# Separation of variables for the generalized Henon-Heiles system and system with quartic potential 

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#### Abstract

We consider two well-known integrable systems on the plane using the concept of natural Poisson bivectors on Riemaninan manifolds. Geometric approach to construction of variables of separation and separated relations for the generalized Henon-Heiles system and the generalized system with quartic potential is discussed in detail.


## 1 Introduction.

A fundamental requirement for new developments in mechanics is to unravel the geometry that underlies different dynamical systems, especially mechanical systems. In fact, geometric analysis of such systems reveals what they have in common and indicates the most suitable strategy to obtain and to analyze their solutions.

The Hamilton-Jacobi theory for finite-dimensional Hamiltonian systems is well understood in both classical and geometric points of view, see foundational works of Jacobi, Stäckel, Levi-Civita and others. Apart from its fundamental aspects such as its relation to the action integral and generating functions of symplectic maps, the theory is known to be very useful in integrating the Hamilton equations using the technique of separation of variables.

An integrable system is separable if there are variables of separation ( $u, p_{u}$ ) and $n$ separation relations

$$
\begin{equation*}
\Phi_{i}\left(u_{i}, p_{u_{i}}, H_{1}, \ldots, H_{n}\right)=0, \quad i=1, \ldots, n, \quad \text { with } \operatorname{det}\left[\frac{\partial \Phi_{i}}{\partial H_{j}}\right] \neq 0 \tag{1.1}
\end{equation*}
$$

connecting single pairs $u_{i}, p_{u_{i}}$ of canonical coordinates with the $n$ Hamiltonians $H_{1}, \ldots, H_{n}$. Solving these relations in terms of $p_{u_{i}}$ one gets the Jacobi equations and a corresponding additively separable complete integral of the Hamilton-Jacobi equation

$$
W=\sum_{i=1}^{n} \int^{u_{i}} p_{u_{i}}\left(u_{i}^{\prime}, \alpha_{1}, \ldots, \alpha_{n}\right) d u_{i}^{\prime}, \quad \alpha_{j}=H_{j}
$$

Any separable system is a bi-integrable system [7, 10, i.e. $n$ functionally independent integrals of motion $H_{k}$ are in bi-involution

$$
\begin{equation*}
\left\{H_{i}, H_{k}\right\}=\left\{H_{i}, H_{k}\right\}^{\prime}=0, \quad i, k=1, \ldots, n \tag{1.2}
\end{equation*}
$$

with respect to compatible Poisson brackets $\{.,$.$\} and \{., .\}^{\prime}$ associated with the Poisson bivectors $P$ and $P^{\prime}$, such that

$$
\begin{equation*}
[P, P]=0, \quad\left[P, P^{\prime}\right]=0, \quad\left[P^{\prime}, P^{\prime}\right]=0 \tag{1.3}
\end{equation*}
$$

Here [., .] is the Schouten bracket.
For the given integrable system fixed by kinematic bivector $P$ and a tuple of integrals of motion $H_{1}, \ldots, H_{n}$ bi-Hamiltonian construction of variables of separation consists in a direct solution of the equations (1.2) and (1.3) with respect to an unknown bivector $P^{\prime}$ [8, 9. The main problem is that
geometrically invariant equations (1.2)1.3) a'priori have infinite number of solutions [7, 10]. So, in order to get a search algorithm of effectively computable solutions we have to narrow the search space by using some non-invariant additional assumptions.

The aim of this note is to prove that the concept of natural Poisson bivectors on the Riemannian manifolds allows us to properly restrict the search space and to calculate new variables of separation for the well-known generalized Henon-Heiles system and the system with quartic potential [2, 3, 4,

## 2 Settings

In this section we recall some necessary facts about natural bi-integrable systems on Riemannian manifolds admitting separation of variables in the Hamilton-Jacobi equation.

Let $Q$ be a $n$-dimensional Riemannian manifold. Its cotangent bundle $T^{*} Q$ is naturally endowed with canonical invertible Poisson bivector $P$, which has a standard form in fibered coordinates $z=$ $\left(q_{1}, \ldots, q_{n}, p_{1}, \ldots, p_{n}\right)$ on $T^{*} Q$

$$
P=\left(\begin{array}{cc}
0 & \mathrm{I}  \tag{2.1}\\
-\mathrm{I} & 0
\end{array}\right), \quad\{f, g\}=\langle P d f, d g\rangle=\sum_{i=1}^{2 n} P_{i j} \frac{\partial f}{\partial z_{i}} \frac{\partial g}{\partial z_{j}}
$$

The Hamilton function for natural system on $Q$

$$
\begin{equation*}
H=T+V=\sum_{i, j=1}^{n} \mathrm{~g}_{i j} p_{i} p_{j}+V\left(q_{1}, \ldots, q_{n}\right) \tag{2.2}
\end{equation*}
$$

is a sum of the geodesic Hamiltonian $T$ and potential energy $V$.
According to [10, 11, for the overwhelming majority of known natural Hamiltonian systems second bivector $P^{\prime}$ usually has a natural form, i.e. $P^{\prime}$ is a sum of the geodesic Poisson bivector $P_{T}^{\prime}$ and the potential Poisson bivector defined by a torsionless $(1,1)$ tensor field $\Lambda\left(q_{1}, \ldots, q_{n}\right)$ on $Q$ associated with potential $V$

$$
P^{\prime}=P_{T}^{\prime}+\left(\begin{array}{cc}
0 & \Lambda_{i j}  \tag{2.3}\\
-\Lambda_{j i} & \sum_{k=1}^{n}\left(\frac{\partial \Lambda_{k i}}{\partial q_{j}}-\frac{\partial \Lambda_{k j}}{\partial q_{i}}\right) p_{k}
\end{array}\right)
$$

The geodesic Poisson bivector $P_{T}^{\prime}$ is defined by $n \times n$ matrix $\Pi$ on $T^{*} Q$ and functions $\mathrm{x}, \mathrm{y}$ and z:

$$
P_{T}^{\prime}=\left(\begin{array}{cc}
\sum_{k=1}^{n} \mathrm{x}_{j k}(q) \frac{\partial \Pi_{j k}}{\partial p_{i}}-\mathrm{y}_{i k}(q) \frac{\partial \Pi_{i k}}{\partial p_{j}} & \Pi_{i j}  \tag{2.4}\\
-\Pi_{j i} & \sum_{k=1}^{n}\left(\frac{\partial \Pi_{k i}}{\partial q_{j}}-\frac{\partial \Pi_{k j}}{\partial q_{i}}\right) \mathrm{z}_{k}(p)
\end{array}\right)
$$

In fact, functions $x, y$ and $z$ are completely determined by the matrix $\Pi$ via compatibility conditions

$$
\begin{equation*}
\left[P, P_{T}^{\prime}\right]=\left[P_{T}^{\prime}, P_{T}^{\prime}\right]=0 \tag{2.5}
\end{equation*}
$$

We can add various integrable potentials $V$ to the given geodesic Hamiltonian $T$ in order to get integrable natural Hamiltonians (2.2). In similar manner we can add different compatible potential matrices $\Lambda$ to the given geodesic matrix $\Pi$ in order to get natural Poisson bivectors $P^{\prime}$ (2.3) compatible with the canonical bivector $P$.

The definitions of natural Hamilton functions (2.2) and natural Poisson bivectors (2.3) are noninvariant because they depend on a choice of coordinate system. Below we show how canonical transformations of variables change this definitions of natural Poisson bivectors.

## 3 Generalized Henon-Heiles system

Let us consider a generalized Henon-Heiles system [2, 3] defined by the following Hamilton function

$$
\begin{equation*}
H_{1}=\frac{p_{1}^{2}+p_{2}^{2}}{2}+\frac{c_{1}}{8} q_{2}\left(3 q_{1}^{2}+16 q_{2}^{2}\right)+c_{2}\left(2 q_{2}^{2}+\frac{q_{1}^{2}}{8}\right)+\frac{c_{4}}{q_{1}^{2}}+\frac{c_{5}}{q_{1}^{6}} \tag{3.1}
\end{equation*}
$$

and second integral of motion

$$
\begin{align*}
H_{2} & =p_{1}^{4}+\left(\frac{q_{1}^{2}\left(3 c_{1} q 2+c_{2}\right)}{2}+\frac{4 c_{4}}{q_{1}^{2}}+\frac{4 c_{5}}{q_{1}^{6}}\right) p_{1}^{2}-\frac{c_{1} q_{1}^{3}}{2} p_{1} p_{2}-\frac{c_{1}^{2} q_{1}^{6}}{32}+\frac{\left(c_{2}-3 c_{1} q_{2}\right)\left(c_{2}+c_{1} q_{2}\right) q_{1}^{4}}{16} \\
& +c_{1} c_{4} q_{2}+\frac{c_{2} c_{5}+4 c_{4}^{2}+3 c_{1} c_{5} q_{2}}{q_{1}^{4}}+\frac{8 c_{4} c_{5}}{q_{1}^{8}}+\frac{4 c_{5}^{2}}{q_{1}^{2}} \tag{3.2}
\end{align*}
$$

At $c_{4}=c_{5}=0$ variables of separation have been obtained in [4], see also discussion in [1, 5]. In this section we recover these results in the framework of the bi-Hamiltonian geometry and obtain new variables of separation for the generic case.

### 3.1 Case $c_{4}=c_{5}=0$

Let us suppose that the required bi-vector $P^{\prime}$ has a natural form (2.3). Substituting $H_{1,2}$ (3.13.2) into the equation (1.2) and solving resulting equation together with (1.3) one gets two distinct solutions $P_{1}^{\prime}$ and $P_{2}^{\prime}$.

First solution $P_{1}^{\prime}$ is defined by the following geodesic matrix

$$
\Pi^{(1)}=\frac{1}{2}\left(\begin{array}{cc}
p_{1}^{2}+\frac{1}{2} p_{2}^{2} & 0  \tag{3.3}\\
\frac{1}{2} p_{1} p_{2} & \frac{1}{2} p_{2}^{2}
\end{array}\right)
$$

and potential matrices

$$
\Lambda^{(1)}=\left(\begin{array}{cc}
\frac{q_{1}^{2}\left(3 c_{1} q_{2}+c_{2}\right)}{8}+c_{1} q_{2}^{3}+c_{2} q_{2}^{2} & \frac{c_{1} q_{1}^{3}}{16}+\left(\frac{3 c_{1} q_{2}}{2}+c_{2}\right) q_{1} q_{2}  \tag{3.4}\\
-\frac{c_{1} q_{1}^{3}}{32} & c_{1} q_{2}^{3}+c_{2} q_{2}^{2}
\end{array}\right)
$$

for which

$$
\mathrm{x}_{j k}=\mathrm{y}_{j k}=\delta_{j k} q_{k}, \quad z_{k}(p)=0
$$

The corresponing recursion operator $N_{1}=P_{1}^{\prime} P^{-1}$ yields the integrals of motion

$$
\begin{equation*}
\mathcal{H}_{k}=\frac{1}{2 k} \operatorname{tr} N_{1}^{k}, \quad k=1,2 \tag{3.5}
\end{equation*}
$$

which form a bi-Hamiltonian hierarchy, i.e. the Lenard relations hold

$$
\begin{equation*}
P^{\prime} d \mathcal{H}_{1}=P d \mathcal{H}_{2} \tag{3.6}
\end{equation*}
$$

These integrals are the following functions of initial integrals of motion (3.13.2)

$$
\mathcal{H}_{1}=2 H_{1} \quad \mathcal{H}_{2}=\frac{H_{2}}{8}+\frac{H_{1}^{2}}{2}
$$

So, the first recursion operator $N_{1}=P_{2}^{\prime} P^{-1}$ gives rise to the action variables $\mathcal{H}_{1,2}$ (3.5) with trivial dynamics.

Second solution $P_{2}^{\prime}$ is defined by the matrices

$$
\Pi^{(2)}=\frac{1}{2 q_{1}^{2}}\left(\begin{array}{cc}
2 p_{1}^{2} & 0  \tag{3.7}\\
p_{1} p_{2} & 0
\end{array}\right), \quad \Lambda^{(2)}=\left(\begin{array}{cc}
\frac{c_{1} q_{2}}{2}+\frac{c_{2}}{4} & \frac{c_{1} q_{1}}{8}+\frac{q_{2}\left(3 c_{1} q_{2}+2 c_{2}\right)}{q_{1}} \\
-\frac{c_{1} q_{1}}{16} & -\frac{c_{1} q_{2}}{4}
\end{array}\right)
$$

and functions

$$
\mathrm{x}_{j 1}=\mathrm{y}_{i 1}=-q_{1}, \quad \mathrm{z}_{k}(p)=0
$$

Instead of the Lenard relations (3.6) here we have the following relations

$$
\begin{equation*}
P^{\prime} d H_{i}=P \sum_{j=1}^{2} F_{i j} d H_{j}, \quad i=1, \ldots, 2 \tag{3.8}
\end{equation*}
$$

where $F$ is a so-called control matrix

$$
F=\frac{1}{2}\left(\begin{array}{cc}
4 p_{1}^{2} q_{1}^{-2}+c_{1} q_{2}+c_{2} & q_{1}^{2} \\
16 H_{2} q_{1}^{-2} & 4 p_{1}^{2} q_{1}^{-2}+c_{1} q_{2}+c_{2}
\end{array}\right)
$$

Eigenvalues of $F$ coincide with the eigenvalues of recursion operator, which are the desired variables of separation.

So, the second recursion operator $N_{2}=P_{2}^{\prime} P^{-1}$ yields the variables of separation with non-trivial separated relations. These variables of separation and the corresponding separated relations are considered in the next section.

As usual, the recursion operators $N_{1,2}$ generate two infinite families of solutions of the equations (1.2|1.3)

$$
\begin{equation*}
P_{1,2}^{(m)}=N_{1,2}^{m} P, \quad m=\ldots,-1,0,1, \ldots \tag{3.9}
\end{equation*}
$$

associated with the Hamiltonians $H_{1,2}$ (3.1(3.2).

### 3.2 Case $c_{4,5} \neq 0$

According to [10] at $c_{5} \neq 0$ we have to apply the following canonical transformation

$$
\begin{equation*}
p_{1} \rightarrow p_{1}+\sqrt{\frac{-2 c_{5}}{q_{1}^{6}}} \tag{3.10}
\end{equation*}
$$

to the natural Poisson bivectors $P_{1,2}^{\prime}$. Namely, in generic case the integrals of motion $H_{1,2}$ (3.1)3.2) are in involution with respect to the Poisson brackets associated with the shifted bivectors

$$
\hat{P}_{1}=P_{1}^{\prime}+\frac{\sqrt{-2 c_{5}}}{q_{1}^{3}}\left(\begin{array}{cccc}
0 & 0 & p_{1}+\frac{1}{2} \sqrt{\frac{-2 c_{5}}{q_{1}^{6}}} & 0  \tag{3.11}\\
* & 0 & p_{2} & 0 \\
* & * & 0 & \frac{3 c_{1}}{8} q_{1}^{2}+6 c_{1} q_{2}^{2}+4 c_{2} q_{2} \\
* & * & * & 0
\end{array}\right)
$$

and

$$
\hat{P}_{2}=P_{2}^{\prime}+\frac{2 \sqrt{-2 c_{5}}}{q_{1}^{5}}\left(\begin{array}{ccc}
0 & 0 & p_{1}+\frac{1}{2} \sqrt{\frac{-2 c_{5}}{q_{1}^{6}}} \tag{3.12}
\end{array} c\right.
$$

These bivectors were obtained by substituting non-homogeneous polynomial ansatz for the geodesic bivector $P_{T}^{\prime}$ into the equation (2.5). In contrast with the pair of bivectors $P_{1,2}^{\prime}$ (3.3|3.7) these bivectors $\hat{P}_{1,2}$ generate variables of separation with nontrivial separated relations in both cases.

Firstly, let us consider the recursion operator $\hat{N}_{2}=\hat{P}_{2} P^{-1}$ and its eigenvalues $u_{1,2}$, which are the roots of the following polynomial

$$
\begin{align*}
B(\lambda) & =\left(\lambda-u_{1}\right)\left(\lambda-u_{2}\right)=\lambda^{2}-\left(\frac{p_{1}^{2}}{q_{1}^{2}}+\frac{c_{1} q_{2}+c_{2}}{4}+\frac{2 \sqrt{-2 c_{5}} p_{1}}{q_{1}^{5}}-\frac{2 c_{5}}{q_{1}^{8}}\right) \lambda \\
& -\frac{c_{1}\left(4 p_{1}^{2} q_{2}-2 q_{1} p_{1} p_{2}-c_{2} q_{1}^{2} q_{2}\right)}{16 q_{1}^{2}}+\frac{c_{1}^{2}\left(8 q_{1}^{2}+q_{2}\right)}{16}-\frac{c_{1} \sqrt{-2 c_{5}}\left(4 p_{1} q_{2}-q_{1} p_{2}\right)}{8 q_{1}^{5}}+\frac{c_{1} c_{5} q_{2}}{2 q_{1}^{8}} . \tag{3.13}
\end{align*}
$$

According to [8, 9, 10] now we are looking for the auxiliary polynomial $A(\lambda)=a_{1} \lambda+a_{0}$, which is solution of the equation

$$
\begin{equation*}
\{B(\lambda), A(\mu)\}=-\frac{\left(d_{2} \mu^{2}+d_{1} \mu+d_{0}\right) B(\lambda)-\left(d_{2} \lambda^{2}+d_{1} \mu+d_{0}\right) B(\mu)}{\lambda-\mu}, \quad\{A(\lambda), A(\mu)\}=0 \tag{3.14}
\end{equation*}
$$

with respect to unknown functions $a_{1,0}, d_{1,2}$ and $d_{0}$. In our case $d_{2}=d_{0}=0, d_{0}=1$, and desired polynomial

$$
A(\lambda)=-\frac{64\left(q_{1}^{3} p_{1}+\sqrt{-2 c_{5}}\right)}{c_{1}^{2} q_{1}^{4}} \lambda-\frac{4\left(4 p_{1} q_{2}-q_{1} p_{2}\right)}{c_{1} q_{1}}-\frac{16 \sqrt{-2 c_{5}} q_{2}}{c_{1} q_{1}^{4}}
$$

satisfies the following equations

$$
\{B(\lambda), A(\mu)\}=-\frac{1}{\lambda-\mu}(B(\lambda)-B(\mu)), \quad\{A(\lambda), A(\mu)\}=0
$$

It entails that

$$
p_{u_{j}}=A\left(\lambda=u_{j}\right), \quad\left\{u_{i}, p_{u_{j}}\right\}=\delta_{i j}, \quad i, j=1,2
$$

are canonically conjugated momenta.
An inverse canonical transformation from variables of separation to the initial variables looks like

$$
\begin{aligned}
& q_{1}=\sqrt{\frac{c_{1}^{2}\left(p_{u_{1}}^{2}-p_{u_{2}}^{2}\right)}{32\left(u_{1}-u_{2}\right)}+32 \frac{c_{2}\left(u_{1}+u_{2}\right)-4\left(u_{1}^{2}-u_{1} u_{2}-u_{2}^{2}\right)}{c_{1}^{2}}} \\
& p_{1}=-\frac{c_{1}^{2}\left(p_{u_{1}}-p_{u_{2}}\right)}{64\left(u_{1}-u_{2}\right)} q_{1}-\frac{\sqrt{-2 c_{5}}}{q_{1}^{3}}, \quad q_{2}=-c_{1}^{3}\left(\frac{p_{u_{1}}-p_{u_{2}}}{32\left(u_{1}-u_{2}\right)}\right)^{2}+\frac{4\left(u_{1}+u_{2}\right)-c_{2}}{c_{1}}, \\
& p_{2}=2 c_{1}^{5}\left(\frac{p_{u_{1}}-p_{u_{2}}}{32\left(u_{1}-u_{2}\right)}\right)^{3}+\frac{c_{1}}{4\left(u_{1}-u_{2}\right)}\left(\frac{p_{u_{1}}-p_{u_{2}}}{4} c_{2}-\left(u_{1}+2 u_{2}\right) p_{u_{1}}+\left(2 u_{1}+u_{2}\right) p_{u_{2}}\right) .
\end{aligned}
$$

Now it is easy to calculate the separated relations

$$
\begin{equation*}
\Phi\left(u_{k}, p_{u_{k}}\right)=\Phi_{+}\left(u_{k}, p_{u_{k}}\right) \Phi_{-}\left(u_{k}, p_{u_{k}}\right)-\frac{c_{4}\left(c_{2}-8 u_{k}\right)}{4}+\frac{c_{1}^{2} \sqrt{-2 c_{5}} p_{u_{k}}}{32}=0, \quad k=1,2 \tag{3.15}
\end{equation*}
$$

where

$$
\Phi_{ \pm}\left(u_{k}, p_{u_{k}}\right)=\left(\frac{c_{1}^{2} p_{u_{k}}^{2}}{32}-H_{1} \pm \frac{\sqrt{H_{2}}}{2}-\frac{128 u_{k}^{3}}{c_{1}^{2}}+\frac{32 c_{2} u_{k}^{2}}{c_{1}^{2}}\right)
$$

These separated relations are given by the affine equations in Hamiltonians $H_{1}$ and $H_{2}-4 H_{1}^{2}$. It means that the generalized Henon-Heiles system belongs to the Stäckel family of separable systems.

At $c_{4}=c_{5}=0$ these separated relations (3.15) may be reduced to a pair of distinct separated relations

$$
\Phi_{+}\left(u_{1}, p_{u_{1}}\right)=0, \quad \text { and } \quad \Phi_{-}\left(u_{2}, p_{u_{2}}\right)=0
$$

and the equations of motion are linearized on two different elliptic curves, see [1, 4, 5].
In generic case $c_{4} \neq 0$ and $c_{5} \neq 0$ equations of motion are linearized on the two copies of nonhyperelliptic curve of genus three defined by (3.15). An explicit description of the linerization procedure is an open problem similar to the generalized Kowalevski and Chaplygin systems [8, 9].

Using the first bivector $\hat{P}_{1}$ (3.11) we can get other variables of separation

$$
\widehat{B}(\lambda)=\left(\operatorname{det}\left(\hat{P}_{1} P^{-1}-\lambda \mathrm{I}\right)\right)^{1 / 2}=\left(\lambda-v_{1}\right)\left(\lambda-v_{2}\right)
$$

which are related with the previous separated variables by canonical transformation

$$
v_{k}=\frac{c_{1}^{2} p_{u_{k}}^{2}}{64}-\frac{64 u_{k}^{3}}{c_{1}^{2}}+\frac{16 c_{2} u_{k}^{2}}{c_{1}^{2}}, \quad k=1,2
$$

## 4 Generalized system with quartic potential

Let us consider a generalization of the system with quartic potential 3] with the Hamilton function

$$
\begin{equation*}
H_{1}=\frac{p_{1}^{2}+p_{2}^{2}}{2}+\frac{c_{1}}{4}\left(q_{1}^{4}+6 q_{1}^{2} q_{2}^{2}+8 q_{2}^{4}\right)+\frac{c_{2}}{2}\left(q_{1}^{2}+4 q_{2}^{2}\right)+\frac{2 c_{3}}{q_{2}^{2}}+\frac{c_{4}}{q_{1}^{2}}+\frac{c_{5}}{q_{1}^{6}} \tag{4.1}
\end{equation*}
$$

and second integral of motion

$$
\begin{align*}
H_{2}=p_{1}^{4} & +p_{1}^{2}\left(c_{1} q_{1}^{4}+6 c_{1} q_{1}^{2} q_{2}^{2}+2 c_{2} q_{1}^{2}+\frac{4 c_{4}}{q_{1}^{2}}+\frac{4 c_{5}}{q_{1}^{6}}\right)-4 c_{1} q_{1}^{3} q_{2} p_{1} p_{2} \\
& +c_{1} q_{1}^{4} p_{2}^{2}+\frac{4 c_{4}^{2}}{q_{1}^{4}}+2 c_{1} c_{4} q_{1}^{2}+4 c_{1} c_{4} q_{2}^{2}+c_{2}^{2} q_{1}^{4}+c_{1} c_{2} q_{1}^{6}+2 c_{1} c_{2} q_{1}^{4} q_{2}^{2}+\frac{c_{1}^{2} q_{1}^{8}}{4} \\
& +c_{1}^{2} q_{1}^{6} q_{2}^{2}+c_{1}^{2} q_{1}^{4} q_{2}^{4}+\frac{4 c_{1} c_{3} q_{1}^{4}}{q_{2}^{2}}+c_{5}\left(\frac{8 c_{4}}{q_{1}^{8}}+\frac{4 c_{5}}{q_{1}^{12}}+\frac{4 c_{2}}{q_{1}^{4}}+\frac{2 c_{1}}{q_{1}^{2}}+\frac{12 c_{1}}{q_{1}^{4} q_{2}^{2}}\right) \tag{4.2}
\end{align*}
$$

At $c_{4}=c_{5}=0$ variables of separation were obtained in 4], see also [5]. In the following section we reproduce this result in the framework of bi-Hamiltonian geometry and obtain variables of separation in the generic case at $c_{4,5} \neq 0$.

### 4.1 Case $c_{4}=c_{5}=0$

According to [6, 10], the geodesic matrices $\Pi^{(1,2)}$ (3.3|3.7) are compatible with another pair of potential matrices

$$
\Lambda^{\left(1^{\prime}\right)}=\left(\begin{array}{cc}
\frac{c_{1} q_{1}^{4}}{4}+\left(3 c_{1} q_{2}^{2}+c_{2}\right) \frac{q_{1}^{2}}{2}+c_{1} q_{2}^{4}+c_{2} q_{2}^{2}+\frac{c_{3}}{q_{2}^{2}} & \frac{c_{1} q_{1}^{3} q_{2}}{2}+\left(2 c_{1} q_{2}^{3}+c_{2} q_{2}-\frac{c_{3}}{q_{2}^{3}}\right) q_{1}  \tag{4.3}\\
-\frac{c_{1} q_{1}^{3} q_{2}}{4} & c_{1} q_{2}^{4}+c_{2} q_{2}^{2}+\frac{c_{3}}{q_{2}^{2}}
\end{array}\right)
$$

and

$$
\Lambda^{\left(2^{\prime}\right)}=\left(\begin{array}{cc}
c_{2}+c_{1}\left(\frac{q_{1}^{2}}{2}+2 q_{2}^{2}\right) & c_{1} q_{1} q_{2}+2 \frac{2 c_{1} q_{2}^{6}+c_{2} q_{2}^{4}-c_{3}}{q_{1} q_{2}^{3}}  \tag{4.4}\\
-\frac{c_{1} q_{1} q_{2}}{2} & -c_{1} q_{2}^{2}
\end{array}\right)
$$

As above, a natural Poisson bivector $P_{1}^{\prime}$ defined by the matrices $\Pi^{(1)}$ and $\Lambda^{\left(1^{\prime}\right)}$ yields recursion operator $N_{1}$ and integrals of motion $\mathcal{H}_{1,2}$ (3.5), which form a bi-Hamiltonian hierarchy (3.6).

Matrices $\Pi^{(2)}$ and $\Lambda^{\left(2^{\prime}\right)}$ define the second natural bivector $P_{2}^{\prime}$ and the recursion operator $N_{2}=P_{2}^{\prime} P^{-1}$, whose eigenvalues are the variables of separation $u_{1,2}$

$$
\begin{align*}
B(\lambda) & =\left(\operatorname{det}\left(N_{2}-\lambda \mathrm{I}\right)\right)^{1 / 2}=\left(\lambda-u_{1}\right)\left(\lambda-u_{2}\right)  \tag{4.5}\\
& =\lambda^{2}+\frac{q_{1}^{4} c_{1}+2 c_{2} q_{1}^{2}+2 q_{1}^{2} c_{1} q_{2}^{2}+2 p_{1}^{2}}{2 q_{1}^{2}} \lambda+\frac{c_{1}\left(q_{2}^{2} q_{1}^{2} p_{2}^{2}+4 c_{3} q_{1}^{2}+4 p_{1}^{2} q_{2}^{4}-4 p_{1} q_{2}^{3} q_{1} p_{2}\right)}{4 q_{1}^{2} q_{2}^{2}}
\end{align*}
$$

In this case equation (3.14) has another solution $d_{2}=d_{0}=0, d_{1}=1$, and

$$
\begin{equation*}
A(\lambda)=-\frac{p_{1}}{c_{1} q_{1}} \lambda-\frac{q_{2}^{2} p_{1}}{q_{1}}+\frac{q_{2} p_{2}}{2} . \tag{4.6}
\end{equation*}
$$

It allows us to calculate the desired momenta

$$
\begin{equation*}
p_{u_{j}}=\frac{A\left(u_{j}\right)}{u_{j}}, \quad\left\{u_{i}, p_{u_{j}}\right\}=\delta_{i j}, \quad i, j=1,2 \tag{4.7}
\end{equation*}
$$

In the variables of separation $\left(u, p_{u}\right)$ the second integral of motion $H_{2}$ (4.2) is a complete square and it is easy to prove that $H_{1}$ and $\sqrt{H_{2}}$ satisfy the following separated relations

$$
\begin{array}{ll}
\Phi_{-}\left(u, p_{u}\right)=H_{1}-\frac{1}{2} \sqrt{H_{2}}+2 c_{1} u p_{u}^{2}-\frac{2 u^{2}}{c_{1}}+\frac{2 c_{2} u}{c_{1}}+\frac{2 c_{1} c_{3}}{u}=0, & u=u_{1}, p_{u}=p_{u_{1}} \\
\Phi_{+}\left(u, p_{u}\right)=H_{1}+\frac{1}{2} \sqrt{H_{2}}+2 c_{1} u p_{u}^{2}-\frac{2 u^{2}}{c_{1}}+\frac{2 c_{2} u}{c_{1}}+\frac{2 c_{1} c_{3}}{u}=0, & u=u_{2}, p_{u}=p_{u_{2}} \tag{4.8}
\end{array}
$$

and equations of motion are linearized on a pair of elliptic curves (see [1, 4, 5]).

### 4.2 Case $c_{4,5} \neq 0$

At $c_{5} \neq 0$ in order to get bi-Hamiltonian structures we apply the same canonical transformation as for the Henon-Heiles system (3.10)

$$
\begin{equation*}
p_{1} \rightarrow p_{1}+\sqrt{\frac{-2 c_{5}}{q_{1}^{6}}} \tag{4.9}
\end{equation*}
$$

which shifts the Poisson bivectors defined by potential matrices 4.3|4.4) by the rule

$$
\widetilde{P}_{1}=P_{1}^{\prime}+\frac{\sqrt{-2 c_{5}}}{q_{1}^{3}}\left(\begin{array}{cccc}
0 & 0 & p_{1}+\frac{1}{2} \sqrt{\frac{-2 c_{5}}{2 q_{1}^{6}}} & 0  \tag{4.10}\\
* & 0 & p_{2} & 0 \\
* & * & 0 & 8 c_{1} q_{2}^{3}+\left(3 c_{1} q_{1}^{2}+4 c_{2}\right) q_{2}-\frac{4 c_{3}}{q_{2}^{3}} \\
* & * & * & 0
\end{array}\right)
$$

and

$$
\widetilde{P}_{2}=P_{2}^{\prime}+\frac{2 \sqrt{-2 c_{5}}}{q_{1}^{5}}\left(\begin{array}{cccc}
0 & 0 & p_{1}+\frac{1}{2} \sqrt{\frac{-2 c_{5}}{q_{1}^{6}}} & 0  \tag{4.11}\\
* & 0 & p_{2} & 0 \\
* & * & 0 & 8 c_{1} q_{2}^{3}+\left(3 c_{1} q_{1}^{2}+4 c_{2}\right) q_{2}-\frac{4 c_{3}}{q_{2}^{3}} \\
* & * & * & 0
\end{array}\right)
$$

At $c_{5} \neq 0$ polynomials $B(\lambda)$ and $A(\lambda)$ are obtained from (4.5) and (4.6) using the canonical transformation (4.9). For instance, a "shifted" polynomial $A(\lambda)$ reads as

$$
A(\lambda)=-\frac{\left(p_{1}+\sqrt{\frac{-2 c_{5}}{q_{1}^{6}}}\right) \lambda}{c_{1} q_{1}}-\frac{q_{2}^{2}\left(p_{1}+\sqrt{\frac{-2 c_{5}}{q_{1}^{6}}}\right)}{q_{1}^{2}}+\frac{p_{2} q_{2}}{2} .
$$

An inverse canonical transformation from variables of separation to the original variables looks like

$$
\begin{aligned}
& q_{1}=\sqrt{\left(-\frac{2\left(u_{1} p_{u_{1}}^{2}-u_{2} p_{u_{2}}^{2}\right)}{u_{1}-u_{2}}+\frac{2 c_{3}}{u_{1} u_{2}}\right) c_{1}+\frac{2\left(u_{1}+u_{2}-c_{2}\right)}{c_{1}}} \\
& p_{1}=\frac{c_{1}\left(u_{1} p_{u_{1}}-u_{2} p_{u_{2}}\right)}{u_{1}-u_{2}} q_{1}-\frac{\sqrt{-2 c_{5}}}{q_{1}^{3}}, \quad q_{2}=\sqrt{-\frac{c_{1} u_{1} u_{2}\left(p_{u_{1}}-p_{u_{2}}\right)^{2}}{\left(u_{1}-u_{2}\right)^{2}}-\frac{c_{3}}{u_{1} u_{2}}} \\
& p_{2}=-\frac{2}{q_{2}}\left(\frac{c_{1}^{2} c_{3}\left(u_{1} p_{u_{1}}-u_{2} p_{u_{2}}\right)}{u_{1} u_{2}\left(u_{1}-u_{2}\right)}+\frac{u_{1} u_{2}\left(p_{\left.u_{1}-p_{u_{2}}\right)}^{\left(u_{1}-u_{2}\right)^{3}}\left(c_{1}^{2}\left(p_{u_{1}}-p_{u_{2}}\right)\left(u_{1} p_{u_{1}}-u_{2} p_{u_{2}}\right)-\left(u_{1}-u_{2}\right)^{2}\right)\right)}{} .\right.
\end{aligned}
$$

Now it is easy to prove that the corresponding separated relations are equal to

$$
\begin{equation*}
\Phi\left(u_{k}, p_{u_{k}}\right)=\Phi_{+}\left(u_{k}, p_{u_{k}}\right) \Phi_{-}\left(u_{k}, p_{u_{k}}\right)+\left(2 u_{k}-c_{2}\right) c_{4}-2 c_{1} \sqrt{-2 c_{5}} u_{k} p_{u_{k}}=0, \quad k=1,2 \tag{4.12}
\end{equation*}
$$

where $\Phi_{ \pm}\left(u, p_{u}\right)$ are given by (4.8). The separated relations are affine equations with respect to the Hamilton functions $H_{1}$ and integral of motion $H_{2}-4 H_{1}^{2}$. It means that the generalized system with quartic potential belongs to the Stäckel family of separable systems.

As above, in the generic case $c_{4} \neq 0$ and $c_{5} \neq 0$ equations of motion are linearized on the two copies of the non-hyperelliptic curve of genus three defined by (4.12) and we do not know how to solve the corresponding Abel-Jacobi equations as yet.

Using the first bivector $\tilde{P}_{1}$ (4.10) we can get other variables of separation

$$
\widetilde{B}(\lambda)=\left(\operatorname{det}\left(\widetilde{P}_{1} P^{-1}-\lambda \mathrm{I}\right)\right)^{1 / 2}=\left(\lambda-v_{1}\right)\left(\lambda-v_{2}\right)
$$

which are related with previous separated variables by the following canonical transformation

$$
v_{k}=c_{1} u_{k} p_{u_{k}}^{2}-\frac{u_{k}^{2}}{c_{1}}+\frac{c_{2} u_{k}}{c_{1}}+\frac{c_{1} c_{3}}{u_{k}}, \quad k=1,2
$$

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