

**CONCENTRATION ON CIRCLES FOR NONLINEAR
SCHRÖDINGER-POISSON SYSTEMS WITH UNBOUNDED
POTENTIALS VANISHING AT INFINITY**

DENIS BONHEURE, JONATHAN DI COSMO, AND CARLO MERCURI

ABSTRACT. The present paper is devoted to weighted Nonlinear Schrödinger- Poisson systems with potentials possibly unbounded and vanishing at infinity. Using a purely variational approach, we prove the existence of solutions concentrating on a circle.

1. INTRODUCTION

The aim of the present paper is to study of the behavior of a certain class of solutions for the following nonlinear Schrödinger-Poisson system

$$\begin{cases} -\varepsilon^2 \Delta u + V(x)u + \rho(x)\phi u = K(x)u^p, & x \in \mathbb{R}^3, \\ -\Delta \phi = \rho(x)u^2, \end{cases} \quad (1)$$

in the semiclassical limit, namely for $\varepsilon \rightarrow 0$, where ε stands for the reduced Planck constant \hbar . In particular, we focus on solutions concentrating on a circle.

Let us choose any 1-dimensional linear subspace $d \subset \mathbb{R}^3$. We denote by π the orthogonal complement of d . If $x \in \mathbb{R}^3$, we will write $x = (x', x'')$ with $x' \in d$ and $x'' \in \pi$.

As a particular case of our main result, we have the following theorem:

Theorem 1. *Let $p > 3$ and $V \in C(\mathbb{R}^3 \setminus \{0\}, \mathbb{R}^+)$ be a radial potential. Write $V(x) = \tilde{V}(x', |x''|)$. If there exists $r^* > 0$ such that the function*

$$\mathcal{M}(r) := r \left[\tilde{V}(0, r) \right]^{\frac{2}{p-1}}$$

has an isolated local minimum at $r = r^$ such that $\mathcal{M}(r^*) > 0$, then for ε small enough, the system*

$$\begin{cases} -\varepsilon^2 \Delta u + V(x)u + \phi u = u^p, & x \in \mathbb{R}^3, \\ -\Delta \phi = u^2, \end{cases}$$

has a positive cylindrically symmetric solution u_ε that concentrates on the circle of radius r^ centered at the origin and contained in the plane π .*

We point out that we have no assumption about the decay of V at infinity. In particular, V could be compactly supported. This is an improvement on previous works, see e.g. [1].

A fundamental physical problem arises from the correspondence principle, according to which quantum mechanics contains classical mechanics as $\hbar \rightarrow 0$. In the framework of the Schrödinger equation with Coulomb potential one can construct solutions which are localized around classical Keplerian elliptic orbits by superposition of states of minimal quantum fluctuation (coherent states), see [9, 15]. Due to the dispersive nature of the Schrödinger equation, a rigorous reduction to classical mechanics cannot in general be performed. By introducing a local nonlinear homogeneous term u^p , in [4], the authors prove the existence of solutions for the 2D nonlinear Schrödinger equation with radial potential, concentrating on a circle. In the case of radial potentials, due to the invariance by rotations, the classical and quantum angular momentum are conserved as indicated by

Date: September 15, 2010.

2000 Mathematics Subject Classification. 35J20 (35B65, 35J60, 35Q55).

Key words and phrases. Stationary nonlinear Schrödinger-Poisson system; weighted Sobolev spaces; degenerate potentials.

Jonathan Di Cosmo is a research fellow of the Fonds de la Recherche Scientifique-FNRS.

Noether's Theorem. This suggests that the solutions concentrating on Keplerian orbits are suitable candidates in order to mimic, in the semi-classical limit, the classical dynamics described by Newton's equations. In [8], the existence of solutions concentrating on circles has been obtained for the 3D nonlinear Schrödinger equation with cylindrically symmetric potential. In both [4, 8] the underlying idea is to find solutions with nonzero angular momentum. By a different method in [7] and [5] the existence of solutions concentrating on points and, respectively, on k -spheres has been obtained for the nonlinear Schrödinger equation. In particular, in [5] the existence of solutions concentrating on a circle has been obtained when radial symmetry occurs, as in Theorem 1. Our aim is to extend [7, 5] to the nonlinear Schrödinger-Poisson system.

Now we describe our assumptions.

1.1. The potentials. We consider a nonnegative potential $V \in C(\mathbb{R}^3 \setminus \{0\})$, a non-negative competing function $K \in C(\mathbb{R}^3 \setminus \{0\})$, $K \not\equiv 0$, and a weight $\rho \in L_{\text{loc}}^{3/2}(\mathbb{R}^3) \cap L_{\text{loc}}^\infty(\mathbb{R}^3 \setminus \{0\})$. We assume that for every $R \in \mathbf{O}(3)$ such that $R(d) = d$, we have $V \circ R = V$, $K \circ R = K$ and $\rho \circ R = \rho$. This will be the case if for example V , K and ρ are radial functions.

1.2. The nonlinearity. We consider, for simplicity, a homogeneous nonlinear term u^p with $3 < p < \infty$. The condition $p > 3$ will be needed in order to ensure the boundedness of Palais-Smale sequences.

1.3. The growth conditions. Let

$$W(x) := V(x) + \frac{\rho(x)}{1 + |x|}.$$

Following [7, 13] we impose one of the three sets of growth conditions at infinity :

(\mathcal{G}_∞^1) there exists $\sigma < p - 3$ such that

$$\limsup_{|x| \rightarrow \infty} \frac{K(x)}{|x|^\sigma} < \infty;$$

(\mathcal{G}_∞^2) there exists $\sigma \in \mathbb{R}$ such that

$$\liminf_{|x| \rightarrow \infty} W(x)|x|^2 > 0 \quad \text{and} \quad \limsup_{|x| \rightarrow \infty} \frac{K(x)}{|x|^\sigma} < \infty;$$

(\mathcal{G}_∞^3) there exist $\alpha < 2$ and $\sigma \in \mathbb{R}$ such that

$$\liminf_{|x| \rightarrow \infty} W(x)|x|^\alpha > 0 \quad \text{and} \quad \limsup_{|x| \rightarrow \infty} \frac{K(x)}{\exp(\sigma|x|^{\frac{2-\alpha}{2}})} < \infty.$$

Note that in comparison with [7], in (\mathcal{G}_∞^2) and (\mathcal{G}_∞^3), V might vanish somewhere. We also impose one of the three sets of growth conditions at the origin, which mirror those at infinity :

(\mathcal{G}_0^1) there exists $\tau > -2$, such that

$$\limsup_{|x| \rightarrow 0} \frac{K(x)}{|x|^\tau} < \infty,$$

(\mathcal{G}_0^2) there exists $\tau \in \mathbb{R}$ such that

$$\liminf_{|x| \rightarrow 0} V(x)|x|^2 > 0 \quad \text{and} \quad \limsup_{|x| \rightarrow 0} \frac{K(x)}{|x|^\tau} < \infty;$$

(\mathcal{G}_0^3) there exist $\gamma > 2$ and $\tau \in \mathbb{R}$ such that

$$\liminf_{|x| \rightarrow 0} V(x)|x|^\gamma > 0 \quad \text{and} \quad \limsup_{|x| \rightarrow 0} \frac{K(x)}{\exp(\tau|x|^{-\frac{\gamma-2}{2}})} < \infty.$$

1.4. **The auxiliary potential.** Before we can state our last assumption, we need a few preliminaries. Let $a, b > 0$. We consider the *limit equation*

$$-\Delta u + au = bu^p \quad \text{in } \mathbb{R}^2. \quad (2)$$

The weak solutions of (2) are critical points of the functional $\mathcal{I}_{a,b} : H^1(\mathbb{R}^2) \rightarrow \mathbb{R}$ defined by

$$\mathcal{I}_{a,b}(u) := \frac{1}{2} \int_{\mathbb{R}^2} (|\nabla u|^2 + au^2) dx - \frac{b}{p+1} \int_{\mathbb{R}^2} u^{p+1} dx. \quad (3)$$

Any nontrivial critical point $u \in H^1(\mathbb{R}^2)$ of $\mathcal{I}_{a,b}$, belongs to the Nehari manifold

$$\mathcal{N}_{a,b} := \{u \in H^1(\mathbb{R}^2) \mid u \neq 0 \text{ and } \langle \mathcal{I}'_{a,b}(u), u \rangle = 0\}.$$

A solution $u \in H^1(\mathbb{R}^2)$ is a *least-energy solution* of (2) if

$$\mathcal{I}_{a,b}(u) = \inf_{v \in \mathcal{N}_{a,b}} \mathcal{I}_{a,b}(v).$$

The *ground-energy function* is defined by

$$\mathcal{E} : \mathbb{R}^+ \times \mathbb{R}^+ \rightarrow \mathbb{R}^+ : (a, b) \mapsto \mathcal{E}(a, b) := \inf_{u \in \mathcal{N}_{a,b}} \mathcal{I}_{a,b}(u).$$

It is standard to show that

$$\mathcal{E}(a, b) = \inf_{\gamma \in \Gamma_{a,b}} \max_{t \in [0,1]} \mathcal{I}_{a,b}(\gamma(t)), \quad (4)$$

where

$$\Gamma_{a,b} := \{\gamma \in C([0, 1], H^1(\mathbb{R}^2)) \mid \gamma(0) = 0, \mathcal{I}_{a,b}(\gamma(1)) < 0\}.$$

The *auxiliary potential* $\mathcal{M} : \mathbb{R}^3 \rightarrow (0, +\infty]$ is defined by

$$(x', x'') \mapsto \mathcal{M}(x', x'') := \begin{cases} |x''| \mathcal{E}(V(x), K(x)) & \text{if } K(x) > 0, \\ +\infty & \text{if } K(x) = 0. \end{cases}$$

The following lemma states some properties of the ground-energy function, see [7, Lemma 3].

Lemma 1.1. *For every $(a, b) \in \mathbb{R}_0^+ \times \mathbb{R}_0^+$, $\mathcal{E}(a, b)$ is a critical value of $\mathcal{I}_{a,b}$ and we have*

$$\mathcal{E}(a, b) = \inf_{\substack{u \in H^1(\mathbb{R}^2) \\ u \neq 0}} \max_{t \geq 0} \mathcal{I}_{a,b}(tu).$$

If $u \in \mathcal{N}_{a,b}$ and $\mathcal{E}(a, b) = \mathcal{I}_{a,b}(u)$, then $u \in C^1(\mathbb{R}^2)$ and up to a translation, u is a radial function such that $\nabla u(x) \cdot x < 0$ for every $x \in \mathbb{R}^2 \setminus \{0\}$. Moreover, the following properties hold:

- (i) \mathcal{E} is continuous in $\mathbb{R}_0^+ \times \mathbb{R}_0^+$;
- (ii) for every $b^* \in \mathbb{R}_0^+$, $a \rightarrow \mathcal{E}(a, b^*)$ is strictly increasing;
- (iii) for every $a^* \in \mathbb{R}_0^+$, $b \rightarrow \mathcal{E}(a^*, b)$ is strictly decreasing;
- (iv) for every $\lambda > 0$, $\mathcal{E}(\lambda a, \lambda b) = \lambda^{-1/2} \mathcal{E}(a, b)$;
- (v) the ground-energy function satisfies

$$\mathcal{E}(a, b) = \mathcal{E}(1, 1) a^{\frac{p+1}{p-1}-1} b^{-\frac{2}{p-1}}.$$

The last property of the preceding lemma implies the following explicit form of the auxiliary potential:

$$\mathcal{M}(x', x'') = \mathcal{E}(1, 1) |x''| [V(x)]^{\frac{p+1}{p-1}-1} [K(x)]^{\frac{-2}{p-1}}.$$

Due to the symmetry that we shall impose on the solution (see (14)), the concentration can only occur in the plane π . We assume that there exists a smooth bounded open set $\Lambda \subset \mathbb{R}^3$ such that

$$\bar{\Lambda} \cap d = \emptyset, \quad \Lambda \cap \pi \neq \emptyset, \quad (5)$$

for every $R \in \mathbf{O}(3)$ such that $R(d) = d$,

$$R(\Lambda) = \Lambda \quad (6)$$

and the following inequalities hold

$$0 < \inf_{\Lambda \cap \pi} \mathcal{M} < \inf_{\partial \Lambda \cap \pi} \mathcal{M}, \quad (7)$$

$$\inf_{\Lambda \cap \pi} \mathcal{M} < 2 \inf_{\Lambda} \mathcal{M}. \quad (8)$$

By continuity of \mathcal{M} in Λ , this last condition is not restrictive. Similarly, we can also assume that $V > 0$ on $\overline{\Lambda}$ and that \mathcal{M} is continuous on $\overline{\Lambda}$.

Our main result is the following.

Theorem 2. *Let $p > 3$ and V, K and ρ be functions satisfying the assumptions in 1.1. Assume that one set (\mathcal{G}_∞^i) of growth conditions at infinity and one set (\mathcal{G}_0^j) of growth conditions at the origin hold. Assume also that there exists an open bounded set $\Lambda \subset \mathbb{R}^3$ such that (5), (6), (7) and (8) hold. Then there exists $\varepsilon_0 > 0$ such that for every $0 < \varepsilon < \varepsilon_0$, problem (1) has at least one positive solution u_ε . Moreover, for every $0 < \varepsilon < \varepsilon_0$, there exists $x_\varepsilon \in \Lambda \cap \pi$ such that u_ε attains its maximum at x_ε ,*

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0, \quad \lim_{\varepsilon \rightarrow 0} \mathcal{M}(x_\varepsilon) = \inf_{\Lambda \cap \pi} \mathcal{M},$$

and there exist $C > 0$ and $\lambda > 0$ such that

$$u_\varepsilon(x) \leq C \exp\left(-\frac{\lambda}{\varepsilon} \frac{d(x, S_\varepsilon^1)}{1 + d(x, S_\varepsilon^1)}\right) (1 + |x|^2)^{-\frac{1}{2}}, \quad \forall x \in \mathbb{R}^3,$$

where S_ε^1 is the circle centered at the origin, contained in the plane π and of radius $|x_\varepsilon''|$.

In Section 2, we deal with an auxiliary penalized problem. This by now classical penalization argument goes back to del Pino and Felmer [10]. The method has then been adapted in [7, 13] in the frame of vanishing or compactly supported potentials. Section 3 is devoted to the asymptotic analysis of the solutions of the penalized problem while in Section 4, we show how to go back to the original problem. At last, we give some final comments in Section 5. Throughout the paper, we use the following notation :

- $\mathcal{D}^{1,2}(\mathbb{R}^3)$ is the space

$$\{u \in L^{2^*}(\mathbb{R}^3) : \nabla u \in L^2(\mathbb{R}^3; \mathbb{R}^3)\}$$

equipped with the norm

$$\|u\|_{\mathcal{D}^{1,2}(\mathbb{R}^3)} := \|\nabla u\|_{L^2(\mathbb{R}^3)};$$

- $L^q_Q(\mathbb{R}^3)$ is the Lebesgue space of measurable functions such that

$$\int_{\mathbb{R}^3} Q(x) |u|^q dx < \infty.$$

As usual, $u_+ := \max(u, 0)$ and $u_- := \max(-u, 0)$, B_R is the open ball of radius R and $c_1, c_2, \dots, c_j, C_1, C_2, \dots, C_k$ always denote positive real constants.

2. EXISTENCE FOR THE PENALIZED PROBLEM

Following [13] and [5], we define the penalization potential $H : \mathbb{R}^3 \rightarrow \mathbb{R}$ by

$$H(x) := \frac{\kappa}{|x|^2 \left((\log|x|)^2 + 1 \right)^{\frac{1+\beta}{2}}}$$

where $\beta > 0$ and $0 < \kappa < \frac{1}{4}$. Notice that for all $x \in \mathbb{R}^3$, we have

$$H(x) \leq \frac{\kappa}{|x|^2}.$$

By Hardy's inequality, we deduce that the quadratic form associated to $-\Delta - H$ is positive, i.e.

$$\int_{\mathbb{R}^3} (|\nabla u|^2 - H u^2) \geq \left(\frac{1}{4} - \kappa\right) \int_{\mathbb{R}^3} \frac{|u(x)|^2}{|x|^2} dx \geq 0, \quad (9)$$

for all $u \in \mathcal{D}^{1,2}(\mathbb{R}^3)$.

This inequality implies the following comparison principle.

Proposition 2.1. *Let $\Omega \subset \mathbb{R}^3 \setminus \{0\}$ be a smooth domain. Let $v, w \in H_{loc}^1(\Omega) \cap C(\overline{\Omega})$ be such that $\nabla(w - v)_- \in L^2(\Omega)$, $(w - v)_-/|x| \in L^2(\Omega)$ and*

$$-\Delta w - Hw \geq -\Delta v - Hv, \quad \forall x \in \Omega. \quad (10)$$

If $\partial\Omega \neq \emptyset$, assume also that $w \geq v$ on $\partial\Omega$. Then $w \geq v$ in Ω .

Proof. It suffices to multiply the inequality (10) by $(w - v)_-$, integrate by parts and use (9). \square

Fix $\mu \in (0, 1)$. We define the penalized nonlinearity $g_\varepsilon : \mathbb{R}^3 \times \mathbb{R} \rightarrow \mathbb{R}$ by

$$g_\varepsilon(x, s) := \chi_\Lambda(x)K(x)s_+^p + (1 - \chi_\Lambda(x)) \min \{ (\varepsilon^2 H(x) + \mu V(x)) s_+, K(x)s_+^p \}.$$

Let $G_\varepsilon(x, s) := \int_0^s g_\varepsilon(x, \sigma) d\sigma$. One can check that g_ε is a Carathéodory function with the following properties :

- (g₁) $g_\varepsilon(x, s) = o(s)$, $s \rightarrow 0^+$, uniformly in compact subsets of \mathbb{R}^3 .
- (g₂) there exists $p > 3$ such that

$$\lim_{s \rightarrow \infty} \frac{g_\varepsilon(x, s)}{s^p} = 0,$$

- (g₃) there exists $2 < \theta \leq p + 1$ such that

$$\begin{aligned} 0 < \theta G_\varepsilon(x, s) &\leq g_\varepsilon(x, s)s && \forall x \in \Lambda, \forall s > 0, \\ 0 < 2G_\varepsilon(x, s) &\leq g_\varepsilon(x, s)s \leq (\varepsilon^2 H(x) + \mu V(x)) s^2 && \forall x \notin \Lambda, \forall s > 0, \end{aligned}$$

- (g₄) the function

$$s \mapsto \frac{g_\varepsilon(x, s)}{s}$$

is nondecreasing for all $x \in \mathbb{R}^3$.

Now we use Critical Point Theory in order to find solutions to the penalized problem

$$\begin{cases} -\varepsilon^2 \Delta u + V(x)u + \rho(x)\phi u = g_\varepsilon(x, u), & x \in \mathbb{R}^3, \\ -\Delta \phi = \rho(x)u^2. \end{cases} \quad (11)$$

For any $u^2 \rho \in L_{loc}^1(\mathbb{R}^3)$ such that

$$\int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{u^2(x)u^2(y)\rho(x)\rho(y)}{|x-y|} dx dy < \infty,$$

the standard distributional solution

$$\phi_u := \frac{1}{4\pi|x|} \star u^2 \rho \quad (12)$$

belongs to $\mathcal{D}^{1,2}(\mathbb{R}^3)$ and is a weak solution in $\mathcal{D}^{1,2}$ (e.g. [16]). Since we consider $u \in \mathcal{D}^{1,2}$, we will assume $\rho \in L_{loc}^{3/2}$. A suitable choice of the space X of admissible functions is given in the work of Ruiz [16], in the case of $V \equiv 0$ and $\rho \equiv 1$. Inspired by [16], we define, for measurable $V, \rho \geq 0$,

$$\|u\|_X^2 := \int_{\mathbb{R}^3} |\nabla u|^2 + V(x)u^2 dx + \left(\int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{u^2(x)u^2(y)\rho(x)\rho(y)}{|x-y|} dx dy \right)^{1/2}$$

and

$$X := \{u \in \mathcal{D}^{1,2}(\mathbb{R}^3) : \|u\|_X < \infty\}. \quad (13)$$

As pointed out in [16], the space X is a uniformly convex Banach space, hence it is reflexive. Precisely, we look for solutions $(u, \phi_u) \in E \times \mathcal{D}^{1,2}(\mathbb{R}^3)$.

We also define $H_{V,\varepsilon}$ to be the closure of $\mathcal{D}(\mathbb{R}^3)$ with respect to the norm

$$\|u\|_{H_{V,\varepsilon}}^2 := \int_{\mathbb{R}^3} \varepsilon^2 |\nabla u|^2 + V(x)u^2 dx.$$

We will focus on the closed subspace $E \subset X$ of functions which are radial in π , namely

$$E := \{u \in X \mid \forall R \in \mathbf{O}(3) \text{ s.t. } R(d) = d, u \circ R = u\}. \quad (14)$$

Solutions of (11) are the critical points of the functional

$$J_\varepsilon(u) := \frac{1}{2} \int_{\mathbb{R}^3} (\varepsilon^2 |\nabla u|^2 + V(x)u^2) dx + \frac{1}{4} \int_{\mathbb{R}^3} \phi_u u^2 \rho(x) dx - \int_{\mathbb{R}^3} G_\varepsilon(x, u) dx,$$

which is $C^1(X; \mathbb{R})$.

In the present section we find critical points for J_ε through a minimax scheme used in [6], modeled on [3].

The main result of this section is

Theorem 3. *Assume V, K, ρ satisfy the assumptions of Theorem 2. Then, for any $\varepsilon > 0$ and $\kappa, \mu > 0$ small enough, there exists a critical point for J_ε at level*

$$c_\varepsilon := \inf_{\gamma \in \Gamma} \max_{t \in [0,1]} J_\varepsilon(\gamma(t)), \quad (15)$$

where

$$\Gamma_\varepsilon := \{\gamma \in C([0, 1], E) : \gamma(0) = 0, J_\varepsilon(\gamma(1)) < 0\}, \quad (16)$$

corresponding to a nontrivial solution $(u, \phi) \in E \times \mathcal{D}^{1,2}(\mathbb{R}^3)$ for (11). Moreover u is positive.

Remark 1. Due to the invariance of the Lebesgue measure by rotations, by the symmetric criticality principle [14], if $u \in E$ is critical for $J_\varepsilon|_E$, then u is also critical for $J_\varepsilon|_X$.

The functional J_ε has the mountain pass geometry, as it is shown in the following

Lemma 2.2. *The functional J_ε satisfies the mountain pass geometry for any $p > 3$, provided $\kappa, \mu > 0$ are small enough. Furthermore, there exists a Palais-Smale (P-S) sequence at the minimax level c_ε . In particular, defining*

$$S := \{u \in E : u_- \equiv 0\},$$

$$S_{1/n} := \{u \in E : \inf_{y \in S} \|u - y\|_E < 1/n\},$$

it is possible to select the P-S sequence $(u_n)_n$ in such a way that $u_k \in S_{1/k}$ for all $k \in \mathbb{N}$.

Proof. We first prove that, for any $p > 3$, the origin is a local minimum for J_ε . Notice that $\|u\|_{L_K^{p+1}(\Lambda)}^{p+1} \leq C \|u\|_E^{p+1}$. Furthermore by Lemma 2.3 below, taking $\kappa, \mu > 0$ small enough, we have

$$J_\varepsilon(u) \geq c \int_{\mathbb{R}^3} (\varepsilon^2 |\nabla u|^2 + V(x)u^2) dx + \frac{1}{4} \int_{\mathbb{R}^3} \phi_u u^2 \rho(x) dx - C \|u\|_E^{p+1}.$$

Since, by definition, we have $(\int_{\mathbb{R}^3} \phi_u u^2 \rho(x) dx)^{1/2} = \|u\|_E^2 - \|u\|_{H_{V,\varepsilon}}^2$, we get

$$\begin{aligned} J_\varepsilon(u) &\geq c \|u\|_{H_{V,\varepsilon}}^2 + \frac{1}{4} \left[\|u\|_E^2 - \|u\|_{H_{V,\varepsilon}}^2 \right]^2 - C \|u\|_E^{p+1} \\ &= c \|u\|_{H_{V,\varepsilon}}^2 + \frac{1}{4} \|u\|_E^4 - \frac{1}{2} \|u\|_{H_{V,\varepsilon}}^2 \|u\|_E^2 + \frac{1}{4} \|u\|_{H_{V,\varepsilon}}^4 - C \|u\|_E^{p+1}. \end{aligned}$$

Therefore, we get

$$J_\varepsilon(u) \geq c \|u\|_{H_{V,\varepsilon}}^2 - \frac{\alpha^2 - 1}{4} \|u\|_{H_{V,\varepsilon}}^4 + \frac{\alpha^2 - 1}{4\alpha^2} \|u\|_E^4 - C \|u\|_E^{p+1}.$$

Let $\|u\|_E^2 < \delta$. Then we have

$$J_\varepsilon(u) \geq \left[c - \frac{\alpha^2 - 1}{4} \delta^2 \right] \|u\|_{H_{V,\varepsilon}}^2 + \left[\frac{\alpha^2 - 1}{4\alpha^2} - C \delta^{p-3} \right] \|u\|_E^4.$$

This yields, for $\alpha > 1$ and δ small enough,

$$J_\varepsilon(u) \geq \left[\frac{\alpha^2 - 1}{4\alpha^2} - C \delta^{p-3} \right] \|u\|_E^4.$$

Hence, the origin is a strict local minimum point for J_ε .

Moreover, J_ε attains negative values along curves of the form $u_t := tu$, with $u \in E$ such that $u^+ \not\equiv 0$ and $t > 0$. Hence J_ε has the mountain pass geometry.

By the general minimax principle [18, p.41], there exists a P-S sequence $(u_n)_n$ such that, if for $\gamma_n \in \Gamma$,

$$\max_{t \in [0,1]} J_\varepsilon(\gamma_n(t)) \leq c_\varepsilon + \frac{1}{n},$$

then

$$\text{dist}(u_n, \gamma_n([0, 1])) < \frac{1}{n}. \quad (17)$$

Finally, since $J_\varepsilon(u) = J_\varepsilon(|u|)$, the conclusion follows from (17). \square

Lemma 2.3. *For any positive constants $c > 0$ there exists $\kappa(c)$ such that*

$$c \int_{\mathbb{R}^3} |\nabla u|^2 dx \geq \int_{\mathbb{R}^3 \setminus \Lambda} H(x) u^2 dx, \quad \forall \kappa < \kappa(c), \quad \forall u \in \mathcal{D}^{1,2}(\mathbb{R}^3),$$

Proof. The claim follows directly from Hardy's inequality. \square

We now study some properties of the P-S sequences found in Lemma 2.2.

Lemma 2.4. *Let $(u_n)_n$ be as in Lemma 2.2 such that $u_k \in S_{1/k}$ for all $k \in \mathbb{N}$. Then*

$$(a) \quad \int_{\mathbb{R}^3} \phi_{(u_n)_-}(x) (u_n)_-^2 \rho(x) dx \rightarrow 0.$$

Furthermore, $(u_n)_n$ is bounded in E , provided $\kappa, \mu > 0$ are small enough, and we have

$$(b) \quad \int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_-^2 \rho(x) dx \rightarrow 0.$$

Proof. By definition, there exists a sequence $(y_n)_n \subset S$ such that

$$\|u_n - y_n\|_E \rightarrow 0.$$

Hence (a) follows:

$$\begin{aligned} \int_{\mathbb{R}^3} \phi_{(u_n)_-}(x) (u_n)_-^2 \rho(x) dx &= \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{(u_n)_-^2(x) \rho(x) (u_n)_-^2(z) \rho(z)}{|x-z|} dx dz \\ &\leq \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{(u_n - y_n)^2(x) \rho(x) (u_n - y_n)^2(z) \rho(z)}{|x-z|} dx dz \\ &\leq \|u_n - y_n\|_E^4 \rightarrow 0 \end{aligned}$$

Notice that (b) follows if we prove that $(u_n)_n$ is bounded. Indeed, define, for f, g measurable and nonnegative functions, the following quantity

$$D(f, g) := \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} f(x) |x-y|^{-1} g(y) dx dy.$$

From [11, p.250], we have

$$|D(f, g)|^2 \leq D(f, f) D(g, g). \quad (18)$$

If $(u_n)_n$ is bounded in E , by the inequality above with $f := u_n^2 \rho$ and $g := (u_n)_-^2 \rho$ and by (a) we have

$$\int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_-^2 \rho(x) dx \leq C \int_{\mathbb{R}^3} \phi_{(u_n)_-}(x) (u_n)_-^2 \rho(x) dx \rightarrow 0$$

We now prove that $(u_n)_n$ is bounded.

Define

$$\Delta_n := \int_{\mathbb{R}^3} (g_\varepsilon(x, u_n) u_n - (p+1) G_\varepsilon(x, u_n)) dx$$

Using Lemma 2.3, we have, choosing $\kappa, \mu > 0$ small enough,

$$\begin{aligned} \Delta_n &\geq -(p+1) \int_{\mathbb{R}^3 \setminus \Lambda} G_\varepsilon(x, u_n) dx \\ &\geq -\frac{p+1}{2} \int_{\mathbb{R}^3 \setminus \Lambda} [\varepsilon^2 H(x) + \mu V(x)] u_n^2 dx \\ &\geq -\frac{p-1}{4} \|u_n\|_{H_{V,\varepsilon}}^2. \end{aligned}$$

Since $(u_n)_n$ is a P-S sequence, the above estimate yields

$$\begin{aligned} C &\geq (p+1)J_\varepsilon(u_n) - (J'_\varepsilon(u_n), u_n) \\ &= \frac{p-1}{2}\|u_n\|_{H^{V,\varepsilon}}^2 + \frac{p-3}{4} \int_{\mathbb{R}^3} \phi_{u_n}(x) u_n^2 \rho(x) dx + \Delta_n \\ &\geq \frac{p-1}{4}\|u_n\|_{H^{V,\varepsilon}}^2 + \frac{p-3}{4} \int_{\mathbb{R}^3} \phi_{u_n}(x) u_n^2 \rho(x) dx. \end{aligned} \quad (19)$$

As a consequence, the claim follows. \square

In the following we shall need a family of cut-off functions. Consider a smooth function $\zeta(r)$ such that $\zeta(r) = 1$ on $[2, \infty)$ and $\zeta(r) = 0$ on $[0, 1]$. Then define

$$\eta_R(x) := \zeta\left(\frac{\log(1+|x|)}{R}\right).$$

One has

$$\| |x| \cdot |\nabla \eta_R(x)| \|_\infty \leq \frac{C}{R}. \quad (20)$$

Lemma 2.5. *Let $(u_n)_n \subset E$ be as in Lemma 2.2 and $u_n \rightharpoonup u \geq 0$ in E . Then, for all $\delta > 0$, there exists a ball $B \subset \mathbb{R}^3$ such that, for all $\kappa, \mu > 0$ small enough,*

$$\begin{aligned} a) \quad & \limsup_{n \rightarrow \infty} \int_{\mathbb{R}^3 \setminus B} \phi_{u_n}(x) u_n^2 \rho(x) dx < \delta, \\ b) \quad & \limsup_{n \rightarrow \infty} \int_{\mathbb{R}^3 \setminus B} V(x) u_n^2 dx < \delta, \\ c) \quad & \limsup_{n \rightarrow \infty} \int_{\mathbb{R}^3 \setminus B} H(x) u_n^2 dx < \delta, \\ d) \quad & \limsup_{n \rightarrow \infty} \int_{\mathbb{R}^3 \setminus B} \phi_{u_n}(x) (u_n)_- \rho(x) dx < \delta, \\ e) \quad & \limsup_{n \rightarrow \infty} \int_{\mathbb{R}^3 \setminus B} \phi_{u_n}(x) (u_n)_+ \rho(x) dx < \delta. \end{aligned}$$

Proof. Consider the above family of cut-off functions. We claim that, uniformly in n ,

$$\int_{\mathbb{R}^3} \left(\frac{1}{2} |\nabla u_n|^2 - H(x) u_n^2 \right) \eta_R^2 dx \geq O\left(\frac{1}{R}\right), \quad R \rightarrow \infty, \quad (21)$$

for all $\kappa > 0$ small enough.

In order to prove this, compute

$$|\nabla(u_n \eta_R)|^2 = \eta_R^2 |\nabla u_n|^2 + 2u_n \eta_R \nabla u_n \nabla \eta_R + u_n^2 |\nabla \eta_R|^2.$$

We have

$$\left| \int_{\mathbb{R}^3} u_n \eta_R \nabla u_n \nabla \eta_R dx \right| \leq C_1 \left| \int_{\mathbb{R}^3} \frac{u_n}{|x|} \nabla u_n |x| \nabla \eta_R dx \right| \leq \| |x| \nabla \eta_R \|_\infty \left| \int_{\mathbb{R}^3} \frac{u_n}{|x|} \nabla u_n dx \right|.$$

By (20), Cauchy-Schwarz and Hardy inequalities, we obtain

$$\left| \int_{\mathbb{R}^3} u_n \nabla u_n \nabla \eta_R dx \right| \leq \frac{C_2}{R} \|\nabla u_n\|_2^2 \leq \frac{C_3}{R}. \quad (22)$$

Here we take into account that, since $u_n \rightharpoonup u$ in E , $\|\nabla u_n\|_2$ is bounded. In the same way, one can easily obtain

$$\int_{\mathbb{R}^3} u_n^2 |\nabla \eta_R|^2 \leq \frac{C_4}{R^2}.$$

Hence, by Hardy's inequality and the above estimates, we have, as $R \rightarrow \infty$,

$$\begin{aligned} \int_{\mathbb{R}^3} \left(\frac{1}{2} |\nabla u_n|^2 - H(x) u_n^2 \right) \eta_R^2 dx &\geq \int_{\mathbb{R}^3} \left(\frac{1}{2} |\nabla(u_n \eta_R)|^2 - \kappa \frac{(u_n \eta_R)^2}{|x|^2} \right) dx + O\left(\frac{1}{R}\right) \\ &\geq O\left(\frac{1}{R}\right), \end{aligned}$$

and the claim follows. Furthermore, simply notice that

$$\int_{\mathbb{R}^3} \nabla u_n \nabla (u_n \eta_R^2) dx = \int_{\mathbb{R}^3} |\nabla u_n|^2 \eta_R^2 dx + O\left(\frac{1}{R}\right), \quad R \rightarrow \infty, \quad (23)$$

Finally, by (21) and (23), we have, for $\mu, \kappa > 0$ small enough,

$$\begin{aligned} o(1) &= (J'_\varepsilon(u_n), u_n \eta_R^2) \\ &\geq \frac{\varepsilon^2}{2} \int_{\mathbb{R}^3} |\nabla u_n|^2 \eta_R^2 dx + \varepsilon^2 \int_{\mathbb{R}^3} \left(\frac{1}{2} |\nabla u_n|^2 - H(x) u_n^2\right) \eta_R^2 dx \\ &\quad + \int_{\mathbb{R}^3} \phi_{u_n} u_n^2 \eta_R^2 \rho(x) dx + (1 - \mu) \int_{\mathbb{R}^3} V(x) u_n^2 \eta_R^2 dx + O\left(\frac{1}{R}\right) \\ &\geq \frac{\varepsilon^2}{2} \int_{\mathbb{R}^3} |\nabla u_n|^2 \eta_R^2 dx + \int_{\mathbb{R}^3} \phi_{u_n} u_n^2 \eta_R^2 \rho(x) dx + (1 - \mu) \int_{\mathbb{R}^3} V(x) u_n^2 \eta_R^2 dx + O\left(\frac{1}{R}\right), \end{aligned}$$

as $R \rightarrow \infty$. Hence, taking $B := \{x \in \mathbb{R}^3 : |x| \leq e^{2R}\}$, since all the terms are nonnegative, the above estimates yield statements (a), (b) and, using (21), statement (c).

In order to prove (d) we use Cauchy-Schwarz inequality and (18), obtaining

$$\int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_- u \rho(x) \eta_R dx \leq (D(u_n^2, (u_n)_-^2))^{1/2} (D(u_n^2, u_n^2) D(u^2, u^2))^{1/4} \rightarrow 0,$$

since $D(u_n^2, u_n^2)$ is bounded and $D(u_n^2, (u_n)_-^2) \rightarrow 0$ by Lemma 2.4.

Finally we prove (e). We have, for any $R > 0$,

$$\begin{aligned} o(1) &= (J'_\varepsilon(u_n), u \eta_R) \\ &\geq \langle u_n, u \eta_R \rangle_{H_{V,\varepsilon}} + \int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_+ u \rho(x) \eta_R dx \\ &\quad - \int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_- u \rho(x) \eta_R dx - \int_{\mathbb{R}^3} (\varepsilon^2 H(x) + \mu V(x)) (u_n)_+ u \eta_R dx, \quad n \rightarrow \infty. \end{aligned}$$

Notice that, by weak convergence, we have, for any R ,

$$\langle u_n, u \eta_R \rangle_{H_{V,\varepsilon}} \rightarrow \langle u, u \eta_R \rangle_{H_{V,\varepsilon}},$$

and

$$\int_{\mathbb{R}^3} (\varepsilon^2 H(x) + \mu V(x)) (u_n)_+ u \eta_R dx \rightarrow \int_{\mathbb{R}^3} (\varepsilon^2 H(x) + \mu V(x)) u^2 \eta_R dx.$$

Now fix $\alpha > 0$ small and take R_α such that for all $R > R_\alpha$ we have

$$\int_{\mathbb{R}^3} (\varepsilon^2 H(x) + \mu V(x)) u^2 \eta_R dx \leq \alpha$$

and, by (d),

$$\int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_- u \rho(x) \eta_R dx \leq \alpha.$$

Arguing as for the estimate (22), we can choose R_α large enough such that

$$\left| \int_{\mathbb{R}^3} u \nabla u \nabla \eta_R dx \right| \leq \frac{C}{R} < \alpha,$$

for every $R > R_\alpha$. Hence, writing $\nabla(\eta_R u) = \eta_R \nabla u + u \nabla \eta_R$, the term $\langle u, u \eta_R \rangle_{H_{V,\varepsilon}}$ is the sum of a positive term plus a small term. Therefore, we obtain

$$o(1) + 3\alpha \geq \int_{\mathbb{R}^3} \phi_{u_n}(x) (u_n)_+ u \rho(x) \eta_R dx$$

and claim (e) follows. This concludes the proof. \square

Arguing as in the above lemmas we have

Lemma 2.6. *Under the assumptions on ρ, V, K given in Theorem 2, let (u_n) be as in the above lemma. Then for all $\delta > 0$, there exists a ball $B(0) \subset \mathbb{R}^3$, such that*

$$\begin{aligned}
(a) \quad & \limsup_{n \rightarrow \infty} \int_{B(0)} \phi_{u_n}(x) u_n^2 \rho(x) dx < \delta, \\
(b) \quad & \limsup_{n \rightarrow \infty} \left| \int_{B(0)} \phi_{u_n}(x) (u_n)_- u \rho(x) dx \right| < \delta, \\
(c) \quad & \limsup_{n \rightarrow \infty} \left| \int_{B(0)} \phi_{u_n}(x) (u_n)_+ u \rho(x) dx \right| < \delta.
\end{aligned}$$

Lemma 2.7. *Let $(u_n)_n$ be as in Lemma 2.5. Then, passing if necessary to a subsequence, we have*

$$\|u_n\|_{H_{V,\varepsilon}}^2 \rightarrow \|u\|_{H_{V,\varepsilon}}^2.$$

Proof. Since $u_n \rightarrow u$ in $H_{V,\varepsilon}$, for some subsequence, we have

$$\begin{aligned}
o(1) &= (J'_\varepsilon(u_n), u_n - u) = \|u_n\|_{H_{V,\varepsilon}}^2 - \|u\|_{H_{V,\varepsilon}}^2 + o(1) \\
&+ \int_{\mathbb{R}^3} \phi_{u_n}(x) u_n (u_n - u) \rho(x) dx + \int_{\mathbb{R}^3} g_\varepsilon(x, u_n) (u_n - u) dx. \tag{24}
\end{aligned}$$

We show that

$$A_n := \int_{\mathbb{R}^3} g_\varepsilon(x, u_n) (u_n - u) dx \rightarrow 0$$

and

$$B_n := \int_{\mathbb{R}^3} \phi_{u_n}(x) u_n (u_n - u) \rho(x) dx \rightarrow 0.$$

Observe that

$$A_n := \int_\Lambda \dots + \int_{B \setminus \Lambda} \dots + \int_{\mathbb{R}^3 \setminus B} \dots,$$

for some large ball B containing Λ . Since $(u_n)_n$ is bounded in E and E is compactly embedded in $L^q(\Lambda)$ for all $q > 1$, passing to a subsequence, we can assume $u_n \rightarrow u$ in $L^{p+1}(\Lambda)$. As a consequence, passing if necessary to a subsequence, we have $|g_\varepsilon(x, u_n)| < g(x)$ for some $g \in L^{\frac{p+1}{p}}(\Lambda)$. Using Hölder inequality and dominated convergence theorem, we have

$$\int_\Lambda g_\varepsilon(x, u_n) (u_n - u) dx \rightarrow 0.$$

In the same way, using the compact embedding $E \hookrightarrow L_{\varepsilon^2 H + \mu V}^2(B \setminus \Lambda)$, it follows that

$$\int_{B \setminus \Lambda} g_\varepsilon(x, u_n) (u_n - u) dx \rightarrow 0.$$

Finally, taking B large and using (b), (c) in Lemma 2.5, we have

$$\int_{\mathbb{R}^3 \setminus B} g_\varepsilon(x, u_n) (u_n - u) dx \rightarrow 0,$$

hence $A_n \rightarrow 0$.

In order to prove $B_n \rightarrow 0$, we use a similar splitting argument. Fix $\delta > 0$.

$$\begin{aligned}
B_n &= \int_{B(0)} \dots + \int_{B \setminus B(0)} \dots + \int_{\mathbb{R}^3 \setminus B} \dots \\
&= I_{1,n} + I_{2,n} + I_{3,n},
\end{aligned}$$

Now we choose B such that, using Lemma 2.5, we have

$$|I_{3,n}| < \delta.$$

Shrinking the ball $B(0)$ if necessary, we infer from Lemma 2.6 that $|I_{1,n}| < \delta$.

Next, we estimate $I_{2,n}$ as follows. By Hölder and Sobolev inequalities, we have

$$\begin{aligned}
\int_{B \setminus B(0)} \phi_{u_n}(x) |u_n (u_n - u)| \rho(x) dx &\leq \\
&C \|\rho\|_{L^\infty(B \setminus B(0))} \|\phi_{u_n}\|_{\mathcal{D}^{1,2}(\mathbb{R}^3)} \|u_n (u_n - u)\|_{L^{6/5}(B \setminus B(0))}. \tag{25}
\end{aligned}$$

Due to the weak convergence in E , $\|\phi_{u_n}\|_{\mathcal{D}^{1,2}(\mathbb{R}^3)}$ is bounded, and therefore, by compactness, we get

$$|I_{2,n}| < \delta.$$

This concludes the proof. \square

Proof of Theorem 3. By Lemma 2.2 and Lemma 2.4, there exists a bounded P-S sequence $(u_n)_n$ at the minimax level c_ε , such that $u_n \rightharpoonup u$ in E . We are going to prove that, passing if necessary to a subsequence,

$$\begin{aligned} i) \quad & J_\varepsilon(u_n) \rightarrow J_\varepsilon(u), \\ ii) \quad & J'_\varepsilon(u) = 0. \end{aligned}$$

This will imply the existence of a nontrivial solution u .

In order to prove *i*), notice that, by Lemma 2.7, it is enough to show that

$$\int_{\mathbb{R}^3} G_\varepsilon(x, u_n) dx \rightarrow \int_{\mathbb{R}^N} G_\varepsilon(x, u) dx$$

and

$$\int_{\mathbb{R}^3} \phi_{u_n}(x) u_n^2 \rho(x) dx \rightarrow \int_{\mathbb{R}^3} \phi_u(x) u^2 \rho(x) dx.$$

In order to prove the former limits, we can argue as for the terms involving g_ε in Lemma 2.7, splitting the integral

$$\int_{\mathbb{R}^3} |G_\varepsilon(x, u_n) - G_\varepsilon(x, u)| dx = \int_{\Lambda} \dots + \int_{B \setminus \Lambda} \dots + \int_{\mathbb{R}^3 \setminus B} \dots$$

We can assume $u_n \rightarrow u$ in $L^{p+1}(\Lambda)$ and almost everywhere. Fix $\delta > 0$. By using the compact embedding $E \hookrightarrow L^q(\Lambda)$ which holds for all $q > 1$, the dominated convergence theorem yields

$$\int_{\Lambda} |G_\varepsilon(x, u_n) - G_\varepsilon(x, u)| dx < \delta$$

for large n and, in the same fashion, using property (g_3) and the compact embedding of E in $L^2_{\varepsilon^2 H + \mu V}(B \setminus \Lambda)$, it follows that

$$\int_{B \setminus \Lambda} |G_\varepsilon(x, u_n) - G_\varepsilon(x, u)| dx < \delta$$

for some subsequence, taking n larger if necessary. Finally, observe that, by $(b), (c)$ of Lemma 2.5, there exists B large enough, such that for n large enough,

$$\int_{\mathbb{R}^3 \setminus B} |G_\varepsilon(x, u_n) - G_\varepsilon(x, u)| dx < \delta.$$

Now we prove the second limit. We compute

$$\begin{aligned} & \left| \int_{\mathbb{R}^3} [\phi_{u_n}(x) u_n^2 \rho(x) - \phi_u(x) u^2 \rho(x)] dx \right| \\ & \leq \left| \int_{B(0)} \dots \right| + \left| \int_{B \setminus B(0)} \dots \right| + \left| \int_{\mathbb{R}^3 \setminus B} \dots \right| \\ & = J_{1,n} + J_{2,n} + J_{3,n}. \end{aligned}$$

Fix $\delta > 0$. Arguing as in the proof of Lemma 2.7, we can take B large enough in such a way that

$$\int_{\mathbb{R}^3 \setminus B} \phi_u(x) u^2 \rho(x) dx < \delta,$$

yielding, with Lemma 2.5,

$$J_{3,n} \leq \left| \int_{\mathbb{R}^3 \setminus B} \phi_{u_n}(x) u_n^2 \rho(x) dx \right| + \left| \int_{\mathbb{R}^3 \setminus B} \phi_u(x) u^2 \rho(x) dx \right| < 2\delta.$$

Since we can shrink $B(0)$ so that

$$\int_{B(0)} \phi_u(x) u^2 \rho(x) dx < \delta,$$

we deduce from Lemma 2.6 that

$$J_{1,n} \leq \left| \int_{B(0)} \phi_{u_n}(x) u_n^2 \rho(x) dx \right| + \left| \int_{B(0)} \phi_u(x) u^2 \rho(x) dx \right| < 2\delta.$$

Now, with by now familiar arguments, we can estimate $J_{2,n}$. Indeed, using Hölder and Sobolev inequalities, we have

$$\begin{aligned} & \int_{B \setminus B(0)} |\phi_{u_n}(x) u_n^2 - \phi_u(x) u^2| \rho(x) dx \leq \\ & \int_{B \setminus B(0)} |\phi_{u_n}(x) u_n^2 - \phi_{u_n}(x) u^2| \rho(x) dx + \int_{B \setminus B(0)} |\phi_{u_n}(x) u^2 - \phi_u(x) u^2| \rho(x) dx \leq \\ & C \|\rho\|_{L^\infty(B \setminus B(0))} \|\phi_{u_n}\|_{\mathcal{D}^{1,2}(\mathbb{R}^3)} \|u_n^2 - u^2\|_{L^{6/5}(B \setminus B(0))} + \\ & \quad + \|\rho\|_{L^\infty(B \setminus B(0))} \int_{B \setminus B(0)} |\phi_{u_n}(x) u^2 - \phi_u(x) u^2| dx. \end{aligned} \quad (26)$$

By compactness, we infer that $\|u_n^2 - u^2\|_{L^{6/5}(B \setminus B(0))} \rightarrow 0$, while $(\phi_{u_n})_n$ is bounded in $\mathcal{D}^{1,2}(\mathbb{R}^3)$, hence the first term in (26) goes to zero. On the other hand, since $\phi_{u_n} \rightharpoonup \phi_u$ in $\mathcal{D}^{1,2}(\mathbb{R}^3)$, we have $\phi_{u_n} \rightarrow \phi_u$ strongly in $L^d(B \setminus B(0))$ for any $d < 2^*$. Hence, Hölder inequality implies the last term in (26) goes also to zero. As a consequence $J_{2,n} \leq \delta$ and this yields *i*).

The proof of *ii*) is rather standard, using the weak convergence in E and the same splitting arguments. The maximum principle implies $u > 0$ on \mathbb{R}^3 . This completes the proof of the theorem. \square

3. ASYMPTOTICS OF SOLUTIONS

In order to show that the solution u_ε found in Theorem 3 satisfies, for ε small enough, the original problem and concentrates around a circle, we need to study the asymptotic behaviour of u_ε as $\varepsilon \rightarrow 0$. Since many arguments are similar to the ones in [5], we only stress the differences with these. We begin with an energy estimate.

Proposition 3.1 (Upper estimate of the critical value). *Suppose that the assumptions of Theorem 3 are satisfied. For ε small enough, the critical value c_ε defined in (15) satisfies*

$$c_\varepsilon \leq \varepsilon^2 \left(\pi \inf_{\Lambda \cap \pi} \mathcal{M} + o(1) \right) \text{ as } \varepsilon \rightarrow 0.$$

Moreover, the solution u_ε of (11) found in Theorem 3 satisfies, for some $C > 0$,

$$\|u_\varepsilon\|_{H_{V,\varepsilon}}^2 \leq C\varepsilon^2 \quad (27)$$

and

$$\int_{\mathbb{R}^3} |\nabla \phi_{u_\varepsilon}|^2 dx = \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{u_\varepsilon^2(x) u_\varepsilon^2(y) \rho(x) \rho(y)}{|x-y|} dx dy \leq C\varepsilon^2. \quad (28)$$

Proof. Take $x_0 = (0, x_0'') \in \Lambda \cap \pi$ such that $\mathcal{M}(x_0) = \inf_{\Lambda \cap \pi} \mathcal{M}$. Denote by I_0 the functional defined by (3) with $a = V(x_0)$ and $b = K(x_0)$ and let $c_0 := \mathcal{E}(V(x_0), K(x_0))$. From (4), we infer that for every $\delta > 0$, there exists a continuous path $\gamma_\delta : [0, 1] \rightarrow H^1(\mathbb{R}^2)$ such that $\gamma_\delta(0) = 0$, $I_0(\gamma_\delta(1)) < 0$ and

$$c_0 \leq \max_{t \in [0,1]} I_0(\gamma_\delta(t)) \leq c_0 + \delta.$$

Let $\eta \in \mathcal{D}(\mathbb{R}_+^2)$ be a cut-off function with support in Λ such that $0 \leq \eta \leq 1$, $\eta = 1$ in a neighbourhood of $(0, |x_0''|)$ and $\|\nabla \eta\|_\infty \leq C$. We consider the path

$$\bar{\gamma}_\delta(t) : x \rightarrow \eta(x', |x''|) \gamma_\delta(t) \left(\frac{x'}{\varepsilon}, \frac{|x''| - |x_0''|}{\varepsilon} \right).$$

Setting

$$\bar{\gamma}_\delta(t)(x', x'') =: v_t \left(\frac{x'}{\varepsilon}, \frac{|x''| - |x_0''|}{\varepsilon} \right),$$

we compute, by a change of variable,

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}^3} (\varepsilon^2 |\nabla \bar{\gamma}_\delta(t)|^2 + V(x) \bar{\gamma}_\delta(t)^2) dx - \int_{\mathbb{R}^3} G_\varepsilon(x, \bar{\gamma}_\delta(t)) dx \\ &= \frac{\pi}{2} \int_{\mathbb{R}} \int_{-\frac{|x_0''|}{\varepsilon}}^{\infty} (|\nabla v_t|^2 + V(\varepsilon y', \varepsilon \sigma + |x_0''|) v_t^2) (\varepsilon \sigma + |x_0''|) \varepsilon d\sigma \varepsilon dy' \\ & \quad - \pi \int_{\mathbb{R}} \int_{-\frac{|x_0''|}{\varepsilon}}^{\infty} G(\varepsilon y', \varepsilon \sigma + |x_0''|, v_t) (\varepsilon \sigma + |x_0''|) \varepsilon d\sigma \varepsilon dy'. \end{aligned}$$

The boundedness of ρ in Λ and Hardy-Littlewood-Sobolev inequality leads to

$$\begin{aligned} & \int_{\mathbb{R}^3} \int_{\mathbb{R}^3} \frac{\bar{\gamma}_\delta(t)(x)^2 \bar{\gamma}_\delta(t)(y)^2 \rho(x) \rho(y)}{|x-y|} dx dy \\ & \leq \|\rho\|_{L^\infty(\Lambda)}^2 \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \frac{v_t^2(x', \sigma) v_t^2(y', \tau)}{\varepsilon (|x' - y'|^2 + |\sigma - \tau|^2)^{\frac{1}{2}}} \varepsilon^4 dx' dy' d\sigma d\tau \\ & \leq C \varepsilon^3 \|v_t\|_{L^2(\mathbb{R}^2)}^4 \\ & = o(\varepsilon^2). \end{aligned}$$

For ε small enough, we obtain

$$\varepsilon^{-2} J_\varepsilon(\bar{\gamma}_\delta(t)) \leq \omega_k |x_0''|^k I_0(\gamma_\delta(t)) + o(1). \quad (29)$$

It follows that for ε small enough, $\bar{\gamma}_\delta$ belongs to the class of paths Γ_ε defined by (16). We deduce from (15) that

$$\begin{aligned} \varepsilon^{-2} c_\varepsilon & \leq \max_{t \in [0,1]} \varepsilon^{-2} J_\varepsilon(\bar{\gamma}_\delta(t)) \\ & \leq \pi |x_0''| \max_{t \in [0,1]} I_0(\gamma_\delta(t)) + o(1) \\ & \leq \pi |x_0''| (c_0 + \delta) + o(1). \end{aligned}$$

Since $\delta > 0$ is arbitrary and $|x_0''| c_0 = \mathcal{M}(x_0)$, the first statement is established. The second statement is proved by a computation similar to (19). \square

Proposition 3.2 (No uniform convergence to 0 in Λ). *Suppose that the assumptions of Theorem 3 are satisfied and let $(u_\varepsilon)_\varepsilon \subset E$ be positive solutions of (11) obtained in Theorem 3. Then there exists $\delta > 0$ such that*

$$\|u_\varepsilon\|_{L^\infty(\Lambda)} \geq \delta.$$

Proof. See [5, Proposition 4.2]. \square

By the symmetry imposed on the solution u_ε , one can write $u_\varepsilon(x', x'') = \tilde{u}_\varepsilon(x', |x''|)$ with $\tilde{u}_\varepsilon : \mathbb{R}_+^2 \rightarrow \mathbb{R}$. Notice that ϕ_{u_ε} has the same symmetry as u_ε , i.e. for all $R \in \mathbf{O}(3)$ such that $R(d) = d$, $\phi_{u_\varepsilon} \circ R = \phi_{u_\varepsilon}$. This follows easily from the representation formula (12).

Since the $H_{V,\varepsilon}$ -norm of u_ε is of the order ε , it is natural to rescale $\tilde{u}_\varepsilon(x', |x''|)$ as $\tilde{u}_\varepsilon(x'_\varepsilon + \varepsilon y', |x''_\varepsilon| + \varepsilon |y''|)$ around a well-chosen family of points $x_\varepsilon = (x'_\varepsilon, x''_\varepsilon) \in \mathbb{R}^3$. The next lemma shows that the sequences of rescaled solutions converge, up to a subsequence, in $C_{\text{loc}}^1(\mathbb{R}^2)$ to a function $v \in H^1(\mathbb{R}^2)$.

Lemma 3.3. *Suppose that the assumptions of Theorem 3 are satisfied. Let $(u_\varepsilon)_\varepsilon \subset E$ be positive solutions of (11) found in Theorem 3, $(\varepsilon_n)_n \subset \mathbb{R}^+$ and $(x_n)_n \subset \mathbb{R}^3$ be sequences such that $\varepsilon_n \rightarrow 0$ and $x_n = (x'_n, x''_n) \rightarrow \bar{x} = (\bar{x}', \bar{x}'') \in \bar{\Lambda}$ as $n \rightarrow \infty$. Set*

$$\Omega_n := \mathbb{R} \times \left] -\frac{|x''_n|}{\varepsilon_n}, +\infty \right[$$

and let $v_n : \Omega_n \rightarrow \mathbb{R}$ be defined by

$$v_n(y, z) := \tilde{u}_{\varepsilon_n}(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z), \quad (30)$$

where $\tilde{u}_{\varepsilon_n} : \mathbb{R}_+^2 \rightarrow \mathbb{R}$ is such that $u_{\varepsilon_n}(x', x'') = \tilde{u}_{\varepsilon_n}(x', |x''|)$. Then, there exists $v \in H^1(\mathbb{R}^2)$ such that, along a subsequence that we still denote by $(v_n)_n$,

$$v_n \xrightarrow{C_{\text{loc}}^1(\mathbb{R}^2)} v.$$

Moreover, v is a solution of the equation

$$-\Delta v + V(\bar{x})v = K(\bar{x})v^p, \quad \bar{x} \in \mathbb{R}^2.$$

Proof. We infer from Proposition 3.1 that for all $n \in \mathbb{N}$,

$$\int_{\Omega_n} (|\nabla v_n(y, z)|^2 + V(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z)|v_n(y, z)|^2) dy dz \leq C, \quad (31)$$

with $C > 0$ independent of n .

Observe also that each v_n solves the equation

$$\begin{aligned} -\Delta v_n - \frac{\varepsilon_n}{z} \frac{\partial v_n}{\partial z} + V(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z)v_n + \rho(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z)\tilde{\phi}_n v_n \\ = g_{\varepsilon_n}(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z, v_n), \quad x \in \mathbb{R}^2, \end{aligned} \quad (32)$$

where we have set $\tilde{\phi}_n(y, z) = \phi_{u_{\varepsilon_n}}(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z)$. As a consequence of (28), the sequence $(\tilde{\phi}_n)_n$ converges to zero in $\mathcal{D}^{1,2}(\mathbb{R}^2)$. It follows then from Hölder inequality that the term $(\rho(x'_n + \varepsilon_n y, |x''_n| + \varepsilon_n z)\tilde{\phi}_n v_n)_n$ is bounded in $L_{\text{loc}}^2(\mathbb{R}^2 \setminus \{0\})$.

Define a cut-off function $\eta_R \in \mathcal{D}(\mathbb{R}^2)$ such that $0 \leq \eta_R \leq 1$, $\eta_R(x) = 1$ if $|x| \leq R/2$, $\eta_R(x) = 0$ if $|x| \geq R$ and $\|\nabla \eta_R\|_{\infty} \leq C/R$ for some $C > 0$. Choose $(R_n)_n$ such that $R_n \rightarrow \infty$ and $\varepsilon_n R_n \rightarrow 0$. Since $\bar{x} \in \Lambda$ and $\bar{\Lambda} \cap d = \emptyset$, one has $\varepsilon_n R_n \leq |x''_n|$ if n is large enough. Define $w_n \in H_{\text{loc}}^1(\mathbb{R}^2)$ by

$$w_n(y) := \eta_{R_n}(y)v_n(y).$$

It was shown in [5, Lemma 4.3] that (31) implies that $(w_n)_n$ is bounded in $H^1(\mathbb{R}^2)$. Since w_n solves equation (32) on $B(0, R_n)$ for all n , classical regularity estimates yield that for every $R > 0$ and every $q > 1$,

$$\sup_{n \in \mathbb{N}} \|w_n\|_{W^{2,q}(B(0,R))} < \infty. \quad (33)$$

Up to a subsequence, we can now assume that $(w_n)_n$ converges weakly in $H^1(\mathbb{R}^2)$ to some function $v \in H^1(\mathbb{R}^2)$. By (33), for every compact set $K \subset \mathbb{R}^2$, w_n converges to v in $C^1(K)$. Moreover, for n large enough, $w_n = v_n$ in K so that $v_n \rightarrow v$ in $C^1(K)$. \square

For $x, y \in \mathbb{R}^3$, denote by

$$d_d(x, y) := \sqrt{|x' - y'|^2 + (|x''| - |y''|)^2}.$$

the distance between the circles centered at x' and y' , and of radius $|x''|$ and $|y''|$ respectively. We denote by B_d the balls for the distance d_d , i.e.,

$$B_d(x, r) = \{y \in \mathbb{R}^3 : d_d(x, y) < r\}.$$

We are now going to estimate from below the critical value c_ε . In the next two lemmas we estimate the action respectively inside and outside neighbourhoods of points.

Lemma 3.4. *Suppose that the assumptions of Theorem 3 are satisfied. Let $u_\varepsilon \in E$ be positive solutions of (11) found in Theorem 3, $(\varepsilon_n)_n \subset \mathbb{R}^+$ and $(x_n)_n \subset \mathbb{R}^n$ be sequences such that $\varepsilon_n \rightarrow 0$ and $x_n = (x'_n, x''_n) \rightarrow \bar{x} = (\bar{x}', \bar{x}'') \in \bar{\Lambda}$ as $n \rightarrow \infty$. If*

$$\liminf_{n \rightarrow \infty} u_{\varepsilon_n}(x_n) > 0, \quad (34)$$

then we have, up to a subsequence,

$$\liminf_{R \rightarrow \infty} \liminf_{n \rightarrow \infty} \varepsilon_n^{-2} \left(\int_{T_n(R)} \frac{1}{2} (\varepsilon_n^2 |\nabla u_{\varepsilon_n}|^2 + V u_{\varepsilon_n}^2) - G_{\varepsilon_n}(x, u_{\varepsilon_n}) \right) \geq \pi \mathcal{M}(\bar{x}),$$

where $T_n(R) := B_d(x_n, \varepsilon_n R)$.

Proof. The proof is the same as the one of Lemma 4.4 in [5]. Indeed, the Poisson term is positive and the equation satisfied by the limit of the sequence of rescaled solutions is the same as in [5]. \square

Lemma 3.5. *Suppose that the assumptions of Theorem 3 are satisfied. Let $u_\varepsilon \in E$ be positive solutions of (11) found in Theorem 3, $(\varepsilon_n)_n \subset \mathbb{R}^+$ and $(x_n^i)_n \subset \mathbb{R}^3$ be sequences such that $\varepsilon_n \rightarrow 0$ and for $1 \leq i \leq M$, $x_n^i \rightarrow \bar{x}^i \in \bar{\Lambda}$ as $n \rightarrow \infty$. Then, up to a subsequence, we have*

$$\liminf_{R \rightarrow \infty} \liminf_{n \rightarrow \infty} \varepsilon_n^{-2} \left(\int_{\mathbb{R}^3 \setminus \mathcal{T}_n(R)} \frac{1}{2} (\varepsilon_n^2 |\nabla u_{\varepsilon_n}|^2 + V u_{\varepsilon_n}^2) - G_{\varepsilon_n}(x, u_{\varepsilon_n}) \right) \geq 0,$$

where $\mathcal{T}_n(R) := \bigcup_{i=1}^K B_d(x_n^i, \varepsilon_n R)$.

Proof. Since the Poisson term is positive, the proof is the same as the one of Lemma 4.5 in [5]. \square

Proposition 3.6 (Lower estimate of the critical value). *Suppose that the assumptions of Theorem 3 are satisfied. Let $u_\varepsilon \in E$ be positive solutions of (11) found in Theorem 3, $(\varepsilon_n)_n \subset \mathbb{R}^+$ and $(x_n^i)_n \subset \mathbb{R}^3$ be sequences such that $\varepsilon_n \rightarrow 0$ and for $1 \leq i \leq M$, $x_n^i \rightarrow \bar{x}^i \in \bar{\Lambda}$ as $n \rightarrow \infty$. If for every $1 \leq i < j \leq M$, we have*

$$\limsup_{n \rightarrow \infty} \frac{d_d(x_n^i, x_n^j)}{\varepsilon_n} = \infty$$

and if for every $1 \leq i \leq M$,

$$\liminf_{n \rightarrow \infty} u_{\varepsilon_n}(x_n^i) > 0,$$

then the critical value c_ε defined in (15) satisfies

$$\liminf_{n \rightarrow \infty} \varepsilon_n^{-2} c_{\varepsilon_n} \geq \pi \sum_{i=1}^M \mathcal{M}(\bar{x}^i).$$

Proof. This is a consequence of the two previous lemmas and of the positivity of the Poisson term, see [7, Proposition 16] for the details. \square

Now we can state a first concentration result. It will be completed in the next section by a decay estimate.

Proposition 3.7 (Uniform convergence to 0 outside small balls). *Suppose that the assumptions of Theorem 3 are satisfied and that Λ satisfies the assumptions (5)-(8). Let $(u_\varepsilon)_\varepsilon \subset E$ be positive solutions of (11) obtained in Theorem 3. If $(x_\varepsilon)_{\varepsilon > 0} \subset \Lambda$ is such that*

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0,$$

then

- (i) $\lim_{\varepsilon \rightarrow 0} \mathcal{M}(x_\varepsilon) = \inf_{\Lambda \cap \pi} \mathcal{M}$,
- (ii) $\lim_{\varepsilon \rightarrow 0} \frac{\text{dist}(x_\varepsilon, \pi)}{\varepsilon} = 0$,
- (iii) $\liminf_{\varepsilon \rightarrow 0} d_d(x_\varepsilon, \partial\Lambda) > 0$,
- (iv) for every $\delta > 0$, there exists $\varepsilon_0 > 0$ and $R > 0$ such that, for every $\varepsilon \in (0, \varepsilon_0)$,

$$\|u_\varepsilon\|_{L^\infty(\Lambda \setminus B_d(x_\varepsilon, \varepsilon R))} \leq \delta.$$

Proof. All the assertions are proved by energy comparisons, using only Propositions 3.1 and 3.6. A detailed proof can be found in [5, Proposition 4.7]. \square

4. SOLUTION OF THE INITIAL PROBLEM

4.1. Linear inequation outside small balls. In this section we prove that for ε small enough, the solutions of the penalized problem (11) are also solutions of the initial problem (1). We follow the arguments of [13] and [5]. First we notice that the solutions of (11) satisfy a linear inequation outside small balls. As observed in [6, Theorem 5], the function ϕ_{u_ε} satisfies the estimate

$$\phi_{u_\varepsilon}(x) \geq \frac{C_\varepsilon}{C'_\varepsilon + |x|},$$

for some constants $C_\varepsilon, C'_\varepsilon > 0$. Set

$$W_\varepsilon(x) := (1 - \mu)V(x) + \frac{C_\varepsilon \rho(x)}{C'_\varepsilon + |x|}.$$

Lemma 4.1. *Suppose that the assumptions of Proposition 3.7 are satisfied and let $(u_\varepsilon)_\varepsilon \subset E$ be positive solutions of (11) found in Theorem 3 and $(x_\varepsilon)_{\varepsilon>0} \subset \Lambda$ be such that*

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0.$$

Then there exist $R > 0$ and $\varepsilon_0 > 0$ such that for all $\varepsilon \in (0, \varepsilon_0)$,

$$-\varepsilon^2(\Delta u_\varepsilon + H u_\varepsilon) + W_\varepsilon u_\varepsilon \leq 0 \quad \text{in } \mathbb{R}^3 \setminus B_d(x_\varepsilon, \varepsilon R). \quad (35)$$

Proof. Set

$$\eta := \inf_{x \in \Lambda} \left(\frac{\mu V(x)}{K(x)} \right)^{\frac{1}{p-1}}.$$

Since V and K are bounded positive continuous functions on $\bar{\Lambda}$, $\eta > 0$. By Proposition 3.7, we can find $\varepsilon_0 > 0$ and $R > 0$ such that for all $\varepsilon \in (0, \varepsilon_0]$, one has

$$u_\varepsilon(x) \leq \eta \quad \text{for all } x \in \Lambda \setminus B_d(x_\varepsilon, \varepsilon R).$$

We conclude that

$$-\varepsilon^2 \Delta u_\varepsilon + (1 - \mu) V u_\varepsilon + \rho \phi_{u_\varepsilon} u_\varepsilon \leq -\varepsilon^2 \Delta u_\varepsilon + V u_\varepsilon + \rho \phi_{u_\varepsilon} u_\varepsilon - K u_\varepsilon^p = 0$$

in $\Lambda \setminus B_d(x_\varepsilon, \varepsilon R)$. The fact that u_ε satisfies (35) in $\mathbb{R}^3 \setminus \Lambda$ follows directly from the definition of the penalized nonlinearity. \square

This lemma suggests that we can compare the solution u_ε with supersolutions of the operator $-\varepsilon^2(\Delta + H) + W_\varepsilon$ in order to obtain decay estimates of u_ε .

4.2. Comparison functions. In this section we recall results from [5] about the comparison functions. The next lemma provides a minimal positive solution of the operator $-\Delta - H$ in $\mathbb{R}^3 \setminus \bar{\Lambda}$.

Lemma 4.2. *For every $\varepsilon > 0$, there exists $\Psi_\varepsilon \in C^2((\mathbb{R}^3 \setminus \{0\}) \setminus \Lambda)$ such that*

$$\begin{cases} -\varepsilon^2(\Delta \Psi_\varepsilon + H \Psi_\varepsilon) + W_\varepsilon \Psi_\varepsilon = 0 & \text{in } \mathbb{R}^3 \setminus \bar{\Lambda}, \\ \Psi_\varepsilon = 1 & \text{on } \partial \Lambda, \end{cases}$$

and

$$\int_{\mathbb{R}^3 \setminus \Lambda} \left(|\nabla \Psi_\varepsilon(x)|^2 + \frac{|\Psi_\varepsilon(x)|^2}{|x|^2} \right) dx < \infty. \quad (36)$$

Moreover, there exists $C > 0$ such that, for every $x \in \mathbb{R}^3 \setminus \Lambda$ and every $\varepsilon > 0$,

$$0 < \Psi_\varepsilon(x) \leq \frac{C}{1 + |x|}. \quad (37)$$

Proof. See [5, Lemma 5.2]. \square

As explained in [13], the estimate (37) is the best one can hope for, at least if W_ε decays rapidly at infinity. However, if W_ε decays quadratically or subquadratically at infinity, we can improve (37).

Lemma 4.3. *Let Ψ_ε be given by Lemma 4.2.*

(1) *If $\liminf_{|x| \rightarrow \infty} W_\varepsilon(x)|x|^2 > 0$, then there exist $\lambda > 0$, $R > 0$ and $C > 0$ such that for every $\varepsilon > 0$ and $x \in \mathbb{R}^3 \setminus B(0, R)$,*

$$\Psi_\varepsilon(x) \leq C \left(\frac{R}{|x|} \right)^{\frac{1}{2} + \sqrt{\frac{1}{4} - \kappa + \frac{\lambda^2}{\varepsilon^2}}}.$$

(2) *If $\liminf_{|x| \rightarrow \infty} W_\varepsilon(x)|x|^\alpha > 0$ with $\alpha < 2$, then there exist $\lambda > 0$, $R > 0$, $C > 0$ and $\varepsilon_0 > 0$ such that for every $\varepsilon \in (0, \varepsilon_0)$ and $x \in \mathbb{R}^3 \setminus B(0, R)$,*

$$\Psi_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \left(|x|^{\frac{2-\alpha}{2}} - R^{\frac{2-\alpha}{2}} \right) \right).$$

(3) If $\liminf_{|x| \rightarrow 0} W_\varepsilon(x)|x|^2 > 0$, then there exist $\lambda > 0$, $r > 0$ and $C > 0$ such that for every $\varepsilon > 0$ and $x \in B(0, r)$,

$$\Psi_\varepsilon(x) \leq C \left(\frac{|x|}{r} \right)^{\sqrt{\frac{1}{4} - \kappa + \frac{\lambda^2}{\varepsilon^2}} - \frac{1}{2}}.$$

(4) If $\liminf_{|x| \rightarrow 0} W_\varepsilon(x)|x|^\alpha > 0$ with $\alpha < 2$, then there exist $\lambda > 0$, $R > 0$, $C > 0$ and $\varepsilon_0 > 0$ such that for every $\varepsilon \in (0, \varepsilon_0)$ and $x \in B(0, r)$,

$$\Psi_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \left(|x|^{-\frac{\alpha-2}{2}} - r^{-\frac{\alpha-2}{2}} \right) \right).$$

Proof. See [5, Lemma 5.3]. \square

Now we provide a comparison function that describes the exponential decay of u_ε inside Λ .

Lemma 4.4. *Let $\bar{x} \in \Lambda$ and $R > 0$ be such that*

$$B_d(\bar{x}, R) \subset \Lambda. \quad (38)$$

Define

$$\Phi_\varepsilon^{\bar{x}}(x) := \cosh \left(\lambda \frac{R - d_d(x, \bar{x})}{\varepsilon} \right). \quad (39)$$

There exists $\lambda > 0$ and $\varepsilon_0 > 0$ such that for every $\varepsilon \in (0, \varepsilon_0)$, one has

$$-\varepsilon^2 \Delta \Phi_\varepsilon^{\bar{x}} + W_\varepsilon \Phi_\varepsilon^{\bar{x}} \geq 0 \text{ in } B_d(\bar{x}, R).$$

Proof. See [5, Lemma 5.4]. \square

Lemma 4.5. *Let $(x_\varepsilon)_\varepsilon \subset \Lambda$ be such that*

$$\liminf_{\varepsilon \rightarrow 0} d_d(x_\varepsilon, \partial\Lambda) > 0$$

and $R > 0$. Then, there exist $\varepsilon_0 > 0$ and a family of functions $(w_\varepsilon)_{0 < \varepsilon < \varepsilon_0} \subset C_{\text{loc}}^{1,1}(\mathbb{R}^3 \setminus \{0\}) \setminus B_d(x_\varepsilon, \varepsilon R)$ such that for all $\varepsilon \in (0, \varepsilon_0)$, one has

(i) w_ε satisfies the inequation

$$-\varepsilon^2 (\Delta + H) w_\varepsilon + W_\varepsilon w_\varepsilon \geq 0 \text{ in } \mathbb{R}^3 \setminus B_d(x_\varepsilon, \varepsilon R),$$

(ii) $\nabla w_\varepsilon \in L^2(\mathbb{R}^3 \setminus B_d(x_\varepsilon, \varepsilon R))$ and $\frac{w_\varepsilon}{|x|} \in L^2(\mathbb{R}^3 \setminus B_d(x_\varepsilon, \varepsilon R))$,

(iii) $w_\varepsilon \geq 1$ on $\partial B_d(x_\varepsilon, \varepsilon R)$,

(iv) for every $x \in B_d(x_\varepsilon, \varepsilon R)$,

$$w_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \frac{d_d(x, x_\varepsilon)}{1 + d_d(x, x_\varepsilon)} \right) (1 + |x|)^{-1}, \quad x \in \mathbb{R}^3.$$

Moreover,

(1) If $\liminf_{|x| \rightarrow \infty} W_\varepsilon(x)|x|^2 > 0$, then there exists $\lambda > 0$, $\nu > 0$ and $C > 0$ such that for $\varepsilon > 0$ small enough,

$$w_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \frac{d_d(x, x_\varepsilon)}{1 + d_d(x, x_\varepsilon)} \right) (1 + |x|)^{-\frac{\nu}{\varepsilon}}.$$

(2) If $\liminf_{|x| \rightarrow \infty} W_\varepsilon(x)|x|^\alpha > 0$ with $\alpha > 2$, then there exists $\lambda > 0$ and $C > 0$ such that for $\varepsilon > 0$ small enough,

$$w_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \frac{d_d(x, x_\varepsilon)}{1 + d_d(x, x_\varepsilon)} (1 + |x|)^{\frac{2-\alpha}{2}} \right).$$

(3) If $\liminf_{|x| \rightarrow 0} W_\varepsilon(x)|x|^2 > 0$, then there exists $\lambda > 0$, $\nu > 0$ and $C > 0$ such that for $\varepsilon > 0$ small enough,

$$w_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \frac{d_d(x, x_\varepsilon)}{1 + d_d(x, x_\varepsilon)} \right) \left(\frac{|x|}{1 + |x|} \right)^{\frac{\nu}{\varepsilon}}.$$

(4) If $\liminf_{|x| \rightarrow 0} W_\varepsilon(x)|x|^\alpha > 0$ with $\alpha > 2$, then there exists $\lambda > 0$ and $C > 0$ such that for $\varepsilon > 0$ small enough,

$$w_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \frac{d_d(x, x_\varepsilon)}{1 + d_d(x, x_\varepsilon)} \left(\frac{|x|}{1 + |x|} \right)^{\frac{\alpha-2}{2}} \right).$$

Proof. See [5, Lemma 5.5]. \square

Thanks to the previous lemma, we obtain an upper bound on the solutions $(u_\varepsilon)_{\varepsilon > 0}$ of (11).

Proposition 4.6. *Suppose that the assumptions of Proposition 3.7 are satisfied. Let $(u_\varepsilon)_{\varepsilon > 0} \subset E$ be the positive solutions of (11) found in Theorem 3 and $(x_\varepsilon)_{\varepsilon > 0} \subset \Lambda$ be such that*

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0.$$

Then there exist $C > 0$, $\lambda > 0$ and $\varepsilon_0 > 0$ such that for all $\varepsilon \in (0, \varepsilon_0)$,

$$u_\varepsilon(x) \leq C \exp \left(-\frac{\lambda}{\varepsilon} \frac{d(x, S_\varepsilon^1)}{1 + d(x, S_\varepsilon^1)} \right) (1 + |x|)^{-1}, \quad x \in \mathbb{R}^3. \quad (40)$$

Moreover, (1), (2), (3) and (4) in Lemma 4.5 hold with u_ε in place of w_ε .

Proof. See [5, Lemma 5.6]. \square

4.3. Solution of the original problem.

Proposition 4.7. *Let $(u_\varepsilon)_{\varepsilon > 0} \subset E$ be the positive solutions of (11) found in Theorem 3. Assume that one set (\mathcal{G}_∞^i) of growth conditions at infinity and one set (\mathcal{G}_0^j) of growth conditions at the origin hold. Then there exists $\varepsilon_0 > 0$ such that for all $\varepsilon \in (0, \varepsilon_0)$, u_ε solves the original problem (1).*

Proof. We infer from Lemma 3.2 that there exists a family of points $(x_\varepsilon)_{\varepsilon > 0} \subset \Lambda$ such that

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0.$$

Assume that the assumptions (\mathcal{G}_∞^1) and (\mathcal{G}_0^1) are satisfied. By Proposition 4.6, we obtain for $\varepsilon > 0$ small enough and $x \in \mathbb{R}^3 \setminus \Lambda$,

$$\begin{aligned} K(x)u_\varepsilon^{p-1} &\leq M(1 + |x|)^\sigma \left(C e^{-\frac{\lambda}{\varepsilon}} \frac{1}{|x|} \right)^{p-1} \\ &\leq C e^{-\frac{\lambda}{\varepsilon}(p-1)} (1 + |x|)^{-(p-1)+\sigma} \\ &\leq \frac{\varepsilon^2 \kappa}{|x|^2 ((\log|x|)^2 + 1)^{\frac{1+\beta}{2}}} = \varepsilon^2 H(x). \end{aligned}$$

We conclude by definition of the penalized nonlinearity g_ε that $g_\varepsilon(x, u_\varepsilon(x)) = K(x)u_\varepsilon^p(x)$, and hence u_ε solves the original problem (1). The other cases can be treated in a similar way. \square

Proof of Theorem 2. We proved in Theorem 3 that, for any $\varepsilon > 0$, the penalized problem (11) possesses a solution u_ε . By Proposition 4.7, for $\varepsilon > 0$ small enough, u_ε is a solution of the initial problem (1). The existence of a sequence $(x_\varepsilon)_{\varepsilon > 0} \subset \Lambda$ such that

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0$$

follows from Lemma 3.2 and the concentration result follows from Proposition 3.7. Finally, Proposition 4.6 yields the decay estimate. \square

5. REMARKS AND FURTHER RESULTS

5.1. Concentration at points. We can also obtain a result about solutions concentrating at points. In this case, the concentration function is given by

$$\mathcal{A}(x) = [V(x)]^{\frac{p+1}{p-1} - \frac{3}{2}} [K(x)]^{\frac{-2}{p-1}}.$$

Theorem 4. *Let $3 < p < 5$, $V, K \in C(\mathbb{R}^3 \setminus \{0\}, \mathbb{R}^+)$, $K \not\equiv 0$ and $\rho \in L_{loc}^{3/2}(\mathbb{R}^3) \cap L_{loc}^\infty(\mathbb{R}^3 \setminus \{0\})$. Assume that one set (\mathcal{G}_∞^i) of growth conditions at infinity and one set (\mathcal{G}_0^j) of growth conditions at the origin hold. Assume also that there exists a smooth open bounded set $\Lambda \subset \mathbb{R}^3$ such that*

$$0 < \inf_{\Lambda} \mathcal{A} < \inf_{\partial\Lambda} \mathcal{A}. \quad (41)$$

Then there exists $\varepsilon_0 > 0$ such that for every $0 < \varepsilon < \varepsilon_0$, problem (1) has at least one positive solution u_ε . Moreover, for every $0 < \varepsilon < \varepsilon_0$, there exists $x_\varepsilon \in \Lambda$ such that u_ε attains its maximum at x_ε ,

$$\begin{aligned} \liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) &> 0, \\ \lim_{\varepsilon \rightarrow 0} \mathcal{A}(x_\varepsilon) &= \inf_{\Lambda} \mathcal{A}, \end{aligned}$$

and there exist $C > 0$ and $\lambda > 0$ such that

$$u_\varepsilon(x) \leq C \exp\left(-\frac{\lambda}{\varepsilon} \frac{|x - x_\varepsilon|}{1 + |x - x_\varepsilon|}\right) (1 + |x - x_\varepsilon|^2)^{\frac{-1}{2}}, \quad \forall x \in \mathbb{R}^3.$$

The proof of this theorem is similar to the proof of Theorem 2, but simpler. Let us only sketch the proof. First of all, we impose no symmetry neither on the potentials nor on the solution. This makes the critical Sobolev exponent to appear, in spite of what happens in the preceding results. We modify the problem in the same way as before and we search for a critical point of the functional J_ε in the space X defined by (13). Theorem 3 remains true with the same proof.

The limiting problem associated to concentration at points is the problem

$$-\Delta u + au = bu^p \quad \text{in } \mathbb{R}^3.$$

Let $x_0 \in \Lambda$ be a point such that $\mathcal{A}(x_0) = \inf_{\Lambda} \mathcal{A}$. We denote by c_0 the least energy critical value of the limiting problem with $a = V(x_0)$ and $b = K(x_0)$. As in Proposition 3.1, we prove that the critical value c_ε defined in (15) satisfies

$$c_\varepsilon \leq \varepsilon^3 (c_0 + o(1)) \quad \text{as } \varepsilon \rightarrow 0.$$

Then we prove as before that the L^∞ -norm of u_ε does not converge to 0 in Λ and that the sequence of rescaled solutions converges in C_{loc}^1 to a solution of the limiting equation. The analogous of Proposition 3.6 is the following one.

Proposition 5.1. *Let $(\varepsilon_n)_n \subset \mathbb{R}^+$ and $(x_n^i)_n \subset \mathbb{R}^3$ be sequences such that $\varepsilon_n \rightarrow 0$ and for $1 \leq i \leq M$, $x_n^i \rightarrow \bar{x}^i \in \bar{\Lambda}$ as $n \rightarrow \infty$. If for every $1 \leq i < j \leq M$, we have*

$$\limsup_{n \rightarrow \infty} \frac{|x_n^i - x_n^j|}{\varepsilon_n} = \infty$$

and if for every $1 \leq i \leq M$,

$$\liminf_{n \rightarrow \infty} u_{\varepsilon_n}(x_n^i) > 0,$$

then

$$\liminf_{n \rightarrow \infty} \varepsilon_n^{-3} c_{\varepsilon_n} \geq \sum_{i=1}^M \mathcal{C}(\bar{x}^i),$$

where $\mathcal{C}(x)$ is the least energy critical value of the limiting problem with $a = V(\bar{x})$ and $b = K(\bar{x})$.

The concentration result can be stated as follows.

Proposition 5.2. *Suppose that Λ satisfies (41). If $(x_\varepsilon)_{\varepsilon > 0} \subset \Lambda$ is such that*

$$\liminf_{\varepsilon \rightarrow 0} u_\varepsilon(x_\varepsilon) > 0,$$

then

- (i) $\lim_{\varepsilon \rightarrow 0} \mathcal{A}(x_\varepsilon) = \inf_{\Lambda} \mathcal{A}$,
- (ii) $\liminf_{\varepsilon \rightarrow 0} d(x_\varepsilon, \partial\Lambda) > 0$,
- (iii) for every $\delta > 0$, there exists $\varepsilon_0 > 0$ and $R > 0$ such that, for every $\varepsilon \in (0, \varepsilon_0)$,

$$\|u_\varepsilon\|_{L^\infty(\Lambda \setminus B(x_\varepsilon, \varepsilon R))} \leq \delta.$$

Finally the comparison arguments in order to get back to the original problem are the same as in section 4.

5.2. Concentration on spheres. Using the same method, we can prove the existence of solutions concentrating on a sphere for the following problem.

$$\begin{cases} -\varepsilon^2 \Delta u + V(x)u + \rho(x)\phi u = K(x)u^p, & x \in \mathbb{R}^3, \\ -\Delta \phi = \varepsilon \rho(x)u^2. \end{cases}$$

However we are not sure whether this problem has a physical meaning.

5.3. Concentration on Keplerian orbits. An interesting question related to [9, 15], concerns the existence of solutions concentrating on Kepler orbits, assuming radial potentials. For the reasons described in the Introduction, this might be a typical situation where the correspondence principle can be checked using solutions localized on classical planar orbits. We wonder if this result could be obtained for the 3D nonlinear Schrödinger and Schrödinger-Poisson equations with radial potentials.

5.4. Concentration driven by ρ . If $V \equiv K \equiv 1$, it is natural to ask whether there still exist solutions with a concentration behaviour. In this case, we expect the location of the concentration points to be governed by the weight ρ . The asymptotic analysis seems more delicate since it requires higher order estimates.

Acknowledgements The authors would like to thank Professor Antonio Ambrosetti for taking their attention to these questions. C.M. would like to thank the members of the department of Mathematics of Université Libre de Bruxelles for the kind hospitality and friendship. C.M. was partially supported by FIRB Analysis and Beyond and PRIN 2008 Variational Methods and Nonlinear Differential Equations.

REFERENCES

- [1] A. Ambrosetti, *On Schrödinger-Poisson systems*. Milan J. Math. 76 (2008), 257–274.
- [2] A. Ambrosetti, V. Felli, and A. Malchiodi, *Ground states of nonlinear Schrödinger equations with potentials vanishing at infinity*, J. Eur. Math. Soc. (JEMS) 7 (2005), no. 1, 117–144.
- [3] A. Ambrosetti and P.H. Rabinowitz, *Dual variational methods in critical point theory and applications*. J. Funct. Anal. 14 (1973), 349–381.
- [4] V. Benci and T. D’Aprile *The semiclassical limit of the nonlinear Schrödinger equation in a radial potential* Journal of Differential equations, 184 (2002) 109-138.
- [5] D. Bonheure, J. Di Cosmo and J. Van Schaftingen, *Nonlinear Schrödinger equation with unbounded or vanishing potentials: solutions concentrating on lower dimensional spheres*, preprint.
- [6] D. Bonheure and C. Mercuri, *Embedding theorems and existence for nonlinear Schrödinger-Poisson systems with unbounded and vanishing potentials*, preprint Sissa (2010).
- [7] D. Bonheure and J. Van Schaftingen, *Bound state solutions for a class of nonlinear Schrödinger equations*, Rev. Mat. Iberoam. 24 (2008), no. 1, 297–351.
- [8] T. D’Aprile, *On a class of solutions with non-vanishing angular momentum for nonlinear Schrödinger equations*. Differential and integral equations, 3 (2003), 349-384.
- [9] J.-C. Gay, D. Delande and A. Bommier, *Atomic quantum states with maximum localization on classical elliptical orbits*. Phys. Rev. A 39 (1989) 6587–6590.
- [10] M. del Pino, P. Felmer, *Local mountain passes for semilinear elliptic problems in unbounded domains*. Calc. Var. 4 (1996), 121-137.
- [11] E.H. Lieb and M. Loss, *Analysis*. Second edition. Graduate Studies in Mathematics, 14. American Mathematical Society, Providence, RI, 2001.
- [12] C. Mercuri, *Positive solutions of nonlinear Schrödinger-Poisson systems with radial potentials vanishing at infinity*, Atti Accad. Naz. Lincei Cl. Sci. Fis. Mat. Natur. Rend. Lincei (9) Mat. Appl. 19 (2008), no. 3, 211–227.
- [13] V. Moroz and J. Van Schaftingen, *Bound state stationary solutions for nonlinear Schrödinger equations with fast decaying potentials*, Calc. Var. Partial Differential Equations 37 (2010), no. 1, 1–27.
- [14] R. Palais, *The principle of symmetric criticality*, Comm. Math Phys. 69 (1979), no. 1, 19–30.
- [15] M. Nauenberg, *Quantum wave packet on Kepler elliptic orbits*. Phys. Rev. A 40 (1989) 1133–1136.
- [16] D. Ruiz, *On the Schrödinger-Poisson-Slater system: behavior of minimizers, radial and nonradial cases*. Preprint.
- [17] D. Ruiz, *The Schrödinger-Poisson equation under the effect of a nonlinear local term*. J. Funct. Anal. 237 (2006), no. 2, 655–674.

- [18] M. Willem, Minimax theorems. Progress in Nonlinear Differential Equations and their Applications, 24. Birkhäuser Boston, Inc., Boston, MA, 1996.

DÉPARTEMENT DE MATHÉMATIQUE, UNIVERSITÉ LIBRE DE BRUXELLES, CP 214, BOULEVARD DU TRIOMPHE, B-1050 BRUXELLES, BELGIUM
E-mail address: `denis.bonheure@ulb.ac.be`

DÉPARTEMENT DE MATHÉMATIQUE, UNIVERSITÉ CATHOLIQUE DE LOUVAIN, CHEMIN DU CYCLOTRON 2, 1348 LOUVAIN-LA-NEUVE, BELGIUM

DÉPARTEMENT DE MATHÉMATIQUE, UNIVERSITÉ LIBRE DE BRUXELLES, CP 214, BOULEVARD DU TRIOMPHE, 1050 BRUXELLES, BELGIUM
E-mail address: `Jonathan.DiCosmo@uclouvain.be`

S.I.S.S.A./I.S.A.S., VIA BONOMEA 265, 34136 TRIESTE, ITALY
E-mail address: `mercuri@sissa.it`