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# STABILITY OF THE SOLUTION TO INVERSE OBSTACLE SCATTERING PROBLEM 

A.G. RAMm<br>Department of Mathematics, Kansas State University, Manhattan, KS 66506-2602, USA


#### Abstract

It is proved that if the scattering amplitudes for two obstacles (from a large class of obstacles) differ a little, then the obstacles differ a little, and the rate of convergence is given. An analytical formula for calculating the characteristic function of the obstacle is obtained, given the scattering amplitude at a fixed frequency.


## Introduction.

Let $D \subset \mathbb{R}^{3}$ be a bounded domain with a smooth boundary $\Gamma$,

$$
\begin{gather*}
\left(\nabla^{2}+k^{2}\right) u=0 \quad \text { in } \quad D^{\prime}:=\mathbb{R}^{3} \backslash D, \quad k=\mathrm{const}>0 ; \quad u=0 \quad \text { on } \quad \Gamma  \tag{1}\\
u=\exp (i k \alpha \cdot x)+A\left(\alpha^{\prime}, \alpha, k\right) r^{-1} \exp (i k r)+o\left(r^{-1}\right), \quad r:=|x| \rightarrow \infty, \quad \alpha^{\prime}:=x r^{-1} . \tag{2}
\end{gather*}
$$

Here $\alpha \in S^{2}$ is a given unit vector, $S^{2}$ is the unit sphere in $\mathbb{R}^{3}$, the function $A\left(\alpha^{\prime}, \alpha, k\right)$ is called the scattering amplitude (the radiation pattern). It is well known [1] that problem (1)-(2) has a unique solution, the scattering solution, so that the map $\Gamma \rightarrow A\left(\alpha^{\prime}, \alpha, k\right)$ is well defined. We consider the inverse obstacle scattering problem (IOSP): given $A\left(\alpha^{\prime}, \alpha\right):=A\left(\alpha^{\prime}, \alpha, k=1\right.$ ) for all $\alpha^{\prime}, \alpha \in S^{2}$ and a fixed $k$ (for example, take $k=1$ without loss of generality), find $\Gamma$.

Let us assume that $\Gamma \subset \gamma_{\lambda}$, where $\gamma_{\lambda}$ is the set of star-shaped (with respect to a common point $O$ ) surfaces, which are located in the annulus $0<a_{0} \leq|x| \leq a_{1}$, and whose equations $x_{3}=\phi\left(x_{1}, x_{2}\right)$ in the local coordinates (in which $x_{3}$ is directed along the normal to $\Gamma$ at a point $s \in \Gamma$ ), have the property

$$
\begin{equation*}
\|\phi\|_{C^{2, \lambda}} \leq c_{0} \tag{3}
\end{equation*}
$$

$C^{2, \lambda}$ is the space of twice differentiable functions, whose second derivatives satisfy the Hölder condition of order $0<\lambda \leq 1, \lambda$ and $c_{0}$ are independent of $\phi$ and $\Gamma$.

Uniqueness of the solution to IOSP with fixed frequency data is first proved in [1, p. 85]. We are interested here in the stability problem: suppose that $\Gamma_{j} \in \gamma_{\lambda}$ generate $A_{j}\left(\alpha^{\prime}, \alpha\right), j=1,2$, and

$$
\begin{equation*}
\max _{\alpha^{\prime}, \alpha \in S^{2}}\left|A_{1}\left(\alpha^{\prime}, \alpha\right)-A_{2}\left(\alpha^{\prime}, \alpha\right)\right|<\delta \tag{4}
\end{equation*}
$$

What can one say about the Hausdorff distance between $D_{1}$ and $D_{2}: \rho:=\sup _{x \in \Gamma_{1}} \inf _{y \in \Gamma_{2}}|x-y|$ Let $\tilde{D}_{1}$ denote a connected component of $D_{1} \backslash D_{2}, D_{12}:=D_{1} \cup D_{2}, \Gamma_{12}:=\partial D_{12}, D_{12}^{\prime}:=\mathbb{R}^{3} \backslash D_{12}, \tilde{\Gamma}_{1}:=\partial \tilde{D}_{1}:=$ $\Gamma_{1}^{\prime} \cup \tilde{\Gamma}_{2}, \tilde{\Gamma}_{2} \subset \Gamma_{2}:=\partial D_{2}, \Gamma_{1}^{\prime} \subset \Gamma_{1}:=\partial D_{1}$. Let us assume, without loss of generality, that $\rho=\left|x_{0}-y_{0}\right|$, $x_{0} \in \Gamma_{1}^{\prime}, y_{0} \in \tilde{\Gamma}_{2}$. Can one obtain a formula for calculating $\Gamma$, given $A\left(\alpha^{\prime}, \alpha\right)$ for all $\alpha^{\prime}, \alpha \in S^{2}, k=1$ is fixed? No such formula is known for IOSP. For inverse potential scattering problem with fixed-energy data such a formula and stability estimates are obtained in [2], [3]. These results are based on the works [7],[8], [10]-[17], [19]-[21].

In section II we prove that $\rho \leq c_{1}\left(\frac{\ln |\ln \delta|}{|\ln \delta|}\right)^{c_{2}}$ as $\delta \rightarrow 0$. We also prove some inversion formula, but it is an open problem to make an algorithm out of this formula. In Remark 3, we comment on some recent papers [4-6] in which attempts are made to study the stability problem and point out a number of errors in these papers. Our result, formulated as Theorem 1 in section II, is stronger than the results announced in Theorem 1 in [4], Theorem 1 in [5] and Theorem 2.10 in [6].

## II. Stability Result and a Reconstruction Formula.

Theorem 1. Under the assumptions of section I, one has $\rho(\delta) \leq c_{1}\left(\frac{\ln |\ln \delta|}{|\ln \delta|}\right)^{c_{2}}$, where $c_{1}$ and $c_{2}$ are positive constants independent of $\delta$.

Proposition 1. There exists a function $\nu_{\epsilon}(\alpha, \theta) \in L^{2}\left(S^{2}\right)$ such that

$$
\begin{equation*}
-4 \pi \lim _{\epsilon \rightarrow 0} \int_{S^{2}} A\left(\theta^{\prime}, \alpha\right) \nu_{\epsilon}(\alpha, \theta) d \alpha=-\frac{\lambda^{2}}{2} \tilde{\chi}_{D}(\lambda) \tag{5}
\end{equation*}
$$

Here $\lambda \in \mathbb{R}^{3}$ is an arbitrary fixed vector, $\chi_{D}(x):=\left\{\begin{array}{ll}1, & x \in D \\ 0, & x \notin D\end{array}, \tilde{\chi}_{D}(\lambda):=\int_{\mathbb{R}^{3}} \exp (-i \lambda \cdot x) \chi_{D}(x) d x\right.$, $\theta, \theta^{\prime} \in M:=\left\{\theta: \theta \in \mathbb{C}^{3}, \theta \cdot \theta=1\right\}, \theta^{\prime}-\theta=\lambda$, and $A\left(\theta^{\prime}, \alpha\right)$ is defined by the absolutely convergent series

$$
\begin{equation*}
A\left(\theta^{\prime}, \alpha\right)=\sum_{\ell=0}^{\infty} A_{\ell}(\alpha) Y_{\ell}\left(\theta^{\prime}\right), \quad \theta^{\prime} \in M, \quad A_{\ell}(\alpha):=\int_{S^{2}} A\left(\alpha^{\prime}, \alpha\right) \overline{Y_{\ell}\left(\alpha^{\prime}\right)} d \alpha^{\prime} \tag{6}
\end{equation*}
$$

where $Y_{\ell}(\alpha)$ are the orthonormal in $L^{2}\left(S^{2}\right)$ spherical harmonics, $Y_{\ell}\left(\theta^{\prime}\right)$ is the natural analytic continuation of $Y_{\ell}\left(\alpha^{\prime}\right)$ from $S^{2}$ to $M$, and the series (6) converges absolutely and uniformly on compact subsets of $S^{2} \times M$.

Remark 1. The stability result given in Theorem 1 is similar to the one in [3], p. 9, formula (2.42), for inverse potential scattering.

Remark 2. Proposition 1 claims the existence of the inversion formula (5). An open problem is to construct the function $\nu_{\epsilon}(\alpha, \theta)$ algorithmically, given the data $A\left(\alpha^{\prime}, \alpha\right) \quad \forall \alpha^{\prime}, \alpha \in S^{2}$.

Proof of Theorem 1. First, we prove that $\rho(\delta) \rightarrow 0$ as $\delta \rightarrow 0$. Then, we prove that $\left|u_{2}\right| \leq c \rho$ in $\tilde{D}_{1}$. Next, we prove that $\left|u_{2}(x)\right| \leq c \epsilon^{\rho^{c^{\prime}}}(*)$ if $\operatorname{dist}\left(x, \Gamma_{1}^{\prime}\right)=O(\rho)$, where $|\ln \epsilon|=c N(\delta), N(\delta):=|\ln \delta| / \ln |\ln \delta|$. From (*) Theorem 1 follows. By $c, c^{\prime}, \tilde{c}, c_{j}$ various positive constants, independent of $\delta$ and on $\Gamma \in \gamma_{\lambda}$, are denoted.

Step 1. Proof of the relation $\rho(\delta) \rightarrow 0$ as $\delta \rightarrow 0$. Assume the contrary:

$$
\begin{equation*}
\rho_{n}:=\rho\left(\delta_{n}\right) \geq c>0 \quad \text { for some sequence } \quad \delta_{n} \rightarrow 0 \tag{7}
\end{equation*}
$$

Let $\Gamma_{j n}, j=1,2$, be the corresponding sequences of the boundaries, $\Gamma_{j n} \in \gamma_{\lambda}$. Due to assumption (3), one can select a convergent in $C^{2, \mu}, 0<\mu<\lambda$, subsequence, which we denote $\Gamma_{j n}$ again. Thus $\Gamma_{j n} \rightarrow \Gamma_{j}$ as $n \rightarrow \infty$. From (7) it follows that ( $\dagger$ ) $\rho\left(D_{1}, D_{2}\right) \geq c>0$, where $D_{j}$ is the obstacle with the boundary $\Gamma_{j}$. By the known continuity of the map $\Gamma_{j} \rightarrow A_{j}, \Gamma_{j} \in \gamma_{\mu}$, it follows that $A_{1}\left(\alpha^{\prime}, \alpha\right)-A_{2}\left(\alpha^{\prime}, \alpha\right)=0$.

By the uniqueness theorem [1, p. 85] it follows that $\Gamma_{1}=\Gamma_{2}$. Thus, $\rho\left(D_{1}, D_{2}\right)=0$ which is a contradiction to $(\dagger)$. This contradiction proves that $\rho(\delta) \rightarrow 0$ as $\delta \rightarrow 0$.

Step 2. Proof of the estimate $\left|u_{2}(x)\right| \leq c \rho$ for $x \in \tilde{D}_{1}$. It is known that $\left\|u_{2}\right\|_{C^{2}\left(D_{2}^{\prime}\right)} \leq c$, where $u_{2}=$ $u_{2}(x, \alpha)$ is the scattering solution corresponding to the obstacle $D_{2}$. Since $u_{2}=0$ on $\tilde{\Gamma}_{2}$, one has $\left|u_{2}(x)\right| \leq$ $\left(\max _{x \in \tilde{D}_{1}}\left|\nabla u_{2}\right|\right) \rho \leq c \rho$.

Step 3. Proof of the estimate $|v(x)| \leq c \epsilon^{d^{c^{\prime}}}$, where $v:=u_{2}-u_{1}$ and $d:=\operatorname{dist}\left(x, \Gamma_{1}^{\prime}\right)$.

From [3, p. 26, formulas (4.12), (4.17), (2.28)], one has

$$
\begin{equation*}
|v(x)| \leq \epsilon:=c \exp \{-\gamma N(\delta)\}, \quad|x|>a_{2}, \quad N(\delta):=\frac{|\ln \delta|}{\ln |\ln \delta|}, \quad \gamma:=\ln \frac{a_{2}}{a_{1}}>0 \tag{8}
\end{equation*}
$$

$a_{2}>a_{1}$ is an arbitrary fixed number, $a_{2} \leq|x| \leq a_{2}+1$ (in [3] it is assumed $a_{2}>a_{1} \sqrt{2}$, but $a_{2}>a_{1}$ is sufficient). Let us derive from (8), from equation (1) for $v(x)$, from the radiation condition for $v(x)$, and from the estimate $\|v\|_{C^{2}\left(D_{12}^{\prime}\right)} \leq c$, the estimate:

$$
\begin{equation*}
|v(x)| \leq c \epsilon^{d^{c^{\prime}}}, \quad x \in D_{12}^{\prime}, \quad c_{3} \rho \leq d \leq c_{4} \rho, \quad c_{3}>0, \quad d=\operatorname{dist}\left(x, \Gamma_{1}^{\prime}\right) \tag{9}
\end{equation*}
$$

If (9) is proved, then Theorem 1 follows. Indeed, $|v(x)|=|v(s)+\nabla v \cdot(x-s)|=O(\rho) \leq c \epsilon^{\rho^{c^{\prime}}}$ if $d$ satisfies (9). Here we use: 1) $v=u_{2}-u_{1}=u_{2}$ on $\Gamma_{1}^{\prime},\left|u_{2}\right|=O(\rho)$ on $\Gamma_{1}^{\prime}$, since $u_{2}=0$ on $\tilde{\Gamma}_{2}$, and $\left|\nabla u_{2}\right| \leq c$, 2) $|x-s|=O(\rho)$ if $\operatorname{dist}\left(x, \Gamma_{1}^{\prime}\right)=O(\rho)$, and 3$) 0<c \leq|\nabla v| \leq \tilde{c}$ if $d$ satisfies (9). The last claim follows from the continuity of $\nabla v(x)$, smallness of $\rho, \rho(\delta) \rightarrow 0$ as $\delta \rightarrow 0$, and the fact that $\left|\nabla u_{j}\right|_{\Gamma_{j}} \neq 0$ almost everywhere (otherwise, by the uniqueness of the solution to the Cauchy problem for (1), one concludes that $u_{j}=0$ in $D_{j}^{\prime}$, which contradicts (2), since, by (2), $\left|u_{j}\right| \rightarrow 1$ as $\left.|x| \rightarrow \infty\right)$. Thus $\ln \rho \leq c \rho^{c^{\prime}} \ln \epsilon$, or $(*) \frac{\rho^{c^{\prime}}}{\ln \left(\rho^{-1}\right)} \leq c / \ln \left(\epsilon^{-1}\right)$, where $\rho$ and $\epsilon$ are small numbers, $0<\rho, \epsilon<1, c, c^{\prime}>0$, and $c$ stands for different constants. It follows from $(*)$ that $\rho \leq\left\{c / \ln \left(\epsilon^{-1}\right)\right\}^{\frac{1+\omega}{c^{\prime}}}$, where $\omega \rightarrow 0$ as $\epsilon \rightarrow 0$. From the definition (8) of $\epsilon$, one gets the estimate of Theorem 1. Thus, the proof of Theorem 1 is completed as soon as (9) is proved.

Our argument remains valid if $|v|=O\left(\rho^{m}\right)$ with some $m, 0<m<\infty$. Such an inequality is always true for a solution $v$ to elliptic equation (1) unless $v \equiv 0$ (see [26, p.14]).

Proof of (9). Since $\|v\|_{C^{2, \mu}\left(D_{12}^{\prime}\right)} \leq c, v(x)$ vanishes at infinity, and $v$ solves (1), one can represent $v(x)$ in $D_{12}^{\prime}$ by the volume potential: $v(x)=\int_{D_{12}} g(x-y) f(y) d y, f \in C^{\mu}\left(D_{12}\right), g(x):=\frac{\exp (i|x|)}{4 \pi|x|}$. The function $|x-y|=\left[r^{2}-2 r|y| \cos \theta+|y|^{2}\right]^{1 / 2}:=R$ admits analytic continuation on the complex plane $z=r \exp (i \psi)$ to the sector $S_{\phi}:|\arg z|<\phi$, if $z^{2}-2 z|y| \cos \theta+|y|^{2} \neq 0$ for $z$ in this sector. We use the branch of $R$ for which $\operatorname{Im} R \geq 0$, and $\left.R e R\right|_{\text {Imz=0 }} \geq 0$. The argument of $R^{2}:=z^{2}-2 z|y| \cos \theta+|y|^{2}$ is defined so that it belongs to the interval $[0,2 \pi)$, so that the analytic continuation of $g(x-y)$ to the sector $S_{\phi}$ is bounded there. It is crucial to have at least boundedness of the norm $(\dagger)\|v\|_{C^{1}\left(D_{12}^{\prime}\right)}$. Indeed, $(\dagger)$ implies that one can extend $v$ from $D_{12}^{\prime}$ to $D_{12}$ as $C^{1}\left(\mathbb{R}^{3}\right)$ functions. This is true although the boundary $\partial D_{12}$ may be nonsmooth to the degree which prevents using the known extension theorems (Stein's theorem, for example). The way to go around this difficulty is to extend $u_{1}$ and $u_{2}$ separately to $D_{1}$ and $D_{2}$ respectively, and then take $v=u_{2}-u_{1}$ as the extension. If $v \in C^{1}\left(\mathbb{R}^{3}\right)$ satisfies the radiation condition and the Helmholtz equation, and is $C^{2}$ in the interior and in the exterior of $D_{12}$, then it is representable as a sum of the volume and single-layer potentials, and our argument, which uses analytic continuation, goes through. Without this assumption the argument is not valid and the conclusion fails, as the following example shows.

Example 1: Let $D:=\left\{x:|x| \leq 1, x \in \mathbb{R}^{3}\right\}, v=v_{\ell}:=\frac{h_{\ell}^{(1)}(r)}{h_{\ell}^{(1)}(1)} Y_{\ell}\left(x^{0}\right)$, where $h_{\ell}^{(1)}(r)$ is the spherical Hankel function, $Y_{\ell}\left(x^{0}\right)$ is the normalized in $L^{2}\left(S^{2}\right)$ spherical harmonic. It is well known that $h_{\ell}^{(1)}(r) \sim$ $i \sqrt{\frac{1}{\left(\ell+\frac{1}{2}\right) r}}\left(\frac{2 \ell+1}{e r}\right)^{\frac{2 \ell+1}{2}}$ as $\ell \rightarrow \infty$ uniformly in $1 \leq r \leq b, b<\infty$ is arbitrary. Therefore $v_{\ell} \sim r^{-(\ell+1)} Y_{\ell}\left(x^{0}\right)$ as $\ell \rightarrow \infty$. In any annulus $\mathcal{A}:=\left\{x: 1<a_{2} \leq r \leq b\right\}$, one has $\left\|v_{\ell}\right\|_{L^{2}(A)} \leq c a_{2}^{-(\ell+1)} \rightarrow 0$ as $\ell \rightarrow \infty$. On the other hand $\left\|v_{\ell}\right\|_{L^{2}\left(S^{2}\right)}=1$ for all $\ell$. Thus, for sufficiently large $\ell$ the solution $v_{\ell}$ to Helmholtz equation is as small as one wishes in the annulus $\mathcal{A}$, but it is not small at the boundary $\partial D$ : for any $\ell$ its $L^{2}(\partial D)$ norm is one. The reason for the solution to fail to be small on $\partial D$ is that the $C^{1}$ norm of $v_{\ell}$ is unbounded, as $\ell \rightarrow \infty$, on $\partial D$.

Let us continue the proof of (9). The function $v\left(r, x^{0}, \alpha\right)$, where $\alpha$ is the same as in (2), $x^{0}:=x / r$, and $r=|x|$, admits an analytic continuation to the sector $S$ on the complex plane $z, S:=\left\{z:\left|\arg \left[z-r\left(x^{0}\right)\right]\right|<\right.$ $\phi\}, \phi>0, r=r\left(x^{0}\right)$ is the equation of the surface $\Gamma_{1}$ in the spherical coordinates with the origin at the point $O$, and $v\left(z, x^{0}, \alpha\right)$ is bounded in $S$. The angle $\phi$ is chosen so that the cone $K$ with the vertex at $r\left(x^{0}\right)$, axis along the normal to $\Gamma_{1}^{\prime}$ at the point $r\left(x^{0}\right)$, and the opening angle $2 \phi$, belongs to $D_{12}^{\prime}$. Such a cone does exist because of the assumed smoothness of $\Gamma_{j}$. The analytic continuation of this type was used in [18]. It follows from (8) that $\sup _{r \geq a_{2}}|v(r)| \leq \epsilon$, and $\sup _{z \in S}|v(z)| \leq c$, since $\operatorname{Im}\left[z^{2}-2 z|y| \cos \theta+|y|^{2}\right]^{1 / 2} \geq 0$ in $S$. From this and the classical theorem about two constants [22, p. 296], one gets $|v(z)| \leq c \epsilon^{h(z)}$, where $h(z)=h(z, L, Q)$ is the harmonic measure of the set $\partial S \backslash L$ with respect to the domain $Q:=S \backslash L$ at the point $z \in Q$. Here $L$ is the ray $\left[a_{2},+\infty\right), \partial S$ is the union of two rays, which form the boundary of the sector $S$, and of the ray $L$. The proof is completed as soon as we demonstrate that $h(z) \sim k d^{c^{\prime}}$ as $z \rightarrow r\left(x^{0}\right)$ along the real axis, $d:=\left|z-r\left(x^{0}\right)\right|, k=$ const $>0, c=$ const $>0$. This, however, is clear: let $r\left(x^{0}\right)$ be the origin, and denote $z-r\left(x^{0}\right)$ by $z$. If one maps conformally the sector $S$ onto the half-plane $\operatorname{Re} z \geq 0$ using the map $w=z^{c^{\prime}}, c^{\prime}=\frac{\pi}{2 \phi}$, then the ray $L$ is mapped onto the ray $L:=\left[a_{2}^{c^{\prime}},+\infty\right.$ ), and (see [22, p. 293]) $h(z, L, Q)=h\left(z^{c^{\prime}}, L^{\prime}, Q^{\prime}\right)$, where $Q^{\prime}$ is the image of $Q$ under the mapping $z \mapsto z^{c^{\prime}}=w$. By the Hopf lemma [23, p. 34], $\frac{\partial h\left(0, L^{\prime}, Q^{\prime}\right)}{\partial w}>0, h\left(0, L^{\prime}, Q^{\prime}\right)=0$, so $h\left(w, L^{\prime}, Q^{\prime}\right) \sim k w=k z^{c^{\prime}}$ as $z \rightarrow 0$, and (9) is proved. Theorem 1 is proved.

Proof of Proposition 1. It is proved in [2, p. 183] that the set $\left\{u_{N}(s, \alpha)\right\}_{\forall \alpha \in S^{2}}$ is complete in $L^{2}(\Gamma)$. This implies existence of a function $\nu_{\epsilon}(\alpha, \theta)$ such that

$$
\begin{equation*}
\left\|\int_{S^{2}} u_{N}(s, \alpha) \nu_{\epsilon}(\alpha, \theta) d \alpha-\frac{\partial \exp (i \theta \cdot s)}{\partial N_{s}}\right\|_{L^{2}(\Gamma)}<\epsilon \tag{10}
\end{equation*}
$$

where $\epsilon>0$ is arbitrarily small fixed number, $N_{s}$ is the exterior normal to $\Gamma$ at the point $s$, and $\theta \in M$ is an arbitrary fixed vector. It is well known [1, p. 52], that

$$
\begin{equation*}
-4 \pi A\left(\theta^{\prime}, \alpha\right)=\int_{\Gamma} \exp \left(-i \theta^{\prime} \cdot s\right) u_{N}(s, \alpha) d s \tag{11}
\end{equation*}
$$

Multiply (11) by $\nu_{\epsilon}(\alpha, \theta)$, integrate over $S^{2}$ and use (10), to get

$$
\begin{equation*}
-4 \pi \lim _{\epsilon \rightarrow 0} \int_{S^{2}} A\left(\theta^{\prime}, \alpha\right) \nu_{\epsilon}(\alpha, \theta) d \alpha=\int_{\Gamma} \exp \left(-i \theta^{\prime} \cdot s\right) \frac{\partial \exp (i \theta \cdot s)}{\partial N_{s}} d s \tag{12}
\end{equation*}
$$

Note that

$$
\begin{align*}
\int_{\Gamma} \exp \left(-i \theta^{\prime} \cdot s\right) \frac{\partial \exp (i \theta \cdot s)}{\partial N_{s}} d s & =\frac{1}{2} \int_{\Gamma} \frac{\partial \exp \left[-i\left(\theta^{\prime}-\theta\right) \cdot s\right]}{\partial N_{s}} d s \\
& =\frac{1}{2} \int_{D} \nabla^{2} \exp (-i \lambda \cdot x) d x=-\frac{\lambda^{2}}{2} \tilde{\chi}_{D}(\lambda) \tag{13}
\end{align*}
$$

where the first equation is obtained with the help of Green's formula. From (12) and (13) one obtains (5). Proposition 1 is proved.

Remark 3. In [4]-[5] attempts are made to obtain stability results for IOSP, but several errors invalidate the proofs in [4], [5] and [6] related to stability for IOSP. Let us point out some of the errors. Lemma 5, as stated in [4, p. 83], repeated as Lemma 4 in [5], claims that if a solution to a homogeneous Helmholtz equation in the exterior of a bounded domain $D$ is small in the annulus $R \leq|x| \leq R+1,|v| \leq \epsilon$ in the annulus, then $|v|_{\partial D} \leq c|\log \epsilon|^{-c_{1}}$. This is incorrect as Example 1 shows. Lemma 3 in [4] is wrong (factor
$\rho^{2 m}$ is forgotten in the argument). In fact, stronger results have been published earlier [17], [2], [3]. In [5] Lemma 2 is intended as a correction of Lemma 3 in [4] (without even mentioning [4]), but its proof is also wrong: the factor $\rho^{2 m}$ is not estimated. There are other mistakes in [5] (e.g., the known asymptotics of Hankel functions in [5, p. 538] is given incorrectly). In [6] these mistakes are repeated (p. 600). There are claims in [6] that: a) there is a gap in the Schiffer's proof of the uniqueness theorem for IOSP with the data $A\left(\alpha^{\prime}, \alpha_{0}, k\right) \forall \alpha^{\prime} \in S^{2}, \forall k>0, \alpha_{0} \in S^{2}$ is fixed [6, p. 605], b) that Theorem 6 in [8] is incorrect, and the proof of Lemma 5 in [8] contains a flaw [6, p. 588]. These claims are wrong, and no justifications of the claims are given. The remark concerning Shiffer's proof in [6, p. 605, line 1] is irrelevant (see [1,pp.85-86]). It should be noted that the arguments in [4]-[5] are based on the well known estimates of Landis [9] for the stability of the solution to the Cauchy problem, but no references to the work of Landis are given. In [6] it is not mentioned that the concept of completeness of the set of products of solutions to PDE (which is discussed in [6]) has been introduced and widely used for the proof of the uniqueness theorems in inverse problems in the works [2], [13], [19]-[21] (see also references in [2], [13]). In [24] and [25] two theorems are announced which contradict each other (Theorem 1 in [25] and Theorem 2 in [24]).
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e-mail: ramm@math.ksu.edu
