

An observation on Turán-Nazarov inequality

O. Friedland Y. Yomdin

Abstract

The main observation of this note is that the Lebesgue measure μ in the Turán-Nazarov inequality for exponential polynomials can be replaced with a certain geometric invariant $\omega \geq \mu$, which can be effectively estimated in terms of the metric entropy of a set, and may be nonzero for discrete and even finite sets. While the frequencies (the imaginary parts of the exponents) do not enter the original Turán-Nazarov inequality, they necessarily enter the definition of ω .

1 Introduction

The classical Turán inequality bounds the maximum of the absolute value of an exponential polynomial $p(t)$ on an interval B through the maximum of its absolute value on any subset Ω of positive measure. Turán [8] assumed Ω to be a subinterval of B , and Nazarov [4] generalized it to any subset Ω of positive measure. More precisely, we have:

Theorem 1.1 ([4]). *Let $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$ be an exponential polynomial, where $c_k, \lambda_k \in \mathbb{C}$. Let $B \subset \mathbb{R}$ be an interval, and let $\Omega \subset B$ be a measurable set. Then*

$$\sup_B |p| \leq e^{\mu_1(B) \cdot \max |\operatorname{Re} \lambda_k|} \cdot \left(\frac{c \mu_1(B)}{\mu_1(\Omega)} \right)^m \cdot \sup_\Omega |p|$$

where $c > 0$ is an absolute constant.

¹Primary Classification 26D05 Secondary Classification 30E05, 42A05

²Keywords. Turán-Nazarov inequality, Metric entropy.

³The research of the second author was supported by ISF grant No. 264/09 and by the Minerva Foundation.

In this note, we generalize and strengthen Turán-Nazarov inequality (and its multi-dimensional analogue stated below) by replacing the Lebesgue measure of Ω with a simple geometric invariant $\omega_D(\Omega)$, the metric span of $\Omega \subset \mathbb{R}^n$ with respect to a “diagram” D comprising the degree of p and its maximal frequency λ . Metric span always bounds the Lebesgue measure from above, and it is strictly positive for sufficiently dense discrete (in particular, finite) sets Ω . It can be effectively estimated in terms of the metric entropy of Ω . See [10] and Section 2.1 below for some basic properties of $\omega_D(\Omega)$.

A somewhat simpler version of the metric span of Ω depending only on the dimension and the degree, and not on the continuous parameters, was originally introduced in [10]. It replaces the Lebesgue measure of Ω in the classical Remez inequality for algebraic polynomials ([6, 2]).

In one-dimensional case for a given exponential polynomial $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$ with $c_k, \lambda_k \in \mathbb{C}$, and for a given interval $B \subset \mathbb{R}$ the diagram $D = D(p, B)$ comprises the degree m , the length $\mu_1(B)$ and the maximal frequency $\lambda = \max_{k=0, \dots, m} |\operatorname{Im} \lambda_k|$. Define the constant M_D (which we call a “frequency bound” for p) as $M_D = \lfloor \frac{d}{2} \rfloor + 1$, where $d = C(m)\mu_1(B)\lambda$. Here $C(m)$ is defined as $C(m) = n(2n+1)^{2n} 2^{2n^2}$, for $n = \frac{(m+1)(m+2)}{2} + 1$. For any bounded subset $\Omega \subset \mathbb{R}$ and for $\epsilon > 0$ let $M(\epsilon, \Omega)$ be the minimal number of ϵ -intervals covering Ω . Now the metric span ω_D is defined as follows:

Definition 1.1. The metric span $\omega_D(\Omega)$ of $\Omega \subset \mathbb{R}$ is given by

$$\omega_D(\Omega) = \sup_{\epsilon > 0} \epsilon [M(\epsilon, \Omega) - M_D]$$

Now we can state our main result in one-dimensional case:

Theorem 1.2. Let $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$ be an exponential polynomial, where $c_k, \lambda_k \in \mathbb{C}$. Let $B \subset \mathbb{R}$ be an interval, and let $\Omega \subset B$ be any set. Then

$$\sup_B |p| \leq e^{\mu_1(B) \cdot \max |\operatorname{Re} \lambda_k|} \cdot \left(\frac{c \mu_1(B)}{\omega_D(\Omega)} \right)^m \cdot \sup_{\Omega} |p|$$

where $c > 0$ is an absolute constant.

Clearly, for any measurable Ω we always have $\omega_D(\Omega) \geq \mu_1(\Omega)$. Indeed, for any $\epsilon > 0$ we have $M(\epsilon, \Omega) \geq \mu_1(\Omega)/\epsilon$. Now substitute into Definition 1.1 and let ϵ tend to zero. Thus, Theorem 1.2 provides a true generalization

and strengthening of the Turán-Nazarov inequality given in Theorem 1.1. Moreover, the result of Theorem 1.2 further develops a remarkable feature of the original Turán-Nazarov inequality: The bound does not depend on the “frequencies”, i.e. on the imaginary parts of λ_k in p .

When we allow into consideration *discrete* (in particular, *finite*) sets Ω , this feature cannot be preserved: Already for a trigonometric polynomial $p(t) = \sin(\lambda t)$, the set Ω of its zeroes (on which the Turán-Nazarov inequality certainly fails) consists of all the points $x_j = \frac{j\pi}{\lambda}$, $j \in \mathbb{N}$, and the number of such points in any interval B is of order $\frac{\mu(B)\lambda}{\pi}$.

So when we replace the Lebesgue measure with the metric span, we have to take into account the imaginary parts of the exponents λ_k . This is exactly what is done in Definition 1.1 and in Theorem 1.2 above. Thus, our result separates the roles of the real and imaginary parts of the exponents: The first enters the main bound, as in the original Turán-Nazarov inequality, while the second enters the definition of the span $\omega_D(\Omega)$. As the density of Ω growth, the influence of the frequencies decreases: See Section 2.1 below.

There is a version of Turán-Nazarov inequality for quasipolynomials in one or several variables due to A. Brudnyi [1, Theorem 1.7]. While less accurate than the original one (in particular, the role of real and complex parts of the exponents is not separated) this result gives an important information for a wider class of quasipolynomials. In Section 3 we provide a strengthening of Brudnyi’s result in the same lines as above: We replace the Lebesgue measure with an appropriate “metric span” which always bounds the Lebesgue measure from above and is strictly positive for sufficiently dense discrete (in particular, finite) sets.

2 One-dimensional case

In this section we prove Theorem 1.2 and provide some of its consequences.

Let $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$ be an exponential polynomial, where $c_k, \lambda_k \in \mathbb{C}$. Let us write $c_k = \gamma_k e^{i\phi_k}$, $\lambda_k = a_k + ib_k$, $k = 0, 1, \dots, m$.

Lemma 2.1.

$$|p(t)|^2 = 2 \sum_{0 \leq k < l \leq m} \gamma_k \gamma_l e^{(a_k + a_l)t} \cos(\phi_k - \phi_l + (b_k - b_l)t)$$

is an exponential-trigonometric polynomial of degree $\frac{(m+1)(m+2)}{2}$ with real coefficients.

Proof. We have

$$p(t) = \sum_{k=0}^m \gamma_k e^{i\phi_k} e^{(a_k+ib_k)t} = \sum_{k=0}^m \gamma_k e^{a_k t + i(\phi_k + b_k t)}, \quad \bar{p}(t) = \sum_{k=0}^m \gamma_k e^{a_k t - i(\phi_k + b_k t)}$$

Therefore

$$|p(t)|^2 = p(t)\bar{p}(t) = \sum_{k,l=0}^m \gamma_k \gamma_l e^{(a_k+a_l)t + i(\phi_k - \phi_l + (b_k - b_l)t)}$$

Adding the expressions in this sum for the indices (k, l) and (l, k) we get

$$|p(t)|^2 = 2 \sum_{k \leq l} \gamma_k \gamma_l e^{(a_k+a_l)t} \cos(\phi_k - \phi_l + (b_k - b_l)t)$$

This completes the proof. ■

The following lemma provides us with the bound on the number of real solutions of the equation $|p(t)|^2 = \eta$. It is a direct consequence of a more general result of Khovanskii [3, Section 1.4] (see also Section 3.1 below).

Lemma 2.2. *For $p(t)$ as above and for each positive $\eta > 0$, the number of non-degenerate solutions of the equation $|p(t)|^2 = \eta$ in the interval $B \subset \mathbb{R}$ does not exceed*

$$d = C(m)\mu_1(B)\lambda$$

where $\lambda = \max |\operatorname{Im} \lambda_k|$, and $C(m) = n(2n+1)^{2n} 2^{2n^2}$, for $n = \frac{(m+1)(m+2)}{2} + 1$.

Let $B \subset \mathbb{R}$ be an interval. We consider the sublevel set $V_\rho = \{t \in B : |p(t)| \leq \rho\}$ of an exponential polynomial $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$, where $c_k, \lambda_k \in \mathbb{C}$. By Lemma 2.2 the boundary of V_ρ given by $\{|p(t)|^2 = \rho^2\}$ consists of at most $d = C(m)\mu_1(B) \max |\operatorname{Im} \lambda_k|$ points (including the endpoints). Therefore, the set V_ρ consists of at most $M_D = \lfloor \frac{d}{2} \rfloor + 1$ subintervals Δ_i (i.e. connected components of V_ρ), with M_D defined as in Theorem 1.2. Let us cover each of these subinterval Δ_i by the adjacent ε -intervals Q_ε starting with the left endpoint. Since all the adjacent ε -intervals, except possibly one, are inside Δ_i , their number doesn't exceed $\lfloor \Delta_i \rfloor / \varepsilon + 1$. Thus, we have

$$M(\varepsilon, V_\rho) \leq (\lfloor \frac{d}{2} \rfloor + 1) + \mu_1(V_\rho)/\varepsilon = M_D + \mu_1(V_\rho)/\varepsilon$$

in notations of Theorem 1.2.

Now let a set $\Omega \subset B$ be given.

Lemma 2.3. *If $\Omega \subset V_\rho$ for a certain $\rho \geq 0$ then $\mu_1(V_\rho) \geq \omega_D(\Omega)$.*

Proof. If $\Omega \subset V_\rho$ then for each $\varepsilon > 0$ we have $M(\varepsilon, \Omega) \leq M(\varepsilon, V_\rho) \leq M_D + \mu_1(V_\rho)/\varepsilon$, or $\mu_1(V_\rho) \geq \varepsilon(M(\varepsilon, \Omega) - M_D)$. Taking supremum with respect to $\varepsilon > 0$ and using Definition 1.1 we conclude that $\mu_1(V_\rho) \geq \omega_D(\Omega)$. ■

Let us now put $\hat{\rho} = \sup_\Omega |p|$. Then by definition we have $\Omega \subset V_{\hat{\rho}}$. Applying Lemma 2.3 we get $\mu_1(V_{\hat{\rho}}) \geq \omega_D(\Omega)$. Finally, we apply the original Turán-Nazarov inequality (Theorem 1.1) to the subset $V_{\hat{\rho}} \subset B$ on which $|p|$ by definition does not exceed $\hat{\rho}$. This completes the proof of Theorem 1.2. ■

Remark 1 We expect that the expression for $C(m)$ in Lemma 2.2 provided by the general result of Khovanskii can be strongly improved in our specific case. Let us recall the following result of Nazarov [4, Lemma 4.2], which gives a much more realistic bound on the local distribution of zeroes of an exponential polynomial:

Lemma 2.4. *Let $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$ be an exponential polynomial, where $c_k, \lambda_k \in \mathbb{C}$. Then the number of zeroes of $p(z)$ inside each disk of radius $r > 0$ does not exceed $4m + 7\hat{\lambda}r$, where $\hat{\lambda} = \max |\lambda_k|$.*

The reason we use the Khovanskii bound in Theorem 1.2 is that it involves only the imaginary parts of the exponents λ_k . In contrast, the bound of Lemma 2.4 is in terms of $\hat{\lambda} = \max |\lambda_k|$. In order to apply Lemma 2.4 we notice that

$$|p(t)|^2 = p(t)\bar{p}(t) = \sum_{k,l=0}^m c_k \bar{c}_l e^{(\lambda_k + \bar{\lambda}_l)t}$$

is an exponential polynomial of degree at most m^2 with the maximal absolute value of the exponents not exceeding $2\hat{\lambda}$. Adding a constant adds at most one to the degree. We conclude that the number of real solutions of $|p(t)|^2 = \eta$ inside the interval B does not exceed $d_1 = 4m^2 + 14\hat{\lambda}\mu_1(B)$. Now we define ω'_D putting $M'_D = \lfloor \frac{d_1}{2} \rfloor + 1$ in Definition 1.1. Repeating verbally the proof of Theorem 1.2 above we obtain:

Theorem 2.5. *For $p(t)$ as above*

$$\sup_B |p| \leq e^{\mu_1(B) \cdot \max |\operatorname{Re} \lambda_k|} \cdot \left(\frac{c\mu_1(B)}{\omega'_D(\Omega)} \right)^m \cdot \sup_\Omega |p|$$

Remark 2 For the case of a real exponential polynomial $p(t) = \sum_{k=0}^m c_k e^{\lambda_k t}$, $c_k, \lambda_k \in \mathbb{R}$, we get especially simple and sharp result. Notice that the number of zeroes of a real exponential polynomial is always bounded by its degree m (indeed, the “monomials” $e^{\lambda_k t}$ form a Chebyshev system on each real interval). Applying this fact in the same way as above we get

Theorem 2.6. *For $p(t)$ a real exponential polynomial of degree m*

$$\sup_B |p| \leq e^{\mu_1(B) \cdot \max |\operatorname{Re} \lambda_k|} \cdot \left(\frac{c\mu_1(B)}{\omega''_D(\Omega)} \right)^m \cdot \sup_\Omega |p|$$

where $\omega''_D(\Omega) = \sup_{\varepsilon > 0} \varepsilon [M(\varepsilon, \Omega) - m]$.

Notice that in this case the metric span $\omega''_D(\Omega)$ depends only on the degree m of p and the result is sharp: For any Ω consisting of at least $m + 1$ points there is an inequality of the required form, while for each m points there is a real exponential polynomial $p(t)$ of degree m vanishing at exactly these points.

2.1 Some examples

In this section we give just a couple of examples illustrating the scope and possible applications of Theorem 1.2.

2.1.1 Subsets Ω dense “in resolution ε ”

Here we show that the role of the frequency bound in the results above decreases as the discrete subset $\Omega \subset B$ becomes denser. For $\Omega \subset B$ and for $\varepsilon > 0$ we define a “measure $\mu_1(\varepsilon, \Omega)$ of Ω in resolution ε ” as the minimal possible measure of the coverings of Ω with ε -intervals.

Proposition 2.7. *For each diagram D and for any $\varepsilon > 0$ the metric span $\omega_D(\Omega)$ satisfies*

$$\omega_D(\Omega) \geq \mu_1(\varepsilon, \Omega) \left(1 - \frac{\varepsilon M_D}{\mu_1(\varepsilon, \Omega)} \right)$$

Proof. By definition $\omega_D(\Omega) \geq \varepsilon [M(\varepsilon, \Omega) - M_D]$. Clearly, $M(\varepsilon, \Omega) \geq \frac{1}{\varepsilon} \mu_1(\varepsilon, \Omega)$. Hence $\omega_D(\Omega) \geq \mu_1(\varepsilon, \Omega) - \varepsilon M_D$. \blacksquare

So if in a small resolution ε , the set Ω looks like a set of measure $\mu > 0$ then we restore the original Turán-Nazarov inequality for Ω , with a correction factor $1 - \frac{\varepsilon M_D}{\mu}$, where M_D being the frequency bound.

2.1.2 Combining the discrete and positive measure cases

Let a diagram D be fixed, and let $\Omega = \Omega_1 \cup \Omega_2 \subset B$, with Ω_1 a set of a positive measure μ , and Ω_2 a discrete set. We assume that the sets Ω_1 and Ω_2 are $2\frac{\mu_1(B)}{M_D}$ -separated, where M_D is the frequency bound for D .

Proposition 2.8. $\omega_D(\Omega) \geq \mu + \omega_D(\Omega_2)$

Proof. By definition $\omega_D(\Omega) = \sup_{\varepsilon} \varepsilon[M(\varepsilon, \Omega) - M_D]$, and this supremum is achieved for $\varepsilon \leq \frac{\mu_1(B)}{M_D}$. Indeed, otherwise $M(\varepsilon, \Omega) - M_D$ would be negative. Hence by a separation assumption we have $M(\varepsilon, \Omega) = M(\varepsilon, \Omega_1) + M(\varepsilon, \Omega_2)$ and therefore $\omega_D(\Omega) = \sup_{\varepsilon} \varepsilon(M(\varepsilon, \Omega_1) + M(\varepsilon, \Omega_2) - M_D) \geq \mu_1(\Omega_1) + \omega_D(\Omega_2)$. ■

So in situations as above Theorem 1.2 improves the original Turán-Nazarov inequality, and the frequency bound applies only to the discrete part of Ω .

2.1.3 Interpolation with exponential polynomials

This is a classical topic starting at least with [5] and actively studied today in connection with numerous applications. Theorems 1.2, 2.5, 2.6 bridge Turán-Nazarov inequality on $\Omega \subset B$ with estimates for the robustness of the interpolation from Ω to B . In particular, they provide robustness estimates in solving the “generalized Prony system” for non-uniform samples. See [7] for some initial results in this direction.

3 Multi-dimensional case

In this section we consider a version of Turán-Nazarov inequality for quasipolynomials in one or several variables due to A. Brudnyi [1, Theorem 1.7]. We provide a strengthening of this result in the same lines as above: The Lebesgue measure is replaced with an appropriate “metric span”.

Before we formulate Brudnyi’s result, let us recall some definitions.

Definition 3.1. Let $f_1, \dots, f_k \in (\mathbb{C}^n)^*$ be a pairwise different set of complex linear functionals f_j which we identify with the scalar products $f_j \cdot z$, $z = (z_1, \dots, z_n) \in \mathbb{C}^n$. We shall write

$$f_j = a_j + ib_j$$

A quasipolynomial is a finite sum

$$p(z) = \sum_{j=1}^k p_j(z) e^{f_j \cdot z}$$

where $p_j \in \mathbb{C}[z_1, \dots, z_n]$ are polynomials in z of degrees d_j . The degree of p is $m = \deg p = \sum_{j=1}^k (d_j + 1)$.

Following A.Brudnyi [1], we introduce the exponential type of p

$$t(p) = \max_{1 \leq j \leq k} \max_{z \in B_c(0,1)} |f_j \cdot z|$$

where $B_c(0, 1)$ is the complex Euclidean ball of radius 1 centered at 0.

Below we consider $p(x)$ for the real variables $x = (x_1, \dots, x_n) \in \mathbb{R}^n$.

Theorem 3.1 ([1]). *Let p be a quasipolynomial with parameters n, m, k defined on \mathbb{C}^n . Let $B \subset \mathbb{R}^n$ be a convex body, and let $\Omega \subset B$ be a measurable set. Then*

$$\sup_B |p| \leq \left(\frac{cn\mu_n(B)}{\mu_n(\Omega)} \right)^\ell \cdot \sup_\Omega |p|$$

where $\ell = (c(m, k) + (m - 1) \log(c_1 \max\{1, t(p)\}) + c_2 t(p) \text{diam}(B))$, and c, c_1, c_2 are absolute positive constants, and $c(k, m)$ is a positive number depending only on m and k .

In generalizing this result we follow the lines of [10] and of Sections 1 and 2 above.

3.1 Covering number of sublevel sets

For a relatively compact $A \subset \mathbb{R}^n$, the covering number $M(\varepsilon, A)$ is defined now as the minimal number of ε -cubes Q_ε covering A (which are translations of the standard ε -cubes $Q_\varepsilon^n := [0, \varepsilon]^n$).

Verbally repeating the proof of Lemma 2.1 above, we conclude that

$$q(x) = |p(x)|^2 = \sum_{0 \leq i \leq j \leq k} e^{(a_i + a_j) \cdot x} [P_{i,j}(x) \sin((b_i - b_j) \cdot x) + Q_{i,j}(x) \cos((b_i - b_j) \cdot x)]$$

with $P_{i,j}, Q_{i,j}$ real polynomials in x of degree $d_i + d_j$. Clearly, all the partial derivatives $\frac{\partial q(x)}{\partial x_j}$ have exactly the same form.

Let us denote the vectors $b_i - b_j \in \mathbb{R}^n$ by $b_{i,j}$ and let $\lambda = \max \|b_{i,j}\|$ be the maximal frequency in q . The following geometric construction is required by the Khovanskii's bound we use below: Let $Q_{i,j} = \{x \in \mathbb{R}^n, b_{i,j} \cdot x \leq \frac{\pi}{2}\}$ and let $Q = \bigcap_{0 \leq i \leq j \leq k} Q_{i,j}$. For any $B \subset \mathbb{R}^n$ we define $M(B)$ as the minimal number of translations of Q covering B . For an affine subspace V of \mathbb{R}^n we define $M(B \cap V)$ as the minimal number of translations of $Q \cap V$ covering $B \cap V$. Notice that for $B = Q_r^n$ a cube of size r we have $M(Q_r^n) \leq (\frac{2}{\pi} \sqrt{nr} \lambda)^n$. Indeed, Q always contains a ball of radius $\frac{\pi}{2\lambda}$.

As above, applying the Khovanskii's bound ([3], Section 1.4) for real exponential-trigonometric quasipolynomials we get the following:

Lemma 3.2. *Let $B \subset \mathbb{R}^n$ and let V be a parallel translation of the coordinate subspace in \mathbb{R}^n generated by x_{j_1}, \dots, x_{j_s} . Then the number of non-degenerate real solutions on $V \cap B$ of the system*

$$\frac{\partial q(x)}{\partial x_{j_1}} = \dots = \frac{\partial q(x)}{\partial x_{j_s}} = 0$$

is at most $C_s \cdot M(B \cap V)$, where

$$C_s = \prod_{r=1}^s (d_{j_r} + 2) \left(\sum_{r=1}^s d_{j_r} + \kappa + s + 1 \right)^\kappa 2^{\kappa(\kappa+1)/2}$$

with $\kappa = (k^2 + 5k + 2)/2$. In particular, for $B = Q_\rho^n$ the number of solutions does not exceed $\hat{C}_s(\rho\lambda)^s$ with $\hat{C}_s = (\frac{2}{\pi} \sqrt{s})^s C_s$.

Let a quasipolynomial p be as above. A sublevel set $A = A_\rho$ of p is defined as $A = \{x \in \mathbb{R}^n : |p(x)| \leq \rho\}$. The following lemma extends to the case of sublevel sets of exponential polynomials the result of Vitushkin [9] for semi-algebraic sets. It can be proved using a general result of Vitushkin in [9] through the use of "multi-dimensional variations". However, in our specific case the proof below is much shorter and it produces explicit ("in one step") constants.

Lemma 3.3. *For any $1 \geq \varepsilon > 0$ we have*

$$M(\varepsilon, A \cap Q_1^n) \leq C_0 + C_1 \left(\frac{1}{\varepsilon}\right) + \cdots + C_{n-1} \left(\frac{1}{\varepsilon}\right)^{n-1} + \mu_n(A) \left(\frac{1}{\varepsilon}\right)^n$$

where C_0, \dots, C_{n-1} are positive constants, which depend only on k, d_i and the maximal frequency λ of the quasipolynomial p .

Proof. The sublevel set A_ρ is defined via the real exponential-trigonometric quasipolynomial $q(x) = |p(x)|^2$, i.e. $A = A_\rho(p) = \{x \in Q_1^n : q(x) \leq \rho^2\}$.

Let us subdivide Q_1^n into adjacent ε -cubes Q_ε with respect to the standard Cartesian coordinate system. Each Q_ε having a nonempty intersection with A , is either entirely contained in A , or it intersects the boundary ∂A of A . Certainly, the number of those boxes Q_ε , which are entirely contained in A , is bounded by $\mu_n(A)/\mu_n(Q_\varepsilon) = \mu_n(A)/\varepsilon^n$. In the other case, where Q_ε intersects ∂A , it has a face of the smallest dimension s that intersects ∂A , for some $s = 0, 1, \dots, n$.

Let us fix an s -dimensional affine subspace V , which corresponds to an s -face F of a Q_ε intersecting ∂A . Then F contains completely some of the connected components of $A \cap V$, otherwise ∂A would intersect a face of Q_ε of a dimension strictly less than s . Clearly, inside each compact connected component of $A \cap V$ there is a critical point of q , which is defined by the system of equations $\frac{\partial q(x)}{\partial x_{j_1}} = \cdots = \frac{\partial q(x)}{\partial x_{j_s}} = 0$ (assuming that V is a parallel translation of the coordinate subspace in \mathbb{R}^n generated by x_{j_1}, \dots, x_{j_s}). After a small perturbation of q we can always assume that all such critical points are non-degenerate. Hence by Lemma 3.2 the number of these points, and therefore of the boxes Q_ε of the considered type, is bounded by $\hat{C}_s \lambda^s$.

According to the partitioning construction of Q_1^n , we have at most $\left(\frac{1}{\varepsilon} + 1\right)^{n-s}$ s -dimensional affine subspaces with respect to the same s coordinates. On the other hand, the number of different choices of s coordinates is $\binom{n}{s}$. It means the number of boxes that have an s -face F , which contains completely some connected component of $A \cap V$, is at most $\binom{n}{s} \cdot \left(\frac{1}{\varepsilon} + 1\right)^{n-s} \hat{C}_s \lambda^s$, which does not exceed, assuming $\varepsilon \leq 1$, the constant $C_{n-s} := \binom{n}{s} 2^{n-s} \hat{C}_s \lambda^s \left(\frac{1}{\varepsilon}\right)^{n-s}$.

Note that C_0 is the bound on the number of boxes that contain completely some of the connected components of A . Thus, we have

$$M(\varepsilon, A) \leq C_0 + C_1 \left(\frac{1}{\varepsilon}\right) + \cdots + C_{n-1} \left(\frac{1}{\varepsilon}\right)^{n-1} + \mu_n(A) \left(\frac{1}{\varepsilon}\right)^n$$

This completes our proof. ■

4 Metric span and generalized Brudnyi's inequality

Let p be a quasipolynomial as above, with the parameters n, k, d_j . These parameters, together with the maximal frequency λ of p form the multi-dimensional diagram D of p . Notice that in contrast to the one-dimensional case (and with Theorem 3.1) we restrict ourselves to the unit box Q_1^n . So B does not appear in the diagram.

For a given $0 < \varepsilon \leq 1$ let us denote by $M_D(\varepsilon)$ the quantity $M_D(\varepsilon) = \sum_{j=0}^{n-1} C_j \left(\frac{1}{\varepsilon}\right)^j$, where C_0, \dots, C_{n-1} are the constants from Lemma 3.3. Extending terminology from the one-dimensional case above, we call $M_D(\varepsilon)$ the “frequency bound” for D . Note that the constants C_j depend only on the parameters n, k, d_i and on the maximal frequency λ of the quasipolynomial p . By Lemma 3.3 for any sublevel set A_ρ of p we have

$$M(\varepsilon, A) \leq M(\varepsilon) + \mu_n(A) \left(\frac{1}{\varepsilon}\right)^n$$

Now for any subset $\Omega \subset Q_1^n$ we introduce the metric span ω_D of Ω with respect to a given diagram D as follows:

Definition 4.1. For a subset $\Omega \subset \mathbb{R}^n$ the metric span ω_D is defined as

$$\omega_D(\Omega) = \sup_{\varepsilon > 0} \varepsilon^n [M(\varepsilon, \Omega) - M_D(\varepsilon)]$$

Lemma 4.1. *Let $A \subset Q_1^n$ be a sublevel set of a real quasipolynomial with the diagram D . Then for any $\Omega \subset A$ we have*

$$\mu_n(A) \geq \omega_D(\Omega)$$

Proof. This fact follows directly from Lemma 3.3. Indeed, for any $\varepsilon > 0$ we have

$$M(\varepsilon, \Omega) \leq M(\varepsilon, A) \leq M_D(\varepsilon) + \mu_n(A) \left(\frac{1}{\varepsilon}\right)^n$$

Consequently, for any $\varepsilon > 0$ we have $\mu_n(A) \geq \varepsilon^n [M(\varepsilon, \Omega) - M_D(\varepsilon)]$. Now, we can take the supremum with respect to ε . ■

For some examples and properties of sets in \mathbb{R}^n with positive metric span, see [10, Section 5]. Here we mention only that for a measurable $\Omega \subset \mathbb{R}^n$ always $\omega_D(\Omega) \geq \mu_n(\Omega)$. The proof is exactly the same as in the remark after Theorem 1.2.

Now we can prove our generalization of Brudnyi's Theorem 3.1 above.

Theorem 4.2. *Let p be as above and let $\Omega \subset Q_1^n$. Then*

$$\sup_{Q_1^n} |p| \leq \left(\frac{cn\mu_n(B)}{\omega_D(\Omega)} \right)^\ell \cdot \sup_{\Omega} |p|.$$

Proof. Let $\hat{\rho} := \sup_{\Omega} |p|$. For the sublevel set $A_{\hat{\rho}}$ of the quasipolynomial p we have $\Omega \subset A_{\hat{\rho}}$. By Lemma 4.1 we have $\mu_n(A_{\hat{\rho}}) \geq \omega_D(\Omega)$. Now since p is bounded in absolute value by ρ on $A_{\hat{\rho}}$ by definition, we can apply Theorem 3.1 with $B = Q_1^n$ and $A_{\hat{\rho}}$. This completes the proof. ■

References

- [1] Brudnyi, A. *Bernstein type inequalities for quasipolynomials*. J. Approx. Theory 112 (2001), no. 1, 28-43.
- [2] Brudnyi, Yu.; Ganzburg, M. *On an extremal problem for polynomials of n variables*. Math. USSR Izv. 37 (1973), 344-355.
- [3] Khovanskii, A. G. *Fewnomials*. Translated from the Russian by Smilka Zdravkovska. Translations of Mathematical Monographs, 88. American Mathematical Society, Providence, RI, 1991. viii+139 pp.
- [4] Nazarov, F. L. *Local estimates for exponential polynomials and their applications to inequalities of the uncertainty principle type*. Algebra i Analiz 5 (1993), no. 4, 3-66; translation in St. Petersburg Math. J. 5 (1994), no. 4, 663-717.
- [5] R. de Prony, *Essai experimentale et analytique*. J. Ecol. Polytech. (Paris), 1 (2) (1795), 24-76.
- [6] Remez, E. J. *Sur une propriete des polynomes de Tchebycheff*. Comm. Inst. Sci. Kharkov 13 (1936) 93-95.

- [7] Sarig, N. *Ph.D thesis*. Weizmann Institute of Science, May 2011.
- [8] Turán, P. *Eine neue Methode in der Analysis und deren Anwendungen*. Akadémiai Kiadó, Budapest, 1953. 196 pp.
- [9] Vitushkin, A. G. *O mnogomernyh Variaziyah*. Gostehisdat, Moskow, (1955).
- [10] Yomdin, Y. *Discrete Remez Inequality*. to appear, Israel J. of Math.

O. Friedland,
Institut de Mathématiques de Jussieu,
Université Pierre et Marie Curie (Paris 6)
4 Place Jussieu,
75005 Paris, France
e-mail: `friedland@math.jussieu.fr`

Y. Yomdin,
Department of Mathematics,
The Weizmann Institute of Science,
Rehovot 76100, Israel
e-mail: `yosef.yomdin@weizmann.ac.il`