Jeep variants

Applications of convoy formulations

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The jeep problem was first solved by O. Helmer and N.J. Fine. But not much later, C.G. Phipps formulated a more general solution. He formulated a so-called convoy or caravan variant of the jeep problem and reduced the original problem to it.

The convoy idea of Phipps was refined in [3]. Here we will apply this refined idea to several variants of the jeep problem.

Key Words: The jeep problem; Phipps' jeep caravans; Dewdney jeeps.

1. A FINE JEEP AND DEPOTS TO BE USED

Suppose we have a jeep that has a fuel capacity of one tankload of fuel, which can ride one distance unit per tankload. Furthermore, the jeep may set up depots of fuel on any position in the desert for future use. We call such a jeep from now on a *Fine jeep*.

Say we have a Fine jeep that must cross a desert in order to reach an oasis, and possibly return to the desert border afterwards. How can this be achieved with a minimal amount of fuel, which is available at the desert border? This problem was solved first in [8] and [7].

We now consider the problem of a Fine jeep crossing the desert in order to reach an oasis, with both depots to be used and depots to be filled. Although we assume that there is only one jeep, we formulate the algorithm as a *backward convoy algorithm*, which has been introduced in [3] using ideas of [13]. The algorithm is both for the outward trip case and the return trip case. For the moment, we assume that the jeep has to end at the oasis finally in the outward trip case.

One of the aspects of a backward convoy algorithm is that compared to a normal algorithm, time is in fact eliminated. But in case of depots to be

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used, time might matter, since some depot must be reached first, before its fuel can be used. So in general, there are positions where fuel is more scarce before than after some depot is reached.

To take this into account, we will split the backward convoy into two parts at some depots. One part is the reaching part: a *forward refueling subconvoy* with relatively less fuel. The other part is the using part: a *backward refueling subconvoy* with relatively more fuel. In case of a round trip to the oasis, one of the double jeeps splits in fact in two single jeeps: one for each subconvoy. The single jeep for the backward refueling convoy is in fact a returning single jeep and therefore called a *ringle jeep*. The other single jeep is just called a single jeep.

In a backward convoy, the forward refueling subconvoy has at most one tankload of fuel, but on the contrary, the backward refueling subconvoy has at most one tankload of *emptiness* in its tanks. As soon as the backward refueling subconvoy gets one tankload of emptiness, one of its jeeps is canceled. This canceling takes only one tankload of fuel, and therefore eliminates all emptiness in the backward refueling convoy.

For an easier formulation, we assume by definition that there is always a forward and a backward refueling subconvoy. The backward refueling subconvoy is improper if it is reduced to a convoy without jeeps or an empty ringle jeep.

ALGORITHM 1.1. Start with a single jeep with one tankload of fuel and possibly an empty ringle jeep. If there is fuel at the oasis, then do the handler of event 1 first. Ride to the desert border. Each time the forward refueling subconvoy gets out of fuel, a double jeep with one tankload of fuel is added to it. A backward refueling subconvoy that only consists of one empty ringle jeep uses fuel of the forward refueling subconvoy.

Event 1: The convoy meets a depot with fuel.

Handler: The forward refueling subconvoy absorbs as much fuel as possible, but each time this subconvoy gets more than one tankload of tank fuel, it cancels a double jeep with one tankload of fuel. If there is more fuel than the forward refueling subconvoy can accept, then we call the current position a *saturation point*. At a saturation point, the backward refueling subconvoy absorbs all remaining fuel. It creates a double jeep with one tankload of fuel each time it gets more fuel than it can absorb. This new double jeep with one tankload of fuel can absorb another tankload of fuel, since its tankfuel capacity is two tankloads.

If fuel need to be restored at the current position for the party organization, or – even worse – more fuel has to be put on the current position than there was before this handler, then do the handler of event 2 first. Ride to the desert border with both subconvoys. The backward refueling subconvoy cancels a double jeep with one tankload of fuel each time it gets

more than one tankload of tank emptiness, since then one double jeep less is required to transport all fuel.

Event 2: The convoy meets a depot to be filled.

Handler: Use fuel of the backward refueling subconvoy, canceling a double jeep with one tankload of fuel each time this subconvoy gets more than one tankload of tank emptiness. If more fuel is needed than the backward refueling subconvoy can give, then the forward refueling subconvoy must give the remaining fuel. To do this, it creates as many double jeeps with one tankload of fuel each as necessary.

Eventually at the desert border, the fuel tanks of the forward refueling subconvoy are filled up to a level of one tankload. The fuel of the tanks of the backward convoy above the level of one tankload, as well as all tank fuel from the ringle jeep, can be returned at the desert border if that is allowed.

In case there is a position where fuel can be used but where fuel has to be put as well, then possibly double jeeps are created that are canceled on the same position in algorithm 1.1. But an algorithm in which this does not happen needs more words. Furthermore, a position may be a saturation point, even if on balance, it requires fuel.

Before we prove the optimality of algorithm 1.1, we formulate a trivial but very important result, which is used implicitly in [11] as well.

PROPOSITION 1.1 (Split Lemma). Suppose we have a Fine jeep that rides from a to b, using fuel from the desert and passing x one or more times. Suppose that this jeep executes some fuel transportations as well along the way.

Then the same consumptions and transportations of fuel can be done by two Fine jeeps in the following way. One jeep rides from $\min\{a, x\}$ to $\min\{b, x\}$ and the other jeep rides from $\max\{a, x\}$ to $\max\{b, x\}$, both without passing x. If we allow borrowing fuel at x that is not yet carried to x, then both jeeps may ride after each other in any order.

Proof. The proof is left as an exercise to the reader.

Let a *rejoining point* be a position where the backward refueling subconvoy gets improper. Now we are ready for our final theorem.

THEOREM 1.1. Algorithm 1.1 is optimal and can be executed as a normal algorithm.

Proof. Let S be a normal algorithm where the jeep reaches the oasis, and T be an instance of algorithm 1.1 that has the same effect on fuel

depots as S, with a ringle jeep if and only if S is a round trip, but in which more fuel might be used from the desert border. We must show that no more fuel is used from the desert border in T. Furthermore, we must show that T can be executed as a normal algorithm as well.

We call the following positions *special*:

- Positions with fuel and rejoining points of T,
- The desert border and the oasis.

Let $G = \{G_1, G_2, \dots, G_r\}$ be the set of special points with $G_1 > G_2 > \dots > G_r = 0$.

Split S into parts S_i on $[G_{i+1}, G_i]$ by way of the split lemma. Split T into parts T_i on $[G_{i+1}, G_i]$. First, we prove that T is optimal. After that, we show that T can be transformed into a normal algorithm.

In order to prove that T is optimal, we show that each of its parts T_i is optimal. Assume by induction that T_1, \ldots, T_{i-1} are optimal. Then in T_{i-1} , at least as much fuel is dumped on G_i or at most as much fuel is taken from G_i on balance as in S_{i-1} . So in T_i , at most as much fuel need to be dumped on G_i or at most as much fuel may be taken from G_i on balance as in S_i .

In case there is no proper backward convoy on the interval (G_{i+1}, G_i) in T, it follows from [3, Th. 4.1] that we can change S_i into a normal algorithm that follows algorithm 1.1. So assume that there is a proper backward convoy on the interval (G_{i+1}, G_i) in T.

There are normal algorithms T_{i1} and T_{i2} corresponding to the forward and backward refueling subconvoy of T respectively over the interval $[G_{i+1}, G_i]$. Since there is no rejoining point between G_{i+1} and G_i exclusive, no fuel is taken from position G_{i+1} in T_{i2} .

 S_i can be split into a part S_{i1} before reaching G_i for the first time and a part S_{i2} after that. If we apply [3, Th. 4.1] on S_{i1} , with the desert border and the oasis replaced by G_{i+1} and G_i respectively, we see that in T_{i1} , no more fuel is used as in S_{i1} .

If we apply [3, Th. 4.1] on S_{i2} , with the desert border and the oasis replaced by G_i and G_{i+1} respectively, we see that we may assume that S_{i2} is derived from a backward convoy algorithm. In a backward convoy algorithm, and hence in S_{i2} , fuel molecules do not need to cross each other. So we may assume that in S_{i2} , either G_i -fuel does not reach G_{i+1} or only G_i -fuel is used.

In the former case, T_{i2} is at least as economical as S_{i2} , since no G_{i+1} fuel is used in T_{i2} . In the latter case, it follows from [3, Th. 4.1] that the amount of G_i -fuel of T and S which reaches G_{i+1} is at least as large in T_{i2} as in S_{i2} . It follows that T_i is optimal.

So the optimality of T follows by induction. Next, we need to show that T can be executed as a normal algorithm. Notice that each of the parts T_{ij} can be executed as a normal algorithm. The only problem is to combine them such that on the special points G_i , no temporary underflows of fuel occur. Assume first that S is a two-way trip. Then T can be executed as a normal algorithm in the order $T_{(r-1)1} \ldots T_{11}T_{12} \ldots T_{(r-1)2}$. This is because the forward parts $T_{(r-1)1} \ldots T_{11}$ are constructed in such a way that only present fuel of the point G_i is used, and in the backward parts $T_{12} \ldots T_{(r-1)2}$, the amount of fuel first only increases and then only decreases on the points G_i .

In case S is a one-way trip, things are more difficult. Assume first that in (G_{i+1}, G_i) , the backward refueling subconvoy is improper. If we do T in the order $T_{r-1}, \ldots, T_{i+1}, T_i, T_{i-1}, \ldots, T_1$, then temporary underflows of fuel might occur, but not during T_i . In order to remove all temporary underflows, we only need to look at blocks of intervals (G_{i+1}, G_i) where the backward convoy is proper.

Let $(G_j, G_{j-1}), \ldots, (G_{i+1}, G_i)$ be such a block. Split T_{k2} into a part T_{k21} before reaching G_{k+1} for the last time and a part T_{k22} thereafter, and execute T_{j-1}, \ldots, T_i in the order $T_{(j-1)1} \ldots T_{i1} T_{i21} \ldots T_{(j-1)21} T_{(j-1)22} \ldots T_{i22}$. This way, no temporary underflows occur in T_{j-1}, \ldots, T_i , as can be shown with essentially the same arguments as in the round trip case.

In case the jeep does not need to end at the oasis or the desert border, the optimal algorithm is the best of the following.

1. The outward trip variant of 1.1.

2. The round trip variant of 1.1.

3. All variants of 1.1 that start with a ringle jeep, but where at some rejoining point, the ringle jeep is thrown away.

The reader may show this. In the normal algorithm corresponding to 3., the jeep ends where the ringle jeep is thrown away.

2. A CONVOY ALGORITHM FOR DEWDNEY JEEPS

We already met Dewdney jeeps in Maddex' jeep problem. A Dewdney jeep has a tank of one unit and in addition, it can transport B cans of C units each. The depots must be made of cans and only can fuel may be used to fill them.

We consider the problem of crossing a desert of d miles $n = n_1 + n_2$ times to reach an oasis on position d, of which exactly n_2 times in both ways. There are n + m Dewdney jeeps to do so, of which exactly $n_1 + m_1$ jeeps do not need to return to the desert border finally. Instead, they may end up anywhere in the desert.

In the backward convoy algorithm for normal jeeps, we did not care in what jeep fuel was transported, since there were no restrictions on trans-

ferring fuel from one jeep to another. In this sense, fuel was global, i.e. belonged to the whole convoy. In the backward convoy formulation with Dewdney jeeps, we will only see the can fuel as global fuel. But fuel in a jeep's fuel tank is local to that jeep.

We allow jeeps to consume can fuel directly, instead of by way of their fuel tank. This is no problem, since instead the jeeps can get a little fuel from the cans such that the convoy can advance a little farther. Despite the fact that tank fuel is local, we will allow jeeps to consume tank fuel from other jeeps in a *backward convoy algorithm for Dewdney jeeps*, but only if the receiving jeep is created at the lowest position. The idea behind this is the following: the receiving jeep is actually created on an even later moment in the backward convoy and its transportation before its real creation is done by means of to and fro's of the jeep which tank fuel is used.

Furthermore, we allow double jeeps to be replaced by single jeeps in the backward convoy algorithm for Dewdney jeeps. If such a replacement takes place on position p, then the following happens in a normal algorithm: the jeep rides from position 0 to a position farther than p first and returns to position p finally.

If on a position, both a single and a double jeep are created, then the double jeep may consume fuel from the tank of the single jeep. So the fuel of the backward convoy can be ordered by applicability. The tank fuel of the jeep that is created the last in the backward convoy is the least applicable, and the can fuel as well as the tank fuel of the n_1 initial single jeeps is the most applicable, provided $n_1 > 0$.

If we include fuel depots with fuel to be used in the backward convoy algorithm for Dewdney jeeps, then cans may become scarce, just as with Maddex' jeep problem. A solution is to use jeeps that have a tank capacity of one unit and can transport BC units of fuel in addition, fuel that may be put in any proportion on the desert just as the fuel of Fine jeeps. Next, we could try to formulate an algorithm for one jeep just as in section 1.

But besides saturation points, there is other trouble that can occur. Suppose we have a depot with fuel to be used. Now it seems optimal to use that fuel to cancel as many double jeeps as possible. But in order to do that, these double jeeps should be able to use all tank fuel available. This is impossible, since tank fuel is not global. For this reason, we do not include depots with fuel to be used in the backward convoy algorithm for Dewdney jeeps.

ALGORITHM 2.1. Start with a convoy at position d with n_1 single jeeps and n_2 double jeeps initially, all jeeps with B full cans of C units of fuel each and one unit of tank fuel. If a depot has to be filled at position d, then call the handler of event 1 first. After that, ride to position 0 with the whole convoy. Each jeeps consumes the least applicable fuel it can

consume, so a jeep use its own tank fuel first, then other tank fuel and at last can fuel.

Event 1: The convoy meets a position where a depot has to be filled.

Handler: Use can fuel to make the depot. If there is not enough fuel to make the depot, then call the handler of event 2 first and then repeat this handler. Otherwise, advance to 0.

Event 2: There is at least one jeep that can not ride farther any more, due to lack of fuel.

Handler: Create a new double jeep with one unit of tank fuel and B full cans of C units of fuel each. If the convoy has less than $m_1 + n_1$ single jeeps now, then replace the oldest double jeep in the backward convoy by a single jeep.

Eventually at the desert border, the amount of fuel of all jeeps is made equal to one unit. So the result of the algorithm is the number of jeeps minus the final amount of fuel.

3. OPTIMALITY RESULTS FOR CONVOYS OF DEWDNEY JEEPS

In the backward convoy algorithm for Fine jeeps in [3], it was possible to remove double jeeps in an extended convoy algorithm if they contained exactly one unit of fuel in their tank. Since the amount of tank fuel can not be controlled with Dewdney jeeps, other methods are needed to remove double jeeps, which we call *jeep merges*. We distinguish two jeep merges:

1. A single jeep and a double jeep with r units of tank fuel together merge to a single jeep with r-1 units of fuel, where $1 \le r \le 2$.

2. Two double jeeps with r units of tank fuel together merge to a double jeep with r-1 units of fuel, where $1 \le r \le 3$.

For each of both merges, B full cans of fuel has to be payed. We allow these jeep merges in an *extended backward convoy algorithm for Dewdney jeeps*, but we do not allow jeeps to consume tank fuel of other jeeps now. Although cans may be transported in backward direction in a normal algorithm, we do not need double jeeps to carry such things as anti-cans, since each such can must be transported in forward direction first. Thus with time eliminated, we can demand that the number of cans each jeep carries lies between 0 and B inclusive in an extended backward convoy algorithm.

Suppose that some jeep turns from backward to forward at some position p > 0. If that jeep passes p after this turn, then this turn corresponds to merge 2, otherwise it corresponds to merge 1. Some jeep merges are illustrated in figure 3. A jeep that rides back to p > 0 and stays there



FIG. 1. An illustration of several types of jeep merges

corresponds to a creation of a single jeep at p, immediately followed by a merge of type 1 at position p.

PROPOSITION 3.1. A normal algorithm for Dewdney jeeps can be transformed to an extended backward convoy algorithm for Dewdney jeeps.

Proof. The proof is similar to that for Fine jeeps instead of Dewdney jeeps in [3, Prop. 3.1], and therefore omitted.

The problem of making a normal algorithm for Dewdney jeeps from a backward convoy algorithms for Dewdney jeeps will be discussed in section

4. For that reason, the word 'optimal' in the theorems below should be read as 'at least as good as an optimal normal algorithm' for the present.

THEOREM 3.1. Algorithm 2.1 is optimal.

Proof. Consider an extended backward convoy algorithm for Dewdney jeeps. We do not transfer can fuel to fuel tanks until position 0: jeep must consume can fuel directly instead. So all jeeps have at most one unit of tank fuel each. Furthermore, we impose the following harmless assumption on the backward convoy algorithm: we postpone adding a jeep to the convoy until no can fuel is left, except if the added jeep is merged immediately.

We first show that jeep merges always coincide with jeep creations, i.e. each jeep merge implies a jeep creation at the same place. Suppose that this is not the case. Say that at the first merge that does not coincide with a jeep creation, some jeep A with x units of tank fuel is merged with a jeep B with y units of tank fuel, where $x \leq y$.

If the number of jeeps of the backward convoy is n before the merge, then the merge will make the number of jeeps of the convoy too small; contradiction. If the number of jeeps of the convoy is more than n, then at least one jeep has already been added to the initial convoy for another reason than a merge. The only reason for that jeep addition can be that the convoy ran out of can fuel. It follows that the amount of can fuel is less than $B \cdot C$ now, which is not enough for a merge; contradiction.

A merge implies a jeep creation at the same place, but both do not cancel out in general. Suppose we have a creation of a jeep and a merge of two other jeeps. The amount of tank fuel of the created jeep is equal to one, but the merging jeeps might have other amounts of tank fuel. Say that at the first merge of the backward convoy, a jeep A with x units of fuel merges with a jeep B with y units of tank fuel, where jeep A is created before jeep B. The jeep merge results in a jeep with x + y - 1 units of tank fuel. Simultaneously, a new jeep with one unit of tank fuel must be created. Since we do not transfer can fuel to fuel tanks before position 0, $y \leq 1$. Therefore, the above jeep merge and jeep creation can be simulated by transferring 1 - y units of tank fuel from jeep A to jeep B, if we allow jeeps to change type between single and double jeep.

Subsequent jeep merges can be simulated in a similar matter. So if we allow that tank fuel is transferred from a jeep A to a jeep B if Ais created before B, as well as changes of type, then jeep merges are no longer necessary. Instead of transferring tank fuel from jeep A to jeep B, we allow jeep B to consume the tank fuel of jeep A directly, just as in algorithm 2.1.

Since tank fuel may be transferred from older jeeps to newer jeeps and single jeeps are more economical than double jeeps, we may assume that the oldest jeeps are single jeeps and the newest jeeps are double jeeps. This is the case in algorithm 2.1. Furthermore, the total number of jeeps is minimal and as many jeeps as possible are single jeeps all the time in algorithm 2.1. So algorithm 2.1 is optimal.

4. A NORMAL ALGORITHM FOR DEWDNEY JEEPS

Let us first turn algorithm 2.1 into a normal convoy algorithm under the assumption that the number of jeeps is unlimited. The problem that must be overcome is that transferring tank fuel from one jeep to another is not allowed. Fortunately, the jeep that receives fuel is always a double jeep and the jeep from which tank fuel is taken is always created earlier in algorithm 2.1. Therefore, the farthest miles of the receiving double jeep can be done by to and fro's of the jeeps corresponding to the single and double jeeps from which tank fuel is taken.

However, some of the n_2 initial double jeeps might consume tank fuel from other jeeps, which makes that the n_2 round trips might be scattered. This is solved by taking all to and fro's together, and next apply the split lemma to give each jeep that perform to and for's an interval that corresponds to its moment of creation in the backward convoy algorithm. It is tank fuel that is used for these to and fro's, thus the jeeps doing them do not need to be with each other to share a can.

Notice that also jeeps corresponding to double jeeps can be ordered to do to and fro's: the double jeep becomes a single jeep later in the backward convoy, saving fuel with respect to the double jeep that receives the tank fuel. As said before, a double jeep that is replaced by a single jeep at position p > 0 in algorithm 2.1 corresponds to a jeep that reaches farther than position p and finally ends at position p in a normal algorithm.

So we can replace algorithm 2.1 by a backward convoy algorithm where no transfers of tank fuel occur, if we see single and double jeeps from which tankfuel is used as triple and quadruple jeeps respectively or bigger. Subsequently, we can formulate a normal algorithm for an unlimited number of jeeps, where those jeeps ride together as far as they are riding on that moment.

Next, assume that there is a limited number of jeeps. Then double jeeps that are replaced by single jeeps might be a serious problem. For that purpose, we start with assuming that $m_1 = 0$. The next problem is that the round trip might be scattered. Therefore, we additionally assume that there are at least n jeeps.

Thus cosider the case that there are exactly n jeeps. Notice that jeeps do not use tank fuel of other jeeps any more after the creation of the $(n+1)^{\text{th}}$ jeep in the backward convoy. Think of the $(n+1)^{\text{th}}$ jeep as a round trip

before the convoy rode out, possibly the farthest reaching jeep of another convoy of at most n jeeps. The (n + 1)th jeep is needed for fuel, so a can is opened.

Now the jeeps in the backward convoy can absorb their portions of the fuel of this can as long as it does not exceed their tanks. If that is the case, the can does not need to be dragged with the backward convoy and it is thus no problem that the convoy is split in subconvoys of at most n jeeps in a normal algorithm, provided we assume that the (n+1)th jeep fills the depots with their portions of fuel from that same can in its outward trip.

More generally, making a normal algorithm is straightforward, as long as the jeeps of the backward convoy can absorb their portions of fuel of the cans after the creation of the $(n + 1)^{\text{th}}$ jeep all the time. So assume that at some point in the backward convoy, a can is opened with more can fuel than the jeeps can absorb. Say that x is the position closest to the desert border where this happens. Let y be the position where the next can is opened in the backward convoy, in case that occurs, and y = 0 otherwise.

We can get a normal algorithm as follows. First, the jeeps ride out in convoys of at most n jeeps to positions less than y, returning to the desert border, provided y > 0. Next, all n jeeps ride to y and next to x, where some jeeps ride to and fro's between y and x, but no jeep gets too far away from the jeep with the can that is opened at position x in the backward convoy. After that, all riding on positions farther than x is done, and induction tells us how, where the desert border is replaced by x. Finally, zero or more jeeps return to the desert border.

5. DEWDNEY JEEPS WITH SEALED CANS

We now consider the problem of Dewdney jeeps with *sealed cans*. In order to take fuel from a sealed can, it must be unsealed. But after unsealing, a can must not be transported any more. It is however not necessary for an unsealed can to be emptied immediately.

We first give a backward convoy algorithm for Dewdney jeeps with sealed cans. Since unsealed cans can be seen as fuel depots to be used, we allow both additional fuel depots to be used and fuel depots to be filled. Depot fuel to be used may be put in the fuel tanks of the jeeps. Can fuel has to be used to fill depots with the indicated amount of fuel.

The problem has some similarities with that of the Fine jeep in section 1. For that problem, it was relatively hard for the jeep to reach a position with lots of fuel and relatively easy after reaching this position. Since each jeep in the convoy must reach such a position, the actual number of jeeps matters. For that reason, we assume that there are exactly n jeeps, all of which have to reach an oasis, of which n_1 jeeps stay at the oasis and n_2

jeeps return to the desert border. Double jeeps that are added later to the backward convoy are to and fro's of the above n jeeps.

For the to and fro's that are global in nature, we add *red double jeeps* for forward loops of the above n jeeps, and *blue double jeeps* for backward loops of the above n jeep. The red and blue double jeeps are replaced by each other when the loop ends. Blue double jeeps have some similarities with the backward refueling subconvoy in section 1.

For very local to and fro's, we introduce another type of jeep, namely *spider jeeps*. Spider jeeps are double jeeps without a fuel tank, which can consume tank fuel of other jeeps. From above, a spider jeep that uses tank fuel of eight surrounding regular jeeps looks like a spider. Spider jeeps may replace or may be replaced by red and blue double jeeps.

ALGORITHM 5.1. Start with a convoy at position d, with n_1 single jeeps with one unit of tank fuel and n_2 regular double jeeps with one unit of tank fuel initially. All jeeps get B sealed cans of C units of fuel each. If there is a depot at d to be used, then call the handler of event 1 first. Ride to position 0 with the whole convoy.

Spider jeeps that are created along the way consume fuel of any other type of jeep with relatively the most fuel, until all such jeeps have at most 50 percent of tank fuel. At that point, all spider jeeps are replaced by red double jeeps.

Blue jeeps that get only one unit of tank fuel are removed from the backward convoy in case there are B sealed cans of C units available to do so. Otherwise, they are replaced by spider jeeps if there is a jeep with more than 50 percent of tank fuel at that moment and by red jeeps if all jeeps have at most 50 percent of tank fuel.

Due to riding, the relative amount of tank fuel decreases at a rate that is equal for all jeeps. Since spider jeeps affect the relative amount of tank fuel of the relatively fullest jeep, the difference in relative amount of tank fuel cannot get larger than 50 percent between two jeeps. Neither do the events below affect this difference property.

Event 1: The convoy meets a depot to be used.

Handler: Distribute the fuel amongst the tanks of regular jeeps and red double jeeps in the backward convoy, such that the minimum relative amount of tank fuel becomes as large as possible, but do not give fuel when tanks get or are more filled than 50 percent. If the relative amount of tank fuel for these jeeps gets 50 percent, then replace all red double jeeps by spider jeeps.

If there is still fuel left, then distribute the fuel amongst all regular jeeps, such that the minimum relative amount of tank fuel of the regular jeeps becomes as large as possible. If there is more fuel than these jeeps can accept, then fill the tank of the blue double jeep with the most tank fuel.

If there is still fuel left, then advance with the blue double jeep with the next most tank fuel, etc.

If there is still fuel left, then replace a spider jeep by a blue double jeep with one unit of tank fuel and fill that blue jeep up to two units. If this is not enough to absorb all fuel, then do the same with another spider jeep, etc. If there is still fuel left, then create a new blue double jeep with one unit of tank fuel and fill its tank. Create blue double jeeps until all fuel can be absorbed. Advance to 0.

Event 2: There is at least one jeep that gets out of fuel and can not ride farther any more.

Handler: Notice that there are no jeeps that are more than half filled, and thus no blue jeeps or spider jeeps. Unseal a can and do the handler of event 1, seeing the opened can as a fuel depot. If there is no can to be unsealed, then create a new red double jeep with one unit of tank fuel and B sealed cans of C units of fuel each first. Advance to 0.

Event 3: The convoy meets a depot to be filled.

Handler: Unseal as many cans as necessary to fill the depot. If there is still fuel needed, then create as many spider jeeps with B cans of C units as necessary. In the last can, some fuel might remain.

Assume first that there is no jeep with more than 50 percent of tank fuel. Then replace all (above) spider jeeps by red double jeeps with one unit of tank fuel. After that, perform the handler of event 1 for the remainder of the last can, if there is. Next, advance to 0.

Assume next that some jeep has more than 50 percent of tank fuel. If some regular double jeep has more than 50 percent of tank fuel and a spider jeep was created to provide some cans, then replace the spider jeep that provided the last can by a blue double jeep with one unit of tank fuel, and use the remainder of the last can to fill the tank of this blue double jeep, until the last can is empty or the blue double jeep has the same amount of fuel as the regular double jeep.

Next, if some can fuel remains in the last can, then perform the handler of event 1 for it. After that, advance to 0.

Eventually at the desert border, the amount of fuel of all jeeps is made equal to one unit. So the result of the algorithm is the number of jeeps minus the final amount of fuel.

In algorithm 5.1, the types of jeeps indicate more or less how a normal algorithm for Dewdney jeeps with sealed cans should look. Furthermore, the cans do not move any more after being opened, so there is not much difference between them in algorithm 5.1 and in a normal algorithm. Nevertheless, making a normal algorithm of algorithm 5.1 is not always possible.

One problem occurs in event 3, in case some fuel remains after filling the depot and there are blue double jeeps. In that case, the can of the remaining fuel must be from a regular jeep or red jeep, since otherwise the regular jeeps and red jeeps are too early to take advantage of the fuel that remains after filling the depot.

Thus is it a good idea to use the cans of blue double jeeps first, but not those of the blue double jeeps that will be canceled, since all the *B* cans of such a jeep are needed for that. Another option is that cans are transferred from a blue double jeep or a spider jeep to a regular jeep, but this is not always possible. It is however possible for blue jeeps at creation and for spider jeeps when there are no blue jeeps.

Talking about the spider jeeps, there is another problem that might occur when making a normal algorithm of algorithm 5.1. The problem is that a spider jeep must use tank fuel of blue jeeps before tank fuel of regular jeeps, since the blue jeeps ride later in a normal algorithm. Sometimes, even the order of blue jeeps matters. In section 7, we will however show that this problem can be overcome.

Another problem occurs when in the last mile of algorithm 5.1, the miles closest to the desert border, the amount of tank fuel in one of the double jeeps becomes larger than x + 1 on position x. We discuss this problem in the rest of this section.

Although the backward convoy algorithm can not always be seen as a normal algorithm (i.e. more fuel is required for a normal algorithm), we roughly describe a way to make a normal algorithm from a backward convoy algorithm first. We start with a convoy of $n_1 + n_2$ jeeps riding the outward part and n_2 jeeps riding the return part. But then, we do not have enough transportation.

Therefore, we add forward loops and backward loops to make the normal algorithm complete. A blue double jeep implies a backward loop there and a red double jeep implies a forward loop there.

We now show that algorithm 5.1 can not always be seen as a normal algorithm. Let $n_1 = 0$ and suppose that there are $n_2 = 5$ double jeeps when the backward convoy reaches position 1. Suppose that all 5 jeeps are empty then and there are only 2 cans of 1 unit of fuel each. Then both cans are unsealed and the convoy can ride to $\frac{4}{5}$ before getting empty again. At position $\frac{4}{5}$, a new double jeep is created and a new can is unsealed. The convoy rides farther to position $\frac{3}{4}$. Next, assume that there is an unlimited depot at position $\frac{3}{4}$. All jeeps can get completely filled at position $\frac{3}{4}$ and can ride to position 0, which they reach with half a unit of tank fuel each.

In order to be canceled, another half a unit of fuel is needed for each jeep, and of course, the cans that are used in the algorithm. But in a normal algorithm, the $n_2 = 5$ initial jeeps need more fuel: at least $\frac{3}{4}$ units of fuel each to be able to reach the unlimited depot at $\frac{3}{4}$ from position 0. The

bound on the amount of fuel is only met if returning tank fuel is allowed at position 0. So it seems a good idea, not to allow more than 1 + x units of tank fuel in initial double jeeps, where x is the position of the jeeps. Similarly, it seems a good idea to bound the amount of fuel in an added double jeep by 1 + 2x, since otherwise such a jeep reaches position 0 with more than 1 unit of tank fuel and can not be canceled. But on $\frac{3}{4}$, the amount of tank fuel of the jeep that is added on position $\frac{4}{5}$ is bounded by 2 rather than $\frac{5}{2}$.

This way, $5 \cdot \frac{3}{4} + \frac{1}{2} = 4\frac{1}{4}$ units of fuel are needed at position 0. But in the following way, the $\frac{1}{2}$ unit of fuel of the added double jeep can be saved and only $3\frac{3}{4}$ units are needed at position 0, i.e. 4 instead of 5 cans. First, the 5 jeeps ride to position $\frac{3}{4}$, using $\frac{3}{4}$ units of fuel from position 0 each. Then, they ride to position 1 and completely refill there, by way of $\frac{5}{4}$ units of can fuel. For that purpose, 2 cans of 1 unit of fuel are unsealed at position 1, so $\frac{3}{4}$ units of can fuel remains. After that, the jeeps go to the oasis and ride back to position 1. Until now, the difference with algorithm 5.1 is that the can at position $\frac{4}{5}$ is not transported yet and can fuel from position 1 is used instead.

The 5 jeeps reach position 1 empty in the return trip. Now, only 3 of them ride farther, using the remaining $\frac{3}{4}$ units of can fuel at position 1. These three jeeps just reach the unlimited depot at position $\frac{3}{4}$. From position $\frac{3}{4}$, the first jeep rides to position 0, carries a can from 0 to $\frac{1}{8}$ and rides back to 0. The second jeep rides to $\frac{1}{8}$, carries the can there to $\frac{1}{4}$ and rides to 0. The third jeep fetches the can at position $\frac{1}{4}$ and rides to position 1. All remaining 3 jeeps ride back to position 0 using fuel from the last can and the unlimited depot.

So we get the following question. Does the above method of restricting the amount of tank fuel from double jeeps work in case there are no real depots in the last mile of the backward convoy algorithm, but only unsealed cans? The answer is affirmative, which the reader may show.

6. OPTIMALITY RESULTS FOR DEWDNEY JEEPS WITH SEALED CANS

We first show that jeep merges do not work with depots of fuel to be used. Let x be a position with a depot of fuel to be used. Say that 2^k double jeeps get completely filled. When those jeeps reach $x - \frac{1}{2}$, they have become half filled, and they can merge to 2^{k-1} completely filled jeeps. When these 2^{k-1} double jeeps reach x - 1, they can merge to 2^{k-2} completely filled jeeps, etc.

For that reason, we do not allow jeep merges in an *extended backward* convoy algorithm for dewdney jeeps with sealed cans. Instead, we allow a double jeep with one unit of tank fuel and B cans with C units of fuel to be

canceled. In addition, we allow spider jeeps to consume tank fuel of other jeeps.

LEMMA 6.1. Assume f is a nowhere constant function of time with finitely many local extrema, of which one local minimum in the interior of its time interval. If f has a global minimum at the beginning of its interval and another global extremum at the end, then up to a transformation of time, the graph of f has one of the following subgraphs.



Proof. Starting at the beginning of the time interval, local maxima and minima vary. These extrema cannot get closer and closer to each other, so we have the following:



PROPOSITION 6.1. A normal algorithm for Dewdney jeeps with sealed cans can be transformed to an extended convoy algorithm for Dewdney jeeps with sealed cans.

Proof. Notice first that each jeep can do the things it should do by means of finitely many changes of direction. So there are only finitely many local extrema. Furthermore, a normal algorithm for which the jeeps do not have interior local minima is already an extended convoy algorithm for Dewdney jeeps with sealed cans. So assume that one of the jeeps, say jeep J, has an interior local minimum. Then the graph of that jeep has a subgraph as in lemma 6.1, where $t_1 < t_2 < t_3$ and $t_4 \notin [t_1, t_3]$. We distinguish three cases:

i) There is a position in the subgraph where jeep J gets twice with the same amount of tank fuel.

Then we can cut off the part in between the two moments at that position from the path of J and replace it by a double jeep. Since the part that is cut off must contain a refuel position (possibly on the edge), the number of times jeep J gets on a refuel position decreases.

ii) Jeep J has more tank fuel on moment t_3 than on moment t_1 . Assuming that we do not have case i), we see that jeep J has more fuel directly after t_2 than directly before t_2 . Thus jeep J refuels its tank on moment t_2 . Now move as much as possible of this refueling to moment t_4 . This results in a completely filled jeep J before t_2 , a completely empty jeep J after t_2 , or no refueling any more on moment t_2 .

If ii) is not preserved during the process, then restore some refueling on moment t_2 to make that jeep J has the same amount tank fuel on moment t_3 as on moment t_1 , such that case i) applies. So assume that ii) is still satisfied. The one can verify that i) applies in all three cases after transferring tank refueling from t_2 to t_4 .

iii) Jeep J has less tank fuel on moment t_3 than on moment t_1 .

Let p_1 be the position where the jeep is on t_2 and t_4 , and p_2 that on t_1 and t_3 . Let p_3 be the smallest refuel position of jeep J between t_1 and t_3 if there is such a position, and take $p_3 = p_2$ otherwise. Assuming that we do not have case i), we see that jeep J has less fuel directly before t_2 than directly after t_2 . Thus jeep J does not refuel on position p_1 on moment t_2 , i.e. $p_3 > p_1$.

Now cut off as much as possible from the round trip from p_3 to p_1 by jeep J as possible, and replace it by a spider jeep that uses tank fuel of jeep J, in the neighborhood of t_4 where jeep J rides from p_1 to p_3 (in case $t_4 < t_2$) or from p_3 to p_1 (in case $t_4 > t_2$).

This results in a completely empty jeep J before t_2 , a completely filled jeep J after t_2 , or that jeep J is on position p_3 on moment t_2 . In the first two cases, either i) or ii) applies. In the last case, jeep J gets one time less on refuel position p_3 as before if $p_3 < p_2$, and a better path in case $p_3 = p_2$ is not a refuel position.

By repeatedly focusing on interior local minima and reducing them, we get an algorithm where the jeeps do not have interior local minima. Thus we finally have an extended backward convoy algorithm for Dewdney jeeps with sealed cans.

THEOREM 6.1. Algorithm 5.1 is optimal.

Proof. As soon as a blue jeep is created in algorithm 5.1, the backward convoy consumes the tank fuel above the level of 50 percent first. Furthermore, given that all available fuel on the road is used, the blue jeeps are canceled as soon as possible if there are enough cans to do so. This is because there are no spider jeeps when there are B or more full cans.

If there are no blue jeeps, then the opening of a can for refueling purposes is postponed as long as possible in algorithm 5.1, and the use of spider jeeps is in such a way that subsequent unsealings for refueling are postponed as long as possible, too.

Since unsealing cans is postponed as long as possible in algorithm, 5.1, so is the creation of a new red double jeep or spider jeep for getting new cans. Thus algorithm 5.1 is optimal.

7. A NORMAL ALGORITHM FOR DEWDNEY JEEPS WITH SEALED CANS

Let $p_0 = 0$ and p_1, p_2, \ldots be the positions > 0 where the regular jeep with the least relative amount of tank fuel has 50 percent of tank fuel in algorithm 5.1, in increasing order. If the oasis to be reached is not included in the positions p_i , then add that as well, to obtain a finite sequence

$$0 = p_0 < p_1 < p_2 < \dots < p_k$$

If we do not count the to and fro's for spider jeeps, then the general scheme is the following. First, the n jeeps do all riding and transportations within $[0, p_i]$, except for n_2 jeeps riding from p_i to 0. Next, the jeeps do all riding and transportations within $[p_i, p_{i+1}]$ except for n_2 jeeps riding from p_{i+1} to p_i . After that, the jeeps do all riding and transportation within $[p_{i+1}, p_k]$. Finally, n_2 jeeps ride from p_{i+1} back to 0.

Notice that red double jeeps have at least as much fuel as regular double jeeps, but no more than 50 percent. On the other hand, blue double jeeps have at most as much fuel as regular double jeeps, but no less than 50 percent. From this, it follows that all double jeeps of any type have 50 percent of tank fuel on p_i for each 0 < i < k, and that the schemes for each i are compatible with each other.

So we only need to describe the riding and transportations within $[p_i, p_{i+1}]$. There are two cases: the relatively emptiest regular jeep has less than 50 percent of tank fuel or this jeep has more than 50 percent of tank fuel in $[p_i, p_{i+1}]$.

Assume first that the relatively emptiest regular jeep has less than 50 percent of tank fuel in $]p_i, p_{i+1}[$. Then all regular jeeps with the same multiplicity (single or double) have the same less than 50 percent of tank fuel in $]p_i, p_{i+1}[$. Furthermore, all double jeeps that are created in $[p_{i+1}, p_k]$

have 50 percent of tank fuel on p_{i+1} and all double jeeps that are created in $]p_i, p_{i+1}[$ are spider jeeps or red jeeps that have 50 percent of tank fuel when they are created.

So all riding of red double jeeps between p_i and p_{i+1} can be done by forward loops form p_i . Perform these forward loops first and ride with njeeps from p_i to p_{i+1} after that, where the n_1 single jeeps perform the to and fro's of the spider jeeps along the road.

If i = 0, then the amount of tank fuel of the jeeps performing the forward loop and regular double jeeps is $\min\{f(x)/2, x\}$ in the return part on position x and $\min\{1 - f(x)/2, 1 - f(x) + x\}$ in the outward part (instead of just f(x)/2 and 1 - f(x)/2 respectively), with f(x) being the amount of tank fuel of the red or regular double jeep at hand on position x. This is to ensure that jeeps return empty on position 0.

Assume next that the relatively emptiest regular jeep has more than 50 percent of tank fuel in $]p_i, p_{i+1}[$. Then all regular jeeps have more than 50 percent of tank fuel in $]p_i, p_{i+1}[$.

Looking at the backward convoy algorithm 5.1, we can see how much riding and transportations need to be done on each interval. With this, we do not count blue double jeeps that are canceled later together with their B cans. These jeeps can be removed from the backward convoy algorithm. This is because spider jeeps are only present in the convoy when there are less than B cans in case there are blue jeep, thus the above blue jeeps do not need to give tank fuel to other jeeps.

Now that the total number of double jeeps of any type is determined everywhere by algorithm 5.1, we replace event 1 of it by the following.

Event 1: The convoy meets a depot to be used.

Handler: Distribute the fuel amongst the regular jeeps and red double jeeps in the backward convoy, such that the minimum relative amount of tank fuel becomes as large as possible, but not larger than 50 percent. If the relative amount of tank fuel for these jeeps gets 50 percent, then replace all red double jeeps by spider jeeps.

If there is still fuel left, then replace all spider jeeps by blue double jeeps and create additional blue double jeeps until the number of double jeeps of any type is what it should be. Next, distribute the fuel amongst all regular and blue double jeeps, under the following conditions:

• The regular double jeeps must not get more than 1 + x units of fuel, where x is the current position, unless the regular single jeeps and blue double jeeps get 100 percent filled.

• The minimum amount of tank fuel for all regular jeeps and blue double jeeps is maximized as a first priority. Next, the minimum amount of tank fuel for all regular single jeeps and blue double jeeps is maximized.

Notice that the spider jeeps are replaced by blue double jeeps on position p_{i+1} . If we ignore the spider jeeps for a moment, then the blue double jeeps can be done as backward loops from the points where they are created or made blue.

So assume that some spider jeep occurs in $]p_i, p_{i+1}[$. The jeeps do not need tank fuel, since they are more than 50 percent filled or have enough to reach 0. Thus there is a depot to be filled. This is done by the spider jeep or a blue double jeep that becomes the spider jeep later in the backward convoy in $]p_i, p_{i+1}[$.

Some regular jeeps and blue double jeeps perform the to and fro's of these spider jeeps, and the order does not matter, since the regular jeeps and blue double jeeps doing so will not get any fuel as long as there are spider jeeps and blue jeeps with a less relative amount of fuel than the regular jeeps.

Therefore, the n regular jeeps start the spidering process, of which the n_2 double jeeps only half of it. Next, the blue double jeeps follow, and at last the other halves of the n_2 double jeep during their returns to the desert border.

This way, the remainder of the last can will not be available for the jeeps. But this remainder can be used for the transportation of some cans by a round trip of one jeep over the last part towards the depot, a round trip that can be performed by one of the n_2 double jeeps during their returns to the desert border, or any single jeep in case $n_2 = 0$.

8. CONCLUSION

We attained optimality results for many jeep variants, using convoy formulations as C.G. Phipps suggested. On the other hand, many jeep variants are still open. These jeep variants seem much harder to solve. So a lot of research can still be done on this topic.

I wonder what our godfather C.G. Phipps would have thought of this article. In his article [13, p. 462] he writes the following.

The number of variations upon these problems is almost endless. One could have rendezvous points where jeeps are to assemble. One could consider the delivery of a certain number of jeeps to another supply station by caravans meet halfway. Still another variation would be to have tank-trucks accompany the jeeps. Most of such problems can be worked by the general principles developed here.

Maybe, C.G. Phipps already knew most of the results attained in this article.

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