# OVERLOAD BEHAVIOR OF CONE SCHEDULES FOR PROCESSING SYSTEMS

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### Abstract

This note complements the analysis of [1] and [2] addressing the case where the traffic load is *not* within the stability region, that is, the system operates in *overload*. For the case where the cone schedule matrix [1] is diagonal, it is shown that the job backlog explodes on a particular ray, as opposed to various subsequences exploding on diverse ones. The context and model used here are those described in [1]. The analysis technique draws on and parallels closely those in [1] and [2].

## **1** Introduction

Consider the model of [1], where the PCS matrix **B** is now diagonal  $\Delta$  (and positive-definite, hence, all its diagonal elements are positive). The system operates in overload, in the sense that  $\rho \notin \mathcal{P}$ , where

$$\mathcal{P} = \left\{ \rho \in \mathbb{R}^Q_+ : \langle \rho, \Delta v \rangle \le \max_{S \in \mathcal{S}} \langle S, \Delta v \rangle \text{ for every } v \in \mathbb{R}^Q \right\},\tag{1.1}$$

as defined in [1]. We consider the limit defined below:

$$H = \limsup_{t \to \infty} \left\langle \frac{X(t)}{t}, \Delta \frac{X(t)}{t} \right\rangle$$
(1.2)

and select a convergent increasing unbounded subsequence  $\{t_c\}$  on which the 'limsup' is attained<sup>4</sup> – hence,

$$\lim_{c \to \infty} \frac{X(t_c)}{t_c} = \eta \tag{1.3}$$

and

$$\limsup_{c \to \infty} \left\langle \frac{X(t_c)}{t_c}, \Delta \frac{X(t_c)}{t_c} \right\rangle = \langle \eta, \Delta \eta \rangle = H.$$
(1.4)

Lemma 1.1 We have

$$\rho \notin \mathcal{P} \implies \eta \neq 0 \tag{1.5}$$

*Proof:* See [2], Proposition 2.1. We have that

$$\rho \notin \mathcal{P} \implies \limsup_{t \to \infty} \frac{X_q(t)}{t} > 0 \text{ for some } q \in \mathcal{Q} \implies \eta \neq 0 \text{ and } \limsup_{t \to \infty} \left\langle \frac{X(t)}{t}, \mathbf{\Delta} \frac{X(t)}{t} \right\rangle = \langle \eta, \Delta \eta \rangle = H > 0.$$
(1.6)

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<sup>&</sup>lt;sup>4</sup>See footnote 12 of [1] concerning why such a subsequence exists

# 2 Overload Regime: $\rho \notin \mathcal{P} \implies \lim_{t \to \infty} \frac{\mathbf{X}(t)}{t} = \eta \neq \mathbf{0}.$

**Theorem 2.1** *When*  $\rho \notin \mathcal{P}$ *, we have* 

$$\lim_{t \to \infty} \frac{X(t)}{t} = \eta \neq 0.$$
(2.1)

That is, the workload explodes on the same non-zero ray  $\eta$  on any subsequence.

#### Proof:

From Section V of [1] on PCS cone geometry, recall that  $C_S = \{x \in \mathbb{R}^Q : \langle S, \Delta x \rangle = \max_{S' \in S} \langle S', \Delta x \rangle\}$  is a cone, and when  $X(t) \in C_S^o$  (the interior of  $C_S$ ) the PCS will choose S(t) = S. Moreover, the *surrounding cone* of any non-zero vector  $\eta$  is the cone

$$\mathcal{C}(\eta) = \bigcup_{S \in \mathcal{S}^*(\eta) - \mathcal{S}^\dagger} C_S \tag{2.2}$$

where  $S^*(\eta) = \operatorname{argmax}_{S \in S} \langle S, \Delta \eta \rangle$  is the set of service vectors of that PCS would select for backlog  $\eta$  and  $S^{\dagger}$  is the set of *non-essential* ones (see [1], end of Section IV). We have

$$X(t) \in \mathcal{C}^{o}(\eta) \implies \langle S(t), \Delta \eta \rangle = \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle$$
(2.3)

where  $C^{o}(\eta)$  is the interior of  $C(\eta)$ . Define now

$$\mathcal{K}(\eta) = \{ x \in \mathbb{R}_{0+}^Q : x_q > \max_{S \in \mathcal{S}} \{ S_q \} \text{ for each } q \text{ with } \eta_q > 0 \},$$
(2.4)

which is upward-scalable; indeed,  $x \in \mathcal{K}(\eta)$  implies  $\alpha x \in \mathcal{K}(\eta)$  for any scalar  $\alpha > 1$ . Note that when  $X(t) \in \mathcal{K}(\eta)$ we have  $X_q(t) > \max_{S \in \mathcal{S}} \{S_q\}$  from all  $q \in \mathcal{Q}$  with  $\eta_q > 0$ , so  $D_q(t) = \min\{X_q(t), S_q(t)\} = S_q(t)$ . Therefore,

$$X(t) \in \mathcal{K}(\eta) \implies D_q(t) = S_q(t) \text{ for all } q \in \mathcal{Q} \text{ with } \eta_q > 0.$$
 (2.5)

that is, all service capacity allocated at slot t to queue q with  $\eta_q > 0$  is used; there is no idling in that time slot. Consider now the set

$$\mathcal{V}(\eta) = \mathcal{K}(\eta) \bigcap \mathcal{C}^{o}(\eta) \tag{2.6}$$

and note that it is upward-scalable, that is,  $x \in \mathcal{V}(\eta)$  implies  $\alpha x \in \mathcal{V}(\eta)$  for any scalar  $\alpha > 1$ . Thus, the set  $\mathcal{V}(\eta)$  is 'cone-like' for large backlog vectors.

#### 2.1 Structural Properties

**Lemma 2.1** For every sequence  $\{t'_c\}$  such that  $t'_c < t_c$  and

$$X(t) \in \mathcal{V}(\eta)$$
 for every  $X(t) \in (t'_c, t_c]$  (2.7)

for every c, we have

$$\left\langle \frac{X(t_c) - X(t'_c)}{t_c - t'_c}, \mathbf{\Delta}\eta \right\rangle = \left\langle \frac{\sum_{t=t'_c}^{t_c - 1} A(t)}{t_c - t'_c}, \mathbf{\Delta}\eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S(t), \mathbf{\Delta}\eta \right\rangle.$$
(2.8)

Proof: We write (using similar arguments like in equations of A.22 to A.27 of [1]),

$$\begin{split} \left\langle X(t_{c}) - X(t_{c}'), \mathbf{\Delta}\eta \right\rangle &= \left\langle \sum_{t=t_{c}'}^{t_{c}-1} A(t), \mathbf{\Delta}\eta \right\rangle - \left\langle \sum_{t=t_{c}'}^{t_{c}-1} D(t), \mathbf{\Delta}\eta \right\rangle \\ &= \left\langle \sum_{t=t_{c}'}^{t_{c}-1} A(t), \mathbf{\Delta}\eta \right\rangle - \sum_{t=t_{c}'}^{t_{c}-1} \left\langle D(t), \mathbf{\Delta}\eta \right\rangle \\ &= \left\langle \sum_{t=t_{c}'}^{t_{c}-1} A(t), \mathbf{\Delta}\eta \right\rangle - \sum_{t=t_{c}'}^{t_{c}-1} \left[ \sum_{q:\eta_{q}>0} D_{q}(t) \mathbf{\Delta}_{qq}\eta_{q} + \sum_{q:\eta_{q}=0} D_{q}(t) \mathbf{\Delta}_{qq}\eta_{q} \right] \\ &= \left\langle \sum_{t=t_{c}'}^{t_{c}-1} A(t), \mathbf{\Delta}\eta \right\rangle - \sum_{t=t_{c}'}^{t_{c}-1} \left[ \sum_{q:\eta_{q}>0} S_{q}(t) \mathbf{\Delta}_{qq}\eta_{q} + \sum_{q:\eta_{q}=0} S_{q}(t) 0 \right] \\ &= \left\langle \sum_{t=t_{c}'}^{t_{c}-1} A(t), \mathbf{\Delta}\eta \right\rangle - \sum_{t=t_{c}'}^{t_{c}-1} \left\langle S(t), \mathbf{\Delta}\eta \right\rangle \\ &= \left\langle \sum_{t=t_{c}'}^{t_{c}-1} A(t), \mathbf{\Delta}\eta \right\rangle - \sum_{S\in\mathcal{S}}^{t_{c}-1} \left\langle S(t), \mathbf{\Delta}\eta \right\rangle (t_{c}-t_{c}'), \end{split}$$
(2.9)

To see the above steps, recall the following. First,  $X(t) \in \mathcal{V}(\eta)$  for every  $t \in (t'_c, t_c]$  and any c, by assumption. Therefore,  $X(t) \in \mathcal{K}(\eta)$ , hence, from (2.5) we get  $D_q(t) = S_q(t)$  for  $q \in \mathcal{Q}$  with  $\eta_q > 0$ , for every  $t \in (t'_c, t_c]$  and any c. Moreover,  $X(t) \in \mathcal{C}(\eta)$ , hence, from (2.3) we get  $\langle S(t), \Delta \eta \rangle = \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle$ , for all  $t \in (t'_c, t_c]$  and any c.

**Lemma 2.2** For any increasing unbounded time sequences  $\{t_n\}$  and  $\{t'_n\}$ , we have

$$\lim_{n \to \infty} \frac{t_n - t'_n}{t_n} = \chi \in (0, 1] \implies \lim_{n \to \infty} \frac{\sum_{t=t'_n}^{t_n - 1} A(t)}{t_n - t'_n} = \rho$$
(2.10)

*Proof:* Note that  $t'_n < t_n$  eventually (for any large n), expand the terms as follows:

$$\frac{\sum_{t=t'_n}^{t_n-1} A(t)}{t_n - t'_n} = \frac{\sum_{t=0}^{t_n-1} A(t)}{t_n - t'_n} - \frac{\sum_{t=0}^{t'_n-1} A(t)}{t_n - t'_n} = \frac{\sum_{t=0}^{t_n-1} A(t)}{t_n} \frac{t_n}{t_n - t'_n} - \frac{\sum_{t=0}^{t_n-1} A(t)}{t'_n} \frac{t'_n}{t_n - t'_n},$$
(2.11)

and observe that letting  $n \rightarrow \infty$  we get

$$\lim_{n \to \infty} \frac{\sum_{t=t'_n}^{t_n - 1} A(t)}{t_n - t'_n} = \rho \, \frac{1}{\chi} - \rho \, (\frac{1}{\chi} - 1) = \rho, \tag{2.12}$$

since  $\lim_{n\to\infty} \frac{\sum_{t=0}^{T} A(t)}{T} = \rho$ . This completes the proof of the lemma.

**Lemma 2.3** For any increasing unbounded subsequence  $\{t_m\}$  with  $\lim_{m\to\infty} \frac{X(t_m)}{t_m} = \mu$ , we have

$$\langle \mu, \Delta \eta \rangle \ge \langle \rho, \Delta \eta \rangle - \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle$$
 (2.13)

Proof: We write

$$X(t_m) = \sum_{t=0}^{t_m-1} A(t) - \sum_{t=0}^{t_m-1} D(t)$$
(2.14)

and observe that  $D_q(t) = \min\{S_q(t), X_q(t)\} \le S_q(t)$  for every  $q \in Q$ , hence,  $-D_q(t) \ge -S_q(t)$ . Therefore, since  $\Delta$  is diagonal (with positive elements), we have  $-\langle D(t), \Delta \eta \rangle \ge \langle S(t), \Delta \eta \rangle \ge -\max_{S \in S} \langle S, \Delta \eta \rangle$ . Projecting on  $\Delta \eta$  we get

$$\langle X(t_m), \mathbf{\Delta}\eta \rangle \ge \left\langle \sum_{t=0}^{t_m-1} A(t), \mathbf{\Delta}\eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S, \mathbf{\Delta}\eta \right\rangle(t_m)$$
 (2.15)

Dividing by  $t_m$  and letting  $m \rightarrow \infty$ , we get

$$\langle \mu, \Delta \eta \rangle \ge \langle \rho, \Delta \eta \rangle - \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle > 0$$
 (2.16)

This completes the proof of the lemma.

**Lemma 2.4** For any increasing unbounded subsequence  $\{t_m\}$  with  $\lim_{m\to\infty} \frac{X(t_m)}{t_m} = \mu$ , we have

$$\langle \mu, \Delta \eta \rangle \ge \langle \eta, \Delta \eta \rangle \implies \mu = \eta$$
 (2.17)

*Proof:* Indeed (recalling that  $\Delta$  is positive-definite), we have

$$0 \leq \langle \mu - \eta, \mathbf{\Delta}(\mu - \eta) \rangle = \langle \mu, \mathbf{\Delta}\mu \rangle - 2 \langle \mu, \mathbf{\Delta}\eta \rangle + \langle \eta, \mathbf{\Delta}\eta \rangle$$
$$\leq \langle \mu, \mathbf{\Delta}\mu \rangle - 2 \langle \eta, \mathbf{\Delta}\eta \rangle + \langle \eta, \mathbf{\Delta}\eta \rangle = \langle \mu, \mathbf{\Delta}\mu \rangle - \langle \eta, \mathbf{\Delta}\eta \rangle, \qquad (2.18)$$

so  $\langle \mu, \Delta \mu \rangle \geq \langle \eta, \Delta \eta \rangle$ . But since  $\langle \eta, \Delta \eta \rangle = \limsup t \to \infty \left\langle \frac{X(t)}{t}, \Delta \frac{X(t)}{t} \right\rangle$ , we must have  $\langle \mu, \Delta \mu \rangle = \langle \eta, \Delta \eta \rangle$ , therefore,  $\langle \mu - \eta, \Delta(\mu - \eta) \rangle = 0$ , which implies  $\mu = \eta$ . This completes the proof of the lemma.

**Lemma 2.5** For every  $\epsilon \in (0, 1)$  we have

$$-\left[\langle \rho, \mathbf{\Delta}\eta \rangle - \max_{S \in \mathcal{S}} \langle S, \mathbf{\Delta}\eta \rangle\right] \frac{\epsilon}{1-\epsilon} + \langle \eta, \mathbf{\Delta}\eta \rangle \frac{1}{1-\epsilon} \ge \langle \eta, \mathbf{\Delta}\eta \rangle$$
(2.19)

*Proof:* Rewrite the inequality as  $-[\langle \rho, \Delta \eta \rangle - \max_{S \in S} \langle S, \Delta \eta \rangle] \epsilon + \langle \eta, \Delta \eta \rangle \ge (1 - \epsilon) \langle \eta, \Delta \eta \rangle$ , since  $1 - \epsilon > 0$ . This is equivalent (since  $\epsilon > 0$ ) to

$$\langle \eta, \Delta \eta \rangle \ge \langle \rho, \Delta \eta \rangle - \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle$$
 (2.20)

But this is true by Lemma 2.3 applied to the sequence  $\{t_c\}$  with  $\lim_{c\to\infty} \frac{X(t_c)}{t_c} = \eta$ . This complete the proof of the lemma.

2.2 Uniqueness of limit  $\lim_{t\to\infty}\frac{X(t)}{t}$  on an individual arrival trace

**Proposition 2.1** There is no subsequence  $\{\mathbf{t}_{\mathbf{a}}\}$  with  $\lim_{\mathbf{a}\to\infty}\frac{\mathbf{X}(\mathbf{t}_{\mathbf{a}})}{\mathbf{t}_{\mathbf{a}}} = \psi \neq \eta$ .

Arguing by contradiction, assume that there is some other convergent subsequence  $\{X(t_a)\}$  such that  $\lim_{a\to\infty} \frac{X(t_a)}{t_a} = \psi \neq \eta$ . We shall show that this is impossible. Note that  $\psi_q < \infty$  for all q. This is easy to see since  $\psi_q = \lim_{a\to\infty} \frac{X_q(t_a)}{t_a} \leq \lim_{a\to\infty} \frac{A_q(t_a)}{t_a} = \rho_q < \infty$ . Define first

$$s_c = \max\{t_a : t_a < t_c\} < t_c \tag{2.21}$$

Lemma 2.6 We have that

$$\liminf_{c \to \infty} \frac{t_c - s_c}{t_c} = \epsilon \in (0, 1)$$
(2.22)

*Proof:* A) We first show that  $\epsilon > 0$ . We start by showing that there is no increasing unbounded subsequence  $\{t_b\}$  of  $\{t_c\}$  such that  $\lim_{b\to\infty} \frac{t_b-s_b}{t_b} = 0$ , where  $s_b = \max\{t_a < t_b\}$ . Note that this also implies that  $\lim_{b\to\infty} \frac{s_b}{t_b} = 1$ . Arguing by contradiction, suppose it exists. Observe that for every  $q \in Q$  we have

$$-\bar{S}_q(t_b - s_b) \le X_q(t_b) - X_q(s_b) \le \bar{A}_q(t_b - s_b),$$
(2.23)

where  $A_q < \infty$  is the maximum workload that can arrive in queue q in any time slot (see model in [1] for assumption of boundedness) and  $\bar{S}_q = \max_{S \in S} \{S_q\} < \infty$  is the maximum workload that can be removed from queue q in any time slot. Dividing by  $t_b$ , letting  $b \to \infty$ , we get

$$\lim_{b \to \infty} \frac{X(t_b) - X(s_b)}{t_b} = 0 = \lim_{b \to \infty} \left[ \frac{X(t_b)}{t_b} - \frac{X(s_b)}{s_b} \frac{s_b}{t_b} \right] = \eta - \psi$$
(2.24)

which implies that  $\eta = \psi$  and establishes the desired contradiction.

B) We still need to show that  $\epsilon \neq 1$  (note that  $\frac{t_c - s_c}{t_c} \leq 1$ ). Arguing by contradiction, suppose there exists a subsequence  $\{t_i\}$  of  $\{t_c\}$  (and corresponding subsequence  $\{s_i\}$  of  $\{s_c\}$ ) such that  $\lim_{i\to\infty} \frac{t_i - s_i}{t_i} = 1$ , hence,  $\lim_{i\to\infty} \frac{s_i}{t_i} = 0$ . Applying Lemmas 2.1 and 2.2 with  $\{t'_i\} = \{s_i\}$ 

$$\lim_{i \to \infty} \left\langle \frac{X(t_i) - X(s_i)}{t_i - s_i}, \Delta \eta \right\rangle = \left\langle \rho, \Delta \eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S(t), \Delta \eta \right\rangle$$
(2.25)

It follows that

$$\begin{aligned} \langle \eta, \mathbf{\Delta} \eta \rangle &= \lim_{i \to \infty} \left\langle \frac{X(t_i)}{t_i}, \mathbf{\Delta} \eta \right\rangle \\ &= \lim_{i \to \infty} \left\langle \frac{X(t_i) - X(s_i)}{t_i - s_i} \frac{t_i - s_i}{t_i} + \frac{X(s_i)}{s_i} \frac{s_i}{t_i}, \mathbf{\Delta} \eta \right\rangle \\ &= \lim_{i \to \infty} \left\langle \frac{X(t_i) - X(s_i)}{t_i - s_i}, \mathbf{\Delta} \eta \right\rangle \frac{t_i - s_i}{t_i} + \left\langle \frac{X(s_i)}{s_i}, \mathbf{\Delta} \eta \right\rangle \frac{s_i}{t_i} \\ &= \left[ \langle \rho, \mathbf{\Delta} \eta \rangle - \max_{S \in \mathcal{S}} \langle S(t), \mathbf{\Delta} \eta \rangle \right] \cdot 1 + \langle \psi, \mathbf{\Delta} \eta \rangle \cdot 0 \\ &= \langle \rho, \mathbf{\Delta} \eta \rangle - \max_{S \in \mathcal{S}} \langle S(t), \mathbf{\Delta} \eta \rangle \end{aligned}$$
(2.26)

Now applying Lemma 2.3 on the subsequence  $\{s_i\}$  with  $\lim_{s_i \to \infty} \frac{X(s_i)}{s_i} = \psi$  we get

$$\langle \psi, \Delta \eta \rangle \ge \langle \rho, \Delta \eta \rangle - \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle = \langle \eta, \Delta \eta \rangle,$$
 (2.27)

using (2.26). Hence,  $\langle \psi, \Delta \eta \rangle \geq \langle \eta, \Delta \eta \rangle$ , which implies  $\psi = \eta$  by Lemma 2.4. But this is impossible since by definition of subsequence  $\{s_c\}, \psi \neq \eta$ , which completes the proof of the lemma.

Select now a subsequence of  $\{t_c\}$  on which this 'liminf' is attained, but keep the same indexing c of the original one for notational simplicity, hence,

$$\lim_{c \to \infty} \frac{t_c - s_c}{t_c} = \epsilon \in (0, 1).$$
(2.28)

Therefore,  $\lim_{c\to\infty} \frac{t_c}{s_c} = \frac{1}{1-\epsilon}$  and  $\lim_{c\to\infty} \frac{t_c-s_c}{s_c} = \frac{\epsilon}{1-\epsilon}$ .

Again, applying Lemmas 2.1 and 2.2 with  $\{t'_c\} = \{s_c\}$ , dividing by  $t_c - s_c$  and letting  $c \rightarrow \infty$ , we get

$$\lim_{c \to \infty} \left\langle \frac{X(t_c) - X(s_c)}{t_c - s_c}, \Delta \eta \right\rangle = \left\langle \rho, \Delta \eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S, \Delta \eta \right\rangle.$$
(2.29)

Then, we can write

$$\begin{aligned} \langle \psi, \mathbf{\Delta} \eta \rangle &= \lim_{c \to \infty} \left\langle \frac{X(s_c)}{s_c}, \mathbf{\Delta} \eta \right\rangle \\ &= \lim_{c \to \infty} \left\langle -\frac{X(t_c) - X(s_c)}{t_c - s_c} \frac{t_c - s_c}{s_c} + \frac{X(t_c)}{t_c} \frac{t_c}{s_c}, \mathbf{\Delta} \eta \right\rangle \\ &= -\left[ \left\langle \rho, \mathbf{\Delta} \eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S, \mathbf{\Delta} \eta \right\rangle \right] \frac{\epsilon}{1 - \epsilon} + \left\langle \eta, \mathbf{\Delta} \eta \right\rangle \frac{1}{1 - \epsilon} \\ &\geq \left\langle \eta, \mathbf{\Delta} \eta \right\rangle \end{aligned}$$
(2.30)

The last equality is due to Lemma 2.5. Therefore,  $\langle \psi, \Delta \eta \rangle \geq \langle \eta, \Delta \eta \rangle$ , which implies  $\psi = \eta$  from Lemma 2.4. But this contradicts the assumption that  $\psi \neq \eta$ . This establishes the sought after contradiction. So for each individual arrival trace, there exists a unique limit  $\lim_{t\to\infty} \frac{X(t)}{t} = \eta$ , which concludes the proof of the proposition. Moreover, since  $\lim_{t\to\infty} \frac{X(t)}{t} = \eta$  this implies that there exists  $t_o < \infty$  such that X(t) is in  $\mathcal{V}(\eta)$  for all  $t > t_o$ . It remains to show that the limit,  $\eta$ , is independent of the particular arrival trace.

## **2.3** Characterizing the limit $\eta$

The purpose of this section is to characterize  $\eta$  in terms of  $\rho$  and service vectors S to establish the independence of  $\eta$  on the individual arrival trace. Knowing that  $\lim_{t\to\infty} \frac{X(t)}{t} = \eta$ , we now turn to identifying a couple of the characteristic properties of  $\eta$ .

Lemma 2.7 Every limit is a fixed point. That is,

$$\eta = \lim_{t \to \infty} \frac{X(t)}{t} = \left[\rho - \sum_{m=1}^{N} \alpha_m S_m\right]^+$$
(2.31)

for some  $\alpha_m \ge 0, \sum_m \alpha_m = 1$ . Furthermore,  $\alpha_m > 0$  implies that  $\eta \in C_{S_m}$ 

*Proof:* Consider a subsequence  $\{t_n\}$  such that for each m:

$$\alpha_m = \lim_{n \to \infty} \frac{\sum_{t=0}^{t_n - 1} \mathbf{1}_{\{S(t) = S_m\}}}{t_n}$$
(2.32)

Note that by definition:  $\alpha_m \in [0, 1]$  and  $\sum_m \alpha_m \leq 1$ . Further, because  $\rho \notin \mathcal{P}$ , there exist q and  $T < \infty$ , such that  $X_q(t) > 0$  for all t > T; hence, PCS will never idle for t > T and  $\sum_m \alpha_m = 1$ .

We have for q such that  $\eta_q > 0$ :

$$\eta_{q} = \lim_{n \to \infty} \frac{X_{q}(t_{n})}{t_{n}}$$

$$= \lim_{n \to \infty} \frac{\sum_{t=0}^{t_{n}-1} \left[A_{q}(t) - D_{q}(t)\right]}{t_{n}}$$

$$= \lim_{n \to \infty} \frac{X_{q}(t_{o}) + \sum_{t=t_{o}}^{t_{n}-1} \left[A_{q}(t) - \sum_{m} S_{m,q} \mathbf{1}_{\{S(t)=S_{m}\}}\right]}{t_{n}}$$

$$= \rho_{q} - \sum_{m} \alpha_{m} S_{m,q}$$
(2.33)

Where  $t_o < \infty$  such that for all  $t > t_o$ ,  $X(t) \in \mathcal{V}(\eta)$ . It's existence is given by Proposition 2.1. For q such that  $\eta_q = 0$ , we have:

$$0 = \eta_{q} = \lim_{n \to \infty} \frac{X_{q}(t_{n})}{t_{n}}$$

$$= \lim_{n \to \infty} \frac{\sum_{t=0}^{t_{n}-1} \left[A_{q}(t) - D_{q}(t)\right]}{t_{n}}$$

$$= \lim_{n \to \infty} \frac{X_{q}(t_{o}) + \sum_{t=t_{o}}^{t_{n}-1} \left[A_{q}(t) - \sum_{m} \min\{X_{q}(t), S_{m,q}\}\mathbf{1}_{\{S(t)=S_{m}\}}\right]}{t_{n}}$$

$$\geq \lim_{n \to \infty} \frac{X_{q}(t_{o}) + \sum_{t=t_{o}}^{t_{n}-1} \left[A_{q}(t) - \sum_{m} S_{m,q}\mathbf{1}_{\{S(t)=S_{m}\}}\right]}{t_{n}}$$

$$= \rho - \sum_{m} \alpha_{m} S_{m,q}$$
(2.34)

Which means that  $\rho_q - \sum_m \alpha_m S_{m,q} \leq 0$  and

$$0 = \eta_q = \left[\rho_q - \sum_m \alpha_m S_{m,q}\right]^+,$$
(2.35)

which gives us that  $\eta = \left[\rho - \sum_{m} \alpha_m S_m\right]^+$ .

Finally, we have to show that if  $\alpha_m > 0$ , then  $\eta \in C_{S_m}$ . We have seen that  $\alpha_m$  is the proportion of time that service vector  $S_m$  is used under PCS once  $X(t) \in \mathcal{V}(\eta)$  for all  $t > t_o$ . By Proposition 2.1, we know that  $t_o$  exists. By contradiction, suppose that  $\eta \notin C_{S_m}$ . This implies that there exists  $m' \neq m$  such that  $\langle \eta, \Delta S_{m'} \rangle > \langle \eta, \Delta S_m \rangle$ . Since  $\alpha_m > 0$ , we must use  $S_m$  for some  $t > t_o$ . This contradicts the definition of  $\mathcal{V}(\eta)$ , which by (2.3) says that PCS would use  $S_{m'}$  rather than  $S_m$  which would imply that  $\alpha_m = 0$ . Hence, if  $\alpha_m > 0$ ,  $\eta \in C_{S_m}$ .

Lemma 2.8 We have

$$\langle \eta, \Delta \eta \rangle = \langle \rho, \Delta \eta \rangle - \max_{S \in \mathcal{S}} \langle S, \Delta \eta \rangle$$
 (2.36)

*Proof:* This follows from Lemma 2.7. Replacing  $\eta = [\rho - \sum_{m=1}^{N} \alpha_m S_m]^+$  we have

$$\langle \eta, \boldsymbol{\Delta} \eta \rangle = \left\langle \left[ \rho - \sum_{m=1}^{N} \alpha_m S_m \right]^+, \boldsymbol{\Delta} \eta \right\rangle$$

$$= \sum_{q:\eta_q > 0} \left[ \rho - \sum_{m=1}^{N} \alpha_m S_m \right]_q \boldsymbol{\Delta}_{qq} \eta_q + \sum_{q:\eta_q = 0} \left[ \rho - \sum_{m=1}^{N} \alpha_m S_m \right]_q^+ \boldsymbol{\Delta}_{qq} \eta_q$$

$$= \sum_{q:\eta_q > 0} \left[ \rho - \sum_{m=1}^{N} \alpha_m S_m \right]_q \boldsymbol{\Delta}_{qq} \eta_q + \sum_{q:\eta_q = 0} \left[ \rho - \sum_{m=1}^{N} \alpha_m S_m \right]_q \boldsymbol{\Delta}_{qq} 0$$

$$= \left\langle \rho - \sum_{m=1}^{N} \alpha_m S_m, \boldsymbol{\Delta} \eta \right\rangle$$

$$= \left\langle \rho, \boldsymbol{\Delta} \eta \right\rangle - \sum_{m=1}^{N} \left\langle \alpha_m S_m, \boldsymbol{\Delta} \eta \right\rangle$$

$$= \left\langle \rho, \boldsymbol{\Delta} \eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S, \boldsymbol{\Delta} \eta \right\rangle$$

$$(2.37)$$

where the last equality follows from the fact that  $\eta$  is a fixed point.

**Lemma 2.9** The vector  $\eta = \lim_{t\to\infty} \frac{X(t)}{t}$  is the <u>unique</u> minimizer of

$$\langle \eta, \mathbf{\Delta}\eta \rangle = \min_{\eta' \in \Psi(\rho, S)} \left\langle \eta', \mathbf{\Delta}\eta' \right\rangle$$
 (2.38)

where

$$\Psi(\rho, \mathcal{S}) = \{\eta' : \eta' = (\rho - r)^+ \text{ with } r \in \mathcal{P}\}$$
(2.39)

and  $\mathcal{P}$  is the stability region given by  $\mathcal{S}$ . Therefore,  $r = \sum_{S \in \mathcal{S}} \alpha_S S$  with  $\sum_{S \in \mathcal{S}} \alpha_S \leq 1$  and  $\alpha_S \geq 0$  for each  $S \in \mathcal{S}$ , where  $\mathcal{S}$  is the set of service vectors.

*Proof:* From Lemma 2.7, we have that  $\eta \in \Psi(\rho, S)$ . Arbitrarily choose any vector

$$\bar{\eta} = \left(\rho - \sum_{S \in \mathcal{S}} \alpha_S S\right)^+$$
, with  $\sum_{S \in \mathcal{S}} \alpha_S \le 1$ , and  $\alpha_S \ge 0, S \in \mathcal{S}$ . (2.40)

Projecting on  $\Delta \eta$  we get

$$\langle \bar{\eta}, \boldsymbol{\Delta} \eta \rangle = \left\langle \left[ \rho - \sum_{S \in \mathcal{S}} \alpha_S S \right]^+, \boldsymbol{\Delta} \eta \right\rangle$$

$$\geq \left\langle \rho - \sum_{S \in \mathcal{S}} \alpha_S S, \boldsymbol{\Delta} \eta \right\rangle$$

$$= \left\langle \rho, \boldsymbol{\Delta} \eta \right\rangle - \sum_{S \in \mathcal{S}} \alpha_S \left\langle S, \boldsymbol{\Delta} \eta \right\rangle$$

$$\geq \left\langle \rho, \boldsymbol{\Delta} \eta \right\rangle - \max_{S \in \mathcal{S}} \left\langle S, \boldsymbol{\Delta} \eta \right\rangle = \left\langle \eta, \boldsymbol{\Delta} \eta \right\rangle$$

$$(2.41)$$

The first inequality comes from the fact that  $\Delta_{qq} > 0$  and  $\eta_q \ge 0$ . The last equality comes from Lemma 2.8. Therefore,  $\langle \bar{\eta}, \Delta \eta \rangle \ge \langle \eta, \Delta \eta \rangle$ . This implies (recalling that  $\Delta$  is positive-definite) that

$$0 \leq \langle \bar{\eta} - \eta, \mathbf{\Delta}(\bar{\eta} - \eta) \rangle$$
  
=  $\langle \bar{\eta}, \mathbf{\Delta}\bar{\eta} \rangle - 2 \langle \bar{\eta}, \mathbf{\Delta}\eta \rangle + \langle \eta, \mathbf{\Delta}\eta \rangle$   
 $\leq \langle \bar{\eta}, \mathbf{\Delta}\bar{\eta} \rangle - 2 \langle \eta, \mathbf{\Delta}\eta \rangle + \langle \eta, \mathbf{\Delta}\eta \rangle$   
=  $\langle \bar{\eta}, \mathbf{\Delta}\bar{\eta} \rangle - \langle \eta, \mathbf{\Delta}\eta \rangle$ , (2.42)

so  $\langle \bar{\eta}, \Delta \bar{\eta} \rangle \geq \langle \eta, \Delta \eta \rangle$  and  $\eta$  is the minimizer of  $\langle \eta', \Delta \eta' \rangle$ .

We still need to prove that the minimizer  $\eta$  is unique. This is done by showing that 1)  $\langle \eta, \Delta \eta \rangle$  is strictly convex in  $\eta$  and 2) the set  $\Psi(\rho, S)$  is convex–uniqueness will follow from convex programming theory. 1) It is trivial to show that  $\langle \eta, \Delta \eta \rangle$  is strictly convex in  $\eta$  since  $\Delta > 0$  is a positive definite matrix. 2) We now show that the set  $\Psi \equiv \Psi(\rho, S)$  is convex. First, we see that for any  $r \in \mathcal{P}$  and corresponding  $x = (\rho - r)^+ \in \Psi$ , there exists  $\bar{x} = \rho - \bar{r} = (\rho - r)^+ = x$  with  $\bar{r} \in \mathcal{P}$ . Let  $\bar{r}_k = \min(\rho_k, r_k) \leq r_k$ . Since  $\bar{r} \leq r \in \mathcal{P}$ , then  $\bar{x} \in \Psi$ . Now, consider two vectors  $x, x' \in \Psi$  with corresponding  $r, r' \in \mathcal{P}$  such that  $x = (\rho - r)^+$  and  $x' = (\rho - r')^+$ . What remains to be shown is that for any  $a \in [0, 1]$ ,  $ax + (1 - a)x' \in \Psi$ . Indeed, we have:

$$ax + (1 - a)x' = a\bar{x} + (1 - a)\bar{x}'$$
  
=  $a(\rho - \bar{r}) + (1 - a)(\rho - \bar{r}')$   
=  $\rho - (a\bar{r} + (1 - a)\bar{r}')$  (2.43)

By the convexity of  $\mathcal{P}$ , we know that  $a\bar{r} + (1-a)\bar{r}' \in \mathcal{P}$  and subsequently,  $\rho - (a\bar{r} + (1-a)\bar{r}') \in \Psi$ . This concludes the proof.

We have just shown that on all arrival traces with system load  $\rho$ ,  $\lim_{t\to\infty} \frac{X(t)}{t} = \eta$ , is unique. Furthermore, the limit,  $\eta$ , is identical across all such traces. This concludes the proof of Theorem 2.1.

## References

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