Return interval distribution of extreme events and long term memory

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The distribution of recurrence times or return intervals between extreme events is important to characterize and understand the behavior of physical systems and phenomena in many disciplines. It is well known that many physical processes in nature and society display long range correlations. Hence, in the last few years, considerable research effort has been directed towards studying the distribution of return intervals for long range correlated time series. Based on numerical simulations, it was shown that the return interval distributions are of stretched exponential type. In this paper, we obtain an analytical expression for the distribution of return intervals in long range correlated time series which holds good when the average return intervals are large. We show that the distribution is actually a product of power law and a stretched exponential form. We also discuss the regimes of validity and perform detailed studies on how the return interval distribution depends on the threshold used to define extreme events.

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I. INTRODUCTION

Extreme events take place frequently in both nature and society. For instance, the recurrence of floods, droughts, earth quakes and economic recession are all examples of extreme events. The consequences of extreme events to life and property are often enormous and hence it is desirable to study their properties and questions related to their predictability. Interestingly, all of these extreme events are also non-equilibrium phenomena and studying the extreme value statistics in them will lead to a better understanding of the models and the phenomenology of non-equilibrium statistical physics. Thus, there is an increasing interest in the physics literature to understand a broad range of issues and phenomena connected with the occurance of extreme events and their dynamics [1, 2].

In the classical extreme value theory, the limiting distribution for the extreme maximal values in sequences of independent and identically distributed random variables can be one of the Fréchet, Gumbel or Weibull distribution depending on the behavior of the tail of the probability density [3]. This has been empirically verified in many cases of practical interest. Many new applications continue to be discovered, for example, the recent one being the distribution of extreme components of the eigenmodes of quantum chaotic systems [4]. In contrast to the questions about the distribution of extrema, one of the problems being addressed in the last few years is the distribution of the returns intervals for the extreme events when the underlying time series displays long memory [5, 6, 7, 8, 9]. This is primarily motivated by the fact that many of the natural and socio-economic phenomena,

e.g., daily temperature, DNA sequences, river run-off, earth quakes, stock markets etc., display long memory or long range correlation [10, 11]. Long memory implies slowly decaying auto correlation function of the power law type such that the system does not exhibit typical time scales. In this case, the intervals between extreme events are likely to be correlated as well. On the contrary, it is known that for an uncorrelated time series, intervals between extreme events are also uncorrelated and are exponentially distributed. The question is how the presence of long range correlation modifies the return interval distribution of extreme events? A definite answer to this question would shed new light on many problems across various disciplines.

Return interval distributions are interesting and useful for several reasons, the most important being that many problems in diverse fields can be formulated in terms of return interval statistics with wide ranging applications. For instance, the problem of recurrence time interval between earthquakes above a given magnitude [12], x-ray solar flare recurrences [13], statistics of acoustic emission from rock fractures [14], inter arrival packet times on computer and cellular networks [15] and the classical problem of Poincare recurrences in Hamiltonian systems [16] can all be formulated as extreme event questions involving return interval distribution. In a non-stationary time series, it is often difficult to reliably estimate its temporal statistical properties such as the autocorrelations or higher order correlations. Thus, return interval distributions are also a useful tool to characterize temporal properties of such systems.

Let x(t) denote a sequence of random variable, where t is the time index. We will call an event extreme if x(t) > q where q is some threshold value. The return interval r is the time between successive occurance of extreme events. With respect to threshold q, we have a well-defined series of return intervals, r_k , k = 1, 2, 3, ...N. This is schematically shown in Fig 1. If the random

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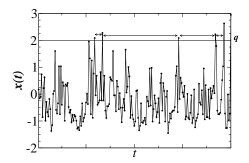


FIG. 1: This schematic diagram shows the return intervals for a threshold value q=2 as a function of time t.

variables x(t) are uncorrelated, then the return intervals r_k are also uncorrelated and they are exponentially distributed as

$$P_q(r) = \frac{1}{\langle r \rangle} e^{-r/\langle r \rangle}. \tag{1}$$

In order to use later, we also define the average return interval dependent on threshold q to be

$$\langle r \rangle_q = \lim_{N \to \infty} \frac{1}{N} \sum_{k=1}^N r_k.$$
 (2)

In contrast to an uncorrelated time series, a long range correlated series has an autocorrelation function that displays power law of the form,

$$C(\tau) = \langle x(t+\tau) \ x(t) \rangle \sim \tau^{-\gamma}, \qquad (0 < \gamma < 1), \quad (3)$$

where $\langle . \rangle$ denotes the temporal average and γ is the auto correlation exponent. The work done in the last few years show that the long range correlation does indeed affect the return interval distribution of extreme events [5, 6, 7, 8, 9]. Empirical results in a series of papers [5, 6, 7, 8, 9] have shown that, in the presence of long range correlation, the return interval distribution becomes a stretched exponential given by,

$$P_q(R) = A(\gamma) e^{-B(\gamma) R^{\gamma}}.$$
 (4)

with scaled return intervals being defined as $R = r/\langle r \rangle$. Both $A(\gamma)$ and $B(\gamma)$ are constants that depend on γ . They can be fixed by normalizing both the probability and the average return interval to unity. It has also been shown that the return intervals themselves are long range correlated.

However, an analytical justification for the stretched exponential distribution in Eq. 4 is still lacking and the main contribution of this paper is to partly fill this void. In this context, it must be noted that deviations from the stretched exponential distribution in Eq. 4 have been noted for return intervals shorter (R < 1) than the average. For short return intervals, i.e, R < 1, empirical results display a power law with the exponent $\sim (\gamma - 1)$ [7], which is not explained by Eq. 4. While the return

interval distribution is expected to depend on the threshold q, the stretched exponential form does not explicitly reveal this dependence. This paper addresses these questions using a combination of analytical and numerical results. Firstly, from theoretical arguments, we obtain an approximate expression for the return interval distribution, which modifies Eq. 4 from a purely stretched exponential form to a product of power law and stretched exponential. Secondly, we systematically study the dependence of return interval distribution on the threshold q and show that our analytical result holds good in the limit of q >> 1. In general, the return interval distribution depends on the value of threshold q.

Recently, in the study of global seismic activity above some magnitude M, the distribution $F(\tau)$ of recurrence times τ have been shown to follow a scaling ansatz of the form

$$F(\tau) = \frac{1}{\bar{\tau}} f(\tau/\bar{\tau}),\tag{5}$$

where the function $f(\tau/\bar{\tau})$ is the gamma distribution [12]. In fact, this scaling relation seems to hold good for forest fire occurance intervals [17], tsunami inter event times [18] and ion channel currents in voltage dependent anion channels in the cell [19]. The analytical distribution obtained in this paper might shed light on this scaling found in a variety of systems.

In the next section, we obtain an analytical expression for the return interval distribution and in the subsequent section we present our numerical results. Further, we systematically study the dependence of the return interval distribution on the threshold used to define the extreme event. Finally, we present our conclusions.

II. RETURN TIME DISTRIBUTION

The starting point of our approach is to transform the given long range correlated time series x(t) with autocorrelation exponent γ into a binary sequence with 1 at positions of extreme events and 0 elsewhere. Thus, we obtain new binary sequence defined by,

$$y(t) = 1$$
, if $x(t) \ge q$
= 0, if $x(t) < q$ (6)

We use the empirical result that for a long range correlated time series with the autocorrelation exponent γ , the return intervals are also long range correlated with the same exponent. Thus, our probability model is the statement that given an extreme event at time t=0, the probability to find an extreme event at time t=r is given by,

$$P_{ex}(r) = ar^{-(2H-1)} = ar^{-(1-\gamma)},$$
 (7)

where 1/2 < H < 1 is the Hurst exponent [20] and a is the normalization constant that will be fixed later. We

have also used the well-known relation between Hurst exponent and autocorrelation exponent; $\gamma=2-2H$. Equation 7 implies that after an extreme event it is highly probable to expect the next event to be an extreme one too; and this is a reasonable proposition for a persistent time series. Notice also that for an uncorrelated time series H=1/2. This leads to P(r) in Eq. 7 becoming independent of r, as would be expected for an uncorrelated time series. Further support for this proposition comes from the theorem due to Newell and Rosenblatt [21, 22] obtained in the context of zero crossing probabilities for Gaussian processes. It states that for a separable Gaussian stationary process X(t) with mean $\langle X \rangle = 0$, the probability g(T) that X(t) > 0 for $0 \ge t \ge T$ is $g(T) = O(T^{-\alpha})$ as $T \to \infty$, where $\alpha > 0$.

Next we calculate the probability that given an extreme event at time t=0, no extreme event occurs in the interval (0,r). For this, we divide the interval r into m sub-intervals indexed by j=0,1,2....(m-1) and we calculate this probability in each of the intervals. For the jth sub-interval, using Eq. 7, the probability of extreme event is given by,

$$h(j) = \frac{a r}{m} \left(\frac{(j+1)r}{m} \right)^{-(1-\gamma)} + \frac{a r}{2m} \left[\left(\frac{jr}{m} \right)^{-(1-\gamma)} - \left(\frac{(j+1)r}{m} \right)^{-(1-\gamma)} \right]$$
(8)

After simplifying this expression, the probability that no extreme event occurs in the jth sub-interval is given by,

$$1 - h(j) = 1 - \frac{ar}{2m} \left(\frac{r}{m}\right)^{-(1-\gamma)} \left[(j+1)^{-(1-\gamma)} + j^{-(1-\gamma)} \right]$$
(9)

At this point, we make an approximation and assume that the probability of no extreme event occurance in each sub-interval to be an independent event. Then, the probability $P_{noex}(r)$ that no extreme event occurs in any of the m sub-intervals in (0,r) is simply the product of probabilities,

$$P_{noex}(r) = \lim_{m \to \infty} \prod_{i=0}^{m-1} 1 - h(j).$$
 (10)

The required probability P(r) dr is simply the product of P_{noex} with the probability P_{ex} that an extreme event takes place in the infinitesimal interval dr beyond r. This can be assembled together as,

$$P(r) dr = P_{noex}(r) P_{ex}(r) dr$$

$$= \lim_{m \to \infty} [1 - \phi_{m,r}] [1 - \phi_{m,r}(2^{-\gamma} + 1)] \qquad (11)$$

$$[1 - \phi_{m,r}(3^{-\gamma} + 2^{-\gamma})] \dots \dots$$

$$[1 - \phi_{m,r}(m^{-\gamma} + (m-1)^{-\gamma})] a r^{-(1-\gamma)} dr$$

where,

$$\phi_{m,r} = \frac{a}{2} \left(\frac{r}{m}\right)^{-\gamma} \tag{12}$$

The value of m can be arbitrarily large and the Eq. 11 can be simplified and rewritten as,

$$P(r) dr = \lim_{m \to \infty} \exp\left(-\frac{a}{2} \left(\frac{r}{m}\right)^{\gamma} \left\{2H_{m-1}^{(\gamma-1)} + m^{-(1-\gamma)}\right\}\right) a r^{-(1-\gamma)} dr$$
 (13)

where $H_{m-1}^{(\gamma-1)}$ is the generalized Harmonic number [23]. In order to take the limit $m\to\infty$, we note that

$$\lim_{m \to \infty} \frac{H_{m-1}^{(\gamma - 1)}}{m^{\gamma}} = \frac{1}{\gamma}, \qquad (0 < \gamma < 1). \tag{14}$$

Using this Eq. 14 in Eq. 13 and taking the limit, we obtain the following result for the distribution of return intervals;

$$P(r)dr = a r^{-(1-\gamma)} e^{-\frac{a}{\gamma}r^{\gamma}} dr.$$
 (15)

The constant a will be fixed by normalization as follows; we demand that the total probability and the average return interval $\langle r \rangle$ be normalized to unity.

$$I = \int_0^\infty P(r) dr = 1 \qquad \text{and} \qquad (16)$$

$$\langle r \rangle = \int_0^\infty r P(r) dr = 1$$
 (17)

However, the distribution in Eq. 15 is already normalized and hence Eq. 17 will be used to determine the value of a. The requirement that $\langle r \rangle = 1$ is equivalent to transforming the return intervals r in units of $\langle r \rangle$. Performing the integrals above, the normalized distribution in the variable $R = r/\langle r \rangle$ turns out to be,

$$P(R) = \gamma \left[\Gamma \left(\frac{1+\gamma}{\gamma} \right) \right]^{\gamma} R^{-(1-\gamma)} e^{-\left[\Gamma \left(\frac{1+\gamma}{\gamma} \right) \right]^{\gamma} R^{\gamma}}$$
 (18)

where $\Gamma(.)$ is the Gamma function. First, we discuss some of the salient features of this distribution. The case $\gamma=1$ defines the crossover to short range or uncorrelated time series. If we put $\gamma=1$ in the distribution in Eq. 18 above, we recover the exponential distribution, $P(R)=\exp(-R)$. In the region $R\ll 1$, i.e., for the return intervals much below the average, the dominant behavior can be seen by taking logarithm on both sides of Eq. 18 leading to,

$$\log P(R) = \log(\gamma \ g_{\gamma}) - (1 - \gamma) \log R - g_{\gamma} R^{\gamma}, \quad (19)$$

where we have used $g_{\gamma} = \left[\Gamma\left(\frac{1+\gamma}{\gamma}\right)\right]^{\gamma}$. For $R \ll 1$, the second term dominates the distribution and thus we obtain a power law with an exponent $(\gamma - 1)$;

$$P(R) \propto R^{-(1-\gamma)} \qquad (R \ll 1) \tag{20}$$

This power law behavior with exponent $(\gamma - 1)$ for short return intervals has already been noted in the numerical

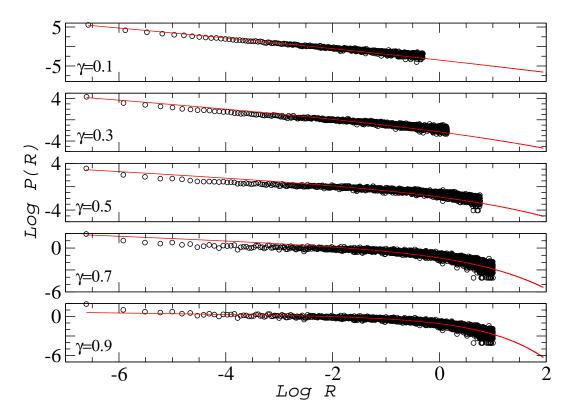


FIG. 2: (Color Online) The simulated return interval distribution (circles) and theoretical distribution in Eq 22 (solid lines) for long range correlated time series. The threshold is q=3.0 with average return interval $\langle r \rangle = 743.0$ for all the cases shown above.

results presented in Ref. [7]. Thus, our approach analytically shows the emergence of a power law regime for short R in contrast to the stretched exponential distribution. On the other hand, for $R\gg 1$, the logarithmic term in Eq. 19 can be dropped and the return interval distribution behaves essentially like a stretched exponential distribution,

$$P(R) \propto e^{-g_{\gamma} R^{\gamma}}.$$
 $(R \gg 1)$ (21)

Thus, stretched exponential is a good approximation for $R \gg 1$. This partly explains why a pure stretched exponential distribution as in Eq. 4 deviates, for R < 1, from the simulated return interval distributions in the earlier works [5, 6, 7, 8, 9]. Finally, we also note that Eq. 18 can also be derived by other methods without actually discretising the interval r as we have done.

As shown above, the return interval distribution in Eq. 18 does reproduce the empirical results already known in the literature but is nevertheless approximate in the following sense. It is known that there exist correlations among the return intervals and they are particularly strong as $\gamma \to 0$. Thus, every return interval de-

pends on the value of previous return interval. This is also well documented in the literature as the conditional probability $P(R|R_0)$ to find return interval R, given that the previous return interval was R_0 [7, 8, 9]. This conditional probability shows interesting features and deviates from the case of uncorrelated return intervals. Equation 18 does not take into account these correlations among intervals and in fact is derived on the assumption that return intervals are independent. This is a gross approximation though in the absence any other definitive model for the correlations among intervals this is a simple and analytically tractable choice. Based on this argument, one can expect Eq. 18 to describe the return interval statistics in the regime where the correlations are not highly dominant, for $\langle r \rangle \gg 1$ [24]. Secondly, note that even though threshold q plays a crucial role as we will describe in the next section, it does not play any role in Eq. 18. Threshold q is related to $\langle r \rangle$ such that higher the value of q, larger is $\langle r \rangle$, though it is not a linear relation. Thus, the theoretical arguments leading to Eq. 18 would best describe an asymptotic limit of $q \gg 1$ or $\langle r \rangle \gg 1$.

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Using Eq. 18 in practice can lead to strong divergence for $r \to 0$. From a physical standpoint, this represents a problem that can be understood based on the fact that there cannot be zero return intervals, but they can be arbitrarily small. By definition r > 0, and if r_{min} is the shortest return interval then its corresponding scaled version would be $r_{min}/\langle r \rangle$. If the original signal is sampled at equal time intervals, r_{min} can be scaled to unity and the shortest scaled return interval would be $1/\langle r \rangle$. The modification of Eq. 18 should be done by replacing the lower limit in the integrals in Eqs 16 and 17 by $1/\langle r \rangle$ instead of 0. This also reflects the general idea that all power laws in practice have a lower bound and the return interval distribution like the Eq. 18 that displays a power law type regime will necessarily have a lower cut off.

We will go back to Eqn. 15 and rewrite the return interval distribution as

$$f(r) = B r^{-(1-\gamma)} e^{-\frac{A}{\gamma}r^{\gamma}},$$
 (22)

where A and B are constants that would now depend on both γ and the average return interval. As usual, both these constants will be fixed by demanding that probability and average return interval normalize to unity. This leads to the following set of integrals;

$$\int_{s_0}^{\infty} f(r) dr = \frac{B}{A} e^{-p} = 1, \tag{23}$$

$$\int_{s_0}^{\infty} r \ f(r) \ dr = \frac{Bs_0}{A} \left(e^{-p} + \frac{\Gamma(1/\gamma, p)}{\gamma \ p^{1/\gamma}} \right) = 1 \ \ (24)$$

where $s_0 = 1/\langle r \rangle$, $p = As_0^{\gamma}/\gamma$ and $\Gamma(.,.)$ is the incomplete Gamma function [25]. The algebraic equations to be solved for A and B are transcendental in nature and closed form solution does not seem possible except for some special values. By further manipulation of Eqns. 23 and 24, we obtain

$$\frac{1}{s_0} = 1 + \frac{e^p \ \Gamma(1/\gamma, p)}{\gamma \ p^{1/\gamma}}.\tag{25}$$

If $p = p_0$ is the solution of Eq 25 for a definite $\langle r \rangle$, then the constants can be obtained as,

$$A = \frac{\gamma \ p_0}{s_0^{\gamma}}, \qquad B = Ae^{p_0}. \tag{26}$$

In the simulations shown in this paper, we have numerically solved for constants A and B in Eq. 22 for various values of $\langle r \rangle$ using Eqns 25 and 26.

III. NUMERICAL RESULTS

In this section, we display the numerical results for the return interval distribution of long range correlated time series drawn from a Gaussian distribution with zero mean

and unit variance. The long range correlated data was generated using the Fourier filtering technique [26]. We generate $2^{25} \sim 3 \times 10^7$ data points for each values of γ and then compute their return interval distribution. The numerical results are displayed in Fig 2 as log-log plot for q=3 along with the theoretical distributions given in Eqns. 18 and 22. The agreement with the theoretical distribution is good and as expected gets better as $\gamma \to 1$. Similar good agreement is also obtained for the values of γ not shown here. The simulated results in Fig 2 does not cover a larger range in $\log R$ because of the large value of threshold q chosen corresponding to an average return interval of $\langle r \rangle = 743.0$. To over come this problem, we will need extremely large sequences of random time series. As we have argued in the previous section, the theoretical distribution can be expected to agree with the data when threshold q or equivalently the average return interval is large. Thus, as we reduce q below 2.5, there are deviations from the theoretical distribution which are systematically studied in the next section.

In Fig 3, we show the power law regime indicated by Eq. 20. In this figure, we focus on the region $R \ll 1$ where we expect the power law to appear. For each value of γ in Fig 3, we have drawn a straight line (shown in red) with the slope $(-1+\gamma)$. Quite clearly, the numerical data show a remarkably good agreement with the theoretical slope. As $\gamma \to 0$, the power law regime holds good in a larger range of R; for instance, see the case of $\gamma = 0.1$ and 0.3. On the other hand, as seen in the case of $\gamma = 0.7$, the power law region becomes shorter and stretched exponential regime begins to dominate as $\gamma \rightarrow 1$. This is an indication that the return interval distribution makes a transition from predominantly (stretched) exponential behavior to predominantly power law type curve as $\gamma \to 0$. It must be pointed out that the agreement with theoretically expected slope $(-1+\gamma)$ is reached only for $q \gg 1$. This is to be expected since the derived distributions in Eqns 18 and 22 do not take into account the correlations among the return intervals. In the next section, we study how the slope in the power law regime changes with threshold q in the numerically simulated long range correlated data.

IV. RETURN INTERVAL DISTRIBUTION AND THRESHOLD FOR EXTREME EVENTS

In this section, we will empirically examine the relation between the return interval distribution, especially in the power law regime, and the threshold q that define the extreme events. Intuitively, we can expect that if the threshold is higher, extreme events will be fewer and hence the return intervals will be longer. Thus, larger q leads to larger average return intervals. Here we address the question of how the return interval distributions in Eqns 18 and 22 are modified by changes in threshold value q. One clear indication is that, approximately for q < 2, the simulated return interval distributions devi-

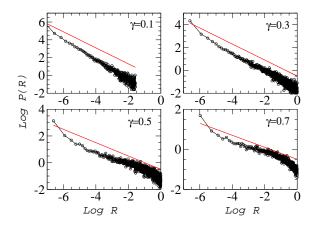


FIG. 3: (Color Online) The return interval distribution focused on the power law regime. The numerical distribution (circles) is nearly a straight line with the slope $(-1+\gamma)$. A straight line with slope $(-1+\gamma)$ is shown as solid (red) line for comparison. For all the cases, q>3.0 corresponding to $\langle r \rangle > 740.0$.

ate systematically from Eqns 18 and 22, in particular for R < 1. To study this, we plot the return interval distribution for the simulated data in a log-log plot as shown in Fig 2 and measure the slope in a linear region for R < 1 for various values of q. The result is displayed in Fig 4 for $\gamma = 0.1$. It is seen that as q increases, the initial part of the distribution, i.e, R < 1 or $\log R < 0$, is closer to being a straight line with slope $(-1 + \gamma)$. A similar behavior is seen for all the values of γ of our interest.

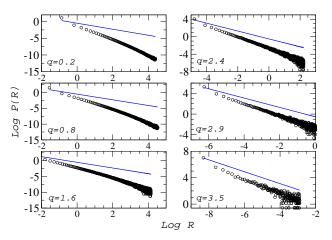


FIG. 4: (Color Online) The return interval distribution for the simulated data (circles) for $\gamma=0.1$ plotted for various values of threshold q. A straight line with slope $(-1+\gamma)$ is shown as solid (blue) line for comparison. Note that as q increases, the initial part of the distribution moves closer to a slope of $(-1+\gamma)$.

In order to see this variation of the slope of the initial part of the distribution with q, we plot in Fig 5(a) the measured slope $s_m(q)$ against the threshold q for various values of γ . The slope is measured in the linear region in log-log plot for $R \ll 1$. For a given value of $\gamma = \gamma_c$, the

slope increases monotonically to reach a saturation value of $(-1+\gamma_c)$ as $q\to\infty$. Once again we point out that this is in agreement with our expectation that the weakly correlated regime would agree with the distribution obtained in Eq. 18 and 22. For the Gaussian distributed data that we use, at q=3, the average return interval is $\langle r \rangle \approx 744.0$. Beyond q=3 with 2^{25} data points the number of returns intervals are not sufficient for reliable statistics. All this would imply that in order to take into account the effect of q, the power law proposed in Eq. 20 could be modified as

$$P(R) \propto R^{-(1-\gamma)\theta(q,\gamma)},$$
 (27)

with the restriction, suggested by the numerical results in Fig 5(a), that $\theta(q,\gamma) \to 1$ as $q \to \infty$. Clearly, the measured slope is simply given by $s_m = -(1 - \gamma)\theta(q, \gamma)$. Thus, we can directly visualize the function $\theta(q, \gamma)$ if we plot $s_m(q)/(\gamma-1)$ as a function of q. This is shown in Fig 5(b). As we anticipated, the function $\theta(q, \gamma)$ tends towards unity as $q \to \infty$. The autocorrelation exponent γ controls the rate at which the limiting value of unity is reached. We believe that the behavior displayed in Fig. 5(a,b) is related to a more fundamental question of how the auto-correlation exponent of a long range correlated time series changes if it is subjected to thresholding such as the one we have applied using Eq. 6. Obviously, every time we choose a subset of events from a larger set, such as the extreme events, implicitly such thresholding is applied. Since the power law regime varies with q and if the distribution has to remain normalized, then the stretched exponential part would also be modified. However, this might be difficult to visualize numerically. The central premise of this section is to show that Eqns 18 and 22 represent return interval distributions in the limit when the threshold or average return interval is large. We have shown through simulations the dependence of return interval distributions on threshold q. This explains why we have chosen q=3 to illustrate our result in Fig 2. Thus, in principle, the exact return interval distribution should depend on $\langle r \rangle$, especially for short return intervals, i.e, R < 1.

V. LONG RANGE PROBABILITY PROCESS

Apart from corrections arising due to dependence on q, the return interval distribution derived in this paper suffers due to approximation arising from assumptions of independence of return intervals. This assumption makes the analysis tractable but does not reflect the reality since we know that the intervals are indeed correlated. In this section, we argue that the deviations from the numerical simulations evident in Fig 2 can be attributed to the presence of correlations in the return interval data. We do this by simulating the probability process in Eq. 7 that forms the basis for the analytical result in Eqn 18 and 22. If the simulated data agrees with the analytical

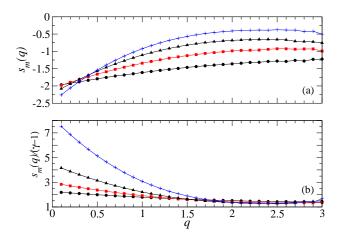


FIG. 5: (Color Online) (a) The measured slope s_m in the power law regime as a function of q for $\gamma=0.1$ (circles), 0.3 (squares), 0.5 (triangles) and 0.7 (plus). (b) The function $\theta(q,\gamma)=s_m/(\gamma-1)$ as a function of q for same values of γ as in (a).

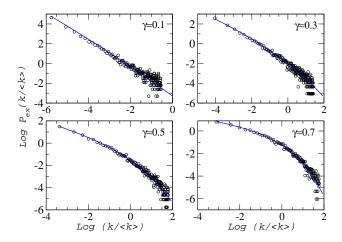


FIG. 6: (Color Online) The simulated return interval distribution (circles) from the probability process in Eq. 7 compared with the theoretical distribution (solid line) given in Eq 22.

result, then we could attribute the deviations seen in Fig 2 to the correlations present in the return intervals.

In order to numerically simulate the probability process in Eq. 7, we first determine the constant a by normalizing it in the region $k_{min} = 1$ and k_{max} . The normalized probability distribution corresponding to Eq. 7 is

$$P(k) = \frac{\gamma}{(k_{max}^{\gamma} - 1)} k^{-\gamma}, \qquad (28)$$

where k = 1, 2, 3.... We generate a random number ξ_k from a uniform distribution at every k and compare it with the value of P(k). A random number is accepted as an extreme event if $\xi_k < P(k)$ at any given value of k. If $\xi_k \ge P(k)$, then it is not an extreme event. By this procedure, we generate a series of extreme events following Eq. 7. We then compute the return intervals and its distribution after scaling it by the average return interval.

In Fig. 6, we show the return interval distribution obtained by simulating our probability process along with the distribution given by Eq 22. The agreement with the theoretical distribution is excellent, including for the values of γ not shown here. Hence, if the long range correlated data had independent return intervals, then we would have obtained nearly perfect agreement with Eq 18 and 22. This implies that the remaining disagreement between the theoretical and numerical results seen in Fig 2 can be attributed to the presence of correlations among the return intervals. On the other hand, if the probability process in Eq 7 was an incorrect assumption, it may not have been possible to obtain the results displayed in Fig 2.

VI. DISCUSSIONS AND CONCLUSIONS

We have studied the distribution of return intervals for the extreme events in long range correlated time series. An approximate analytical expression for this distribution has been obtained starting from the empirically established fact that returns intervals are long range correlated. This distribution is a product of a power law and a stretched exponential and explains the observed power law for short return intervals. For large return intervals, the distribution is dominated by a stretched exponential decay. The works reported earlier have empirically proposed stretched exponential form for the return interval distribution which is now shown to be valid in the domain of large return intervals. Further, we have also carefully studied the role played by the threshold q or equivalently the average return interval in the return time statistics. We show that it modifies the return interval distribution, especially in the power law regime of short return intervals. We believe that the results obtained in this paper explains most of the empirically observed features in the return time distributions of long range correlated time series. In the simulations reported in this work, we have used Gaussian distributed random numbers. As studied in Ref. [7], it is natural to ask if the exponential or power law distributed data would modify the results of this paper. We expect that the functional form of the distribution in Eq 22 would not be modified though the normalization constants A and B might change due to their dependence on the threshold q. The question of verifying the results of this paper with a measured time series is underway and would be reported elsewhere.

As pointed out before, the inter-event time distribution has applications across many disciplines. Hence, it appears in different settings in different areas. In the statistical literature, a related problem of zero crossings, i.e, the probability that X(t)>0 for $0\geq t\geq T$ has been considered. Under certain conditions, for a stationary Gaussian process, the upper bound for zero crossing probability is shown to be a stretched exponential [21]. This result does not strictly apply to the case of recurrence interval statistics because the zero crossing prob-

ability does not make statements about occurrence or non-occurance of another zero crossing after the interval T. A return interval, by definition, requires two crossings separated by an interval with no crossings. Finally, we would like to remark that the analytical distribution obtained in this paper appears to be related to the universal scaling form proposed recently [12] in the context of earth quakes but appears to be more generally valid. Thus it is likely that the exact return interval distribution might

incorporate corrections to the one obtained in this paper. Indeed, if the exact distribution is known, it will also become possible to determine the precise time scales over which power law and exponential decay operate. This, in turn, should help address questions of hazard estimation for extreme events more carefully and, needless to say, this has enormous interest in the insurance industry [2] and as a tool for decision support system [27].

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