

1+1 Gaudin Model

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Abstract

We study 1+1 field-generalizations of the rational and elliptic Gaudin models. For $\mathfrak{sl}(N)$ case we introduce equations of motion and L-A pair with spectral parameter on the Riemann sphere and elliptic curve. In $\mathfrak{sl}(2)$ case we study the equations in details and find the corresponding Hamiltonian densities. The n -site model describes n interacting Landau-Lifshitz models of magnets. The interaction depends on position of the sites (marked points on the curve). We also analyze the 2-site case in its own right and describe its relation to the principle chiral model. We emphasize that 1+1 version impose a restriction on a choice of flows on the level of the corresponding 0+1 classical mechanics.

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1 Introduction

Gaudin model (or Gaudin magnet) was introduced by M. Gaudin [1] as a quasiclassical limit of spin-1/2 chain and was studied via the Bethe ansatz [2, 3]. Let us start with a general rational model underlying Gaudin magnets. The classical rational Gaudin model is defined by the following quadratic Hamiltonians:

$$H_a = -\frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{z_a - z_c}, \quad a = 1 \dots n, \quad (1.1)$$

where $S^a \in \mathfrak{sl}(2, \mathbb{C})$, $\{z_1, \dots, z_n\} \in \mathbb{CP}^1$ - marked points and $\langle \ \rangle$ denotes the trace.

From the point of view of the Lax pair the model is described by a general Lax matrix which is a $\mathfrak{sl}(N, \mathbb{C})$ -valued function $L(z)$ on $\mathbb{CP}^1 \setminus \{z_1, \dots, z_n\}$ with simple poles at $\{z_1, \dots, z_n\}$ and some given residues $\text{Res}_{z_a} L(z) = S^a \in \mathfrak{sl}(N, \mathbb{C})$:

$$L(z) = \sum_{a=1}^n \frac{S^a}{z - z_a}. \quad (1.2)$$

The generating function of the Hamiltonians is

$$\frac{1}{2} \langle L^2(z) \rangle = \frac{1}{2} \sum_{a=1}^n \frac{\langle (S^a)^2 \rangle}{(z - z_a)^2} + \sum_{a \neq b} \frac{1}{z - z_a} \frac{\langle S^a S^b \rangle}{z_a - z_b}. \quad (1.3)$$

The first sum in (1.3) shows that the eigenvalues λ_a of S^a are the constant \mathbb{C} -numbers. Thus, the phase space is a direct product¹ of the coadjoint orbits by $\text{SL}(N, \mathbb{C})$ action: $M = \mathcal{O}^1 \times \dots \times \mathcal{O}^n$. This phase space is naturally equipped with a linear Poisson-Lie structure:

$$\{S_\alpha^a, S_\beta^b\} = \delta^{ab} \sum_{\gamma} C_{\alpha\beta}^\gamma S_\gamma^a, \quad (1.4)$$

where S_α^a are coefficients in some basis $\{T_\alpha\}$: $S^a = \sum_{\alpha} S_\alpha^a T_\alpha$ and $C_{\alpha\beta}^\gamma$ are the structure constants of $\mathfrak{sl}(N, \mathbb{C})$ in this basis. The natural basis is described in the Appendix. The Hamiltonians (1.1) in $\mathfrak{sl}(N, \mathbb{C})$ case are replaced by

$$H_a = -\frac{1}{N} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{z_a - z_c}, \quad a = 1 \dots n, \quad (1.5)$$

The dynamics with respect to the Hamiltonians (1.5) is given by the following equations²:

$$\begin{cases} \partial_{t_a} S^a = \{H_a, S^a\} = - \sum_{c \neq a} \frac{[S^a, S^c]}{z_a - z_c}, \\ \partial_{t_a} S^b = \{H_a, S^b\} = \frac{[S^a, S^b]}{z_a - z_b}, \quad \text{for } a \neq b. \end{cases} \quad (1.6)$$

These equations of motion can be represented in the Lax form

¹In fact, there is coadjoint action of $\text{SL}(N, \mathbb{C})$ on M which provides the constraint $\sum_a S^a = 0$ with some fixation of $\text{SL}(N, \mathbb{C})$ action. Then one can make a reduction $M \rightarrow M // \text{SL}(N, \mathbb{C})$. But we do not go into details of this reduction here. In [17, 19] the examples of the reduction for the Painlevé VI equation are discussed. The r -matrix of the reduced models satisfies the reflection equations. Thus, the models live on the boundaries of the finite lattices.

²Here we imply some choice of the normalization by the Killing form $\langle \ \rangle$, see also (B.6)

$$\partial_{t_a} L = [L, M_a] \quad (1.7)$$

with the Lax pair

$$\begin{aligned} L(z) &= \sum_{c=1}^n \frac{S^c}{z-z_c}, \\ M_a(z) &= \frac{S^a}{z-z_a}. \end{aligned} \quad (1.8)$$

In such a generality the model was studied many times. For example, the non-autonomous version corresponds to the Schlesinger system of the isomonodromic deformations on a sphere. It was studied a hundred years ago [4].

In the elliptic case [5] the Lax matrix (1.2) is replaced by

$$L(z) = \sum_{a=1}^n \sum_{\alpha} S_{\alpha}^a \varphi_{\alpha}(z - z_a) T_{\alpha}, \quad (1.9)$$

where $z \in \Sigma_{\tau}$ is a coordinate on an elliptic curve Σ_{τ} with moduli τ . Basis $\{T_{\alpha}\}$ and the corresponding Poisson structure is defined in the Appendix (B.4). Functions $\varphi_{\alpha}(z - z_a)$ (B.13) form a basis in $\Gamma(\text{End}V, \Sigma_{\tau})$ with a simple pole at z_a for some fixed holomorphic vector bundle V of degree one. The Poisson structure (1.4) for the structure constants (B.7) is related to the existence of the r -matrix of the Belavin-Drinfeld type [6]. The quadratic Poisson structure can be defined by the same r -matrix [7].

Most of problems natural for integrable systems have been studied for the Gaudin model as well. Among them the separation of variables [8], relations to monodromy preserving and Knizhnik-Zamolodchikov equations [9], quantum quadratic algebras and bihamiltonian structures [10], quantization [11] and Langlands duality [12]. It should be mentioned that the elliptic Gaudin model was originally defined by B.Enriquez and V.Rubtsov [13] as an example of the Hitchin-type system [15]. "Dynamical" case was considered first by A.Gorsky and N.Nekrasov [14]. That case corresponded to degree zero vector bundle V (that is to nontrivial moduli space of bundles) or to the "spin" extensions of the Calogero model. In [24] it was shown that the top-like models and Calogero-type models are related by means of the modification procedure (the later changes the degree of V). In this sense the models are equivalent.

Consideration of particular cases and different types of reductions leads to relations between Gaudin model and a number of known integrable systems such as interacting tops [16], Painlevé VI equation and Zhukovsky-Volterra gyrostat [17], Neumann system [18].

With the advent of the Inverse Scattering Method the Lax equations or the zero-curvature equations [20] (with spectral parameter) became a main tool for investigation of nonlinear equations [21, 22]. Different applications and classifications can be found in [23]. In this paper we are predominantly interested in the Landau-Lifshitz equation [26] (which describes the continuous limit of the XYZ model [27, 28]) and the principle chiral model [29, 30].

In [24] a general scheme was suggested for constructing $1 + 1$ (or field) generalizations of the Gaudin-type models as typical examples of the Hitchin systems. As a by-product of this work the field generalization of the elliptic Calogero model was obtained³ and its equivalence to the Landau-Lifshitz equation was shown in terms of the special singular gauge transformations.

The purpose of the paper is to present explicit L-A pairs for $1 + 1$ Gaudin model, to propose corresponding Hamiltonian description and to find out relationships between the obtained equations and some known models such as the Heisenberg Model, the Landau-Lifshitz Equation and the Principle Chiral Model. The results of the paper can be briefly summarized as follows:

³This result was first obtained by I.Krichever in [25].

<u>(0+1) Mechanics:</u>	<u>(1+1) Field Version:</u>	<u>Type of Models:</u>	
Gaudin flows $\{H_a\}$	1 st flows $\{\mathcal{H}_{a,1}\}$	n-site Generalization of Principle Chiral Model	(1.10)
Gaudin flows $\{\tilde{H}_a\}$ ("Reformulated version")	2 nd flows $\{\mathcal{H}_{a,2}\}$	Interacting Models of Landau-Lifshitz type	

The first flows are described by the following equations:

$$\begin{cases} \partial_{t_a} S^a - k \partial_x S^a = - \sum_{c \neq a} [S^a, \hat{\varphi}_{ac}(S^c)], \\ \partial_{t_a} S^b = [S^b, \hat{\varphi}_{ba}(S^a)]. \end{cases} \quad (1.11)$$

In "2-site" case and rational limit these are the equations of the Principle Chiral Model:

$$\begin{cases} \partial_t l_1 - k \partial_x l_0 + \frac{2}{z_1 - z_2} [l_1, l_0] = 0, \\ \partial_t l_0 - k \partial_x l_1 = 0 \end{cases} \quad (1.12)$$

with $l_0 = S^1 + S^2$ and $l_1 = S^1 - S^2$.

The equations for the second flows are of the form (here we put $\mathfrak{sl}(2, \mathbb{C})$ case and $\mathfrak{sl}(N, \mathbb{C})$ is considered below):

$$\begin{cases} \partial_{t_a} S^a - k \partial_x \eta^a = [S^a, \hat{\varphi}(S^a)] + \sum_{c \neq a} [\eta^a, \hat{\varphi}_{ca}(S^c)] - [\hat{F}_{ca}(S^c), S^a], \\ \partial_{t_a} S^b = [\hat{\varphi}_{ab}(\eta^a), S^b] + [S^b, \hat{F}_{ba}(S^a)], \end{cases} \quad (1.13)$$

where $\eta^a = -\frac{k}{4\lambda^2} [S^a, S_x^a] + \sum_{c \neq a} \hat{\varphi}_{ac}(S^c)$. Note that in "1-site" case $n = 1$ the first one equation in (1.13) is the Landau-Lifshitz equation (for $t_1 = t$):

$$\partial_t S + \frac{k^2}{4\lambda^2} [S, S_{xx}] = [S, \hat{\varphi}(S)] \quad (1.14)$$

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2 $\mathfrak{sl}(N, \mathbb{C})$ Elliptic Gaudin Model

2.1 Standard Description

The phase space of the Gaudin model is a direct product of orbits $\mathcal{O}_1 \times \dots \times \mathcal{O}_n$ by the coadjoint action of $\mathrm{SL}(N, \mathbb{C})$). The coordinates $\{S_\alpha^c\}$ on each orbit $S^c \in \mathcal{O}_c$ are chosen to be dual to the basis $\{T_\alpha\}$ of the Lie algebra $\mathfrak{sl}(N, \mathbb{C})$. The later basis $\{T_\alpha\}$ is built as the projective representation of $(\mathbb{Z}/N\mathbb{Z} \oplus \mathbb{Z}/N\mathbb{Z})$ in $\mathrm{GL}(N, \mathbb{C})$ (see (B.4)). The corresponding structure constants (B.7) provides the Poisson-Lie brackets:

$$\{S_\alpha^a, S_\beta^b\} = \delta^{ab} c_{\alpha,\beta} S_{\alpha+\beta}. \quad (2.1)$$

Let us introduce now the Lax matrix defined on the elliptic curve $\Sigma_\tau = \mathbb{C}/(\mathbb{Z} + \tau\mathbb{Z})$ with modular parameter τ ($\Im m(\tau) > 0$):

$$L(z) = \sum_{c=1}^n \sum_{\alpha \in \Gamma'} S_\alpha^c T_\alpha \varphi_\alpha(z - z_c), \quad (2.2)$$

where $\Gamma'_N = \tilde{\mathbb{Z}}_N^{(2)}$ (see (B.3)) and functions $\{\varphi_\alpha(z - z_c)\}$ form the basis in the space of sections $\Gamma(\text{End}V, \Sigma_\tau)$ with simple poles at $\{z_c\}$, $c = 1 \dots n$ for the holomorphic vector bundle V of degree one associated with the principle $\text{GL}(N, \mathbb{C})$ -bundle over Σ_τ . In fact the Lax matrix is fixed by the quasiperiodic properties with (B.1-B.2):

$$L(z+1) = QL(z)Q^{-1}, \quad L(z+\tau) = \Lambda L(z)\Lambda^{-1} \quad (2.3)$$

and residues $\text{Res}_{z_a} L(z) = S^a$.

The invariants of the Lax matrix generate commuting Hamiltonians

$$\frac{1}{2N} \langle L^2(z) \rangle = \sum_{c=1}^n (H_{2,c} \wp(z - z_c) - H_{1,c} E_1(z - z_c)) - H_0, \quad (2.4)$$

where $H_{2,c} = \frac{1}{2N} \langle (S^c)^2 \rangle = \frac{1}{2} \sum_{\alpha \in \Gamma'_N} S_\alpha^c S_{-\alpha}^c$ are the Casimir functions corresponding to the orbits \mathcal{O}_c and the Hamiltonians are:

$$H_{1,a} = -\frac{1}{N} \sum_{c \neq a} \langle S^a \hat{\varphi}_{ac}(S^c) \rangle = -\sum_{c \neq a} \sum_{\alpha \in \Gamma'_N} S_{-\alpha}^a S_\alpha^c \varphi_\alpha(z_a - z_c) \quad (2.5)$$

$$H_0 = \frac{1}{2N} \sum_c \langle S^c \hat{\wp}(S^c) \rangle - \frac{1}{2N} \sum_{b \neq c} \langle S^b \hat{f}_{bc}(S^c) \rangle = \quad (2.6)$$

$$\frac{1}{2} \sum_c \sum_{\alpha \in \Gamma'_N} S_{-\alpha}^c S_\alpha^c \wp(\omega_\alpha) - \frac{1}{2} \sum_{b \neq c} \sum_{\alpha \in \Gamma'_N} S_{-\alpha}^b S_\alpha^c f_\alpha(z_b - z_c),$$

where we use the following notations: $\wp(\omega_\gamma)$ is defined in (B.11), functions $\varphi_\gamma(z)$ and $f_\gamma(z)$ - in (B.13-B.14). We also define the linear operators:

$$\hat{\wp} : S_\alpha \rightarrow S_\alpha \wp(\omega_\alpha), \quad \hat{\varphi}_{ab} : S_\alpha \rightarrow S_\alpha \varphi_\alpha(z_a - z_b), \quad \hat{f}_{ab} : S_\alpha \rightarrow S_\alpha f_\alpha(z_a - z_b) \quad (2.7)$$

In the following we also use $\hat{E}_1 : S_\alpha \rightarrow S_\alpha E_1(\omega_\alpha)$. Note that

$$\hat{\varphi}_{ab}^* = -\hat{\varphi}_{ba} \quad (2.8)$$

in the sense that $\langle S^a \hat{\varphi}_{ab}(S^b) \rangle = -\langle S^b \hat{\varphi}_{ba}(S^a) \rangle$ due to (A.10). Similarly, $\hat{f}_{ab}^* = \hat{f}_{ba}$, $\hat{\wp}^* = \hat{\wp}$ and $\hat{E}_1^* = -\hat{E}_1$.

⁴Note that we use both the Eisenstein and the Weierstrass functions. They are simply related (A.7-A.8).

The commutativity of the Hamiltonians with respect to (2.1) follows from the underlying linear r-matrix structure of the Belavin-Drinfeld type: $r_{12}^{BD}(z, w) = \sum_{\alpha \in \Gamma'} \varphi_\alpha(z-w) T_\alpha \otimes T_{-\alpha}$ [6].

Note also that the Hamiltonians $H_{1,a}$ are not independent:

$$\sum_{a=1}^n H_{1,a} = -\frac{1}{N} \sum_{a=1}^n \sum_{c \neq a} \langle S^a \hat{\varphi}_{ac}(S^c) \rangle \stackrel{(2.8)}{=} 0 \quad (2.9)$$

The appropriate number of independent Hamiltonians is achieved by taking into account H_0 and all higher Hamiltonians.

Let us write down equations of motion with respect to the Hamiltonians (2.5-2.6):

$$\partial_{t_a} S^a = \{H_{1,a}, S^a\} = - \sum_{c \neq a} [S^a, \hat{\varphi}_{ac}(S^c)] \quad (2.10)$$

$$\partial_{t_a} S^b = \{H_{1,a}, S^b\} = [S^b, \hat{\varphi}_{ba}(S^a)] \quad (2.11)$$

$$\partial_{t_0} S^a = \{H_0, S^a\} = [S^a, \hat{\varphi}(S^a)] - \sum_{c \neq a} [S^a, \hat{f}_{ac}(S^c)] \quad (2.12)$$

Proposition 2.1 *The equations of motion (2.10-2.12) can be presented in the Lax form (1.7) with the Lax matrix $L(z)$ defined in (2.2) and M-matrices given as follows:*

$$M_a = \sum_{\alpha \in \Gamma'_N} S_\alpha^a T_\alpha \varphi_\alpha(z - z_a) \quad (2.13)$$

$$M_0 = - \sum_{b=1}^n \sum_{\gamma \in \Gamma'_N} S_\gamma^b T_\gamma f_\gamma(z - z_b) \quad (2.14)$$

Proof:

The proof is direct. It is based on the usage of (B.19-B.23). Let us prove identity (B.23) which is the most nontrivial here. For a generic point $w \in \Sigma_\tau$ consider $m_\gamma^a(z, w) = \varphi_\gamma(z-w)\varphi_\gamma(w-z_a)$:

$$\begin{aligned} m_\gamma^a &\stackrel{(B.22)}{=} \varphi_\gamma(z-z_a)(E_1(z-w) + E_1(w-z_a) + E_1(\omega_\gamma) - E_1(\omega_\gamma + z - z_a)) = \\ &\varphi_\gamma(z-z_a)(E_1(z-w) + E_1(w-z_a)) - f_\gamma(z-z_a) \end{aligned}$$

Combining (B.19) and (B.22) which are implied to be known we have:

$$\begin{aligned} \varphi_\beta(z-z_c)m_\gamma^a &= (\varphi_\beta(z-z_c)\varphi_\gamma(z-w))\varphi_\gamma(w-z_a) \stackrel{(B.19)}{=} \\ &\varphi_\beta(w-z_c)(\varphi_{\beta+\gamma}(z-w)\varphi_\gamma(w-z_a)) + \varphi_{\beta+\gamma}(z-z_c)(\varphi_\gamma(z_c-w)\varphi_\gamma(w-z_a)) \stackrel{(B.19),(B.22)}{=} \\ &\varphi_\beta(w-z_c)\varphi_{\beta+\gamma}(z-z_a)\varphi_{-\beta}(w-z_a) + \varphi_\beta(w-z_c)\varphi_\gamma(z-z_a)\varphi_\beta(z-w) + \\ &\varphi_{\beta+\gamma}(z-z_c)\varphi_\gamma(z_c-z_a)(E_1(z_c-w) + E_1(w-z_a) + E_1(\omega_\gamma) - E_1(\omega_\gamma + z_c - z_a)) \stackrel{(B.22)}{=} \\ &\varphi_\gamma(z-z_a)m_\beta^c - \\ &\varphi_{\beta+\gamma}(z-z_a)\varphi_\beta(z_a-z_c)(E_1(w-z_c) + E_1(z_a-w) + E_1(\omega_\beta) - E_1(\omega_\beta + z_a - z_c)) + \\ &\varphi_{\beta+\gamma}(z-z_c)\varphi_\gamma(z_c-z_a)(E_1(z_c-w) + E_1(w-z_a) + E_1(\omega_\gamma) - E_1(\omega_\gamma + z_c - z_a)) = \\ &\varphi_\gamma(z-z_a)m_\beta^c - \varphi_{\beta+\gamma}(z-z_c)f_\gamma(z_c-z_a) + \varphi_{\beta+\gamma}(z-z_a)f_\beta(z_a-z_c) + \\ &(E_1(z_c-w) + E_1(w-z_a))(\varphi_{\beta+\gamma}(z-z_c)\varphi_\gamma(z_c-z_a) + \varphi_{\beta+\gamma}(z-z_a)\varphi_\beta(z_a-z_c)) \stackrel{(B.19)}{=} \end{aligned}$$

$$\varphi_\gamma(z - z_a)m_\beta^c - \varphi_{\beta+\gamma}(z - z_c)f_\gamma(z_c - z_a) + \varphi_{\beta+\gamma}(z - z_a)f_\beta(z_a - z_c) + (E_1(z_c - w) + E_1(w - z_a))\varphi_\gamma(z - z_a)\varphi_\beta(z - z_c)$$

This ends the proof of (B.23).

□

2.2 Useful Reformulation

In this subsection we rewrite the equations of motion in a form which will be convenient for $1 + 1$ generalization. First, consider the following expressions for $a = 1 \dots n$:

$$\begin{aligned} & \sum_{\gamma \in \Gamma'_N} T_\gamma \varphi_\gamma(z - z_a) \sum_{c \neq a} S_\gamma^c \varphi_\gamma(z_a - z_c) \stackrel{(B.22)}{=} \\ & \sum_{\gamma \in \Gamma'_N} T_\gamma \sum_{c \neq a} S_\gamma^c \varphi_\gamma(z - z_c) (E_1(z - z_a) + E_1(z_a - z_c) + E_1(\omega_\gamma) - E_1(z - z_c + \omega_\gamma)) = \\ & E_1(z - z_a)(L - M_a) + \sum_{c \neq a} M_c E_1(z_a - z_c) + M_0 + \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^a f_\gamma(z - z_a) = \\ & E_1(z - z_a)L + \sum_{c \neq a} M_c E_1(z_a - z_c) + M_0 - \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^a F_\gamma(z - z_a) \end{aligned} \quad (2.15)$$

Then let us define new M-matrices in the following way:

$$\tilde{M}_a = \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^a F_\gamma(z - z_a) + \sum_{\gamma \in \Gamma'_N} T_\gamma \eta_\gamma^a \varphi_\gamma(z - z_a), \quad a = 1 \dots n, \quad (2.16)$$

where

$$\eta^a = \sum_{c \neq a} T_\gamma S_\gamma^c \varphi_\gamma(z_a - z_c) = \sum_{c \neq a} M^c(z_a) = \text{Res}_{z=z_a} \left(\frac{1}{z - z_a} L(z) \right) \quad (2.17)$$

From (2.15) we can see that the new M-matrices are the linear combinations of (2.13-2.14):

$$\tilde{M}_a = E_1(z - z_a)L + \sum_{c \neq a} M_c E_1(z_a - z_c) + M_0 \quad (2.18)$$

Then the Lax equations yield

$$\partial_{\tilde{t}_a} L = [L, \sum_{c \neq a} M_c E_1(z_a - z_c) + M_0] = \sum_{c \neq a} E_1(z_a - z_c) \partial_{t_c} L + \partial_{t_0} L$$

and the equations of motion are:

$$\begin{aligned} \partial_{\tilde{t}_a} S^a &= \sum_{c \neq a} E_1(z_a - z_c) \partial_{t_c} S^a + \partial_{t_0} S^a \stackrel{(2.10-2.12)}{=} \\ & \sum_{c \neq a} [S^a, E_1(z_a - z_c) \hat{\varphi}_{ac}(S^c) - \hat{f}_{ac}(S^c)] + [S^a, \hat{\varphi}(S^a)] \end{aligned}$$

while for $b \neq a$:

$$\begin{aligned} \partial_{\tilde{t}_a} S^b &= \partial_{t_b} S^b E_1(z_a - z_b) + \sum_{c \neq a, b} \partial_{t_c} S^b E_1(z_a - z_c) + \partial_{t_0} S^b = [S^b, \hat{\varphi} S^b] - \\ & E_1(z_a - z_b) \sum_{c \neq b} [S^b, \hat{\varphi}_{bc}(S^c)] + \sum_{c \neq a, b} E_1(z_a - z_c) [S^b, \hat{\varphi}_{bc}(S^c)] - \sum_{c \neq b} [S^b, \hat{f}_{bc}(S^c)] = \\ & [S^b, \hat{\varphi}(S^b) + E_1(z_b - z_a) \hat{\varphi}_{ba}(S^a) - \hat{f}_{ba}(S^a)] + \\ & \sum_{c \neq a, b} [S^b, (E_1(z_b - z_a) + E_1(z_a - z_c)) \hat{\varphi}_{bc}(S^c) - \hat{f}_{bc}(S^c)] \end{aligned}$$

Finally, we have

$$\partial_{\tilde{t}_a} S^a = [S^a, \hat{\rho} S^a] + \sum_{c \neq a} [S^a, \hat{F}_{ac}(S^c)] \quad (2.19)$$

$$\begin{aligned} \partial_{\tilde{t}_a} S^b &= [S^b, \hat{\rho} S^b] + [S^b, \hat{F}_{ba}(S^a)] + \sum_{\substack{c \neq a, b \\ b \neq c}} [S^b, \hat{\varphi}_{ba}(\hat{\varphi}_{ac}(S^c))] = \\ &= \sum_{c \neq a} [S^b, \hat{\varphi}_{ba}(\hat{\varphi}_{ac}(S^c))] + [S^b, \hat{F}_{ba}(S^a)] = [S^b, \hat{\varphi}_{ba}(\eta^a)] + [S^b, \hat{F}_{ba}(S^a)] \end{aligned} \quad (2.20)$$

The corresponding Hamiltonians are obtained in the same way:

$$\begin{aligned} H_0 + \sum_{c \neq a} E_1(z_a - z_c) H_c &= \frac{1}{2N} \sum_c \langle S^c \hat{\rho} S^c \rangle - \frac{1}{2N} \sum_{b \neq c} \langle S^c \hat{f}_{cb}(S^b) \rangle - \\ &= \frac{1}{N} \sum_{c \neq a} E_1(z_a - z_c) \sum_{b \neq c} \langle S^c \hat{\varphi}_{cb}(S^b) \rangle = \frac{1}{2N} \sum_c \langle S^c \hat{\rho} S^c \rangle - \frac{1}{2N} \sum_{\substack{b, c \neq a, \\ b \neq c}} \langle S^c \hat{f}_{cb}(S^b) \rangle - \\ &= \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{f}_{ac}(S^c) \rangle - \frac{1}{2N} \sum_{\substack{b, c \neq a, \\ b \neq c}} (E_1(z_a - z_c) - E_1(z_a - z_b)) \langle S^c \hat{\varphi}_{cb}(S^b) \rangle - \\ &= \frac{1}{N} \sum_{c \neq a} E_1(z_a - z_c) \langle S^c \hat{\varphi}_{ca}(S^a) \rangle = \\ &= \frac{1}{2N} \sum_c \langle S^c \hat{\rho} S^c \rangle + \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{F}_{ac}(S^c) \rangle + \frac{1}{2N} \sum_{\substack{b, c \neq a, \\ b \neq c}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle \end{aligned} \quad (2.21)$$

The last one term equals:

$$\begin{aligned} \frac{1}{2N} \sum_{\substack{b, c \neq a, \\ b \neq c}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle &= \frac{1}{2N} \sum_{\substack{b, c \neq a \\ c \neq a}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle - \frac{1}{2N} \sum_{c \neq a} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ac}(S^c)) \rangle = \\ &= \frac{1}{2N} \sum_{\substack{b, c \neq a \\ c \neq a}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle - \frac{1}{2N} \sum_{c \neq a} \langle S^c \hat{\rho}(S^c) \rangle + \frac{1}{2N} \sum_{c \neq a} \langle S^c S^c \rangle \varrho(z_a - z_c) \end{aligned} \quad (2.22)$$

From (2.21-2.22) we conclude that the Hamiltonians for the reformulated version of the Gaudin model are of the form:

$$\tilde{H}_a = \frac{1}{2N} \langle S^a \hat{\rho} S^a \rangle + \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{F}_{ac}(S^c) \rangle + \frac{1}{2N} \sum_{\substack{b, c \neq a \\ b \neq c}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle, \quad a = 1 \dots n \quad (2.23)$$

or

$$\tilde{H}_a = \frac{1}{2N} \sum_c \langle S^c \hat{\rho} S^c \rangle + \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{F}_{ac}(S^c) \rangle + \frac{1}{2N} \sum_{\substack{b, c \neq a, \\ b \neq c}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle, \quad a = 1 \dots n.$$

Two last forms of the Hamiltonians are differ by the constant $\frac{1}{2N} \sum_{c \neq a} \langle S^c S^c \rangle \varrho(z_a - z_c)$. Let us summarize the obtained in results in

Proposition 2.2 *The dynamics of the Gaudin model produced by Hamiltonians*

$$\tilde{H}_a = \frac{1}{2N} \langle S^a \hat{\rho} S^a \rangle + \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{F}_{ac}(S^c) \rangle + \frac{1}{2N} \sum_{\substack{b, c \neq a \\ b \neq c}} \langle S^c \hat{\varphi}_{ca}(\hat{\varphi}_{ab}(S^b)) \rangle \quad (2.24)$$

is given by equations

$$\partial_{\tilde{t}_a} S^a = [S^a, \hat{\rho} S^a] + \sum_{c \neq a} [S^a, \hat{F}_{ac}(S^c)] \quad (2.25)$$

$$\partial_{\tilde{t}_a} S^b = [S^b, \hat{\varphi}_{ba}(\eta^a)] + [S^b, \hat{F}_{ba}(S^a)], \quad \eta^a = \sum_{c \neq a} \hat{\varphi}_{ac}(S^c) \quad (2.26)$$

and can be presented in the Lax form with $L(z)$ from (2.2) and

$$\tilde{M}_a = \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^a F_\gamma(z - z_a) + \sum_{\gamma \in \Gamma'_N} T_\gamma \eta_\gamma^a \varphi_\gamma(z - z_a), \quad a = 1 \dots n. \quad (2.27)$$

The Gaudin Hamiltonians (2.5) and (2.24) are simplified when written in terms of η^a (2.17):

$$H_a = -\langle S^a \eta^a \rangle, \quad \tilde{H}_a = \frac{1}{2N} \langle S^a \hat{\rho} S^a \rangle - \frac{1}{2N} \langle (\eta^a)^2 \rangle + \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{F}_{ac}(S^c) \rangle. \quad (2.28)$$

In the end of the section let us also give the rational "reformulated" version since it is more illuminating:

$$\tilde{M}_a = \sum_{c \neq a} \frac{M_c}{z_a - z_c} + \frac{1}{z - z_a} L = \frac{1}{z - z_a} M_a + \frac{\eta^a}{z - z_a}, \quad (2.29)$$

where

$$\eta^a = \sum_{c \neq a} \frac{S^c}{z_a - z_c}. \quad (2.30)$$

Hamiltonians:

$$\tilde{H}_a = -\frac{1}{2N} \left\langle \left(\sum_{c \neq a} \frac{S^c}{z_a - z_c} \right)^2 \right\rangle + \frac{1}{N} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2}. \quad (2.31)$$

The later follows from simple evaluation:

$$\begin{aligned} \sum_{c \neq a} \frac{H_c}{z_a - z_c} &= -\frac{1}{N} \sum_{c \neq a} \sum_{b \neq c} \frac{1}{z_a - z_c} \frac{\langle S^c S^b \rangle}{z_c - z_b} = \frac{1}{N} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} + \\ \frac{1}{N} \sum_{b, c \neq a; b \neq c} \frac{\langle S^c S^b \rangle}{(z_c - z_a)(z_c - z_b)} &= -\frac{1}{2N} \langle (\eta^a)^2 \rangle + \frac{1}{N} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} + \frac{1}{2N} \sum_{c \neq a} \frac{\langle (S^c)^2 \rangle}{(z_a - z_c)^2}. \end{aligned} \quad (2.32)$$

The last one term is the analogue of the constant $\frac{1}{2N} \sum_{c \neq a} \langle S^c S^c \rangle \wp(z_a - z_c)$ in (2.22). The corresponding equations of motion are:

$$\begin{cases} \partial_{\bar{t}_a} S^a = \sum_{c \neq a} \frac{[S^a, S^c]}{(z_a - z_c)^2} \\ \partial_{\bar{t}_a} S^b = \frac{[S^b, S^a]}{(z_a - z_b)^2} + \frac{1}{z_a - z_b} \sum_{c \neq a} \frac{[S^c, S^b]}{z_a - z_c} = \frac{[S^b, S^a]}{(z_a - z_b)^2} + \frac{[\eta^a, S^b]}{z_a - z_b}. \end{cases} \quad (2.33)$$

3 Field Version

3.1 1+1 $\mathfrak{sl}(N, \mathbb{C})$ Gaudin Model

The general construction of the field version for the Hitchin systems was described in [24]. For our current purposes we only need to define the phase space. By analogy with mechanics let us consider a collection (direct product) of n orbits assigned to the marked points, i.e. let $\text{Res}_{z=z_a} L(z) = S^a(x)$ be elements of the loop coalgebras $\hat{\mathfrak{sl}}^*(N, \mathbb{C})$ and x be a loop variable. We imply that the values of the invariants under the coadjoint action (or the eigenvalues of S^a) are fixed. More over we assume for simplicity that the eigenvalues are \mathbb{C} -numbers (independent of x). From the physical point of view it means that the magnetic momentum vector is normalized (as it is assumed in the Landau-Lifshitz model). The boundary conditions are chosen to be periodic. In summary, $S^a(x)$ are $\hat{\mathfrak{sl}}^*(N, \mathbb{C})$ -valued periodic functions on a unit circle \mathbb{S}^1 : $S^a(x+2\pi) = S^a(x)$ with eigenvalues $\{\lambda_{k,a}, k = 1 \dots N, a = 1 \dots n\}$ fixed to be \mathbb{C} -numbers: $\partial_x \lambda_a = 0$.

In the field case the Lax equations (1.7) a replaced by the zero-curvature equations:

$$\partial_{t_a} L - k \partial_x M_a = [L, M_a] \quad (3.1)$$

In fact, the numeration of M_a should include two type of indices as in (2.5): the first one type describes the number of the flow in the hierarchy and runs over $1 \dots N$ in $0 + 1$ mechanics or $1 \dots \infty$ in $1 + 1$ field theory while the second one runs over $1 \dots n$ in both cases and describes the assignment of the Hamiltonians to the marked points. In this paper we are not going to concern the whole hierarchy but only two first flows (as we did in $0 + 1$ case).

We will see that the first n flows of the hierarchy corresponds to the Gaudin Hamiltonians in the standard description (2.5) supplemented by the momenta P_a along x while the second n flows naturally related to reformulated version (2.24).

$$\begin{array}{ccc} \boxed{\text{Standard Description } H_a} & \longrightarrow & \boxed{\text{1st flows}} \\ \boxed{\text{Reformulated Version } \tilde{H}_a} & \longrightarrow & \boxed{\text{2nd flows}} \\ \dots & \longrightarrow & \dots \end{array} \quad (3.2)$$

Thus we do not use multi-index for times. It is sufficient to use t_a and \tilde{t}_a for our purposes and we keep these notations for the field version.

It should be mentioned that the field generalization of the Lax pair into "L-A" pair satisfying (3.1) is nontrivial. The fact that the L -matrix (2.2) is unchanged in the field version follows from the triviality of the moduli space of bundles of degree one. It is explained in [24] in detail. As a result we deal with the following Lax matrix:

$$L = \sum_{c=1}^n \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^c \varphi_\gamma(z - z_c) \quad (3.3)$$

The M_a -matrices for the first flow coincide with the mechanical versions either:

$$M_a = \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^a \varphi_\gamma(z - z_a) \quad (3.4)$$

Proposition 3.1 *The zero-curvature equations (3.1) with L from (3.3) and M_a from (3.4) are equivalent to the following equations:*

$$\begin{cases} \partial_{t_a} S^a - k \partial_x S^a = - \sum_{c \neq a} [S^a, \hat{\varphi}_{ac}(S^c)], \\ \partial_{t_a} S^b = [S^b, \hat{\varphi}_{ba}(S^a)]. \end{cases} \quad (3.5)$$

The proof is the same as in the mechanical case. As we will see below the Hamiltonian corresponding to M_a has the form

$$\mathcal{H}_a = \oint_{\mathbb{S}^1} dx (P_a + H_a(S(x))), \quad (3.6)$$

where $\oint_{\mathbb{S}^1} dx P_a$ is the shift operator in the loop algebra $\hat{\mathfrak{sl}}(N, \mathbb{C})$: $\{\oint_{\mathbb{S}^1} dx P_a(x), S^b(y)\} = \delta_{ab} \partial_y S^b(y)$ and H_a is defined as in (1.5) or (2.5). Thus the Hamiltonian describing equations (3.5) has the form:

$$\mathcal{H}_a = \oint_{\mathbb{S}^1} dx \left(P_a - \frac{1}{N} \sum_{c \neq a} \langle S^a \hat{\varphi}_{ac}(S^c) \rangle \right). \quad (3.7)$$

The phase space is a direct product of the symplectic orbits of the loop group $\hat{\text{SL}}(N, \mathbb{C})$ with linear Poisson structure:

$$\{S_\alpha^a(x), S_\beta^b(y)\} = \delta_{ab}\delta(x-y)c_{\alpha,\beta}S_{\alpha+\beta}^a(x), \quad a, b = 1 \dots n. \quad (3.8)$$

The second flows are of our main interest.

Proposition 3.2 *The zero-curvature equations*

$$\partial_{\tilde{t}_a} L - k\partial_x \tilde{M}_a = [L, \tilde{M}_a]$$

with L from (3.3) and

$$\tilde{M}_a = \sum_{\gamma \in \Gamma'_N} T_\gamma S_\gamma^a F_\gamma(z - z_a) + \sum_{\gamma \in \Gamma'_N} T_\gamma \eta_\gamma^a \varphi_\gamma(z - z_a), \quad a = 1 \dots n, \quad (3.9)$$

where $\eta^a = \eta'^a + \Delta\eta^a$, $\eta'^a = \sum_{c \neq a} \hat{\varphi}_{ac}(S^c)$ are equivalent to the following equations:

$$\begin{cases} \partial_{\tilde{t}_a} S^a - k\partial_x \eta^a = [S^a, \hat{\varphi}(S^a)] + \sum_{c \neq a} [S^a, \hat{F}_{ac}(S^c)] + \sum_{c \neq a} [\hat{\varphi}_{ac}(S^c), \eta^a] + \\ \left[\hat{E}_1(S^a), \Delta\eta^a \right] + \left[S^a, \hat{E}_1(\Delta\eta^a) \right] - \hat{E}_1[S^a, \Delta\eta^a] \\ \partial_{\tilde{t}_a} S^b = [S^b, \hat{\varphi}_{ba}(\eta^a)] + [S^b, \hat{F}_{ba}(S^a)], \\ -k\partial_x S^a = [S^a, \Delta\eta^a]. \end{cases} \quad (3.10)$$

The proof is also similar to the one given for the mechanical case. Functions η^a are not uniquely defined by equations $-k\partial_x S^a = [S^a, \Delta\eta^a]$. We fix this ambiguity by requiring $\eta^a \rightarrow \eta'^a = \sum_{c \neq a} \hat{\varphi}_{ac}(S^c)$ or $\Delta\eta^a \rightarrow 0$ in $0+1$ limit. As for the equation $-k\partial_x S^a = [S^a, \Delta\eta^a]$ itself only some special cases were studied such as "vector" case [34, 35] and "Grassmannian" case (special coadjoint orbits) [36]. For $\hat{\text{sl}}(2, \mathbb{C})$ case the answer is well known: $\Delta\eta^a = -\frac{k}{4\lambda_2^2}[S^a, S_x^a]$.

3.2 2-site Case and Principle Chiral Model

L-A pair for the principle chiral model was suggested in [29] (see also [21, 30, 31, 32]). Consider the first flows of the Gaudin model (3.5) with 2 sites or marked points ($n = 2$). It is convenient to start from the rational version:

$$L = \frac{S^1}{z - z_1} + \frac{S^2}{z - z_2} = M_1 + M_2 \quad (3.11)$$

The corresponding M-matrix is known to be

$$M = M_1 - M_2 = \frac{S^1}{z - z_1} - \frac{S^2}{z - z_2}. \quad (3.12)$$

Therefore the equations of motion are

$$\begin{cases} \partial_t S^1 - k\partial_x S^1 = -\frac{2}{z_1 - z_2}[S^1, S^2], \\ \partial_t S^2 + k\partial_x S^2 = \frac{2}{z_1 - z_2}[S^1, S^2]. \end{cases} \quad (3.13)$$

Then the Hamiltonian describing equations (3.13) has a form:

$$\mathcal{H} = \mathcal{H}_1 - \mathcal{H}_2 = \oint_{\mathbb{S}^1} dx \left(P_1 - P_2 - \frac{\langle S^1 S^2 \rangle}{z_1 - z_2} \right)^5 \quad (3.14)$$

⁵See section "Hamiltonian description" and (4.42).

and the phase space is a direct product of two symplectic orbits of the loop group $\widehat{\text{SL}}(N, \mathbb{C})$ with the linear Poisson structure:

$$\{S_\alpha^a(x), S_\beta^b(y)\} = \delta_{ab}\delta(x-y)c_{\alpha,\beta}S_{\alpha+\beta}^a(x), \quad a, b = 1, 2. \quad (3.15)$$

Remark: One can make a substitution $S^1 = \frac{1}{2}(l_0 + l_1)$ and $S^2 = \frac{1}{2}(l_0 - l_1)$ to represent equations (3.13) in its traditional form

$$\begin{cases} \partial_t l_1 - k\partial_x l_0 + \frac{2}{z_1 - z_2}[l_1, l_0] = 0, \\ \partial_t l_0 - k\partial_x l_1 = 0 \end{cases} \quad (3.16)$$

or change the coordinates (x, t) to "light-cone" coordinates: $\xi = \frac{t+k^{-1}x}{2}$, $\eta = \frac{t-k^{-1}x}{2}$:

$$\begin{cases} \partial_\eta S^1 = -\frac{2}{z_1 - z_2}[S^1, S^2], \\ \partial_\xi S^2 = \frac{2}{z_1 - z_2}[S^1, S^2]. \end{cases} \quad (3.17)$$

Elliptic case. For L-A pair $L = M_1 + M_2$ and $M = M_1 - M_2$ with $M_a = \sum_{\alpha \in \Gamma'_N} T_\alpha S_\alpha^a \varphi_\alpha(z - z_a)$, $a = 1, 2$ the equations (3.5) yields $(\partial_t = \partial_{t_1} - \partial_{t_2})$:

$$\begin{cases} \partial_t S^1 - k\partial_x S^1 = -2[S^1, \hat{\varphi}_{12}(S^2)], \\ \partial_t S^2 + k\partial_x S^2 = 2[S^2, \hat{\varphi}_{21}(S^1)]. \end{cases} \quad (3.18)$$

or by analogy with (3.17)

$$\begin{cases} \partial_\eta S^1 = -2[S^1, \hat{\varphi}_{12}(S^2)], \\ \partial_\xi S^2 = 2[S^2, \hat{\varphi}_{21}(S^1)]. \end{cases} \quad (3.19)$$

In $\text{sl}(2, \mathbb{C})$ case this result was obtained by I.Cherednik [30]. Here we see that the principle chiral model corresponds to the special (2-site) case of the first flows of 1 + 1 Gaudin model. It should be also mentioned that in [30] the equations for $\text{sl}(2, \mathbb{C})$ case were obtained as a filed version of XYZ model, i.e. from the second flow of 1-site Gaudin model (or $\text{sl}(2, \mathbb{C})$ elliptic top). It may be explained as follows: consider stationary solutions $S^a = S^a(\eta)$ (or $\partial_\xi S^a = 0$). Then fixing the ambiguity in solutions of the equation $[S^2, \hat{\varphi}_{21}(S^1)] = 0$ as $S^2 = -\frac{1}{2}\hat{\varphi}_{21}(S^1)$ we have

$$\partial_\eta S^1 = [S^1, \hat{\varphi}_{12}\hat{\varphi}_{21}(S^1)] = [S^1, \hat{\varphi}(S^1)]$$

which is the equation of $\text{sl}(N, \mathbb{C})$ elliptic top (or 1-site elliptic Gaudin model) corresponding to the second flow $H = \frac{1}{2N}\langle S^1 \hat{\varphi}(S^1) \rangle$.

4 $\text{sl}(2, \mathbb{C})$ 1+1 Gaudin Models

4.1 1+1 XXX Gaudin Magnet: Interacting Heisenberg Models

Let us consider the case $\text{Res}_{z_a} L(z) = S^a \in \text{sl}(2, \mathbb{C})$ in detail. The linear Poisson-Lie structure in this case:

$$\{S_\alpha^a, S_\beta^b\} = 2\sqrt{-1}\delta^{ab}\varepsilon_{\alpha\beta\gamma}S_\gamma^a, \quad (4.1)$$

where S_α^a are coefficients in the basis of Pauli matrices: $S^a = \sum_{\alpha=1}^3 S_\alpha^a \sigma_\alpha$.

The Gaudin Hamiltonians are:

$$H_a = - \sum_{c \neq a} \frac{S_1^a S_1^c + S_2^a S_2^c + S_3^a S_3^c}{z_a - z_c} \quad (4.2)$$

while the Hamiltonians of the reformulated version are:

$$\tilde{H}_a = \frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} - \frac{1}{4} \left\langle \left(\sum_{c \neq a} \frac{S^c}{z_a - z_c} \right)^2 \right\rangle + \frac{H_a^2}{2\lambda_a^2} \quad (4.3)$$

since

$$\begin{aligned} \sum_{c \neq a} \frac{H_c}{z_a - z_c} + \frac{H_a^2}{2\lambda_a^2} &= -\frac{1}{2} \sum_{c \neq a} \sum_{b \neq c} \frac{1}{z_a - z_c} \frac{\langle S^c S^b \rangle}{z_c - z_b} + \frac{H_a^2}{2\lambda_a^2} = \\ &= \frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} + \frac{1}{2} \sum_{b, c \neq a; b \neq c} \frac{\langle S^c S^b \rangle}{(z_c - z_a)(z_c - z_b)} + \frac{H_a^2}{2\lambda_a^2} = \\ &= \frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} - \frac{1}{4} \sum_{b, c \neq a; b \neq c} \frac{\langle S^c S^b \rangle}{(z_a - z_c)(z_a - z_b)} + \frac{H_a^2}{2\lambda_a^2} = \\ &= \frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} + \frac{1}{4} \sum_{c \neq a} \frac{\langle (S^c)^2 \rangle}{(z_a - z_c)^2} - \frac{1}{4} \left\langle \left(\sum_{c \neq a} \frac{S^c}{z_a - z_c} \right)^2 \right\rangle + \frac{H_a^2}{2\lambda_a^2}. \end{aligned} \quad (4.4)$$

Then the corresponding equations of motion are:

$$\begin{cases} \partial_{\tilde{t}_a} S^a = \sum_{c \neq a} \frac{[S^a, S^c]}{(z_a - z_c)^2} - \frac{H_a}{\lambda_a^2} \sum_{c \neq a} \frac{[S^a, S^c]}{z_a - z_c} \\ \partial_{\tilde{t}_a} S^b = \frac{[S^b, S^a]}{(z_a - z_b)^2} + \frac{1}{z_a - z_b} \sum_{c \neq a} \frac{[S^c, S^b]}{z_a - z_c} + \frac{H_a}{\lambda_a^2} \frac{[S^a, S^b]}{z_a - z_b} = \frac{[S^b, S^a]}{(z_a - z_b)^2} + \frac{[\eta'^a, S^b]}{z_a - z_b}, \end{cases} \quad (4.5)$$

where

$$\eta'^a = \sum_{c \neq a} \frac{S^c}{z_a - z_c} + \frac{H_a}{\lambda_a^2} S^a \quad (4.6)$$

Remark: (4.6) differs from (2.30) by $\frac{H_a}{\lambda_a^2} S^a$ and the corresponding Hamiltonian (4.4) differs from (2.32) by $\frac{H_a^2}{2\lambda_a^2}$. This difference does not follow from ansatz (3.9) but appears from the Hamiltonian description (see section 4.3). The corresponding Lax pair is given by L from (1.2) and

$$\tilde{M}_a = \sum_{c \neq a} \frac{M_c}{z_a - z_c} + \frac{1}{z - z_a} L + \frac{H_a}{\lambda_a^2} M_a = \frac{1}{z - z_a} M_a + \frac{\eta'^a}{z - z_a} \quad (4.7)$$

1+1 version

Let $S^a(x) \in \hat{\mathfrak{sl}}(2, \mathbb{C})$ be periodic $\mathfrak{sl}(2, \mathbb{C})$ -valued functions on a circle \mathbb{S}^1 : $S^a(x + 2\pi) = S^a(x)$ with eigenvalues $\{\lambda_a\}$ fixed to be \mathbb{C} -numbers: $\partial_x \lambda_a = 0$. The Poisson structure now is

$$\{S_\alpha^a(x), S_\beta^b(y)\} = 2\sqrt{-1} \delta^{ab} \varepsilon_{\alpha\beta\gamma} S_\gamma^a(x) \delta(x - y). \quad (4.8)$$

Consider

$$\tilde{M}_a = \frac{S^a}{(z - z_a)^2} + \frac{\eta^a}{z - z_a}, \quad (4.9)$$

where

$$\eta^a = -\frac{k}{4\lambda_a^2}[S^a, S_x^a] + \sum_{c \neq a} \frac{S^c}{z_a - z_c} + \frac{H_a}{\lambda_a^2} S^a = -\frac{k}{4\lambda_a^2}[S^a, S_x^a] + \eta'^a, \quad S_x^a \equiv \partial_x S^a \quad (4.10)$$

Let us remark here that in (0+1) limit $\eta^a = \eta'^a$ (4.6). Then the zero-curvature equation

$$\partial_{\tilde{t}_a} L - k \partial_x \tilde{M}_a = [L, \tilde{M}_a] \quad (4.11)$$

reads as follows

$$\begin{cases} \partial_{\tilde{t}_a} S^a - k \partial_x \eta^a = [\sum_{c \neq a} \frac{S^c}{z_a - z_c}, \eta^a] + \sum_{c \neq a} \frac{[S^a, S^c]}{(z_a - z_c)^2} \\ \partial_{\tilde{t}_a} S^b = \frac{[S^b, S^a]}{(z_a - z_b)^2} + \frac{[\eta^a, S^b]}{z_a - z_b} \end{cases} \quad (4.12)$$

These equation generalize the Heisenberg model which appears from (4.12) in $n = 1$ (1-site) case:

$$\partial_t S + \frac{k^2}{4\lambda^2} [S, S_{xx}] = 0 \quad (4.13)$$

and described by the Hamiltonian

$$\mathcal{H} = \frac{k^2}{16\lambda^2} \oint_{\mathbb{S}^1} dx \langle (\partial_x S)^2 \rangle. \quad (4.14)$$

4.2 1+1 XYZ Gaudin Magnet: Interacting Landau-Lifshitz Models

By analogy with the previous section the Hamiltonians in 0+1 $\mathfrak{sl}(2, \mathbb{C})$ case:

$$\tilde{H}_a = \frac{1}{4} \langle S^a \hat{\phi}(S^a) \rangle + \frac{1}{2} \sum_{c \neq a} \langle S^a \hat{F}(S^c) \rangle - \frac{1}{4} \langle \left(\sum_{c \neq a} \hat{\phi}_{ac}(S^c) \right)^2 \rangle + \frac{H_a^2}{2\lambda_a^2} \quad (4.15)$$

Consider now the following L-A pair:

$$\begin{aligned} L(z) &= \sum_{c=1}^n \sum_{\alpha=1}^3 S_\alpha^c \sigma_\alpha \varphi_\alpha(z - z_c) \\ \tilde{M}_a(z) &= \sum_{\alpha=1}^3 \eta_\alpha^a \sigma_\alpha \varphi_\alpha(z - z_a) + S_\alpha^a \sigma_\alpha \varphi_\beta(z - z_a) \varphi_\gamma(z - z_a), \end{aligned} \quad (4.16)$$

where α, β, γ are different indices equivalent to 1, 2, 3 up to a cyclic permutation and (compare with (4.10))

$$\eta^a = -\frac{k}{4\lambda_a^2}[S^a, S_x^a] + \sum_{c \neq a} \hat{\phi}_{ac}(S^c) + \frac{H_a}{\lambda_a^2} S^a \quad (4.17)$$

The zero curvature equation (4.11) leads to equations of motion:

$$\begin{cases} \partial_{\tilde{t}_a} S^a - k \partial_x \eta^a = [S^a, \hat{\phi}(S^a)] + \sum_{c \neq a} [\eta^a, \hat{\phi}_{ca}(S^c)] - \hat{\phi}_{ca}([S^c, \hat{\phi}_{ca}(S^a)]), \\ \partial_{\tilde{t}_a} S^b = [\hat{\phi}_{ab}(\eta^a), S^b] + \hat{\phi}_{ba}([\hat{\phi}_{ba}(S^b), S^a]) \end{cases} \quad (4.18)$$

⁶The remark about the term $\frac{H_a}{\lambda_a^2} S^a$ in the previous section is reasonable here as well.

and η^a (4.17) is a particular solution of the equation

$$-kS_x^a = [S^a, \eta^a - \sum_{c \neq a} \hat{\varphi}_{ac}(S^c)]. \quad (4.19)$$

It is fixed if we require $\eta^a \rightarrow \eta^a = \sum_{c \neq a} \hat{\varphi}_{ac}(S^c) + \frac{H_a}{\lambda_a^2} S^a$ in (0+1) limit. The proof follows from (C.4-C.10). In particular, from (C.8) it follows that $\hat{\varphi}_{ca}([S^c, \hat{\varphi}_{ca}(S^a)]) = [\hat{F}_{ca}(S^c), S^a]$. Then (4.18) is written in the form close to (3.10):

$$\begin{cases} \partial_{\bar{t}_a} S^a - k\partial_x \eta^a = [S^a, \hat{\varphi}(S^a)] + \sum_{c \neq a} [\eta^a, \hat{\varphi}_{ca}(S^c)] - [\hat{F}_{ca}(S^c), S^a], \\ \partial_{\bar{t}_a} S^b = [\hat{\varphi}_{ab}(\eta^a), S^b] + [S^b, \hat{F}_{ba}(S^a)]. \end{cases} \quad (4.20)$$

The last three terms in the first equation of (3.10) vanish. It is due to (C.6) that $\forall A, B \in \mathfrak{sl}(2, \mathbb{C})$:

$$\hat{E}_1([A, B]) = [\hat{E}_1(A), B] + [A, \hat{E}_1(B)].$$

Note that in case $n = 1$ the first one equation in (4.20) is the Landau-Lifshitz equation:

$$\partial_t S + \frac{k^2}{4\lambda^2} [S, S_{xx}] = [S, \hat{\varphi}(S)] \quad (4.21)$$

described by the Hamiltonian

$$\mathcal{H} = \oint_{\mathbb{S}^1} dx \left(\frac{1}{4} \langle S \hat{\varphi}(S) \rangle + \frac{k^2}{16\lambda^2} \langle (\partial_x S)^2 \rangle \right). \quad (4.22)$$

4.3 Hamiltonian Description

The explicit form of the conserved quantities in terms of the fields are obtained by solving the Riccati equation. First, we make the gauge transformation (see for example [24, 33]):

$$\left(k\partial_x + \begin{pmatrix} L_{11} & L_{12} \\ L_{21} & -L_{11} \end{pmatrix} \right) \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = 0 \rightarrow \left(k\partial_x + \begin{pmatrix} 0 & 1 \\ T & 0 \end{pmatrix} \right) \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = 0 \quad (4.23)$$

with

$$T = L_{12}L_{21} + L_{11}^2 + kL_{11} \frac{\partial_x L_{12}}{L_{12}} - k\partial_x L_{11} - \frac{k^2}{2} \frac{\partial_x^2 L_{12}}{L_{12}} + \frac{3k^2}{4} \left(\frac{\partial_x L_{12}}{L_{12}} \right)^2 \quad (4.24)$$

which leads to the Schrödinger equation:

$$(-k^2 \partial_x^2 + T)\psi_1 = 0. \quad (4.25)$$

Taking wave function in the form $\psi_1 = e^{\frac{1}{k} \int_{x_0}^x dy \chi(y)}$ we come to the Riccati equation:

$$k\partial_x \chi + \chi^2 - T = 0. \quad (4.26)$$

The solution is obtained via local decompositions:

$$\chi_a = \frac{1}{z-z_a} \chi_{a,-1} + \chi_{a,0} + (z-z_a) \chi_{a,1} + \dots, \quad T = \frac{1}{(z-z_a)^2} T_{a,-2} + \frac{1}{z-z_a} T_{a,-1} + T_{a,0} + \dots \quad (4.27)$$

$$L = \frac{1}{z - z_a} L^{a,-1} + L^{a,0} + (z - z_a) L^{a,1} + \dots \quad (4.28)$$

Then (4.26) gives:

$$\begin{aligned} \chi_{a,-1}^2 &\equiv \lambda_a^2 = T_{a,-2}, \\ \chi_{a,0} &= \frac{1}{2\chi_{a,-1}} (T_{a,-1} - k\partial_x \chi_{a,-1}), \\ \chi_{a,1} &= \frac{1}{2\chi_{a,-1}} (T_{a,0} - \frac{T_{a,-1}^2}{4T_{a,-2}}), \\ &\dots \end{aligned} \quad (4.29)$$

As it was shown in [33] $\chi_{a,k}$ (4.29) are the densities of the conservation laws. We will use notation

$$h_{a,k}(x) = -\lambda_a \chi_{a,k-1} \quad (4.30)$$

for the densities and

$$\mathcal{H}_{a,k} = \oint_{\mathbb{S}^1} dx h_{a,k}(x) \quad (4.31)$$

for the Hamiltonians. The coefficients (4.28) of the decomposition of L -matrices in rational and elliptic cases:

$$\begin{aligned} L^{a,-1} &= S^a, & L^{a,-1} &= S^a, \\ L^{a,0} &= \sum_{c \neq a} \frac{S^c}{z_a - z_c}, & L^{a,0} &= \sum_{c \neq a} \hat{\varphi}_{ac}(S^c), \\ L^{a,1} &= -\sum_{c \neq a} \frac{S^c}{(z_a - z_c)^2}, & L^{a,1} &= -\frac{1}{2} \hat{\varphi}(S^a) - \sum_{c \neq a} \hat{F}_{ac}(S^c), \\ &\dots & &\dots \end{aligned} \quad (4.32)$$

In what follows we sometimes omit for the simplicity the index a for L -matrix and its elements assuming decompositions (4.27-4.28). Substituting (4.28) into (4.24) we get:

$$\begin{aligned} T_{a,-2} &= L_{12}^{-1} L_{21}^{-1} + L_{11}^{-1} L_{11}^{-1} \\ T_{a,-1} &= L_{12}^{-1} L_{21}^0 + L_{12}^0 L_{21}^{-1} + 2L_{11}^0 L_{11}^{-1} + k \frac{L_{11}^{-1} \partial_x L_{12}^{-1}}{L_{12}^{-1}} - k \partial_x L_{11}^{-1} \\ T_{a,0} &= L_{12}^1 L_{21}^{-1} + L_{12}^{-1} L_{21}^1 + 2L_{11}^1 L_{11}^{-1} + L_{12}^0 L_{21}^0 + L_{11}^0 L_{11}^0 + \\ &\frac{k}{L_{12}^{-1}} \left(L_{11}^0 \partial_x L_{12}^{-1} + L_{11}^{-1} \partial_x L_{12}^0 - \frac{L_{12}^0 L_{11}^{-1} \partial_x L_{12}^{-1}}{L_{12}^{-1}} \right) - k \partial_x L_{11}^0 - \frac{k^2}{2} \frac{\partial_x^2 L_{12}^{-1}}{L_{12}^{-1}} + \frac{3k^2}{4} \left(\frac{\partial_x L_{12}^{-1}}{L_{12}^{-1}} \right) \end{aligned} \quad (4.33)$$

Let us summarize the obtained results.

Proposition 4.1 *The density of the Hamiltonian $\chi_{a,0}$ has the following form in terms of the decomposition of the L -matrix (4.28):*

$$2\lambda_a \chi_{a,0} = T_{a,-1} = \langle L^{-1} L^0 \rangle - 2P_a = -2(H_a + P_a), \quad (4.34)$$

where P_a is the density of the Hamiltonian of the shift operator along x corresponding to the a^{th} site (marked point):

$$\left\{ \oint_{\mathbb{S}^1} dx P_a(x), S^b(y) \right\} = k \delta_{ab} \partial_y S^a, \quad P_a(x) = -\frac{k}{2} L_{11}^{a,-1}(x) \frac{\partial_x L_{12}^{a,-1}(x)}{L_{12}^{a,-1}(x)} \quad (4.35)$$

Proof:

The nontrivial part of the proof is related to the shift operators P_a . Brackets (4.8) have the following form in standard basis (here we omit index a as above):

$$\begin{aligned} \{L_{12}^{-1}(x), L_{11}^{-1}(y)\} &= 2L_{12}^{-1}(x)\delta(x-y), \quad \{L_{21}^{-1}(x), L_{11}^{-1}(y)\} = -2L_{21}^{-1}(x)\delta(x-y), \\ \{L_{12}^{-1}(x), L_{21}^{-1}(y)\} &= -4L_{11}^{-1}(x)\delta(x-y). \end{aligned} \quad (4.36)$$

For example, let us verify that $\oint_{\mathbb{S}^1} dx \{L_{11}^{-1}(x) \frac{\partial_x L_{12}^{-1}(x)}{L_{12}^{-1}(x)}, L_{21}^{-1}(y)\} = -2k \partial_y L_{21}^{-1}(y)$:

$$\begin{aligned} &\oint_{\mathbb{S}^1} dx \{L_{11}^{-1}(x) \frac{\partial_x L_{12}^{-1}(x)}{L_{12}^{-1}(x)}, L_{21}^{-1}(y)\} = \\ &\oint_{\mathbb{S}^1} dx \{L_{11}^{-1}(x), L_{21}^{-1}(y)\} \frac{\partial_x L_{12}^{-1}(x)}{L_{12}^{-1}(x)} - \oint_{\mathbb{S}^1} dx \partial_x L_{11}^{-1}(x) \{\ln L_{12}^{-1}(x), L_{21}^{-1}(y)\} = \\ &2L_{21}^{-1}(y) \frac{\partial_y L_{12}^{-1}(y)}{L_{12}^{-1}(y)} + 4L_{11}^{-1}(y) \frac{\partial_y L_{11}^{-1}(y)}{L_{12}^{-1}(y)} = -2k \partial_y L_{21}^{-1}(y). \end{aligned} \quad (4.37)$$

The later follows from the condition $\partial_y \lambda_a^2 = 0 = \partial_y ((L_{11}^{-1}(y))^2 + L_{12}^{-1}(y)L_{21}^{-1}(y))$. The verification of (4.35) for other components can be performed in the same way.

□

Proposition 4.2 *The density of the Hamiltonian $\chi_{a,1}$ has the following form in terms of the decomposition of the L -matrix (4.28):*

$$\begin{aligned} 8\lambda_a^3 \chi_{a,1} &= 4\lambda_a^2 T_{a,0} - T_{a,-1}^2 = \\ &2\langle L^{a,-1} L^{a,-1} \rangle \left(\frac{1}{2} \langle L^{a,0} L^{a,0} \rangle + \langle L^{a,1} L^{a,-1} \rangle \right) - (\langle L^{a,-1} L^{a,0} \rangle)^2 + \\ &2k \langle L^{a,0} \partial_x L^{a,-1} L^{a,-1} \rangle - \frac{k^2}{2} \langle (\partial_x L^{a,-1})^2 \rangle \end{aligned} \quad (4.38)$$

Proof:

Our purpose is to show that $\oint_{\mathbb{S}^1} dx$ l.h.s.(4.38) = $\oint_{\mathbb{S}^1} dx$ r.h.s.(4.38). The proof is direct. It is based on the integration by parts. For example,

$$\begin{aligned} &\oint_{\mathbb{S}^1} dx 4\lambda_a^2 \left(-\frac{k^2}{2} \frac{\partial_x^2 L_{12}^{-1}}{L_{12}^{-1}} + \frac{3k^2}{4} \left(\frac{\partial_x L_{12}^{-1}}{L_{12}^{-1}} \right) \right) - k^2 \left(\frac{L_{11}^{-1} \partial_x L_{12}^{-1}}{L_{12}^{-1}} - \partial_x L_{11}^{-1} \right)^2 = \\ &- \oint_{\mathbb{S}^1} dx \frac{k^2}{2} \langle L_x^{-1} L_x^{-1} \rangle \end{aligned} \quad (4.39)$$

and

$$\begin{aligned} &\oint_{\mathbb{S}^1} dx 4\lambda_a^2 \frac{k}{L_{12}^{-1}} \left(L_{11}^0 \partial_x L_{12}^{-1} + L_{11}^{-1} \partial_x L_{12}^0 - \frac{L_{12}^0 L_{11}^{-1} \partial_x L_{12}^{-1}}{L_{12}^{-1}} \right) - \\ &- 2k \left(\frac{L_{11}^{-1} \partial_x L_{12}^{-1}}{L_{12}^{-1}} - \partial_x L_{11}^{-1} \right) (L_{12}^{-1} L_{21}^0 + L_{12}^0 L_{21}^{-1} + 2L_{11}^0 L_{11}^{-1}) = 2k \oint_{\mathbb{S}^1} dx \langle L^0 L_x^{-1} L^{-1} \rangle. \end{aligned} \quad (4.40)$$

□

Finally, we have the following densities of the Hamiltonians describing the first and the second flows:

$$\begin{aligned}
h_{a,1} &= -\lambda_a \chi_{a,0} = -\frac{1}{2} T_{a,-1} = P_a - \frac{1}{2} \langle L^{a,-1} L^{a,0} \rangle \\
h_{a,2} &= -\lambda_a \chi_{a,1} = -\frac{1}{2} \left(T_{a,0} - \frac{1}{4\lambda_a^2} T_{a,-1}^2 \right) = -\frac{1}{4} \langle L^{a,0} L^{a,0} \rangle \\
&\quad - \frac{1}{2} \langle L^{a,1} L^{a,-1} \rangle + \frac{1}{8\lambda_a^2} \langle L^{a,-1} L^{a,0} \rangle^2 - \frac{k}{4\lambda_a^2} \langle L^{a,0} \partial_x L^{a,-1} L^{a,-1} \rangle + \frac{k^2}{16\lambda_a^2} \langle (\partial_x L^{a,-1})^2 \rangle
\end{aligned} \tag{4.41}$$

These equalities are understood in a sense that $\oint_{\mathbb{S}^1} dx$ l.h.s.(4.41) = $\oint_{\mathbb{S}^1} dx$ r.h.s.(4.41).

Proposition 4.3 *Hamiltonian density (4.41) provides equations (4.12) and (4.20).*

Substituting (4.32) into (4.41) we obtain explicit expressions for the Hamiltonians. In rational case:

$$\mathcal{H}_{a,1} = \oint_{\mathbb{S}^1} dx h_{a,1}(x) = \oint_{\mathbb{S}^1} dx \left(P_a - \frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{z_a - z_c} \right) = \oint_{\mathbb{S}^1} dx (P_a + H_a), \tag{4.42}$$

$$\begin{aligned}
\mathcal{H}_{a,2} &= \oint_{\mathbb{S}^1} dx h_{a,2}(x) = \oint_{\mathbb{S}^1} dx \left(\frac{1}{2} \sum_{c \neq a} \frac{\langle S^a S^c \rangle}{(z_a - z_c)^2} - \frac{1}{4} \left\langle \left(\sum_{c \neq a} \frac{S^c}{z_a - z_c} \right)^2 \right\rangle + \frac{1}{8\lambda_a^2} \left(\sum_{c \neq a} \frac{\langle S^a S^c \rangle}{z_a - z_c} \right)^2 \right. \\
&\quad \left. - \frac{k}{4\lambda_a^2} \sum_{c \neq a} \frac{\langle S^c \partial_x S^a S^a \rangle}{z_a - z_c} + \frac{k^2}{16\lambda_a^2} \langle (\partial_x S^a)^2 \rangle \right) = \\
&\quad \oint_{\mathbb{S}^1} dx \left(\tilde{H}_a - \frac{k}{4\lambda_a^2} \sum_{c \neq a} \frac{\langle S^c \partial_x S^a S^a \rangle}{z_a - z_c} + \frac{k^2}{16\lambda_a^2} \langle (\partial_x S^a)^2 \rangle \right)
\end{aligned} \tag{4.43}$$

and in the elliptic case:

$$\mathcal{H}_{a,1} = \oint_{\mathbb{S}^1} dx h_{a,1}(x) = \oint_{\mathbb{S}^1} dx \left(P_a - \frac{1}{2} \sum_{c \neq a} \langle S^a \hat{\varphi}_{ac}(S^c) \rangle \right) = \oint_{\mathbb{S}^1} dx (P_a + H_a), \tag{4.44}$$

$$\begin{aligned}
\mathcal{H}_{a,2} &= \oint_{\mathbb{S}^1} dx h_{a,2}(x) = \oint_{\mathbb{S}^1} dx \left(\frac{1}{4} \langle S^a \hat{\varphi}(S^a) \rangle + \frac{1}{2} \sum_{c \neq a} \langle S^a \hat{F}(S^c) \rangle - \frac{1}{4} \left\langle \left(\sum_{c \neq a} \hat{\varphi}_{ac}(S^c) \right)^2 \right\rangle \right. \\
&\quad \left. + \frac{1}{8\lambda_a^2} \left(\sum_{c \neq a} \langle S^a \hat{\varphi}_{ac}(S^c) \rangle \right)^2 - \frac{k}{4\lambda_a^2} \sum_{c \neq a} \langle \hat{\varphi}_{ac}(S^c) \partial_x S^a S^a \rangle + \frac{k^2}{16\lambda_a^2} \langle (\partial_x S^a)^2 \rangle \right) = \\
&\quad \oint_{\mathbb{S}^1} dx \left(\tilde{H}_a - \frac{k}{4\lambda_a^2} \sum_{c \neq a} \langle \hat{\varphi}_{ac}(S^c) \partial_x S^a S^a \rangle + \frac{k^2}{16\lambda_a^2} \langle (\partial_x S^a)^2 \rangle \right),
\end{aligned} \tag{4.45}$$

where in H_a, \tilde{H}_a from (4.2-4.3) and in (4.15) we assume $S^a = S^a(x)$.

5 Appendix: Elliptic Functions

5.1 Basic Definitions and Properties

We assume that $q = \exp(2\pi i\tau)$, where τ is the modular parameter of the elliptic curve Σ_τ which is realized as \mathbb{C}/Γ_τ , $\Gamma_\tau = \mathbb{Z} \oplus \mathbb{Z}\tau$.

The basic element is the theta function:

$$\vartheta(z|\tau) = q^{\frac{1}{8}} \sum_{n \in \mathbb{Z}} (-1)^n \mathbf{e}\left(\frac{1}{2}n(n+1)\tau + nz\right) = \quad (\mathbf{e} = \exp 2\pi i) \quad (\text{A.1})$$

$$q^{\frac{1}{8}} e^{-\frac{i\pi}{4}} (e^{i\pi z} - e^{-i\pi z}) \prod_{n=1}^{\infty} (1 - q^n)(1 - q^n e^{2i\pi z})(1 - q^n e^{-2i\pi z}).$$

The Eisenstein functions

$$E_1(z|\tau) = \partial_z \log \vartheta(z|\tau), \quad E_1(z|\tau) \sim \frac{1}{z} - 2\eta_1 z, \quad (\text{A.2})$$

where

$$\eta_1(\tau) = \frac{3}{\pi^2} \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty'} \frac{1}{(m\tau + n)^2} = \frac{24}{2\pi i} \frac{\eta'(\tau)}{\eta(\tau)} \quad (\text{A.3})$$

and $\eta(\tau) = q^{\frac{1}{24}} \prod_{n>0} (1 - q^n)$ is the Dedekind function.

$$E_2(z|\tau) = -\partial_z E_1(z|\tau) = \partial_z^2 \log \vartheta(z|\tau), \quad E_2(z|\tau) \sim \frac{1}{z^2} + 2\eta_1. \quad (\text{A.4})$$

The higher Eisenstein functions

$$E_j(z) = \frac{(-1)^j}{(j-1)!} \partial^{(j-2)} E_2(z), \quad (j > 2). \quad (\text{A.5})$$

It is easy to see that the even-numbered functions are even and the odd-numbered ones are odd:

$$E_{2k}(-z) = E_{2k}(z), \quad E_{2k+1}(-z) = -E_{2k+1}(z) \quad (\text{A.6})$$

Relation to the Weierstrass functions

$$\zeta(z, \tau) = E_1(z, \tau) + 2\eta_1(\tau)z, \quad (\text{A.7})$$

$$\wp(z, \tau) = E_2(z, \tau) - 2\eta_1(\tau). \quad (\text{A.8})$$

The next important function is

$$\phi(u, z) = \frac{\vartheta(u+z)\vartheta'(0)}{\vartheta(u)\vartheta(z)}. \quad (\text{A.9})$$

$$\phi(u, z) = \phi(z, u), \quad \phi(-u, -z) = -\phi(u, z). \quad (\text{A.10})$$

It has a pole at $z = 0$ and

$$\phi(u, z) = \frac{1}{z} + E_1(u) + \frac{z}{2}(E_1^2(u) - \wp(u)) + \dots \quad (\text{A.11})$$

Let $f(u, z) = \partial_u \phi(u, z)$. Then

$$f(u, z) = \phi(u, z)(E_1(u+z) - E_1(u)). \quad (\text{A.12})$$

Heat equation

$$\partial_\tau \phi(u, w) - \frac{1}{2\pi i} \partial_u \partial_w \phi(u, w) = 0. \quad (\text{A.13})$$

Quasi-periodicity

$$\vartheta(z+1) = -\vartheta(z), \quad \vartheta(z+\tau) = -q^{-\frac{1}{2}} e^{-2\pi i z} \vartheta(z), \quad (\text{A.14})$$

$$E_1(z+1) = E_1(z), \quad E_1(z+\tau) = E_1(z) - 2\pi i, \quad (\text{A.15})$$

$$E_2(z+1) = E_2(z), \quad E_2(z+\tau) = E_2(z), \quad (\text{A.16})$$

$$\phi(u, z+1) = \phi(u, z), \quad \phi(u, z+\tau) = e^{-2\pi i u} \phi(u, z). \quad (\text{A.17})$$

$$f(u, z+1) = f(u, z), \quad f(u, z+\tau) = e^{-2\pi i u} f(u, z) - 2\pi i \phi(u, z). \quad (\text{A.18})$$

The Fay three-section formula:

$$\phi(u_1, z_1) \phi(u_2, z_2) - \phi(u_1 + u_2, z_1) \phi(u_2, z_2 - z_1) - \phi(u_1 + u_2, z_2) \phi(u_1, z_1 - z_2) = 0. \quad (\text{A.19})$$

Particular case of this formula is the Calogero functional equation

$$\phi(u, z) \partial_v \phi(v, z) - \phi(v, z) \partial_u \phi(u, z) = (E_2(u) - E_2(v)) \phi(u+v, z), \quad (\text{A.20})$$

$$\phi(u, z) \phi(-u, z) = E_2(z) - E_2(u). \quad (\text{A.21})$$

$$\phi(z, u_1) \phi(z, u_2) = \phi(z, u_1 + u_2) (E_1(z) + E_1(u_1) + E_1(u_2) - E_1(z + u_1 + u_2)) \quad (\text{A.22})$$

Another important relation is

$$\phi(v, z-w) \phi(u_1 - v, z) \phi(u_2 + v, w) - \phi(u_1 - u_2 - v, z-w) \phi(u_2 + v, z) \phi(u_1 - v, w) = \quad (\text{A.23})$$

$$\phi(u_1, z) \phi(u_2, w) f(u_1, u_2, v),$$

where

$$f(u_1, u_2, v) = E_1(v) - E_1(u_1 - u_2 - v) + E_1(u_1 - v) - E_1(u_2 + v). \quad (\text{A.24})$$

Taking limit $u_2 \rightarrow 0$ in (A.23) we obtain:

$$\begin{aligned} \phi(v, z-w) \phi(u_1 - v, z) \phi(v, w) - \phi(u_1 - v, z-w) \phi(v, z) \phi(u_1 - v, w) = \\ \phi(u_1, z) (E_2(v) - E_2(u_1 - v)), \end{aligned} \quad (\text{A.25})$$

which is equivalent to (A.20) due to (A.12).

Theta functions with characteristics:

For $a, b \in \mathbb{Q}$ by definition:

$$\theta \left[\begin{array}{c} a \\ b \end{array} \right] (z, \tau) = \sum_{j \in \mathbb{Z}} \mathbf{e} \left((j+a)^2 \frac{\tau}{2} + (j+a)(z+b) \right).$$

In particular, the function ϑ (A.1) is a theta function with characteristics:

$$\vartheta(x, \tau) = \theta \left[\begin{array}{c} 1/2 \\ 1/2 \end{array} \right] (x, \tau). \quad (\text{A.26})$$

Properties:

$$\begin{aligned} \theta \left[\begin{array}{c} a \\ b \end{array} \right] (z+1, \tau) &= \mathbf{e}(a) \theta \left[\begin{array}{c} a \\ b \end{array} \right] (z, \tau), \\ \theta \left[\begin{array}{c} a \\ b \end{array} \right] (z+a'\tau, \tau) &= \mathbf{e} \left(-a'^2 \frac{\tau}{2} - a'(z+b) \right) \theta \left[\begin{array}{c} a+a' \\ b \end{array} \right] (z, \tau), \\ \theta \left[\begin{array}{c} a+j \\ b \end{array} \right] (z, \tau) &= \theta \left[\begin{array}{c} a \\ b \end{array} \right] (z, \tau), \quad j \in \mathbb{Z}. \end{aligned}$$

The following notations are used: $\theta \left[\begin{array}{c} a/2 \\ b/2 \end{array} \right] (z) = \theta_{ab}(z)$. Then $\theta_{11}(z) = \vartheta(z)$ from (A.1).

5.2 Lie Algebra $\mathfrak{sl}(N, \mathbb{C})$ and Elliptic Functions

Introduce the notation

$$\mathbf{e}_N(z) = \exp\left(\frac{2\pi i}{N}z\right)$$

and two matrices

$$Q = \text{diag}(\mathbf{e}_N(1), \dots, \mathbf{e}_N(m), \dots, 1) \quad (\text{B.1})$$

$$\Lambda = \begin{pmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \\ 1 & 0 & 0 & \cdots & 0 \end{pmatrix}. \quad (\text{B.2})$$

Let

$$\Gamma_N = \mathbb{Z}_N^{(2)} = (\mathbb{Z}/N\mathbb{Z} \oplus \mathbb{Z}/N\mathbb{Z}), \quad \Gamma'_N = \tilde{\mathbb{Z}}_N^{(2)} = \mathbb{Z}_N^{(2)} \setminus (0, 0) \quad (\text{B.3})$$

be the two-dimensional lattices of orders N^2 and $N^2 - 1$ correspondingly. The generators of the lattice Γ_N corresponding to the elliptic curve Σ_τ (generated by the lattice Γ_τ) are $\frac{1}{N}$ and $\frac{1}{\tau}$. The matrices $Q^{a_1} \Lambda^{a_2}$, $a = (a_1, a_2) \in \mathbb{Z}_N^{(2)}$ generate a basis in the group $\text{GL}(N, \mathbb{C})$, while $Q^{\alpha_1} \Lambda^{\alpha_2}$, $\alpha = (\alpha_1, \alpha_2) \in \tilde{\mathbb{Z}}_N^{(2)}$ generate a basis in the Lie algebra $\mathfrak{sl}(N, \mathbb{C})$. Consider the projective representation of $\mathbb{Z}_N^{(2)}$ in $\text{GL}(N, \mathbb{C})$

$$a \rightarrow T_a = \mathbf{e}_N\left(\frac{a_1 a_2}{2}\right) Q^{a_1} \Lambda^{a_2}, \quad (\text{B.4})$$

$$T_a T_b = \mathbf{e}_N\left(-\frac{a \times b}{2}\right) T_{a+b}, \quad (a \times b = a_1 b_2 - a_2 b_1) \quad (\text{B.5})$$

The natural Killing form is

$$\langle T_\alpha T_\beta \rangle \stackrel{\text{def}}{=} \text{Tr}(T_\alpha T_\beta) = N \delta_{0, \alpha+\beta} \text{ mod } \Gamma_N \quad (\text{B.6})$$

It follows from (B.5) that

$$[T_\alpha, T_\beta] = c_{\alpha, \beta} T_{\alpha+\beta}, \quad (\text{B.7})$$

where

$$c_{\alpha,\beta} = 2\sqrt{-1} \sin \frac{\pi}{N} (\alpha \times \beta) \quad (\text{B.8})$$

are the structure constants of $\mathfrak{sl}(N, \mathbb{C})$. They obey the following properties:

$$\begin{aligned} c_{\alpha,\beta} &= c_{\alpha,\beta+\alpha} \\ c_{\alpha,\beta} &= -c_{\beta,\alpha} = c_{\beta,-\alpha} \end{aligned} \quad (\text{B.9})$$

Introduce the following constants on $\tilde{\mathbb{Z}}^{(2)}$:

$$\vartheta(\omega_\gamma) = \vartheta\left(\frac{\gamma_1 + \gamma_2\tau}{N}\right), \quad (\text{B.10})$$

$$E_1(\omega_\gamma) = E_1\left(\frac{\gamma_1 + \gamma_2\tau}{N}\right), \quad E_2(\omega_\gamma) = E_2\left(\frac{\gamma_1 + \gamma_2\tau}{N}\right), \quad \wp(\omega_\gamma) = \wp\left(\frac{\gamma_1 + \gamma_2\tau}{N}\right) \quad (\text{B.11})$$

and the quasi-periodic functions on Σ_τ

$$\phi_\gamma(z) = \phi\left(\frac{\gamma_1 + \gamma_2\tau}{N}, z\right), \quad (\text{B.12})$$

$$\varphi_\gamma(z) = \mathbf{e}_N(\gamma_2 z) \phi_\gamma(z), \quad (\text{B.13})$$

$$f_\gamma(z) = \mathbf{e}_N(\gamma_2 z) \partial_u \phi(u, z)|_{u=\frac{\gamma_1 + \gamma_2\tau}{N}} = \varphi_\gamma(z) (E_1(\omega_\gamma + z) - E_1(\omega_\gamma)), \quad (\text{B.14})$$

$$F_\gamma(z) = \varphi_\gamma(z) E_1(z) - f_\gamma(z) = \varphi_\gamma(z) (E_1(z) + E_1(\omega_\gamma) - E_1(\omega_\gamma + z)). \quad (\text{B.15})$$

Function $\varphi_\gamma(z)$ is an element of the basis in the space of sections with a simple pole at $z = 0$ of the bundle $\text{End}(V)$ for the holomorphic vector bundle V of degree 1. It follows from (A.9) that

$$\varphi_\gamma(z+1) = \mathbf{e}_N(\gamma_2) \varphi_\gamma(z), \quad \varphi_\gamma(z+\tau) = \mathbf{e}_N(-\gamma_1) \varphi_\gamma(z) \quad (\text{B.16})$$

$$f_\gamma(z+1) = \mathbf{e}_N(\gamma_2) f_\gamma(z), \quad f_\gamma(z+\tau) = \mathbf{e}_N(-\gamma_1) f_\gamma(z) - 2\pi i \varphi_\gamma(z) \quad (\text{B.17})$$

$$F_\gamma(z+1) = \mathbf{e}_N(\gamma_2) F_\gamma(z), \quad F_\gamma(z+\tau) = \mathbf{e}_N(-\gamma_1) F_\gamma(z) \quad (\text{B.18})$$

Function $F_\gamma(z)$ is the quasi-periodic and has the second order pole at $z = 0$.

Let us write down the Fay-type formulae. It follows from (A.19-A.22) that

$$\varphi_\gamma(z - z_a) \varphi_\beta(z - z_c) \stackrel{(\text{A.19})}{=} \varphi_{\beta+\gamma}(z - z_a) \varphi_\beta(z_a - z_c) + \varphi_{\beta+\gamma}(z - z_c) \varphi_\gamma(z_c - z_a) \quad (\text{B.19})$$

$$\varphi_\beta(z) f_\gamma(z) - \varphi_\gamma(z) f_\beta(z) \stackrel{(\text{A.20})}{=} \varphi_{\beta+\gamma}(z) (\wp(\omega_\beta) - \wp(\omega_\gamma)) \quad (\text{B.20})$$

$$\varphi_\alpha(z) \varphi_{-\alpha}(z) \stackrel{(\text{A.21})}{=} \wp(z) - \wp(\omega_\alpha) \quad (\text{B.21})$$

$$\varphi_\beta(z) \varphi_\gamma(z) \stackrel{(\text{A.22})}{=} \varphi_{\beta+\gamma}(z) (E_1(z) + E_1(\omega_\beta) + E_1(\omega_\gamma) - E_1(z + \omega_\beta + \omega_\gamma)), \quad (\text{B.22})$$

$$\varphi_\gamma(z_1) \varphi_\gamma(z_2) \stackrel{(\text{A.22})}{=} \varphi_\gamma(z_1 + z_2) (E_1(z_1) + E_1(z_2) + E_1(\omega_\gamma) - E_1(z_1 + z_2 + \omega_\gamma))$$

The last one identity can be also rewritten (using (A.10) which is $\varphi_\gamma(-z) = -\varphi_{-\gamma}(z)$ and (A.6)) as follows:

$$\varphi_\gamma(z_1) \varphi_{-\gamma}(z_2) = -\varphi_\gamma(z_1 - z_2) (E_1(z_1) - E_1(z_2) + E_1(\omega_\gamma) - E_1(z_1 - z_2 + \omega_\gamma))$$

We also need the following relation:

$$\begin{aligned} & -\varphi_\beta(z - z_c) f_\gamma(z - z_a) + \varphi_\gamma(z - z_a) f_\beta(z - z_c) = \\ & -\varphi_{\beta+\gamma}(z - z_c) f_\gamma(z_c - z_a) + \varphi_{\beta+\gamma}(z - z_a) f_\beta(z_a - z_c) \end{aligned} \quad (\text{B.23})$$

α	(1,0)	(0,1)	(1,1)
σ_α	σ_3	σ_1	σ_2
half-periods	$\omega_1 = \frac{1}{2}$	$\omega_2 = \frac{\tau}{2}$	$\omega_3 = \frac{1+\tau}{2}$
$\varphi_\alpha(z)$	$\frac{\theta_2(z)\theta'_1(0)}{\theta_2(0)\theta_1(z)}$	$\frac{\theta_4(z)\theta'_1(0)}{\theta_4(0)\theta_1(z)}$	$\frac{\theta_3(z)\theta'_1(0)}{\theta_3(0)\theta_1(z)}$

5.3 Lie Algebra $\mathfrak{sl}(2, \mathbb{C})$ and Elliptic Functions

For $\mathrm{SL}(2, \mathbb{C})$ instead of T_α we use the basis of sigma-matrices

$$\sigma_0 = Id, \quad \sigma_1 = T_{0,1}, \quad \sigma_2 = T_{1,1}, \quad \sigma_3 = -T_{1,0}, \quad (\text{C.1})$$

$$\{\sigma_a\} = \{\sigma_0, \sigma_\alpha\}, \quad (a = 0, \alpha), \quad (\alpha = 1, 2, 3)$$

$$\sigma_+ = \frac{\sigma_1 - \iota\sigma_2}{2}, \quad \sigma_- = \frac{\sigma_1 + \iota\sigma_2}{2}.$$

The standard theta-functions with the characteristics are

$$\theta_{0,0} = \theta_3, \quad \theta_{1,0} = \theta_2, \quad \theta_{0,1} = \theta_4, \quad \theta_{1,1} = \theta_1. \quad (\text{C.2})$$

For $\alpha = 1, 2, 3$ and $\{\omega_\alpha\} = \{\frac{\tau}{2}, \frac{\tau+1}{2}, \frac{1}{2}\}$

$$\varphi_\alpha(z) = \mathbf{e}(z\partial_\tau\omega_\alpha) \frac{\vartheta'(0)\vartheta(z+\omega_\alpha)}{\vartheta(z)\vartheta(\omega_\alpha)} \quad (\text{C.3})$$

In $\mathfrak{sl}(2, \mathbb{C})$ case some more properties appear in addition to the previously listed. In what follows α, β, γ are different indices equivalent to 1, 2, 3 up to a cyclic permutation. Then $\omega_\alpha + \omega_\beta = \omega_\gamma \bmod \Gamma_2$ and $\varphi_{\alpha+\beta}(z) = \varphi_\gamma(z)$.

$$\varphi_{-\alpha}(z) = \varphi_\alpha(z), \quad \varphi_\alpha(-z) = -\varphi_\alpha(z) \quad (\text{C.4})$$

$$E_1(\omega_\alpha) = -2\pi\sqrt{-1}\partial_\tau\omega_\alpha \quad (\text{C.5})$$

Indeed, from (A.6) and (A.15) we have $-E_1(\frac{\tau}{2}) = E_1(\frac{\tau}{2} - \tau) = E_1(\frac{\tau}{2}) + 2\pi\sqrt{-1}$. Then

$$E_1(\omega_\alpha) + E_1(\omega_\beta) = E_1(\omega_\alpha + \omega_\beta) \quad (\text{C.6})$$

$$(\varphi_\alpha(z))^2 = \wp(z) - \wp(\omega_\alpha) \quad (\text{C.7})$$

For small z :

$$\varphi_\alpha(z) = \frac{1}{z} - \frac{z}{2}\wp(\omega_\alpha) + \dots$$

From (C.6) we also have

$$F_\alpha(z) = \varphi_\beta(z)\varphi_\gamma(z) = -\partial_z\varphi_\alpha(z) \quad (\text{C.8})$$

The Fay identity (A.19) reads:

$$\varphi_\gamma(z - z_a)\varphi_\beta(z - z_c) = \varphi_\alpha(z - z_a)\varphi_\beta(z_a - z_c) - \varphi_\alpha(z - z_c)\varphi_\gamma(z_a - z_c) \quad (\text{C.9})$$

Combining (C.9) we may get:

$$\begin{aligned} \varphi_\beta(z-z_c)\varphi_\beta(z-z_a)\varphi_\alpha(z-z_a) &= \varphi_\beta(z-z_a)\varphi_\gamma(z-z_a)\varphi_\beta(z_a-z_c)+ \\ \varphi_\alpha(z-z_c)\varphi_\alpha(z_c-z_a)\varphi_\beta(z_c-z_a) &- \varphi_\alpha(z-z_a)\varphi_\alpha(z_c-z_a)\varphi_\gamma(z_c-z_a) \end{aligned} \quad (\text{C.10})$$

or

$$\begin{aligned} \varphi_\gamma(z-z_c)\varphi_\alpha(z-z_a)\varphi_\gamma(z-z_a) &= \varphi_\beta(z-z_a)\varphi_\gamma(z-z_a)\varphi_\gamma(z_a-z_c)+ \\ \varphi_\alpha(z-z_a)\varphi_\alpha(z_c-z_a)\varphi_\beta(z_a-z_c) &- \varphi_\alpha(z-z_c)\varphi_\alpha(z_c-z_a)\varphi_\gamma(z_a-z_c) \end{aligned} \quad (\text{C.11})$$

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