Common Fixed Point Theorems with Applications in Dynamic Programming

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Abstract

In this paper, the concepts of compatible mappings of type (A) and type (P) are introduced in an induced metric space, two common fixed point theorems for two pairs of compatible mappings of type (A) and type (P) in an induced complete metric space are established, and the

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existence and uniqueness results of common solution for a system of functional equations arising in dynamic programming as applications of these common fixed point theorems presented are discussed.

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1 Introduction and Preliminaries

Contractive type mappings and corresponding fixed or common fixed point theorems and their applications have been studied and discussed during the past decades, see [1-17] and the references therein. In particular, Huang, Lee and Kang [4] established a common fixed point theorems for two pairs of compatible mappings A, S and B, T in a complete metric space (X, d) which satisfy the following condition

$$d(Ax, By) \le \phi \Big(\max \Big\{ d(Sx, Ty), d(Sx, Ax), d(Ty, By),$$

$$\frac{1}{2} [d(Sx, By) + d(Ty, Ax)] \Big\} \Big), \quad \forall x, y \in X,$$

$$(1.1)$$

where $\phi : [0, \infty) \to [0, \infty)$ is nondecreasing, upper semi-continuous and $\phi(t) < t$ for all t > 0. Moreover, Pathak, Cho, Kang and Lee [17] produced several common fixed point theorems for two pairs of compatible mappings of type (P) satisfying (1.1).

As proposed in Bellman and Lee [1], the essential form of the functional equation in dynamic programming is

$$f(x) = \underset{y \in D}{\text{opt}} H(x, y, f(T(x, y))), \quad \forall x \in S,$$
(1.2)

where x and y denote the state and decision vectors, respectively. T denotes the transformation of the process, f(x) denotes the optimal return function with the initial state x, and the opt represents sup or inf.

Bhakta and Mitra [3], Huang, Lee and Kang [4], Liu [5-7], Liu, Agarwal and Kang [9], Liu and Kang [10-11], Liu and Kim [12], Liu and Ume [13], Liu, Ume and Kang [14], Liu, Xu, Ume and Kang [15], Pathak and Fisher [16], Pathak, Cho, Kang and Lee [17] and others established the existence and uniqueness of solutions or common solutions for several classes of functional equations or systems of functional equations arising in dynamic programming by means of various fixed and common fixed point theorems. Bhakta and

Choudhury [2] obtained two fixed point theorems by using countable family of pseudometrics and discussed also the existence of solutions for the following functional equation:

$$f(x) = \inf_{y \in D} G(x, y, f), \quad \forall x \in S.$$
 (1.3)

Aroused and motivated by the above achievements in [1-17], we introduce the following contractive type mappings and system of functional equations arising in dynamic programming, respectively,

$$d_k^{s+t}(fx,gy)$$

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(lx,hy), d_k(fx,lx), d_k(gy,hy),$$

$$d_k(fx,gy) \} \} \cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(lx,hy),$$

$$d_k(fx,lx), d_k(gy,hy), d_k(fx,gy) \},$$

$$q \in \{ d_k(fx,hy), d_k(gy,lx) \} \Big\} \Big\}, \quad \forall x,y \in X, k \geq 1,$$

$$(1.4)$$

where s and t are some nonnegative numbers with s+t>0 and $\varphi \in \Phi$, where $\Phi = \{\varphi : \varphi : \mathbb{R}^+ \to \mathbb{R}^+ \text{ is a continuous nondecreasing function satisfying } \varphi(t) < t, \quad \forall t>0\}$, and

$$f_{1}(x) = \underset{y \in D}{\text{opt}} \{ u(x, y) + H_{1}(x, y, f_{1}(T(x, y))) \}, \quad \forall x \in S,$$

$$f_{2}(x) = \underset{y \in D}{\text{opt}} \{ u(x, y) + H_{2}(x, y, f_{2}(T(x, y))) \}, \quad \forall x \in S,$$

$$g_{1}(x) = \underset{y \in D}{\text{opt}} \{ u(x, y) + G_{1}(x, y, g_{1}(T(x, y))) \}, \quad \forall x \in S,$$

$$g_{2}(x) = \underset{y \in D}{\text{opt}} \{ u(x, y) + G_{2}(x, y, g_{2}(T(x, y))) \}, \quad \forall x \in S.$$

$$(1.5)$$

The main aim in this paper is to study the existence and uniqueness of common fixed point for the contractive type mappings (1.4) in an induced complete metric space, which is generated by a countable family of pseudometrics $\{d_k\}_{k\geq 1}$. Under certain conditions, we prove two common fixed point theorems for the contractive type mappings (1.4). As applications, we use the common fixed point theorems presented to establish the existence and uniqueness results of common solutions for the system of functional equations (1.5).

Throughout this paper, let $\mathbb{R}^+ = [0, +\infty)$ and $\{d_k\}_{k\geq 1}$ be a countable family of pseudometrics on a nonempty set X such that for any distinct $x, y \in X, d_k(x, y) \neq 0$ for some $k \geq 1$. Define

$$d(x,y) = \sum_{k=1}^{\infty} 2^{-k} \frac{d_k(x,y)}{1 + d_k(x,y)}, \quad \forall x, y \in X.$$

It is clear that d is a metric on X and the metric d and the metric space (X,d) are called, respectively, an induced metric and induced metric space by the countable pseudometircs family $\{d_k\}_{k\geq 1}$, respectively. A sequence $\{x_n\}_{n\geq 1}\subseteq X$ converges to a point $x\in X$ if and only if $d_k(x_n,x)\to 0$ as $n\to\infty$ for each $k\geq 1$, and $\{x_n\}_{n\geq 1}\subseteq X$ is a Cauchy sequence if and only if $d_k(x_n,x_m)\to 0$ as $n,m\to\infty$ for each $k\geq 1$. The induced metric space (X,d) is called complete if each Cauchy sequence in X converges to some point in X. A self mapping f on (X,d) is said to be continuous in X if $\lim_{n\to\infty} fx_n = fx$ whenever $\{x_n\}_{n\geq 1}\subseteq X$ such that $\{x_n\}_{n\geq 1}$ converges to $x\in X$.

2 Unique Common Fixed Point Theorems

Throughout this section, we assume that (X, d) is the induced metric space by the countable pseudometrics family $\{d_k\}_{k\geq 1}$ such that for any distinct $x, y \in X, d_k(x, y) \neq 0$ for some $k \geq 1$.

Firstly, we introduce the concepts of compatible mappings of type (A) and type (P) in the induced metric space (X, d).

Definition 2.1. The mappings $g, h: (X, d) \to (X, d)$ are said to be *compatible of type* (A) if

$$\lim_{n \to \infty} d_k(ghx_n, hhx_n) = 0 \quad \text{and} \quad \lim_{n \to \infty} d_k(hgx_n, ggx_n) = 0, \quad \forall k \ge 1,$$

whenever $\{x_n\}_{n\geq 1}$ is a sequence in X such that $\lim_{n\to\infty} gx_n = \lim_{n\to\infty} hx_n = z$ for some $z\in X$.

Definition 2.2. The mappings $g, h: (X, d) \to (X, d)$ are said to be *compatible of type* (P) if

$$\lim_{n \to \infty} d_k(ggx_n, hhx_n) = 0, \quad \forall k \ge 1,$$

whenever $\{x_n\}_{n\geq 1}$ is a sequence in X such that $\lim_{n\to\infty} gx_n = \lim_{n\to\infty} hx_n = z$ for some $z\in X$.

Secondly, we establish two common fixed point theorems for contractive type mappings (1.4) in the induced complete metric spaces (X, d).

Theorem 2.3. Let the induced metric space (X, d) be complete and f, g, h and l be four self mappings of (X, d) such that

- (B1) one of f, g, h and l is continuous;
- (B2) the pairs f, l and g, h are compatible of type (A);
- (B3) $f(X) \subseteq h(X), g(X) \subseteq l(X);$
- (B4) there exist some $\varphi \in \Phi$, $s, t \in \mathbb{R}^+$ with s + t > 0 satisfying (1.4), then f, g, h and l have a unique common fixed point in X.

(2.2)

Proof. Let x_0 be an arbitrary point in X. In terms of (B3) there exist two sequences $\{x_n\}_{n\geq 0} \subseteq X, \{y_n\}_{n\geq 1} \subseteq X$ such that $fx_{2n} = hx_{2n+1} = y_{2n+1},$ $gx_{2n+1} = lx_{2n+2} = y_{2n+2}$ for $n \geq 0$. Define $d_{kn} = d_k(y_n, y_{n+1})$ for $n \geq 1$ and $k \geq 1$. We firstly demonstrate that

$$d_{kn+1}^{s+t} \le \varphi(d_{kn}^{s+t}), \quad \forall n \ge 1, \ k \ge 1.$$

$$(2.1)$$

In view of (1.4), we acquire that, $\forall k \geq 1$

$$d_{k2n+1}^{s+t}$$

$$= d_k^{s+t}(fx_{2n}, gx_{2n+1})$$

$$\leq \varphi \left(\max \left\{ \left\{ p^s q^t : p, q \in \left\{ d_k(lx_{2n}, hx_{2n+1}), d_k(fx_{2n}, lx_{2n}), d_k(gx_{2n+1}, hx_{2n+1}), d_k(fx_{2n}, gx_{2n+1}) \right\} \right\}$$

$$\cup \left\{ p^s \left(\frac{q}{2} \right)^t, p^t \left(\frac{q}{2} \right)^s : p \in \left\{ d_k(lx_{2n}, hx_{2n+1}), d_k(fx_{2n}, lx_{2n}), d_k(gx_{2n+1}, hx_{2n+1}), d_k(fx_{2n}, gx_{2n+1}) \right\},$$

$$q \in \left\{ d_k(fx_{2n}, hx_{2n+1}), d_k(gx_{2n+1}, lx_{2n}) \right\} \right\} \right)$$

$$\leq \varphi \left(\max \left\{ \left\{ p^s q^t : p, q \in \left\{ d_{k2n}, d_{k2n+1} \right\} \right\} \cup \left\{ p^s \left(\frac{q}{2} \right)^t, p^t \left(\frac{q}{2} \right)^s : p \in \left\{ d_{k2n}, d_{k2n+1} \right\}, q \in \left\{ 0, d_{k2n} + d_{k2n+1} \right\} \right\} \right) \right)$$

$$= \varphi \left(\max \left\{ d_{k2n}^{s+t}, d_{k2n+1}^{s+t}, d_{k2n}^{s} d_{k2n+1}^{t}, d_{k2n}^{t} d_{k2n+1}^{s}, d_{k2n+1}^{t}, d_{k2n}^{t} d_{k2n+1}^{s}, d_{k2n}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t}, d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{k2n+1}^{t} d_{$$

Suppose that $d_{k2n+1} > d_{k2n}$ for some $n \ge 1$ and $k \ge 1$. It follows from (2.2) that $d_{k2n+1}^{s+t} \le \varphi(d_{k2n+1}^{s+t}) < d_{k2n+1}^{s+t}$, which is a contradiction. Hence $d_{k2n+1} \le d_{k2n}$ for any $n \ge 1$ and $k \ge 1$. Thus (2.2) means that $d_{k2n+1}^{s+t} \le \varphi(d_{k2n}^{s+t})$ for any $n \ge 1$ and $k \ge 1$. Similarly we conclude that $d_{k2n}^{s+t} \le \varphi(d_{k2n-1}^{s+t})$ for each $n \ge 1$ and $k \ge 1$. It follows that (2.1) holds.

Now we demonstrate that

$$\lim_{n \to \infty} d_{kn} = 0, \quad \forall k \ge 1. \tag{2.3}$$

In view of (2.1) and the continuity of φ , we deduce that

$$0 \le d_{kn+1}^{s+t} \le \varphi(d_{kn}^{s+t}) \le d_{kn}^{s+t} \le \varphi(d_{kn-1}^{s+t})$$

$$\le d_{kn-1}^{s+t} \le \dots \le \varphi(d_{k1}^{s+t}) \le d_{k1}^{s+t}, \quad \forall n \ge 1, \ k \ge 1,$$

which deduces that $\lim_{n\to\infty} d_{kn}^{s+t} = a$ for some $a \in \mathbb{R}^+$. Thus $a = \lim_{n\to\infty} \varphi(d_{kn}^{s+t}) = \varphi(a)$, therefore a = 0. It follows that (2.3) holds.

For the sake of showing that $\{y_n\}_{n\geq 1}$ is a Cauchy sequence, in view of (2.3), it is sufficient to show that $\{y_{2n}\}_{n\geq 1}$ is a Cauchy sequence. Suppose that $\{y_{2n}\}_{n\geq 1}$ is not a Cauchy sequence. Hence there exists a positive number ε and $k\geq 1$ on condition that for each even integer 2r, there are even integers 2m(r) and 2n(r) such that 2m(r)>2n(r)>2r, and

$$d_k(y_{2m(r)}, y_{2n(r)}) > \varepsilon.$$

For each even integer 2r, let 2m(r) be the least even integer exceeding 2n(r) satisfying the above inequality, therefore we obtain that

$$d_k(y_{2m(r)-2}, y_{2n(r)}) \le \varepsilon \quad \text{and} \quad d_k(y_{2m(r)}, y_{2n(r)}) > \varepsilon. \tag{2.4}$$

It follows that for each even integer 2r,

$$d_k(y_{2m(r)}, y_{2n(r)}) \le d_{k2m(r)-1} + d_{k2m(r)-2} + d_k(y_{2m(r)-2}, y_{2n(r)}).$$

According to (2.3), (2.4) and the above inequality we conclude that

$$\lim_{r \to \infty} d_k(y_{2m(r)}, y_{2n(r)}) = \varepsilon. \tag{2.5}$$

It is apparent that for any $r \geq 1$,

$$|d_k(y_{2m(r)}, y_{2n(r)+1}) - d_k(y_{2m(r)}, y_{2n(r)})| \le d_{k2n(r)},$$

$$|d_k(y_{2m(r)+1}, y_{2n(r)+1}) - d_k(y_{2m(r)}, y_{2n(r)+1})| \le d_{k2m(r)},$$

and

$$|d_k(y_{2m(r)+1}, y_{2n(r)+2}) - d_k(y_{2m(r)+1}, y_{2n(r)+1})| \le d_{k2n(r)+1}.$$

In light of (2.3), (2.5) and the above inequalities we draw that

$$\varepsilon = \lim_{r \to \infty} d_k(y_{2m(r)}, y_{2n(r)+1}) = \lim_{r \to \infty} d_k(y_{2m(r)+1}, y_{2n(r)+1})$$
$$= \lim_{r \to \infty} d_k(y_{2m(r)+1}, y_{2n(r)+2}).$$

By (1.4), we arrive at

$$d_k^{s+t}(fx_{2m(r)}, gx_{2n(r)+1})$$

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(lx_{2m(r)}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, lx_{2m(r)}), d_k(gx_{2n(r)+1}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, gx_{2n(r)+1}) \} \Big\}$$

$$\cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(lx_{2m(r)}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, hx_{2n(r)+1}) \Big\} \Big\}$$

$$d_k(fx_{2m(r)}, lx_{2m(r)}), d_k(gx_{2n(r)+1}, hx_{2n(r)+1}), d_k(fx_{2m(r)}, gx_{2n(r)+1})\},$$

$$q \in \{d_k(fx_{2m(r)}, hx_{2n(r)+1}), d_k(gx_{2n(r)+1}, lx_{2m(r)})\}\}\}.$$

Letting $r \to \infty$, we get that

$$\varepsilon^{s+t} \le \varphi \left(\max \left\{ \varepsilon^{s+t}, 0, \varepsilon^s \left(\frac{\varepsilon}{2} \right)^t, \varepsilon^t \left(\frac{\varepsilon}{2} \right)^s \right\} \right) = \varphi(\varepsilon^{s+t}) < \varepsilon^{s+t},$$

which is a contradiction. Thus $\{y_n\}_{n\geq 1}$ is a Cauchy sequence and it converges to a point $u\in X$ by completeness of X. Suppose that l is continuous. Consequently, we have that

$$\lim_{n \to \infty} ll x_{2n} = \lim_{n \to \infty} l y_{2n} = lu.$$

In light of (B2), we obtain that

$$\lim_{n \to \infty} f y_{2n} = \lim_{n \to \infty} f l x_{2n} = l u.$$

We subsequently produce that u is a common fixed point of f, g, h and l. It follows from (1.4) that

$$d_k^{s+t}(fy_{2n}, gx_{2n+1})$$

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(ly_{2n}, hx_{2n+1}), d_k(fy_{2n}, ly_{2n}), d_k(gx_{2n+1}, hx_{2n+1}), d_k(fy_{2n}, gx_{2n+1}) \} \Big\} \cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(ly_{2n}, hx_{2n+1}), d_k(fy_{2n}, ly_{2n}), d_k(gx_{2n+1}, hx_{2n+1}), d_k(fy_{2n}, gx_{2n+1}) \}, q \in \{ d_k(fy_{2n}, hx_{2n+1}), d_k(gx_{2n+1}, ly_{2n}) \} \Big\} \Big\}, \quad \forall k \geq 1.$$

As $n \to \infty$ in above inequality, we infer that

$$d_k^{s+t}(lu, u) \le \varphi(d_k^{s+t}(lu, u)) \le d_k^{s+t}(lu, u), \quad \forall k \ge 1,$$

which signifies that $d_k(lu, u) = 0$ for any $k \ge 1$, that is, lu = u. By (1.4) we get that

 $d_{1}^{s+t}(fu, ax_{2n+1})$

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(lu, hx_{2n+1}), d_k(fu, lu), d_k(gx_{2n+1}, hx_{2n+1}), d_k(fu, gx_{2n+1}) \} \Big\} \cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(lu, hx_{2n+1}), d_k(fu, lu), d_k(gx_{2n+1}, hx_{2n+1}), d_k(fu, gx_{2n+1}) \},$$

 $q \in \{d_k(fu, hx_{2n+1}), d_k(qx_{2n+1}, lu)\}\}\}, \forall k > 1.$

As $n \to \infty$ in the above inequality, we gain that

$$d_k^{s+t}(fu,u) \le \varphi(d_k^{s+t}(fu,u)) \le d_k^{s+t}(fu,u), \quad \forall k \ge 1,$$

which implies that $d_k(fu, u) = 0$ for any $k \ge 1$. Therefore fu = u. In view of (B3), there exists a point $w \in X$ such that u = fu = hw. Using (1.4), we conclude that

$$\begin{split} d_k^{s+t}(u,gw) &= d_k^{s+t}(fu,gw) \\ &\leq \varphi \big(\max \big\{ \{ p^s q^t : p,q \in \{ d_k(lu,hw), d_k(fu,lu), d_k(gw,hw), \\ d_k(fu,gw) \} \big\} \cup \big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(lu,hw), \\ d_k(fu,lu), d_k(gw,hw), d_k(fu,gw) \big\}, \\ q &\in \{ d_k(fu,hw), d_k(gw,lu) \} \big\} \big\} \big) \\ &= \varphi (d_k^{s+t}(u,gw)) \leq d_k^{s+t}(u,gw), \quad \forall k \geq 1, \end{split}$$

which implies that $d_k(u, gw) = 0$ for each $k \ge 1$. Thereupon u = gw. By means of (B2) and gw = hw = u, we come into $d_k(gu, hu) = d_k(ghw, hhw) = 0$ for any $k \ge 1$, which means that gu = hu. In a similar manner, by (1.4) we know that

$$d_k^{s+t}(fu, gu) \le \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(lu, hu), d_k(fu, lu), d_k(gu, hu), d_k(fu, gu) \} \} \cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(lu, hu), d_k(fu, lu), d_k(gu, hu), d_k(fu, gu) \},$$

$$q \in \{ d_k(fu, hu), d_k(gu, lu) \} \} \Big\} \Big), \quad \forall k \ge 1,$$

which deduces that

$$d_k^{s+t}(fu,gu) \leq \varphi(d_k^{s+t}(fu,gu)) \leq d_k^{s+t}(fu,gu), \quad \forall k \geq 1,$$

which implies that $d_k(fu, gu) = 0$ for each $k \ge 1$. Therefore, fu = gu. Hence we come to a conclusion that fu = gu = hu = lu = u. Similarly, we can obtain this result in the case of the continuity of f or g or h.

We finally demonstrate that u is a unique common fixed point of f, g, h and l. If $v \in X \setminus \{u\}$ is another common fixed point of f, g, h and l, it is easy to see that from (1.4)

$$d_k^{s+t}(u,v) = d_k^{s+t}(fu,gv) \leq \varphi(d_k^{s+t}(u,v)) \leq d_k^{s+t}(u,v), \quad \forall k \geq 1,$$

which implies that $d_k(u, v) = 0$ for all $k \geq 1$. That is, u = v, which is a contradiction. This completes the proof.

Theorem 2.4. Let the induced metric space (X,d) be complete and f, g, h and l be four self mappings of (X,d) such that (B1),(B3),(B4) and (B5) the pairs f, l and g, h are compatible mappings of type (P), then f, g, h and l have a unique common fixed point in X.

Proof. As in the proof of Theorem 2.3, we arrive at $\{y_n\}_{n\geq 1}$ is a Cauchy sequence and it converges to a point $u\in X$ by completeness of X. Suppose that l is continuous. It follows that

$$\lim_{n \to \infty} ll x_{2n} = \lim_{n \to \infty} l y_{2n} = lu.$$

In view of (B5), we obtain that

$$\lim_{n \to \infty} f y_{2n+1} = \lim_{n \to \infty} f f x_{2n} = lu.$$

The rest of the proof is the similar as that of Theorem 2.3. This completes the proof. \Box

Remark 2.5. The conditions (B1) and (B4) in Theorem 2.3 and 2.4 weaken and improve the corresponding conditions in Theorem 3.1 of Pathak, Cho, Kang and Lee [17].

3 Applications

In this section, we assume that $(X, \|\cdot\|)$ and $(Y, \|\cdot\|_1)$ be both real Banach spaces, $S \subseteq X$ be the state space, and $D \subseteq Y$ be the decision space. Denote by BB(S) the set of all real-value mappings on S that are bounded on bounded subsets of S. It is easy to verify that BB(S) is a linear space over \mathbb{R} under usual definitions of addition and multiplication by scalars. For $k \geq 1$ and $f, g \in BB(S)$, let

$$d_k(f,g) = \sup\{|f(x) - g(x)| : x \in \overline{B}(0,k)\},\$$

$$d(f,g) = \sum_{k=1}^{\infty} 2^{-k} \frac{d_k(f,g)}{1 + d_k(f,g)},$$

where $\overline{B}(0,k) = \{x : x \in S \text{ and } ||x|| \le k\}$. Clearly, $\{d_k\}_{k \ge 1}$ is a countable family of pseudometrics on BB(S) and (BB(S),d) is a complete metric space.

Now we study the existence and uniqueness of common solutions for the systems of functional equations (1.5) in the deduced complete metric space (BB(S), d).

Theorem 3.1. Let $u: S \times D \to S, T: S \times D \to S$ and $H_1, H_2, G_1, G_2: S \times D \times \mathbb{R} \to \mathbb{R}$ satisfy the following conditions:

(C1) for given $k \ge 1$ and $a \in BB(S)$, there exists r(k, a) > 0 such that

$$|u(x,y)| + \max\{|H_i(x,y,a(T(x,y)))|, |G_i(x,y,a(T(x,y)))| : i \in \{1,2\}\}$$

$$\leq r(k, a), \quad \forall (x, y) \in \overline{B}(0, k) \times D;$$

(C2) there exists $\varphi \in \Phi, s, t \in \mathbb{R}^+$ and $s + t \ge 1$ such that

$$|H_1(x, y, a(w)) - H_2(x, y, b(w))|^{s+t}$$
 (3.2)

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(J_1 a, J_2 b), d_k(A_1 a, J_1 a), d_k(A_2 b, J_2 b), \Big\} \Big) \Big\}$$

$$d_k(A_1a, A_2b)\}\} \cup \{p^s(\frac{q}{2})^t, p^t(\frac{q}{2})^s : p \in \{d_k(J_1a, J_2b), \}\}$$

$$d_k(A_1a, J_1a), d_k(A_2b, J_2b), d_k(A_1a, A_2b)\}, q \in \{d_k(A_1a, J_2b), q \in \{d_k(A_1$$

$$d_k(A_2b, J_1a)\}\}\}$$
, $\forall (x, y, w) \in \overline{B}(0, k) \times D \times S, k \ge 1$,

where A_1 , A_2 , J_1 and J_2 are defined as follows:

$$A_i a(x) = \underset{y \in D}{\text{opt}} \{ u(x, y) + H_i(x, y, a(T(x, y))) \},$$

$$J_i a(x) = \inf_{y \in D} \{ u(x, y) + G_i(x, y, a(T(x, y))) \},$$

for all $(x, a) \in S \times BB(S)$, $i \in \{1, 2\}$; (C3) either there exists $A_i \in \{A_1, A_2\}$ such that for any sequence $\{a_n\}_{n\geq 1} \subset BB(S)$, $a \in BB(S)$ and $k \geq 1$,

$$\lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |a_n(x) - a(x)| = 0 \Rightarrow \lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |A_i a_n(x) - A_i a(x)| = 0$$

or there exists $J_i \in \{J_1, J_2\}$ such that for any sequence $\{a_n\}_{n\geq 1} \subset BB(S)$, $a \in BB(S)$ and $k \geq 1$,

$$\lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |a_n(x) - a(x)| = 0 \Rightarrow \lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |J_i a_n(x) - J_i a(x)| = 0;$$

$$(C4)$$
 $A_1(BB(S)) \subseteq J_2(BB(S))$ and $A_2(BB(S)) \subseteq J_1(BB(S))$;

(C5) for any $k \ge 1$ and $i \in \{1, 2\}$

$$\lim_{n\to\infty} \sup_{x\in\overline{B}(0,k)} |A_i J_i a_n(x) - J_i J_i a_n(x)|$$

$$= \lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |J_i A_i a_n(x) - A_i A_i a_n(x)| = 0$$

whenever $\{a_n\}_{n\geq 1}\subset BB(S)$ is a sequence in BB(S) such that

$$\lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |A_i a_n(x) - a(x)| = \lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |J_i a_n(x) - a(x)| = 0$$

for some $a \in BB(S)$,

then the system of functional equations (1.5) possesses a unique common solution in BB(S).

Proof. It follows from (C1) and (C2) that A_1, A_2, J_1 and J_2 are self mappings in BB(S). Clearly, (C3) implies that one of A_1, A_2, J_1 and J_2 is continuous, and (C5) means that A_1, J_1 and A_2, J_2 are compatible mappings of type (A).

Presume that $\operatorname{opt}_{y\in D}=\inf_{y\in D}$. Let $a,b\in BB(S),\ k\geq 1, x\in \overline{B}(0,k)$ and $\varepsilon>0$. Using (3.2), we deduce that there exist $y,z\in D$ such that

$$A_1 a(x) > u(x, y) + H_1(x, y, a(T(x, y))) - \varepsilon,$$
 (3.3)

$$A_2b(x) > u(x,z) + H_2(x,z,b(T(x,z))) - \varepsilon.$$
 (3.4)

It is easy to see that

$$A_1 a(x) \le u(x, z) + H_1(x, z, a(T(x, z))),$$
 (3.5)

$$A_2b(x) \le u(x,y) + H_2(x,y,b(T(x,y))).$$
 (3.6)

By virtue of (3.4) and (3.5), we infer that

$$A_{1}a(x) - A_{2}b(x) < H_{1}(x, z, a(T(x, z))) - H_{2}(x, z, b(T(x, z))) + \varepsilon$$

$$\leq |H_{1}(x, z, a(T(x, z))) - H_{2}(x, z, b(T(x, z)))| + \varepsilon.$$
(3.7)

From (3.3) and (3.6) we conclude that

$$A_{1}a(x) - A_{2}b(x) > H_{1}(x, y, a(T(x, y))) - H_{2}(x, y, b(T(x, y))) - \varepsilon$$

$$\geq -|H_{1}(x, y, a(T(x, y))) - H_{2}(x, y, b(T(x, y)))| - \varepsilon.$$
(3.8)

It follows from (3.7) and (3.8) that

$$|A_1 a(x) - A_2 b(x)| \le \max\{|H_1(x, y, a(T(x, y))) - H_2(x, y, b(T(x, y)))|, |H_1(x, z, a(T(x, z))) - H_2(x, z, b(T(x, z)))|\} + \varepsilon.$$

(3.1), the above inequality and the mean value theorem lead to

$$|A_1 a(x) - A_2 b(x)|^{s+t}$$

$$\leq (\max\{|H_1(x, y, a(T(x, y))) - H_2(x, y, b(T(x, y)))|, |H_1(x, z, a(T(x, z))) - H_2(x, z, b(T(x, z)))|\} + \varepsilon)^{s+t}$$

(3.9)

$$\leq (\max\{|H_{1}(x, y, a(T(x, y))) - H_{2}(x, y, b(T(x, y)))|, \\ |H_{1}(x, z, a(T(x, z))) - H_{2}(x, z, b(T(x, z)))|\})^{s+t} \\ + (s+t)(2r(k, a) + \varepsilon)^{s+t-1}\varepsilon$$

$$\leq \varphi(\max\{\{p^{s}q^{t} : p, q \in \{d_{k}(J_{1}a, J_{2}b), d_{k}(A_{1}a, J_{1}a), d_{k}(A_{2}b, J_{2}b), \\ d_{k}(A_{1}a, A_{2}b)\}\} \cup \{p^{s}\left(\frac{q}{2}\right)^{t}, p^{t}\left(\frac{q}{2}\right)^{s} : p \in \{d_{k}(J_{1}a, J_{2}b), \\ d_{k}(A_{1}a, J_{1}a), d_{k}(A_{2}b, J_{2}b), d_{k}(A_{1}a, A_{2}b)\},$$

$$q \in \{d_{k}(A_{1}a, J_{2}b), d_{k}(A_{2}b, J_{1}a)\}\}\})$$

$$+ (s+t)(2r(k, a) + \varepsilon)^{s+t-1}\varepsilon,$$

which yields that

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(J_1 a, J_2 b), d_k(A_1 a, J_1 a), d_k(A_2 b, J_2 b), d_k(A_1 a, A_2 b) \} \Big\} \cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(J_1 a, J_2 b), d_k(A_1 a, J_1 a), d_k(A_2 b, J_2 b), d_k(A_1 a, A_2 b) \}, \Big\}$$

 $d_k^{s+t}(A_1a, A_2b)$

$$q \in \{d_k(A_1a, J_2b), d_k(A_2b, J_1a)\}\}\}$$
$$+(s+t)(2r(k, a) + \varepsilon)^{s+t-1}\varepsilon.$$

Similarly we infer that (3.9) also holds for ${\rm opt}_{y\in D}=\sup_{y\in D}$. Letting $\varepsilon\to 0$ in (3.9), we deduce that

$$d_k^{s+t}(A_1a, A_2b)$$

$$\leq \varphi \Big(\max \Big\{ \{ p^s q^t : p, q \in \{ d_k(J_1a, J_2b), d_k(A_1a, J_1a), d_k(A_2b, J_2b), d_k(A_1a, A_2b) \} \Big\} \cup \Big\{ p^s \Big(\frac{q}{2} \Big)^t, p^t \Big(\frac{q}{2} \Big)^s : p \in \{ d_k(J_1a, J_2b), d_k(A_1a, J_1a), d_k(A_2b, J_2b), d_k(A_1a, A_2b) \}, d_k(A_1a, J_2b), d_k(A_2b, J_1a) \Big\} \Big\} \Big).$$

Theorem 2.3 ensures that A_1 , A_2 , J_1 and J_2 have a unique common fixed point $j \in BB(S)$. That is, j is a unique common solution of the system of functional equations (1.5). This completes the proof.

Theorem 3.2. Let $u: S \times D \to S, T: S \times D \to S$ and $H_1, H_2, G_1, G_2: S \times D \times \mathbb{R} \to \mathbb{R}$ satisfy (C1), (C2), (C3), (C4) and (C6) For any $k \geq 1$ and $i \in \{1, 2\}$

$$\lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |A_i A_i a_n(x) - J_i J_i a_n(x)| = 0$$

whenever $\{a_n\}_{n\geq 1}\subset BB(S)$ is a sequence in BB(S) such that

$$\lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |A_i a_n(x) - a(x)| = \lim_{n \to \infty} \sup_{x \in \overline{B}(0,k)} |J_i a_n(x) - a(x)| = 0$$

for some $a \in BB(S)$,

then the system of functional equations in (1.5) possesses a unique common solution in BB(S).

Proof. Note that (C6) means that A_1, J_1 and A_2, J_2 are compatible mappings of type (P). The rest of the proof is similar to that of Theorem 3.1. This completes the proof.

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