute, then Eq. (4) can be written as

$$\Omega_{\{r_k\}} = \hat{T}(\{r_k\}) \otimes I\left\{I \otimes \varepsilon \left[|\Phi^+\rangle \langle \Phi^+\right]\right\} \hat{T}(\{r_k\}) \otimes I$$
(5)

which gives rise to

$$\rho_{\varepsilon} = \hat{T}^{-1}(\{r_k\}) \otimes I \Omega_{\{r_k\}} \hat{T}^{-1}(\{r_k\}) \otimes I.$$
 (6)

Here $\hat{T}^{-1}(\{r_k\})$ is defined as $\hat{T}(\{r_k^{-1}\})$. If we test the one-sided map $I \otimes \varepsilon$ with the limited entangled state $|\phi(\{r_k\})\rangle$ and we find that the outcome state is $\Omega_{\{r_k\}}$, then, using Eq. (6) we can determine the output state when the input state is $|\Phi^+\rangle$. We can then use Eq. (3) to predict the output state of *any* single-mode input state on mode *b*. Explicitly, if the input state is $|\psi(\{c_k\})\rangle = \sum_k c_k |k\rangle$, the output state becomes

$$\rho_{\psi} = \operatorname{tr}_{\mathbf{a}} \left[|\psi(c_k^*/r_k)\rangle \langle \psi(c_k^*/r_k)| \otimes I \cdot \Omega_{\{r_k\}} \right]$$
(7)

where $|\psi(c_k^*/r_k)\rangle = \sum_k (c_k^*/r_k)|k\rangle$.

For a state in Fock space, s is infinite and $|k\rangle$ is a Fock state which can be generated by the creation operator a^{\dagger} on the vacuum state $|0\rangle$. We can implement a similar technique to the one presented above to characterize an unknown quantum optical process with only *one* weaklyentangled state, i.e., a two-mode squeezed state (TMSS).

Process tomography with one TMSS.— A TMSS is defined by $|\chi(q)\rangle = c_q \exp(qa^{\dagger}b^{\dagger})|00\rangle$, where $c_q = \sqrt{1-q^2}$, and q is real. The (un-normalized) maximally-entangled state here is $|\Phi^+\rangle = \lim_{q \to 1} \exp(qa^{\dagger}b^{\dagger})|00\rangle = \sum_{k=0}^{\infty} |kk\rangle$, where x^{\dagger} is the creation operator for mode x.

We define the projection operator $\hat{T}(q) = c_q \exp[(\ln q)a^{\dagger}a]$ which has the property: $\hat{T}(q) (a, a^{\dagger}) \hat{T}^{-1}(q) = (a/q, qa^{\dagger})$. The TMSS $|\chi(q)\rangle$ can be written as

$$|\chi(q)\rangle = \hat{T}(q) \otimes I|\Phi^+\rangle.$$
(8)

Assume now that the black box process acts only on mode b of the bipartite state $|\chi(q)\rangle$. After the process, we obtain a two-mode state Ω_q . We now wish to predict the evolution of any state under the same process, using the information on how the input state $|\chi(q)\rangle$ changes under this map. According to Eq. (8), we have

$$\Omega_q = \hat{T}(q) \otimes I \cdot \rho_\varepsilon \cdot \hat{T}(q) \otimes I \tag{9}$$

where $\rho_{\varepsilon} = I \otimes \varepsilon (|\Phi^+\rangle \langle \Phi^+|)$. Naturally,

$$\rho_{\varepsilon} = \hat{T}^{-1}(q) \otimes I \cdot \Omega_q \cdot \hat{T}^{-1}(q) \otimes I.$$
(10)

We now also formulate the output state of any singlemode input state $|\psi(\{c_k\})\rangle = \sum_k c_k |k\rangle$ of mode b. According to Eq. (3), we obtain the output state

$$\rho_{\psi} = \operatorname{tr}_{\mathbf{a}} \left[|\psi^*(\{c_k/q^k\})\rangle \langle \psi^*(\{c_k/q^k\})| \otimes I \cdot \Omega_q \right] \\ = {}_a \langle \psi^*(\{c_k/q^k\})|\Omega_q|\psi^*(\{c_k/q^k\})\rangle_a.$$
(11)

More explicit expressions can be obtained by using the Q-function. If the single-mode input state on mode b is a coherent state $|\alpha\rangle$, the output state then becomes

$$\rho_{\alpha} = \langle \alpha^* | \rho_{\varepsilon} | \alpha^* \rangle = \langle \alpha^* | \hat{T}^{-1}(q) \otimes I \cdot \Omega_q \cdot \hat{T}^{-1}(q) \otimes I | \alpha^* \rangle.$$

Note that the state $|\alpha^*\rangle$ here is a single-mode coherent state on mode a. Using the property of $\hat{T}(q)$ and the definition of CSs, $a|\alpha^*\rangle = \alpha^*|\alpha^*\rangle$, we easily find

$$\hat{T}^{-1}(q) \otimes I \mid \alpha^* \rangle = \mathcal{N}_q(\alpha) \mid \alpha^*/q \rangle \tag{12}$$

where the factor $\mathcal{N}_q(\alpha) = \exp\left[-|\alpha|^2(1-1/q^2)/2\right]/c_q$, and $|\alpha^*/q\rangle$ is a coherent state on mode *a* defined by $a|\alpha^*/q\rangle = (\alpha^*/q)|\alpha^*/q\rangle$. Thus, the output state of mode *b* is

$$\rho_{\alpha} = |\mathcal{N}_q(\alpha)|^2 \ _a \langle \alpha^*/q \ |\Omega_q \ |\alpha^*/q \rangle_a . \tag{13}$$

Assume the Q-function for Ω_q is $Q_{\Omega_q}(Z_a^*, Z_b^*, Z_a, Z_b)$. According to its definition, $Q_{\Omega_q}(Z_a^*, Z_b^*, Z_a, Z_b) = \langle Z_a, Z_b | \Omega_q | Z_a, Z_b \rangle$, where $|Z_a, Z_b \rangle$ is a two-mode coherent state defined by $(a, b) | Z_a, Z_b \rangle = (Z_a, Z_b) | Z_a, Z_b \rangle$. Hence the corresponding density operator is $\Omega_q =: Q(a^{\dagger}, b^{\dagger}, a, b) :$, where the normal order notation : ...: indicates that any term inside it is reordered by placing the creation operator in the left. For example, $: aba^{\dagger}b^{\dagger}a := a^{\dagger}b^{\dagger}a^{2}b$. Therefore, using Eq. (13) and the normally-ordered form of Ω_q , we have the following simple form for the Q-function

$$Q_{\rho_{\alpha}}(Z_{b}^{*}, Z_{b}) = |N_{q}(\alpha)|^{2} Q_{\Omega_{q}}(\alpha/q, Z_{b}^{*}, \alpha^{*}/q, Z_{b})$$
(14)

of the output state ρ_{α} . Eqs. (13, 14) are the explicit expressions of the output state for the input of *any* coherent state $|\alpha\rangle$. According to Ref. [2], if we know the output states for all input CSs, we know the output states of all states in Fock space. In our approach, given any input state $|\psi\rangle$, we can write it in its linear superposition form in the coherent state basis, and then obtain the *Q*-function of its output state by using Eq. (14). These and Eqs. (7, 11), can be summarized as follows:

Theorem 1: Any process in Fock space is fully characterized by the bipartite state Ω_q , which is the output of the initial TMSS $|\chi(q)\rangle$, if $q \neq 0$. Any process on *s*dimensional states is characterized by the bipartite state $\Omega_{\{r_k\}}$, which is the output state from the initial bipartite state $|\phi(\{r_k\}),$ if $r_k \neq 0$ for all ks.

Characterizing a Gaussian process by testing the map with a few CSs. — One can also choose to test a process with only single-mode states. As shown in Ref. [2], if we only use CSs in the test, the tomography of an unknown process in Fock space requires tests with all CSs. Though this problem can be solved by taking the photon-numbercut-off approximation, in a quantum-optical process associated with intense light, one still needs a huge number of different CSs for the test. Here we show that the most important process in quantum optics, the Gaussian process, can be *exactly* characterized with only a few CSs in the test.

A Gaussian process maps Gaussian states into Gaussian states. Therefore the Q-function of the operator ρ_{ε} must be Gaussian:

$$Q_{\rho_{\varepsilon}}(Z_{a}^{*}, Z_{b}^{*}, Z_{a}, Z_{b}) = \exp(c_{0} + L + L^{\dagger} + S + S^{\dagger} + S_{0}), \quad (15)$$

where $L = \mathcal{G}\begin{pmatrix} Z_a \\ Z_b \end{pmatrix}$, $S = \frac{1}{2}(Z_a, Z_b)X\begin{pmatrix} Z_a \\ Z_b \end{pmatrix}$, $S_0 = (Z_a^*, Z_b^*)Y\begin{pmatrix} Z_a \\ Z_b \end{pmatrix}$, $\mathcal{G} = (\Gamma_a, \Gamma_b)$, $X = X^T = \begin{pmatrix} X_{aa} & X_{ab} \\ X_{ba} & X_{bb} \end{pmatrix}$, and $Y = Y^{\dagger} = \begin{pmatrix} Y_{aa} & Y_{ab} \\ Y_{ba} & Y_{bb} \end{pmatrix}$. Before testing the map, all these are unknowns. The

Before testing the map, all these are unknowns. The normally-ordered form of the density operator ρ_{ε} is : $Q_{\rho_{\varepsilon}}(a^{\dagger}, b^{\dagger}, a, b)$:. The output state from any single-mode input coherent state $|u\rangle$ (on mode b) is

$$\rho_u = \operatorname{tr}_a \left[\left(|u^*\rangle \langle u^*| \right)_a \otimes I \cdot \rho_\varepsilon \right] \tag{16}$$

Its Q-function is

$$Q_{\rho_u}(Z_b^*, Z_b) = Q_{\rho_{\varepsilon}}(u, Z_b^*, u^*, Z_b)$$

= exp(c_u + L_u + L_u[†] + R + R[†] + R₀), (17)

where $L_u = (\Gamma_b + u^* X_{ab} + u Y_{ab}) Z_b$, $R = Z_b X_{bb} Z_b/2$, $R_0 = Z_b^* Y_{bb} Z_b$, and c_u is determined by c_0 , Γ_a , X_{aa} and Y_{aa} . Explicitly,

$$c_u = c_0 + Re \left(2\Gamma_a u^* + u^* X_{aa} u^* + u Y_{aa} u^* \right)$$
(18)

The quadratic functional terms, (R, R^{\dagger}, R_0) on the exponent in Eq. (17) are independent of u; these terms must be the same for the output states from any initial CSs. Therefore, these can be known by testing the map with one coherent state. Thus, we do not need to consider these terms below. Now suppose that we test the process with six different CSs, $|\alpha_i\rangle$, and $i = 1, \dots 6$. Assume also that the detected Q-function of the output states is

$$Q_{\rho_{\alpha_i}}(Z_b^*, Z_b) = \exp(c_i + D_i + D_i^{\dagger} + R + R^{\dagger} + R_0)$$
(19)

where $D_i = d_i Z_b$ is the detected (hence known) linear term. According to Eq. (17), the *Q*-function of the output state from the initial state $|\alpha_i\rangle$ of mode *b* must be $Q_{\rho_{\alpha_i}}(Z_b^*, Z_b) = Q_{\rho_{\varepsilon}}(\alpha_i, Z_b^*, \alpha_i^*, Z_b)$. Therefore, we can derive self-consistent equations by using the detected data from ρ_{α_i} and setting $u = \alpha_i$ in Eq. (17):

$$L_i = D_i; \ c_{\alpha_i} = c_i \tag{20}$$

where L_i , c_{α_i} are just L_u , c_u , respectively, after setting $u = \alpha_i$ in Eqs. (17-18); D_i and c_i are known from tests. Explicitly, $L_i = (\Gamma_b + \alpha_i^* X_{ab} + \alpha_i Y_{ab}) Z_b$. The first part of Eq. (20) causes:

$$K \cdot (\Gamma_b, X_{ab}, Y_{ab})^T = d, \qquad (21)$$

where $K = \begin{pmatrix} 1 & \alpha_1^* & \alpha_1 \\ 1 & \alpha_2^* & \alpha_2 \\ 1 & \alpha_3^* & \alpha_3 \end{pmatrix}$, $d = (d_1, d_2, d_3)^T$. There are three unknowns (Γ, X) and Y_1 with three equa-

are three unknowns $(\Gamma_b, X_{ab}, \text{ and } Y_{ab})$ with three equations now. We find

$$(\Gamma_b, X_{ab}, Y_{ab})^T = K^{-1}d.$$
 (22)

If the Gaussian process is known to be trace-preserving, then Eq. (22) completes the tomography: up to a numerical factor, we can deduce all the output states of the other input CSs, $|\alpha_i\rangle$, for i = 4, 5, 6. The term c_i can be fixed through normalization, which is determined by the quadratic and linear functional terms on the exponent of the *Q*-functions. Knowing these $\{c_i\}$, one can construct ρ_{ε} completely, as shown below. For any map, c_i can be known from tests with $|\alpha_i\rangle$. We then have

$$J \cdot (c_0, \ \Gamma_a, \ \Gamma_a^*, \ X_{aa}, \ X_{aa}^*, \ Y_{aa})^T = c , \qquad (23)$$

$$= \begin{pmatrix} 1 \ \alpha_1^* \ \alpha_1 \ \frac{1}{2}\alpha_1^{*2} \ \frac{1}{2}\alpha_2^2 \ \frac{1}{2}\alpha_2^2 \ \frac{1}{2}\alpha_2^2 \ |\alpha_2|^2 \\ 1 \ \alpha_3^* \ \alpha_3 \ \frac{1}{2}\alpha_3^{*2} \ \frac{1}{2}\alpha_3^2 \ \frac{1}{2}\alpha_3^2 \ |\alpha_3|^2 \\ 1 \ \alpha_4^* \ \alpha_4 \ \frac{1}{2}\alpha_4^{*2} \ \frac{1}{2}\alpha_4^2 \ |\alpha_4|^2 \\ 1 \ \alpha_5^* \ \alpha_5 \ \frac{1}{2}\alpha_5^{*2} \ \frac{1}{2}\alpha_5^2 \ |\alpha_6|^2 \end{pmatrix}, \ c = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \\ c_6 \end{pmatrix}$$

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$$(c_0, \ \Gamma_a, \ \Gamma_a^*, \ X_{aa}, \ X_{aa}^*, \ Y_{aa})^T = J^{-1}c \ .$$
 (24)

Theorem 2: Given K and J defined by Eqs. (21, 23), then the QPT of any single-mode Gaussian process in Fock space can be performed with six input CSs, when det $K \neq 0$ and det $J \neq 0$. The QPT of any tracepreserving single-mode Gaussian process in Fock space can be executed with three input CSs, when det $K \neq 0$.

For example, one can simply choose $\alpha_1 = 0$, $\alpha_2 = 1$, $\alpha_3 = i$, $\alpha_4 = -1$, $\alpha_5 = -i$, and $\alpha_6 = 1 + i$. One finds

$$c_{0} = c_{1}, \Gamma_{b} = d_{1}$$

$$X_{ab} = \left[-(1+i)d_{1} + d_{2} + id_{3}\right]/2$$

$$Y_{ab} = \left[-(1-i)d_{1} + d_{2} - id_{3}\right]/2$$

$$\Gamma_{a} = \left(c_{2} + ic_{3} - c_{4} - ic_{5}\right)/4$$

$$X_{aa} = \left[2ic_{1} + (1-2i)c_{2} - (1+2i)c_{3} + c_{4} - c_{5} + 2ic_{6}\right]/4$$

$$Y_{aa} = -c_{1} + (c_{2} + c_{3} + c_{4} + c_{5})/4$$
(25)

where $\{d_i\}$ and $\{c_i\}$ are defined in Eq (19).

An example.—As a check of our conclusion, we calculate the output state of a beam-splitter (BS) process as shown in Fig. 1. The BS has input modes b and c and output modes b' and c'. Regarding this as a black-box process, the only input is mode b and the only output is mode b'. We set mode c to be vacuum. The BS transforms the creation operators of modes b, c by:

$$U_{BS}\left(b^{\dagger},\ c^{\dagger}\right)U_{BS}^{-1}=\left(b^{\dagger},\ c^{\dagger}\right)\ M_{BS} \tag{26}$$



FIG. 1: Gaussian Map constructed by a beam-splitter

where $M_{BS} = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$. If we test such a process with a coherent state $|\alpha_i\rangle$, we shall find $\rho_{\alpha_i} = |\cos\theta\alpha_i\rangle\langle\cos\theta\alpha_i|$. Comparing this with Eq. (19), we have $d_i = \alpha_i^*\cos\theta$ and $c_i = -|\alpha_i\cos\theta|^2$. Using Eqs. (22, 24), we find

$$Y_{bb} = -1, \ X_{ab} = \cos \theta, \ Y_{aa} = -\cos^2 \theta, \Gamma_a = \Gamma_b = Y_{ab} = X_{aa} = X_{bb} = c_0 = 0$$
(27)

Therefore $\rho_{\varepsilon} =: \exp(a^{\dagger}b^{\dagger}\cos\theta - a^{\dagger}a\cos^{2}\theta - b^{\dagger}b + ab\cos\theta):$. With this we can predict the output state of any input state, for example the displaced squeezed state $|\xi(r,Z)\rangle = \exp\left(-\frac{r}{2}b^{\dagger 2} + \frac{r}{2}b^{2}\right)\exp\left(Zb^{\dagger} - Z^{*}b\right)|0\rangle$, where r is real. According to our Eq. (3), $\rho_{\xi} = \operatorname{tr}_{a}\left[(|\xi(r,Z^{*})\rangle\langle\xi(r,Z^{*})|)_{a}\otimes I_{b}\cdot\rho_{\varepsilon}\right]$. As a result, $Q_{\rho_{\xi}}(Z_{b}^{*},Z_{b}) = C\exp(\mathcal{H}_{1}-\mathcal{H}_{2}+\mathcal{H}_{3}+\mathcal{H}_{4})$, where C is the normalization factor, and $\mathcal{H}_{1} = |Z_{b}|^{2}(\tanh^{2}r\sin^{2}\theta - 1)/g, \ \mathcal{H}_{2} = (Z_{b}^{2} + Z_{b}^{*2})\tanh r\cos^{2}\theta/(2g), \ \mathcal{H}_{3} = Z_{b}\cos\theta(Z^{*} - Z\tanh r\sin^{2}\theta)/(g\cosh r), \ \mathcal{H}_{4} = Z_{b}^{*}\cos\theta(Z - Z^{*}\tanh r\sin^{2}\theta)/(g\cosh r), \ \text{and} g = 1 - \tanh^{2}r\sin^{4}\theta.$ This is same with the result from direct calculations using Eq. (26).

Multi-mode extension.— Multi-mode Gaussian QPT has many important applications. For example, it applies to a complex linear optical circuit with BSs, squeezers, homodyne detections, linear losses, Gaussian noises and so on. Consider now a Gaussian process acting on a kmode input state (on mode $b_1, b_2, \dots b_k$), with outcome also a k-mode state. Even though other methods [2] can also be extended to the multi-mode case, the number of input states required there increases exponentially with the number of modes k, because the number of ket-bra operators $|\{n_i\}\rangle\langle\{m_i\}|$ in Fock space increases exponentially with k. As shown below, the number of input states in our method increases polynomially.

To apply isomorphism [3], we consider k pairs of maximally entangled states, each on modes $a_1, b_1; a_2, b_2, \cdots$ a_k, b_k . Explicitly, $|\Phi^+\rangle = |\phi^+\rangle_1 |\phi^+\rangle_2 \cdots |\phi^+\rangle_k$. Here $|\phi^+\rangle_i = \lim_{q\to 1} \exp\left(qa_i^{\dagger}b_i^{\dagger}\right)|00\rangle$ indicates a maximallyentangled state on modes a_i, b_i . Subspaces a and b each are now k-mode. Any state $|\psi\rangle$ in subspace b, can still be written in the form of Eq. (1), with the new definitions for $|\psi\rangle$ and $|\Phi^+\rangle$. Using Eq. (10), it is obvious that the output state of these k-pairs-TMSS fully characterize the process. A k-mode QPT can also be tested with k-mode CSs, if the process in Gaussian. The main Eqs. (22, 24) still hold after redefining the nota-

tions there. First, Γ_a , Γ_b , u, α_i , d_i , Z_a , Z_b are now k-mode vectors. For example, $|\alpha_i\rangle = |\alpha_{i1}, \alpha_{i2}, \cdots , \alpha_{ik}\rangle$, $Z_b = (Z_{b1}, Z_{b2}, \cdots Z_{bk}), d_i = (d_{i1}, d_{i2}, \cdots d_{ik}),$ and so on. Following Eq. (15), \mathcal{X}_{xy} is now a $k \times k$ matrix, for $\mathcal{X} = X$ or Y with x = a, b, y = a, b. We still apply Eqs. (22, 24) to calculate $\{\Gamma_b, X_{ab}, Y_{ab}\}$ and $\{\Gamma_a, X_{aa},$ Y_{aa} , respectively, but keep in mind that the matrices K, J and symbols d, c are now redefined. There are (2k+1)k unknowns in $(\Gamma_B, X_{ab}, Y_{ab})$. We need 2k+1different CSs of k-mode to fix these unknowns. Matrix Kis now $(2k+1) \times (2k+1)$, since each α_i here is a k-mode row vector. Here d is a $(2k + 1) \times k$ matrix as $d^T =$ $(d_1^T, d_2^T, \cdots d_{2k+1}^T)$, with $d_i = (d_{i1}, d_{i2}, \cdots d_{ik})$. Similarly, J is now $N \times N$ and N = (k+1)(2k+1), since α_i^2 and $|\alpha_i|^2$ here are row vectors of $\alpha_i^2 = (E_{i1}, E_{i2}, \cdots E_{ik})$ and $|\alpha_i|^2 = (\tilde{E}_{i1}, \tilde{E}_{i2}, \cdots \tilde{E}_{ik}),$ and each element of E_{im} (or \tilde{E}_{im}) is a vector with (k-m+1) modes (or k modes), as $E_{im} = (\alpha_{im}^2, \alpha_{im}\alpha_{i,m+1}, \alpha_{im}\alpha_{i,m+2}, \cdots, \alpha_{im}\alpha_k, \alpha_k^2)$ and $\tilde{E}_{im} = (\alpha_{im}\alpha_{i1}^*, \alpha_{im}\alpha_{i2}^*, \cdots \alpha_{im}\alpha_{i,k-1}^*, \alpha_{im}\alpha_{ik}^*).$ Obviously, c is a column vector with N elements. Therefore we conclude with this:

Corollary 1: Any k-mode map ε in Fock space is characterized by the output state of k-pair-TMSS under onesided map $I \otimes \varepsilon$. Any k-mode Gaussian QPT can be performed with (k + 1)(2k + 1) different CSs of k-mode; or with 2k + 1 different CSs of k-mode if the process is trace-preserving.

In summary, we have presented explicit formulas quantum process characterization with only one weakly entangled state, as well as the tomography of a quantum optical Gaussian process with a few different coherent states. These results have been extended to multi-mode quantum optical process and the number of test states required increases only polynomially with the number of modes.

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