Incomplete Hypergeometric Systems Associated to 1-Simplex \times (n-1)-Simplex

Kenta Nishiyama *

December 17, 2010

Abstract

The \mathcal{A} -hypergeometric system was introduced by Gel'fand, Kapranov and Zelevinsky in the 1980's. Among several classes of \mathcal{A} -hypergeometric functions, those for 1-simplex \times (n-1)-simplex are known to be a very nice class. We will study an incomplete analog of this class.

1 Introduction

The \mathcal{A} -hypergeometric systems was introduced by Gel'fand, Kapranov and Zelevinsky in the 1980's ([1]). It is a system of homogeneous differential equations with parameters associated to an integer matrix A and contains a broad class of hypergeometric functions as solutions. Recently, the incomplete \mathcal{A} -hypergeometric system was proposed toward applications to statistics and a

detailed study was given in the case of
$$A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{pmatrix} = 1$$
-simplex ×

1-simplex ([6]). The system includes the incomplete Gauss' hypergeometric integral $I_{(a,b)}(\alpha,\beta,\gamma;x) = \int_a^b t^{\beta-1} (1-t)^{\gamma-\beta-1} (1-xt)^{\alpha} dt$ and the incomplete

elliptic integral of the first kind
$$F(z;k) = \int_0^z \frac{1}{\sqrt{(1-t^2)(1-k^2t^2)}} dt$$
 as solution. It is interesting to describe proportion of these functions in a general

tion. It is interesting to describe properties of these functions in a general framework. Among several classes of (complete) \mathcal{A} -hypergeometric functions, those for $\Delta_1 \times \Delta_{n-1}$ (1-simplex \times (n-1)-simplex) are known to be a very nice class (see, e.g., [9, Section 1.5]).

In this paper, we study an incomplete analog of this class. In the section 2, we give a definition of an incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system and prove that the existence of a solution of the system. In the section 3, we give

^{*}Department of Mathematics, Kobe University and JST CREST.

a particular solution of the system and describe general solutions by combining with a base of the solutions of (homogeneous) \mathcal{A} -hypergeometric system. In the last section 4, we give the complete list of contiguity relations for the incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric function.

2 Incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system

We will work over the Weyl algebra in 2n variables $D = \mathbf{C} \left\langle \begin{array}{c} x_{11}, \dots, x_{1n}, \partial_{11}, \dots, \partial_{1n} \\ x_{21}, \dots, x_{2n}, \partial_{21}, \dots, \partial_{2n} \end{array} \right\rangle$.

Definition 1 We call the following system of differential equations the *incomplete* $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system:

$$\begin{cases}
(\theta_{i1} + \theta_{i2} - \alpha_i) \bullet f = 0, & (1 \leq i \leq n) \\
\left(\sum_{i=1}^{n} \theta_{2i} + \gamma + 1\right) \bullet f = [g(t, x)]_{t=a}^{t=b}, & (1) \\
(\partial_{1i}\partial_{2j} - \partial_{1j}\partial_{2i}) \bullet f = 0, & (1 \leq i < j \leq n)
\end{cases}$$

where $g(t,x) = t^{\gamma+1} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_k}$ and $\alpha_i, \gamma \in \mathbf{C}$ are parameters. The operator $\theta_{ij} = x_{ij}\partial_{ij}$ is called the Euler operator.

If g(t,x) = 0 in (1), the system agrees with the A-hypergeometric or GKZ hypergeometric system associated to $\Delta_1 \times \Delta_{n-1}$.

Remark 1 The incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system introduced in Definition 1 is a special but interesting case of the incomplete \mathcal{A} -hypergeometric system (see appendix, [6]). Let A be the following $(n+1) \times 2n$ matrix:

$$A = \begin{pmatrix} 1 & 1 & & & & & 0 \\ & & 1 & 1 & & & \\ & & & \ddots & & \\ 0 & & & & 1 & 1 \\ 0 & 1 & 0 & 1 & \cdots & 0 & 1 \end{pmatrix}.$$

We set $\beta = (\alpha_1, \dots, \alpha_n, -\gamma - 1) \in \mathbf{C}^{n+1}$ and $g = (0, \dots, 0, [g(t, x)]_{t=a}^{t=b})$. Then the incomplete \mathcal{A} -hypergeometric system associated to A, β, g is the incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system.

We note that the ideal $\langle \partial_{1i}\partial_{2j} - \partial_{1j}\partial_{2i} | 1 \leq i < j \leq n \rangle$ generated by the third operators of (1) is called the affine toric ideal associated to the matrix A and it is denoted by I_A . Moreover, I_A is Cohen-Macaulay because A is normal ([2]).

We note that the inhomogeneous system (1) does not necessarily have a solution f, when the inhomogeneous part $[g(t,x)]_{t=a}^{t=b}$ is randomly given.

Proposition 1 For any α_i , $\gamma \in \mathbb{C}$, there exists a classical solution of the incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system.

Proof. We may verify conditions (7) and (8) in Theorem 5 in the appendix with respect to $g = (0, ..., 0, [g(t, x)]_{t=a}^{t=b})$. For $1 \le i \le n$, we have

$$(\theta_{1i} + \theta_{2i} - \alpha_i) \bullet t^{\gamma+1} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_k}$$

$$= \alpha_i x_{1i} t^{\gamma+1} (x_{1i} + x_{2i}t)^{\alpha_i - 1} \prod_{k \neq i}^{n} (x_{1k} + x_{2k}t)^{\alpha_k}$$

$$+ \alpha_i x_{2i} t^{\gamma+2} (x_{1i} + x_{2i}t)^{\alpha_i - 1} \prod_{k \neq i}^{n} (x_{1k} + x_{2k}t)^{\alpha_k} - \alpha_i t^{\gamma+1} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_k}$$

$$= \{x_{1i} + x_{2i}t - (x_{1i} + x_{2i}t)\} \alpha_i t^{\gamma+1} (x_{1i} + x_{2k}t)^{\alpha_i - 1} \prod_{k \neq i}^{n} (x_{1k} + x_{2k}t)^{\alpha_k}$$

$$= 0.$$

Thus the condition (7) holds.

For $1 \le i < j \le n$, we have

$$\partial_{1i}\partial_{2j} \bullet g(t,x) = \partial_{1i} \bullet \alpha_j t^{\gamma+2} (x_{1j} + x_{2j}t)^{\alpha_j - 1} \prod_{k \neq j}^n (x_{1k} + x_{2k}t)^{\alpha_k}$$

$$= \alpha_i \alpha_j t^{\gamma+2} (x_{1i} + x_{2i}t)^{\alpha_i - 1} (x_{1j} + x_{2j}t)^{\alpha_j - 1} \prod_{k \neq i,j}^n (x_{1k} + x_{2k}t)^{\alpha_k}.$$

Since this expression is symmetric in the indices i and j, we have $(\partial_{1i}\partial_{2j} - \partial_{1j}\partial_{2i}) \bullet g(t,x) = 0$. Thus the condition (8) holds.

Our definition of the incomplete $\Delta_1 \times \Delta_{n-1}$ hypergeometric system is natural in terms of a definite integral with parameters.

Proposition 2 If Re γ , Re $\alpha_i > 0$, then the integral

$$\Phi(\beta; x) = \int_{a}^{b} t^{\gamma} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_k} dt$$
 (2)

is a solution of the incomplete $\Delta_1 \times \Delta_{n-1}$ hypergeometric system (Definition 1).

Proof. From the general theory of \mathcal{A} -hypergeometric systems, $\Phi(\beta; x)$ is annihilated by the elements of I_A and $\theta_{i1} + \theta_{i2} - \alpha_i$ for $1 \leq i \leq n$ (see, e.g., [9, Section 5.4]). We will prove that

$$\left(\sum_{i=1}^{n} \theta_{2i} + \gamma + 1\right) \bullet \Phi(\beta; x) = [g(t, x)]_{t=a}^{t=b}.$$

Applying $\sum_{i=1}^{n} \theta_{2i}$ to the integrand, we get

$$\left(\sum_{i=1}^{n} \theta_{2i}\right) \bullet t^{\gamma} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}} = \sum_{i=1}^{n} \alpha_{i} x_{2i} (x_{1i} + x_{2i}t)^{\alpha_{i}-1} t^{\gamma+1} \prod_{k \neq i}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}}$$

$$= \sum_{i=1}^{n} t^{\gamma+1} \frac{\partial (x_{1i} + x_{2i}t)^{\alpha_{i}}}{\partial t} \prod_{k \neq i}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}}$$

$$= t^{\gamma+1} \frac{\partial (\prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}})}{\partial t}.$$

By Stokes' theorem, we obtain

$$\left(\sum_{i=1}^{n} \theta_{2i}\right) \bullet \Phi(\beta; x) = \int_{a}^{b} \left(\sum_{i=1}^{n} \theta_{2i}\right) \bullet t^{\gamma} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}} dt$$

$$= \int_{a}^{b} t^{\gamma+1} \frac{\partial \left(\prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}}\right)}{\partial t} dt$$

$$= \left[t^{\gamma+1} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_{k}}\right]_{t=a}^{t=b} - (\gamma + 1)\Phi(\beta; x).$$

Thus the proposition is proved.

Example 1 We consider the following system of differential equations:

$$\begin{cases} (\partial_{11}\partial_{22} - \partial_{12}\partial_{21}) \bullet f &= 0, \\ (\theta_{11} + \theta_{21} - \alpha_1) \bullet f &= 0, \\ (\theta_{12} + \theta_{22} - \alpha_2) \bullet f &= 0, \\ (\theta_{21} + \theta_{22} + \gamma + 1) \bullet f &= [g(t, x)]_{t=0}^{t=b}. \end{cases}$$

Here, $g(t,x) = t^{\gamma+1}(x_{11} + x_{21}t)^{\alpha_1}(x_{12} + x_{22}t)^{\alpha_2}$.

This is the incomplete $\Delta_1 \times \Delta_1$ hypergeometric system for $A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{pmatrix}$, $\beta = (\alpha_1, \alpha_2, -\gamma - 1)$, and $g_1 = 0, g_2 = 0, g_3 = [g(t, x)]_{t=a}^{t=b}$.

A detailed study on the system is given in [6].

3 Series Solution

The Lauricella function F_D is defined by

$$F_D(a, b_1, \dots, b_n, c; z_1, \dots, z_n) = \sum_{m_1 = m_2 = 0}^{\infty} \frac{(a)_{m_1 + \dots + m_n} (b_1)_{m_1} \cdots (b_n)_{m_n}}{(c)_{m_1 + \dots + m_n} (1)_{m_1} \cdots (1)_{m_n}} z_1^{m_1} \cdots z_n^{m_n}.$$

It is well-known that the Lauricella function F_D of n-1 variables gives a series solution of $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system. We can give series solutions of our incomplete system in terms of the Lauricella series when parameters are generic. We need F_D of n variables to give a solution.

Theorem 1 If γ is not negative integer, the incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system has a series solution which can be expressed in terms of the Lauricella function F_D as

$$F(\beta; x) = \prod_{k=1}^{n} x_{1k}^{\alpha_k} \left(\frac{b^{\gamma+1}}{\gamma+1} F_D\left(\gamma+1; -\alpha_1, \dots, -\alpha_n; \gamma+2; \frac{-x_{21}b}{x_{11}}, \dots, \frac{-x_{2n}b}{x_{1n}} \right) - \frac{a^{\gamma+1}}{\gamma+1} F_D\left(\gamma+1; -\alpha_1, \dots, -\alpha_n; \gamma+2; \frac{-x_{21}a}{x_{11}}, \dots, \frac{-x_{2n}a}{x_{1n}} \right) \right).$$

Proof. For simplicity, we introduce some multi-index notations. An n-dimensional multi-index is an n-tuple $m=(m_1,\ldots,m_n)$ of non-negative integers. The norm of a multi-index is defined by $|m|=m_1+\cdots+m_n$. For a vector $x_i=(x_{i1},\ldots,x_{in})$ (i=1,2), define $x_i^m=x_{i1}^{m_1}\cdots x_{in}^{m_n}$ and for a vector $\alpha=(\alpha_1,\ldots,\alpha_n)\in \mathbb{C}^n$, define the Pochhammer symbol by $(\alpha)_m=(\alpha_1)_{m_1}\cdots(\alpha_n)_{m_n}$. By using these notations, the series F can be written as

$$F = x_1^{\alpha} \sum_{m \ge 0} c_m \left(\frac{x_2}{x_1}\right)^m, \quad c_m = \frac{(-1)^{|m|} (-\alpha)_m}{(\gamma + |m| + 1)(1)_m} (b^{\gamma + |m| + 1} - a^{\gamma + |m| + 1}).$$

We note that

$$\theta_{1k} \bullet F = (\alpha_k - m_k)F,$$

 $\theta_{2k} \bullet F = m_k F.$

We now prove that the series F satisfies the incomplete system (1). Firstly, $(\theta_{1i} + \theta_{2i} - \alpha_i) \bullet F = 0$ for $1 \le i \le n$ follows from above fact immediately.

Secondly, we will prove $\left(\sum_{i=1}^n \theta_{2i} + \gamma + 1\right) \bullet F = [g(t,x)]_{t=a}^{t=b}$, which can be

$$\left(\sum_{i=1}^{n} \theta_{2i} + \gamma + 1\right) \bullet F = (|m| + \gamma + 1)F$$

$$= x_1^{\alpha} \sum_{m \ge 0} \frac{(-1)^{|m|} (-\alpha)_m}{(1)_m} (b^{\gamma + |m| + 1} - a^{\gamma + |m| + 1}) \left(\frac{x_2}{x_1}\right)^m$$

$$= \left[t^{\gamma + 1} x_1^{\alpha} \sum_{m \ge 0} \frac{(-\alpha)_m}{(1)_m} \left(-\frac{x_2 t}{x_1}\right)^m\right]_{t=a}^{t=b}$$

$$= \left[t^{\gamma + 1} x_1^{\alpha} \prod_{k=1}^{n} \left(1 + \frac{x_{2k} t}{x_{1k}}\right)^{\alpha_k}\right]_{t=a}^{t=b}$$

$$= \left[t^{\gamma + 1} \prod_{k=1}^{n} (x_{1k} + x_{2k} t)^{\alpha_k}\right]_{t=a}^{t=b}.$$

In the last two steps, we take a branch such that the equality holds.

Finally, we will prove $(\partial_{1i}\partial_{2j} - \partial_{1j}\partial_{2i}) \bullet F = 0$ for $1 \leq i < j \leq n$. This follows from the following two calculations:

$$\left(\theta_{1i}\theta_{2j} - \frac{x_{2j}x_{1i}}{x_{1j}x_{2i}}\theta_{1j}\theta_{2i}\right) \bullet F = x_1^{\alpha} \sum_{m \ge 0} (\alpha_i - m_i)m_j c_m \left(\frac{x_2}{x_1}\right)^m - x_1^{\alpha} \sum_{m \ge 0} (\alpha_j - m_j)m_i c_m \left(\frac{x_2}{x_1}\right)^{m - e_i + e_j}$$

$$= x_1^{\alpha} \sum_{m \ge 0} (\alpha_i - m_i)(m_j + 1)c_{m + e_j} \left(\frac{x_2}{x_1}\right)^{m + e_j}$$

$$- x_1^{\alpha} \sum_{m \ge 0} (\alpha_j - m_j)(m_i + 1)c_{m + e_i} \left(\frac{x_2}{x_1}\right)^{m + e_j}$$

and

$$(\alpha_{i} - m_{i})(m_{j} + 1)c_{m+e_{j}} = (\alpha_{i} - m_{i})(m_{j} + 1)\frac{(-1)^{|m+e_{j}|}(-\alpha)_{m+e_{j}}}{(\gamma + |m+e_{j}| + 1)(1)_{m+e_{j}}}(b^{\gamma + |m+e_{j}| + 1} - a^{\gamma + |m+e_{j}| + 1})$$

$$= \frac{(-1)^{|m|+1}(-\alpha)_{m+e_{j}+e_{i}}}{(\gamma + |m| + 2)(1)_{m}}(b^{\gamma + |m| + 2} - a^{\gamma + |m| + 2})$$

$$= (\alpha_{j} - m_{j})(m_{i} + 1)\frac{(-1)^{|m+e_{i}|}(-\alpha)_{m+e_{i}}}{(\gamma + |m+e_{i}| + 1)(1)_{m+e_{i}}}(b^{\gamma + |m+e_{i}| + 1} - a^{\gamma + |m_{i}| + 1})$$

$$= (\alpha_{j} - m_{j})(m_{i} + 1)c_{m+e_{i}}.$$

Therefore, the theorem is proved.

Gel'fand, Kapranov and Zelevinsky ([1]) gave a base of the solutions of the (complete) A-hypergeometric system. We will give a base of solutions of our incomplete system by utilizing their result and Theorem 1.

For a parameter $\beta = (\alpha_1, \dots, \alpha_n, -\gamma - 1) \in \mathbb{C}^{n+1}$, we set a $2 \times n$ matrix

$$s^{(\ell)} = (s_{ij}^{(\ell)}) = \begin{pmatrix} \beta_1 & \cdots & \beta_{\ell-1} & \sum_{j=\ell}^{n+1} \beta_j & 0 & \cdots & 0 \\ 0 & \cdots & 0 & -\sum_{j=\ell+1}^{n+1} \beta_j & \beta_{\ell+1} & \cdots & \beta_n \end{pmatrix}$$

for $1 \le \ell \le n$. Let $M^{(\ell)}$ be a set of $2 \times n$ matrices

$$M^{(\ell)} = \sum_{k=1}^{\ell-1} \mathbf{N}_0 \cdot (e_{2k} + e_{1\ell} - e_{1k} - e_{2\ell}) + \sum_{k=\ell+1}^n \mathbf{N}_0 \cdot (e_{1k} + e_{2\ell} - e_{2k} - e_{1\ell}),$$

where e_{ij} is the $2 \times n$ matrix whose (i, j)-entry is 1 and the other entries are 0. We suppose that the condition of parameter β called "T-nonresonant", that is the sets $s^{(\ell)} \pm M^{(\ell)}$ $(1 \le \ell \le n)$ are pairwise disjoint ([1, Definition 3]). Define series $\Psi^{(\ell)}(x)$ as

$$\Psi^{(\ell)}(x) = \Gamma(s^{(\ell)} + 1) \sum_{k \in M^{(\ell)}} \frac{1}{\Gamma(s^{(\ell)} + k + 1)} x^{s^{(\ell)} + k},$$

where $\Gamma(s^{(\ell)}+k+1) = \prod_{i=1}^2 \prod_{j=1}^n \Gamma(s_{ij}^{(\ell)}+k_{ij}+1)$ and $x^{s^{(\ell)}+k} = \prod_{i=1}^2 \prod_{j=1}^n x_{ij}^{s_{ij}^{(\ell)}+k_{ij}}$. These series are linearly independent and have the open domain

$$\left| \frac{x_{21}}{x_{11}} \right| < \left| \frac{x_{22}}{x_{12}} \right| < \dots < \left| \frac{x_{2n}}{x_{1n}} \right|$$

as a common domain of convergence. Moreover they span the solution space of (complete) $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system ([1, Theorem 3]).

By using this result, we obtain the following theorem.

Theorem 2 Suppose the parameter β is T-nonresonant and γ is not negative integer.

1. The common domain of convergence of $F(\beta;x)$ and $\Psi^{(\ell)}(x)$ is

$$U: \left| \frac{x_{21}}{x_{11}} \right| < \left| \frac{x_{22}}{x_{12}} \right| < \dots < \left| \frac{x_{2n}}{x_{1n}} \right| < \frac{1}{\max(|a|,|b|)}.$$

2. Any holomorphic solution of the incomplete system (1) on U can be written as

$$F(\beta; x) + \sum_{\ell=1}^{n} c_i \Psi^{(\ell)}(x), \qquad c_i \in \mathbf{C}.$$

Proof. Since the domain of convergence of the series F is

$$U_0: \left|\frac{x_{21}}{x_{11}}\right| < \frac{1}{\max(|a|,|b|)}, \left|\frac{x_{22}}{x_{12}}\right| < \frac{1}{\max(|a|,|b|)}, \cdots, \left|\frac{x_{2n}}{x_{1n}}\right| < \frac{1}{\max(|a|,|b|)},$$

we have the statement 1. The statement 2 is clear.

Theorem 3 For $\sigma \in \mathfrak{S}_n$, we suppose the parameter $\sigma(\beta)$ is T-nonresonant and γ is not negative integer.

1. The domain of convergence of the series $F(\beta;x)$ and $\sigma(\Psi^{(\ell)}(x))$ is

$$\sigma(U): \left| \frac{x_{2\sigma(1)}}{x_{1\sigma(1)}} \right| < \left| \frac{x_{2\sigma(2)}}{x_{1\sigma(2)}} \right| < \dots < \left| \frac{x_{2\sigma(n)}}{x_{1\sigma(n)}} \right| < \frac{1}{\max(|a|,|b|)}.$$

2. Any holomorphic solution of the incomplete system (1) on $\sigma(U)$ can be written as

$$F(\beta; x) + \sum_{\ell=1}^{n} c_i \sigma(\Psi^{(\ell)}(x)), \qquad c_i \in \mathbf{C}.$$

Here, $\sigma(\Psi^{(\ell)}(x))$ is given by the permutations $x_{ij} \leftrightarrow x_{i\sigma(j)}$, $s_{ij}^{(\ell)} \leftrightarrow s_{i\sigma(j)}^{(\ell)}$ and $\beta_j \leftrightarrow \beta_{\sigma(j)}$.

Proof. The theorem follows immediately from the σ -invariance of F.

Remark 2 The closure of the union of $\sigma(U)$ coincides with the closure of U_0 . That is

$$\overline{U_0} = \bigcup_{\sigma \in \mathfrak{S}_n} \overline{\sigma(U)}.$$

4 Contiguity Relation

Contiguity relation is a relation among two functions of which parameters are different by integer. Miller ([5]) gave contiguity relations for Lauricella functions and Sasaki ([11]) gave contiguity relations for Aomoto-Gel'fand hypergeometric functions, which include the case of complete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric functions. In [8] and [9], they give algorithms to compute contiguity relations in the case of \mathcal{A} -hypergeometric functions. These results are for complete functions. In [6], an algorithm of computing contiguity relations under some conditions is given for incomplete \mathcal{A} -hypergeometric functions and the complete list of them for the incomplete $\Delta_1 \times \Delta_1$ -hypergeometric function is derived.

We will give contiguity relations of our incomplete system in this section. We put $\delta = -\gamma - 1$ (i.e., $\beta = (\alpha_1, \dots, \alpha_n, \delta)$) to make formulas of contiguity relations of the incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric function simpler forms. We put

$$\Phi(\beta; x) = \int_a^b t^{-\delta - 1} \prod_{k=1}^n (x_{1k} + x_{2k}t)^{\alpha_k} dt,$$

and assume Re $(-\delta - 1)$, Re $\alpha_k > 0$. Then, we note that $\Phi(\beta; x)$ is a solution of the following incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric system:

$$\begin{cases} z_{i} \bullet f &= 0, & z_{i} := \theta_{1i} + \theta_{2i} - \alpha_{i}, \\ z \bullet f &= [g(t, x)]_{t=a}^{t=b}, & z := \sum_{i=1}^{n} \theta_{2i} - \delta, \\ I_{A} \bullet f &= 0, \end{cases}$$
 (1 \le i \le n)

where $g(t,x) = t^{-\delta} \prod_{k=1}^{n} (x_{1k} + x_{2k}t)^{\alpha_k}$. Let a_{1k} and a_{2k} be vectors corresponding to the (2k-1)-st and the 2k-th columns of A respectively.

Theorem 4 The incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric function $\Phi(\beta; x)$ satisfies the following contiguity relations.

• Shifts with respect to a_{1k} :

$$S(\beta; -a_{1k})\Phi(\beta; x) = \alpha_k \Phi(\beta - a_{1k}; x),$$

$$S(\beta - a_{1k}; +a_{1k})\Phi(\beta - a_{1k}; x) = \left(\sum_{i=1}^n \alpha_i - \delta\right) \Phi(\beta; x) - [g(t, x)]_{t=a}^{t=b},$$
(4)

where

$$S(\beta; -a_{1k}) = \partial_{1k},$$

$$S(\beta - a_{1k}; +a_{1k}) = \sum_{i=1, i \neq k}^{n} (x_{1i}x_{2k} - x_{1k}x_{2i})\partial_{2i} + \sum_{i=1}^{n+1} \alpha_i x_{1k}.$$

• Shifts with respect to a_{2k} :

$$S(\beta; -a_{2k})\Phi(\beta; x) = \alpha_k \Phi(\beta - a_{2k}; x), \tag{5}$$

$$S(\beta - a_{2k}; +a_{2k})\Phi(\beta - a_{2k}; x) = \delta\Phi(\beta; x) + [g(t, x)]_{t=a}^{t=b},$$
 (6)

where

$$S(\beta; -a_{2k}) = \partial_{2k},$$

$$S(\beta - a_{2k}; +a_{2k}) = \sum_{i=1, i \neq k}^{n} x_{1k} x_{2i} \partial_{1i} + \left(\sum_{i=1, i \neq k}^{n} \theta_{2i} + \alpha_k\right) x_{2k}.$$

Proof. The down-step relations (3) and (5) are easily verified. We will prove only the up-step relations (4) and (6).

Let L_1 be the operator

$$\left(\sum_{i=1,i\neq k}^{n}(x_{1i}x_{2k}-x_{1k}x_{2i})\partial_{2i}+\sum_{i=1}^{n}\alpha_{i}x_{1k}\right)\partial_{1k}-\alpha_{k}\left(\sum_{i=1}^{n}\alpha_{i}-\delta\right)+\alpha_{k}\left(\sum_{i=1}^{n}\theta_{2i}-\delta\right).$$

We now prove that $L_1 \bullet \Phi(\beta; x) = 0$ which together with (3) will prove the contiguity relation (4). The operator L_1 can be reduced by z_k $(1 \le k \le n)$ as

follows:

$$L_{1} = \sum_{i=1, i \neq k}^{n} x_{1i} x_{2k} \partial_{2i} \partial_{1k} - \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i}) \theta_{1k} + \theta_{2k} \theta_{1k} - \alpha_{k} \sum_{i=1}^{n} \alpha_{i} + \alpha_{k} \sum_{i=1}^{n} \theta_{2i}$$

$$= \sum_{i=1, i \neq k}^{n} x_{1i} x_{2k} \partial_{2i} \partial_{1k} - \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i}) (\theta_{1k} + \theta_{2k} - \alpha_{k})$$

$$+ \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i}) (\theta_{2k} - \alpha_{k}) + \theta_{2k} \theta_{1k} + \alpha_{k} \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i})$$

$$= \sum_{i=1, i \neq k}^{n} x_{1i} x_{2k} \partial_{2i} \partial_{1k} - \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i}) z_{k} + \sum_{i=1}^{n} \theta_{2k} (\theta_{2i} - \alpha_{i}) + \theta_{2k} \theta_{1k}$$

$$= \sum_{i=1, i \neq k}^{n} x_{1i} x_{2k} \partial_{2i} \partial_{1k} - \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i}) z_{k} + \sum_{i=1}^{n} \theta_{2k} (\theta_{1i} + \theta_{2i} - \alpha_{i}) - \sum_{i=1}^{n} \theta_{2k} \theta_{1i} + \theta_{2k} \theta_{1k}$$

$$= \sum_{i=1, i \neq k}^{n} x_{1i} x_{2k} (\partial_{2i} \partial_{1k} - \partial_{2k} \partial_{1i}) - \sum_{i=1}^{n} (\theta_{2i} - \alpha_{i}) z_{k} + \sum_{i=1}^{n} \theta_{2k} z_{i}.$$

Since the $\partial_{2i}\partial_{1k} - \partial_{2k}\partial_{1i}$ are elements of the toric ideal I_A , we obtain $L_1 \bullet \Phi(\beta; x) = 0$.

Let L_2 be the operator

$$\left(\sum_{i=1,i\neq k}^{n} x_{1k} x_{2i} \partial_{1i} + \left(\sum_{i=1,i\neq k}^{n} \theta_{2i} + \alpha_k\right) x_{2k}\right) \partial_{2k} - \alpha_k \delta + \alpha_k \left(\sum_{i=1}^{n} \theta_{2i} - \delta\right).$$

Since L_2 can be written as

$$L_{2} = \sum_{i=1, i \neq k}^{n} x_{1k} x_{2i} (\partial_{1i} \partial_{2k} - \partial_{2i} \partial_{1k}) + \sum_{i=1}^{n} \theta_{2i} z_{k},$$

we obtain $L_2 \bullet \Phi(\beta; x) = 0$ in an analogous calculation with the case of L_1 .

Theorem 4 gives contiguity relations for $e_k = a_{1k} = (0, \dots, 0, \overset{k}{1}, 0, \dots, 0)$ $(1 \le k \le n)$, but it does not give those for $e_{n+1} = (0, \dots, 0, 1)$. The set of vectors $\{e_1, \dots, e_{n+1}\}$ is the standard basis of \mathbf{Z}^{n+1} . The contiguity relations for e_{n+1} can be obtained from Theorem 4 as follows.

Corollary 1 The incomplete $\Delta_1 \times \Delta_{n-1}$ -hypergeometric function $\Phi(\beta; x)$ satisfies the following contiguity relations.

• Shifts with respect to e_{n+1} :

$$S(\beta + e_{n+2}; -e_{n+2})\Phi(\beta + e_{n+2}; x) = \alpha_k \left(\sum_{i=1}^n \alpha_i - \delta\right) \Phi(\beta; x) - \alpha_k [g(t, x)]_{t=a}^{t=b},$$

$$S(\beta - e_{n+2}; +e_{n+2})\Phi(\beta - e_{n+2}; x) = \alpha_k \delta \Phi(\beta; x) + \alpha_k [g(t, x)]_{t=a}^{t=b},$$

where

$$S(\beta + e_{n+2}; -e_{n+2}) = S(\beta - a_{1k}; +a_{1k})\partial_{2k},$$

$$S(\beta - e_{n+2}; +e_{n+2}) = S(\beta - a_{2k}; +a_{2k})\partial_{1k} \quad \text{for } 1 \le k \le n+1.$$

Although we prove these contiguity relations for the integral representation of the incomplete $\Delta_1 \times \Delta_{n-1}$ function, they hold for functions which satisfy the system and the two conditions (3) and (5). By an easy calculation to check these conditions for the series solution $F(\beta; x)$, we obtain the following corollary.

Corollary 2 The series solution $F(\beta; x)$ satisfies the same contiguity relations.

We note that $\Phi(\beta; x)$ can be formally expanded in $F(\beta; x)$.

5 Appendix: A solvability of incomplete \mathcal{A} -hypergeometric systems

Let D be the Weyl algebra in n variables. We denote by $A = (a_{ij})$ a $d \times n$ -matrix whose elements are integers. We suppose that the set of the column vectors of A spans \mathbf{Z}^d .

Definition 2 ([6]) We call the following system of differential equations $H_A(\beta, g)$ an *incomplete* A-hypergeometric system:

$$(E_i - \beta_i) \bullet f = g_i, \quad E_i - \beta_i = \sum_{j=1}^n a_{ij} x_j \partial_j - \beta_i, \qquad (i = 1, \dots, d)$$

$$\square_{u,v} \bullet f = 0, \quad \square_{u,v} = \prod_{i=1}^n \partial_i^{u_i} - \prod_{j=1}^n \partial_j^{v_j}$$

with $u, v \in \mathbf{N}_0^n$ running over all u, v such that Au = Av.

Here, $\mathbf{N}_0 = \{0, 1, 2, \ldots\}$, and $\beta = (\beta_1, \ldots, \beta_d) \in \mathbf{C}^d$ are parameters and $g = (g_1, \ldots, g_d)$ where g_i are given holonomic functions.

We denote by $E - \beta$ the sequence $E_1 - \beta_1, \dots, E_d - \beta_d$ and I_A the affine toric ideal generated by $\square_{u,v}$ (Au = Av) in $\mathbf{C}[\partial_1, \dots, \partial_n]$.

Lemma 1 If the first homology of the Euler-Koszul complex vanishes;

$$H_1(K_{\bullet}(E - \beta; D/DI_A)) = 0,$$

then the syzygy module $\operatorname{syz}(E_1 - \beta_1, \dots, E_d - \beta_d) \subset (D/DI_A)^d$ is generated by $(E_i - \beta_i)e_j - (E_j - \beta_j)e_i \ (1 \le i < j \le d).$

Proof. The Euler-Koszul complex of D/DI_A is the following complex

$$0 \longrightarrow D/DI_A \xrightarrow{d_d} \cdots \xrightarrow{d_3} (D/DI_A)^{\binom{d}{2}} \xrightarrow{d_2} (D/DI_A)^d \xrightarrow{d_1} D/DI_A \longrightarrow 0$$

and the differential is defined by

$$d_p(e_{i_1,\dots,i_p}) = \sum_{k=1}^p (-1)^{k-1} (E_{i_k} - \beta_{i_k}) e_{i_1,\dots,\widehat{i_k},\dots,e_p}.$$

Here, $e_{i_1,...,i_p}$ are basis vectors of $(D/DI_A)^{\binom{d}{p}}$. The kernel of d_1 is $\operatorname{syz}(E_1 - \beta_1,...,E_d - \beta_d)$ and the image of d_2 is generated by $(E_i - \beta_i)e_j - (E_j - \beta_j)e_i$ $(1 \le i < j \le d)$ over $(D/DI_A)^d$. Since the first homology is zero, the conclusion is obtained.

Theorem 5 ([12]) If the first homology $H_1(K_{\bullet}(E-\beta;D/DI_A))$ vanishes and the g_i are holonomic functions satisfying the following relations

$$(E_i - \beta_i) \bullet g_j = (E_j - \beta_j) \bullet g_i, \qquad (i, j = 1, \dots, d)$$
(7)

$$\square_{u,v} \bullet g_i = 0, \qquad (i = 1, \dots, d, Au = Av, u, v \in \mathbf{N}_0^n)$$
(8)

then the incomplete hypergeometric system has a (classical) solution.

Proof. By virtue of [3, Theorem 4.1], $\mathcal{E}xt^1_{\mathcal{D}}(\mathcal{D}/\mathcal{D}H_A(\beta), \mathcal{O})$ vanishes at generic points in \mathbb{C}^n . Therefore, it is sufficient to prove that $\ell_1g_1+\cdots+\ell_dg_d=0$ for all $(\ell_1,\ldots,\ell_d,\ell_{d+1},\cdots,\ell_{d+m})\in\operatorname{syz}(E-\beta,\Box)$, where \Box is a finite sequence $\Box_{u_1,v_1},\ldots,\Box_{u_m,v_m}$ which are generators of I_A . Since for $(\ell_1,\ldots,\ell_d,\ell_{d+1},\cdots,\ell_{d+m})\in\operatorname{syz}(E-\beta,\Box)$, the relation $\sum_{i=1}^d\ell_i(E_i-\beta_i)+\sum_{i=1}^m\ell_{d+i}\Box_{u_i,v_i}=0$ holds, we have $(\ell_1,\ldots,\ell_d)\in\operatorname{syz}(E-\beta)$ over $(D/DI_A)^d$. By Lemma 1,

$$\ell_{1}g_{1} + \dots + \ell_{d}g_{d} = (\ell_{1}, \dots, \ell_{d}) \cdot g$$

$$= \sum_{1 \leq i < j \leq d} c_{ij} \{ (E_{i} - \beta_{i})e_{j} - (E_{j} - \beta_{j})e_{i} \} \cdot g, \qquad c_{ij} \in \mathbf{C}$$

$$= \sum_{1 \leq i < j \leq d} c_{ij} \{ (E_{i} - \beta_{i})g_{j} - (E_{j} - \beta_{j})g_{i} \}$$

$$= 0$$

Remark 3 Matusevich, Miller and Walther ([4, Theorem 6.3]) showed that if the toric ideal I_A is Cohen-Macaulay, the *i*-th homology of the Euler-Koszul complex vanishes for all positive integers *i*.

The following facts are known about Cohen-Macaulay property of toric ideals.

- 1. If the initial monomial ideal of I_A is square-free, then A is normal (see, e.g., [10, Proposition 13.15]).
- 2. If the matrix A is normal, then I_A is Cohen-Macaulay ([2]).

This is an easy tool for showing Cohen-Macaulayness of toric ideals. When A is $\Delta_1 \times \Delta_{n-1}$, we can easily verify the condition 1.

References

- [1] I.M. Gel'fand, A.V. Zelevinsky, M.M. Kapranov, Hypergeometric functions and toral manifolds. Functional Analysis and its Applications 23 (1989), 94–106.
- [2] M. Hochster, Rings of Invariants of Tori, Cohen-Macaulay Rings Generated by Monomials, and Polytopes, The Annals of Mathematics 96 (1972), 318– 337.
- [3] M. Kashiwara, On the Maximally Overdetermined System of Linear Differential Equations I, Publications of RIMS, Kyoto University 10 (1975), 563–579.
- [4] L.F. Matusevich, E. Miller, U. Walther, Homological methods for hypergeometric families, Journal of the American Mathematical Society 18 (2005), 919–941.
- [5] W. Miller, Lie theory and Lauricella functions F_D , Journal of Mathematical Physics **13** (1972), 1393–1399.
- [6] K. Nishiyama, N. Takayama, Incomplete A-Hypergeometric Systems, arXiv:0907.0745.
- [7] M. Saito, Contiguity Relations for the Lauricella Functions, Funkcialaj Ekvacioj **38** (1995), 37–58.
- [8] M. Saito, B. Sturmfels, and N. Takayama, Hypergeometric polynomials and integer programing, Compositio Mathematica 115 (1999), 185–204.
- [9] M. Saito, B. Sturmfels, and N. Takayama, *Gröbner Deformations of Hypergeometric Differential Equations*, Springer, 2000.
- [10] B. Sturmfels, Gröbner Bases and Convex Polytopes, University Lecture Notes, Vol. 8, American Mathematical Society, 1995.
- [11] T. Sasaki, Contiguity relations of Aomoto-Gel'fand hypergeometric functions and applications to Appell's system F_3 and Goursat's system $_3F_2$, SIAM Journal of Mathematical Analysis **22** (1991), 821–846.
- [12] N. Takayama, Private communication, 2010.