

Using self-similarity and renormalization group to analyze time series

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Abstract

An algorithm based on Renormalization Group (RG) to analyze time series forecasting was proposed in cond-mat/0110285. In this paper we explicitly code and test it. We choose in particular some financial time series (stocks, indexes and commodities) with daily data and compute one step ahead forecasts. We then construct some indicators to evaluate performances. The algorithm is supposed to prescribe the future development of the time series by using the self-similarity property intrinsically present in RG approach. This property could be potentially very attractive for the purpose of building winning trading systems. We discuss some relevant points along this direction. Although current performances have to be improved the algorithm seems quite reactive to various combinations of input parameters and different past values sequences. This makes it a potentially good candidate to detect sharp market movements. We finally mention current drawbacks and sketch how to improve them.

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1 Introduction

Some years ago a novel approach based on Renormalization Group (RG) to analyze time series was proposed in [1]. An algorithm to make forecasts was outlined and some applications to financial markets were also examined in [2], [3].

The underlying idea of the algorithm is that the evolution of the market can be formulated by means of a group property with respect to an “effective” time, similarly to the evolution of a Hamiltonian with respect to its parameters in statistical renormalization group. Sharp structural changes in the market, like booms and crashes, should be then the equivalent of critical phenomena of a physical system (for reviews on renormalization group, phase transitions and critical phenomena see [4], [5], [6]).

In the present paper we explicitly test the algorithm proposed in [1] coding it in R language [7]. We choose in particular some financial time series with daily data and compute one step ahead forecasts (i.e. one day in this case). We then construct some indicators to make a performance evaluation of the algorithm. We also briefly outline some key points that one has to consider in order to use this or any other algorithm to develop a (possibly) winning trading system (the author is currently working on building automated trading systems).

We refer for the general philosophy of the approach and details to [1]. However, there is one important point we would like to underline and seems to the author particularly interesting to investigate. The algorithm deeply relies on the concept of *self-similarity* which is intrinsically present in the RG philosophy. RG represents indeed a functional generalization of usual (i.e. power) self-similar transformations. This symmetry is *not* a symmetry of the physical system but a symmetry of the solution considered as a function of the relevant physical variables (up to some specified boundary conditions). It is this symmetry which is supposed to provide the tool to detect the different “regimes” of the time series under consideration, in this case bullish or bearish market movements, trends, crashes and so on.

As a consequence there is an important difference between traditional forecasting models (like ARIMA, GARCH and similar) and the present one. In the former case one is instructed to compute the predicted value as a linear or more complicated function of past times series values including in general some kind of noise. In the latter case, on the other hand, RG self-similarity is not an attempt to discover a relation between historical points, but tries to discover dynamic trends resulting in these points. This methodology can be potentially very important in the case of financial time series.

The way in which self-similarity is used in this approach is also different from the way it is usually meant in connection with fractals: in that case, once a scaling relation is assumed, the function which describes the forecast is automatically computed; in the present case, on the other hand, one is referring to *group* self-similarity, therefore the equation which determines the function describing the forecast (27) has to be solved as we are going to see in Section 2.

The paper is organized as follows: in Section 2 we review the algorithm proposed in [1]. In Section 3 we recall the application of the algorithm to time series. We simply present the final formulas which we have coded to test the algorithm. In Section 4 we report the results of the computer runnings. We first explain the kind of tests we have carried out and the types of inputs and indicators we have used. We explicitly show then the results of the tests. We end the Section with a brief excursus on trading systems to give a taste to the reader of the plethora of factors to be kept into account, beyond the algorithm itself, to build winning trading system. In Section 5 we discuss a statistical approach which we are currently testing and should allow to weight in a consistent way the predictions of the algorithm. We end up in Section 6 with Outlooks and Conclusions.

2 Review of the algorithm

In this Section we review the main ideas and step underlying the algorithm and list the formulas which we have used to code it. We refer as said to [1] for a detailed and exhaustive discussion.

From a broad point of view the self-similar extrapolation used to make forecasts turns out to be at the end of the day an asymptotic expansion constructed out of past data. Let us review then briefly the various steps of the derivation, at a formal level first and then moving to the explicit example of time series.

Consider a function $f(x)$ and assume

$$f(x) \sim p_k(x) \text{ as } x \rightarrow 0 \tag{1}$$

The set of approximations $\{p_k(x)\}$ is meaningful and convergent only asymptotically as $x \rightarrow 0$. It diverges for *finite* x . One therefore is not allowed to write

$$p_{k+1}(x) = f(p_k(x)) \tag{2}$$

since the limit of $p_k(x)$ for $k \rightarrow \infty$ does not exist. Standard re-summation techniques, on the other hand, would require the knowledge of ten or more p_k . The self-similar approximation theory developed in [1] comes into help. The idea is to reorganize the sequence of approximations

$p_k(x)$ in such a way to have convergence at finite x . This is done using renormalization. Formally one renormalizes with the help of a transformation U the sequence of approximations $\{p_k(x)\}$ according to

$$U[p_k(x)] = \{F_k(x, s)\} \quad (3)$$

where s are the so called control functions $s = s_k(x)$. $\{F_k(x, s_k(x))\}$ is now convergent. One defines then an expansion function $x = x(\phi, s)$ such that

$$F_0(x, s) = \phi \implies x = x(\phi, s) \quad (4)$$

It follows that

$$y_k(\phi, s) = F_k(x(\phi, s), s) \implies F_k(x, s) = y_k(F_0(x, s), s) \quad (5)$$

Therefore $\{y_k(\phi, s)\}$ is in one to one correspondence with $\{F_k(x, s)\}$. The limit $f^*(x)$ of $F_k(x, s_k(x))$ as $k \rightarrow \infty$ exists now by construction and this is the sought function $f(x)$. Due to this 1-1 correspondence this limit represents a fixed point for the $\{y_k\}$ dynamics. In particular, near a fixed point, one can show that

$$y_{k+p} = y_k(y_p(\phi, s), s) \quad (6)$$

and this is nothing else than the self-similarity property. In continuous time one clearly has

$$y_k(\phi, s) = y(t = k, s, \phi) \quad (7)$$

By means of self-similarity one can easily prove that

$$\frac{\partial y(t, \phi, s)}{\partial t} = v(y(t, \phi, s)) \quad (8)$$

This corresponds to the well-known β -function describing the RG flow. Integrating

$$\int_{y_k}^{y_{k+1}^*} \frac{dy}{v(y)} = \tau \quad (9)$$

where $y_k = y_k(\phi)$ and $y_{k+1}^* = y_{k+1}^*(\phi, \tau)$. Using Euler discretization for the velocity one has

$$v_k(\phi, s) = y_k(\phi, s) - y_{k-1}(\phi, s) \quad (10)$$

Consider now a concrete application of the previous steps. Let

$$f(x) \sim f_k(x) = \sum_{n=0}^k a_n x^{\alpha_n} \quad (11)$$

as $x \rightarrow 0$. To get dimensionless units and scale invariance define then

$$\phi_k(x) = \frac{f_k(x)}{f_0(x)} = \sum_{n=0}^k b_n x_n^\beta \quad (12)$$

with $b_n = a_n/a_0$ and $\beta_n = \alpha_n - \alpha_0$. This expansion diverges for finite x . As explained before, apply then renormalization. It is convenient to choose the control functions using a power law transformation

$$\Phi_k(x, s) = x^s \phi_k(x) \quad (13)$$

It follows that

$$\Phi_k(x, s) = \sum_{n=0}^k b_n x^{s+\beta_n} \quad (14)$$

Now $\Phi_k(x, s)$ converges in $|x| < 1$ (as $s \rightarrow \infty$). Define then the expansion function ϕ

$$\Phi_0(x, s) = \phi \implies x = \phi^{1/s} \quad (15)$$

One easily finds

$$y_k(\phi, s) = \Phi_k(x(\phi, s), s) = \sum_{n=0}^k b_n \phi^{1+\frac{\beta_n}{s}} \quad (16)$$

The “effective time” τ_n to reach a fixed point after n steps is given by

$$\int_n^{n+\tau_n} dt = \int_{y_{n-1}}^{y_n^*} \frac{d\phi}{v_n(\phi, s)} \quad (17)$$

One can show in a straightforward way that

$$\Phi_n^* = \left(\Phi_{n-1}^{-\beta_n/s} - \frac{\beta_n}{s} b_n \tau_n \right)^{-s/\beta_n} \quad (18)$$

One then goes back to $\phi_k(x)$ using the inverse of (13). Consider for instance the first order self similar approximation

$$\phi_1^* = \lim_{s \rightarrow \infty} x^{-s} \Phi_1^*(x, s) = \exp(b_1 \tau_1 x_1^\beta) \quad (19)$$

Higher order approximations have been obtained in [1] by means of a “self-similar” bootstrap procedure. One gets at the end of the day

$$\phi_k^*(x) = \exp(c_1 x^{\nu_1} \exp(c_2 x^{\nu_2} \dots \exp(c_k x^{\nu_k})) \dots) \quad (20)$$

with

$$c_n = \frac{a_n}{a_{n-1}} \tau_n, \quad \nu_n = \alpha_n - \alpha_{n-1}, \quad (n = 1, 2, \dots, k) \quad (21)$$

Notice that the effective time τ_n which appears in the previous formulas has not been defined yet. It was determined in [1] by using a time-distance cost functional F

$$F = \sum_n \left(\left(\tau_n - \frac{1}{n} \right)^2 + (v_n \tau_n)^2 \right) \quad (22)$$

By minimizing it w.r.t. τ_n one has

$$\tau_n = \frac{1}{n(1 + v_n^2)} \quad (23)$$

In a previous version of the algorithm [2], the effective time was determined by a fixed point condition having the form of a minimal difference criterion. Such an equation, however, did *not* always have explicit solutions. We have checked this explicitly. We have also observed that the effective time is in general *smaller* than the real time separation between time series data.

3 Application to Time series

We finally come to the application of the algorithm to time series. Following again the notation of [1] one arranges time series in backward recursion, i.e. one assumes $t_{n+1} < t_n$ with $(n = 0, 1, 2, \dots, k)$ and the initial time $t_0 = 0$. The past history is then given by

$$D_k = \{f_k, f_{k-1}, \dots, f_0 \mid t_k < t_{k-1} < \dots < 0\} \quad (24)$$

In this case the sequence of approximations $f_k(t)$

$$f_k(t) = \sum_{n=0}^k a_n t^n \quad (a_0 = f_0) \quad (25)$$

is such that it interpolates the given past history (24)

$$f_k(t_n) = f_n, \quad (n = 0, 1, 2, \dots, k) \quad (26)$$

Using the same machinery discussed above one gets the final formula for the forecasts:

$$f_k^*(t) = f_0 \exp(c_1 t \exp(c_2 t \dots \exp(c_k t) \dots)) \quad (27)$$

with the controllers, the “effective” time and the “velocity” respectively given by

$$c_n(t) = \frac{a_n}{a_{n-1}} \tau_n(t) \quad (28)$$

$$\tau_n = \frac{1}{n[1 + v_n^2(t)]}, \quad v_n(t) = \frac{a_n t^n}{f_0}, \quad (n = 1, 2, \dots, k) \quad (29)$$

This super-exponential function gives the forecast for the future time interval $[0, 1]$ once the past history of k values is given as input and it is supposed to incorporate the mixture of different tendencies and regimes of the time series. This is the formula that we have used in coding the algorithm in R language.

4 Testing financial times series

4.1 Type of tests

The results of the tests only provide of course a limited case study, though we covered altogether almost five years of predictions.

First of all there is an almost infinite number of financial time series to be tested: one can study a stock, an index, a commodity or whatever for instance; in turn one can focus on stocks belonging to some specific sector; one can choose assets according to their correlation properties and so on. It depends of course on the targets one has. For instance, the choice could be motivated by some asset allocation procedure to construct a portfolio.

In addition, once the underlying has been chosen, one can study its time series depending on the time frames one wishes to focus on. Daily, monthly or annual data can be some possible

reasonable choices. One can also use tick data and so on. Again, depending on the targets, one is supposed to make the most convenient choice among a huge number of possibilities.

In addition, even when one has chosen the set of time series to analyze, the tests have to cover as much as possible all the “phase space” of available parameters and time intervals. A generic algorithm, for instance, can work well only in some specific conditions and/or periods. From this point of view we have tried to be quite exhaustive by exploring different choices of inputs.

Apart from considering a variety of financial time series, however, *the target of these tests was to explore, as a first step, if the algorithm is reactive and how to different input choices.* It turns out that it is and this is a positive sign.

We have therefore focused on daily data and computed one day ahead predictions (and also “intraday”, see below). We have studied three well known indexes: DAX, SP500 and VIX; one commodity, oil, and finally two stocks: UBS and CreditSuisse. Before examining the results let us explain the parameters and indicators which we have used in the tests.

Examine first the inputs. First of all the number of past time series values. We have followed the choice made in [2] and [3] namely 3, 4, 5 and 6 points. This number of points ranging from 3 to 6 corresponds to the value of k in the formula (27). Keeping in mind that each point basically adds an exponential in the formula (27) going beyond six points does not seem to make much sense. As we observe below in Section 5 and already proposed in [1], we have also considered the possibility to give as an input not only a different number k of past values, but also different past-history sequences. So we have taken into account the most obvious sequence of past values at times $t = (-1, -2, -3, -4, -5, -6)$ (SequenceA), the sequences $t = (0, -1, -2, -3, -5, -8, -13)$ (SequenceB-i.e. the Fibonacci series) and $t = (0, -2, -4, -6, -8, -10, -12)$ (SequenceC, i.e. evenly spaced values). Of course an infinite amount of choices is possible. Finally, for a one day prediction the time ahead is 1 (to be defined however as limit from the left according to the asymptotic expansion previously reviewed). We have also considered, however, the values 0.1, 0.3, 0.5, 0.7, i.e. which represents fractions of a day and therefore are to be considered “intraday” intervals. This is to test, once again, how reactive the algorithm is.

At the level of outputs we have constructed the following indicators: MAPE (i.e. the standard mean average percentage error) of the predicted values w.r.t to the real values. We have then computed the percentage number of cases in which APE (i.e. the absolute percentage error) between the predicted value and the real future value is less than the volatility of the future real value w.r.t the the previous past real value. We call this indicator OKAPE, more precisely the ok is when APE is less than this volatility . We have computed than another indicator which tells the percentage number of cases in which the predicted values agree with up/down movement of the real value: for instance if the real future value is bigger than the past real one, is it true that the predicted value as well is bigger than the past real one? We call this indicator %TrendOK, since it tells us if the prediction “gets the trend”. This can be important for instance if one has in mind to construct trading strategies. It *can be the case* indeed that it is more fundamental to predict the correct trend rather than having a small MAPE.

In the following tables we have considered the inputs and the outputs discussed above doing

at the same time an “ensemble average” (we return on this point in Section 5). More precisely: we have given as inputs the number of points, the sequences and the times ahead discussed above all varying within their respective ranges and performed then the same forecast using all the possible combinations of the inputs’ ranges, which amount to $4 * 3 * 5 = 60$, since we have used 4 training windows made of 3,4,5 or 6 points respectively, 3 sequences A,B,C of past points and 5 time ahead intervals (0.1,0.3,0.5,0.7,1). So each time we make a prediction we have produced actually 60 possible outcomes. The best one each time could be determined having a suitable “weight” acting on the space of predictions, as we will discuss in Section 5. As a first step, may be too crude but just to get an overall performance evaluation, we fix one of the three inputs and simply take the average of the other two. For instance, if the number of input points k is equal to 3, we take the 15 predictions and compute their average.(15 since once k is fixed we do not have any more $4 * 3 * 5 = 60$ possibilities, but only $3 * 5 = 15$ remain). Same story with for the other parameters. The tables below are constructed according to this scheme. For instance, in the generic row SequenceA we will report the indicators that have been obtained once SequenceA is fixed, while k and the times ahead are free to change. In this case each prediction will be the average of $3 * 5 = 15$ predictions and the average indicators MAPE, OKAPE and % TrendOK will be constructed out of these predictions; therefore they will be an average of an ensemble of averaged predictions. Let us move to the discussion of the specific cases.

4.2 Results

Consider the case study of the SP500 index ². We have done a test which covers the whole 2007. Here are the results.

k	MAPE	OKAPE	% TrendOK
3	1.112	28.6	45.9
4	1.203	28.6	48.5
5	1.29	27.3	51.1
6	1.351	27	52.4
Sequence	MAPE	OKAPE	% TrendOK
A	1.07	33.3	51.2
B	1.239	27.9	49.2
C	1.408	22.3	48.1
Time.ahead	MAPE	OKAPE	% TrendOK
0.1	1.209	28.4	49.9
0.3	1.215	28.4	50.3
0.5	1.247	27.7	49.4
0.7	1.263	27.5	49.1
1	1.261	27.3	48.8

MAPE is normally quite low (around 1 %) but the percentage number of cases in which it is smaller than the volatility (OKAPE) is quite low in all cases. Nevertheless, the percentage number of cases in which the correct trend is captured(% TrendOK) is above 50% in some cases.

Consider now DAX index ³ this time on a much shorter period, namely October 2007. The

²SP500 is an index containing the stocks of 500 large-cap corporations, most of which are American.

³DAX is a Blue Chip stock market index consisting of the 30 major German companies trading on the Frankfurt Stock Exchange.

results are

k	MAPE	OKAPE	% TrendOK
3	0.819	21.8	37.6
4	0.933	24	43
5	1.061	24.5	43.6
6	1.159	20.9	37.9
Sequence	MAPE	OKAPE	% TrendOK
A	0.937	19.5	30.7
B	0.986	18.9	36.4
C	1.055	30	54.5
Time.ahead	MAPE	OKAPE	% TrendOK
0.1	1.002	22.3	39.8
0.3	0.979	23.5	40.1
0.5	1.006	23.5	40.5
0.7	0.986	22.7	40.9
1	0.993	22	41.3

MAPE is normally below one percent, but the other two indicators do not display positive results. Consider now VIX index ⁴. The test has been performed on the whole 2007. The results are

k	MAPE	OKAPE	% TrendOK
3	9.614	33.5	50.2
4	10.141	34.1	52.3
5	10.073	34.5	53.7
6	10.057	35.9	54
Sequence	MAPE	OKAPE	% TrendOK
A	8.882	37	52.5
B	9.867	34.7	51.5
C	11.165	31.8	53.7
Time.ahead	MAPE	OKAPE	% TrendOK
0.1	9.54	35.9	53.8
0.3	9.595	35.4	53.3
0.5	9.896	34.8	52.7
0.7	10.351	33.7	51.9
1	10.475	32.6	51.2

Both MAPE and OKAPE are not particularly good. Note, however, that the % TrendOK indicator is always above 50%. In one case even 54%. This is a clear example in which despite the fact MAPE is quite big, the prediction gets the right trend more then half of the times.

Consider now a commodity, namely oil. The tests have been carried out for the whole 2007. Here are the results

⁴VIX is the ticker symbol for the Chicago Board Options Exchange Volatility Index, a popular measure of the implied volatility of SP500 index options. It can be thought as a sort of thermometer of the market's expectation of volatility.

k	MAPE	OKAPE	%TrendOK
3	2.457	34.4	51.1
4	2.677	30.6	50.1
5	2.978	29	50.7
6	3.278	26.3	48.8
Sequence	MAPE	OKAPE	%TrendOK
A	2.511	33.1	51.1
B	2.844	31.3	51.2
C	3.187	25.7	48.2
Time.ahead	MAPE	OKAPE	%TrendOK
0.1	2.854	29.8	50
0.3	2.856	29.6	50
0.5	2.86	29.9	50.3
0.7	2.842	30.3	50.5
1	2.826	30.6	50.1

Again MAPE and OK APE are not quite satisfactory, but the trend indicator seems to give promising results. We finally move than to stocks: we consider UBS and Credit Suisse for the period from 14 Jan to 29 Feb 2008, in which both stocks experienced quite dramatic draw-downs. A challenging test for the algorithm then. In the case of UBS one has

k	MAPE	OKAPE	% TrendOK
3	4.706	30.5	48.8
4	5.98	25.3	43.6
5	7.385	18.1	41.7
6	8.138	18.3	43.8
Sequence	MAPE	OKAPE	% TrendOK
A	5.248	23.4	40.7
B	7.585	15.7	36.7
C	6.824	30	56
Time.ahead	MAPE	OKAPE	% TrendOK
0.1	6.761	22.1	43.1
0.3	6.735	22.4	44.1
0.5	6.59	22.6	44.8
0.7	6.346	24	45
1	6.329	24.1	45.5

while for the case of Credit Suisse

k	MAPE	OKAPE	%TrendOK
3	3.647	35.2	51.7
4	4.684	28.7	56
5	5.566	24.4	52.1
6	6.409	15.7	46.7
Sequence	MAPE	OKAPE	%TrendOK
A	4.047	27.6	50.3
B	5.805	21.7	44.7
C	5.377	28.8	59.9
Time.ahead	MAPE	OKAPE	%TrendOK
0.1	5.37	25.2	52.3
0.3	5.287	25.5	52.5
0.5	5.214	25.3	51.3
0.7	4.92	25.8	50.8
1	4.59	28.3	51.3

Notice MAPE and OKEAPE are more or less similar; actually the two time series are quite correlated, so this fact does not sound so unreasonable. In the case of CreditSuisse, however, the algorithm is much more successful in getting the trend, up to 59.9% in one case!.

Altogether the results are not yet completely satisfactory. In the next Section we will sketch the steps to improve them. The algorithm, however, is very “reactive” according to the different types of inputs. The back tests above, *have been carried out using a “rolling forward” training modality*, i.e. the past history of k-points is rolled forward as soon as one moves ahead to compute the predictions. *At each prediction, therefore, the algorithm makes the prediction according to a rolling forward training window and the mixture of exponential reacts each time to capture the time series tendencies.*

We have also used a standard optimization procedure to see if there are “magic combinations” or some preferred parameters. The results are shown in the table below where the entries express the percentage number of times in which the corresponding row parameter best performed.

Parameter	SP500	DAX	VIX	OIL	UBS	CS
k=3	36.2	45.5	35.6	36.1	40	45.5
k=4	21.9	22.7	16	21.3	31.4	27.3
k=5	21	22.7	20	19.7	11.4	15.2
k=6	21	9.1	28.4	22.9	17.1	12.1
SeqA	35.7	18.2	33.2	33.7	28.6	33.3
SeqB	17.6	40.9	16.4	20.1	22.9	30.3
SeqC	46.7	40.9	50.4	46.2	48.6	36.4
Time.ahead.0.1.	56.7	27.3	64	55.4	51.4	30.3
Time.ahead.0.3.	5.7	4.5	2	3.2	5.7	3
Time.ahead.0.5.	4.8	9.1	5.6	5.6	5.7	3
Time.ahead.0.7.	7.6	4.5	6.4	7.2	14.3	21.2
Time.ahead.1	25.2	54.5	22	28.5	22.9	42.4

One can notice that the best results would have been obtained using in all cases k equal to three as far as the number of training points concerns. This seems to be in agreement with the

general philosophy of RG flows: collective coherent behavior should require only a few renormalization steps to get convergence much like the case of phase transitions. The most intuitive sequence A i.e. past values at times $t = 0, -1, -2, \dots, -6$ is not the best one.

4.3 Intermezzo: trading systems and trading performance reports

In the next Section we discuss possible improvements of the performances of the algorithm. Before moving to these aspects, we briefly recall some essential points concerning trading systems. The algorithm has been applied to financial time series but of course, apart from the outputs and relative error between real future data and predicted values, the essential point in this context is what to do with the forecasts and which strategy one is supposed to implement.

A considerable number of factors has indeed to be taken into account and according to them one can establish if the prediction is “good” or “bad”. Many of these points are actually not commonly discussed in the mathematical finance literature (see for instance [8], [9]), but they do play a fundamental role. We mention just a few of them to give a taste to the reader.

Commissions costs and slippages for instance. It can be that an algorithm detects the right patterns and is able to predict them in the future. However, the potential gain can be eaten by commissions and slippage costs. Consider then time frames: for example intraday or daily. One algorithm could give good daily predictions and be suitable for daily trading then but not for intraday trading. Another point: although one algorithm could give not quite satisfactory results, still, however, in suitable diversified portfolio, the net profit could be positive. And so on.

There are then certain indicators which appear in almost all trading strategy performance reports which are of fundamental importance: total net profit, number of winning/losing trades, largest winning/losing trade, average winning/losing trade, max drawdown, max consecutive winners/losers and so on. Again many factors can influence these final indicators and the forecasting algorithm is only one of them.

This is of course an extremely! brief and not exhausting discussion of trading systems but suffices to show that many factors apart from the predictive algorithm have to be taken into account. Therefore, even if the algorithm performed extremely well, it would not be obvious that one would be able to build a winning strategy. On the other hand, even if the results of the algorithm do not seem good enough, may be, if they combined with other tools, they can lead to a winning trading system. For instance: in all cases in which the indicator %TrendsOK constructed before is above 50%, although MAPE is high, it could be a good starting point to construct a winning strategy. For more details on trading systems we refer the interested reader to [10], [11], [12], [13].

5 Improving performances: a statistical mechanics of possible scenarios

The results we have shown in the previous Section have to be improved. One natural way would be to define an averaged forecast weighted by some suitable probabilities. In a way, it amounts

to do statistical mechanics with a partition function and a probability measure.

In a sense the scheme used to produce the tables shown before already goes along this direction: we do not compute a single prediction each time, but an ensemble of predictions according to the possible different combinations of the inputs, which turn out to be 60 in our case. We have made then a performance evaluation analysis simply taking the averages: once we fix one of the three inputs (k or Sequence or Times ahead) we consider all the forecasts obtained by letting the other two change and take an average. This is a too crude way of weighting however and it is not able to pick out the best combinations.

Indeed let us reconsider the previous tests. This time, however, we consider the $4*3*5 = 60$ possible combinations of the inputs without fixing any of them and averaging over the other two as we did before. Take DAX as an example. We show here only some of the most significant combinations

k	Sequence	Time.ahead	MAPE	OKAPE	%trendOK
3	3	0.1	0.701	27.3	54.5
3	3	0.3	0.674	36.4	54.5
3	3	0.5	0.786	36.4	59.1
3	3	0.7	0.761	31.8	54.5
3	3	1	0.686	31.8	54.5
4	3	0.1	0.963	36.4	63.6
4	3	0.3	0.914	36.4	63.6
4	3	0.5	0.834	36.4	63.6
4	3	0.7	0.777	36.4	68.2
4	3	1	0.873	36.4	68.2
5	3	0.1	1.099	31.8	54.5
5	3	0.3	1.052	31.8	54.5
5	3	0.5	1.229	31.8	54.5
5	3	0.7	1.187	31.8	59.1
5	3	1	1.179	27.3	54.5

As one can notice for $k = 4$ there are some combinations which capture the trend more than 60 % of the times and this is a very positive outcome. The same is true for the other underlings. Consider for instance UBS. Here is a list of good combinations which correctly get the trends

k	Sequence	Time.ahead	MAPE	OKAPE	% TrendOK
4	3	0.1	5.482	34.3	62.9
4	3	0.3	5.831	34.3	62.9
4	3	0.5	5.88	34.3	57.1
4	3	0.7	6.176	37.1	57.1
5	3	0.3	7.586	28.6	62.9
5	3	0.5	7.071	28.6	62.9
5	3	0.7	6.958	25.7	57.1
5	3	1	7.615	22.9	57.1

A similar story holds for the other assets. The natural question is then how to pick up the best forecast out the different ones obtained with different inputs. In other words one should find a way to compute weights which are able to pick up the best predictions. This is currently under investigation. The general philosophy, however, was already outlined in Section 4 of [1].

In a nutshell, the past history has to take into account not only the number of past points k but also different time scales. To fix ideas define the past data base as ensemble of possible scenarios

$$D_k(j) = (f_k^{(j)}, f_{k-1}^{(j)}, \dots, f_0 \mid t_k^{(j)} < t_{k-1}^{(j)} < \dots < 0) \quad (30)$$

where k stands as usual for the number of past points, while j specifies the chosen time sequence for the past (The analogue of the choice of Sequences A,B,C in the tests we have done). One however has to define a probability weight $p_k(j, t)$, which will be able to select the best forecast out of the combinations of the (k, j, t) values chosen. Notice that this is just a more compact form to express the same choice of inputs we have used in our tests.

One proposal could be the following

$$p_k(j, t) = \frac{1}{Z_k(t)} \exp(-\Delta S_k(j, t)) \quad Z_k(t) = \sum_j \exp(-\Delta S_k(j, t)) \quad (31)$$

where

$$\Delta S_k(j, t) = S_k(j, t) - S_1(j, t), \quad S_k(j, t) = \ln |\delta f_k^*(j, t)| \quad (32)$$

with $S_k(j, t)$ representing a dynamical entropy. Define then a bunch of multipliers $m_k(j, t)$ as follows

$$\Delta S_k(j, t) = \ln |m_k(j, t)| \quad (33)$$

and an average multiplier $\bar{m}_k(t)$

$$\frac{1}{\bar{m}_k(t)} = \sum_j \frac{1}{|m_k(j, t)|} \quad (34)$$

One can easily show that

$$p_k(j, t) = \left| \frac{\bar{m}_k(t)}{m_k(j, t)} \right| \quad (35)$$

The most probable scenario is given by

$$\max_j p(j, t) \quad (36)$$

The forecast will be then a weighted sum of the different forecasts

$$\langle f(t) \rangle = \sum_j \sum_k p_k(j, t) f_k^*(j, t) \quad (37)$$

with t as usual in the interval $[0, 1]$.

6 Outlooks and Conclusions

We have tested the algorithm on different financial time series. The results can certainly be improved and in the previous Section we have outlined a possible path, which should give the right way to weight different forecasts obtained using different inputs.

There are however other points which are currently under investigation and which could improve the algorithm; we list them briefly:

- In order to determine the effective time τ one has to minimize the cost function (22). The choice made in [1] seems reasonable, but other choices are of course possible as well and this could improve the performances of the algorithm.

- One can of course give as an input to the algorithm not the time series itself, but some sequence obtained by transforming the original time series. The log of the original time series or the differenced time series for instance are standard transformations which could be worth checking.

- Filter the original time series before making the forecasts. One could use wavelets and apply multiresolution analysis to decompose according to different time scales (The R package `waveslim` provides all the necessary functions to investigate this point).

- Considering external variables could be also a very promising path to explore. The external force, however, as recalled in [2], has to be not too strong, otherwise it could break self-similarity properties. In the opinion of the author it is however quite tough to measure in a quantitative way the strength of the external forces so it is definitively worth trying to add external or even categorical variables to the model.

- The number of points given as input in our tests ranges between 3 and 6. Of course one could use more, but then the final formula (27) would contain too many exponentials. Of course one may object that a training window with a maximum number of 6 points is not enough to learn the past history: think for instance about neural networks which need quite massive training sets to learn and become then predictive. It depends however on the targets one has. From the author's point of view, the main interest to investigate this algorithm, apart from the conceptual one of extending applications of the RG, is to find out if it is quite reactive enough to detect trends, possibly without too much delay. From this perspective a maximum number of six training points perhaps is not too low.

All these issues are currently under investigation.

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