# INELASTIC CHARACTER OF SOLITONS OF SLOWLY VARYING GKDV EQUATIONS 

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#### Abstract

In this paper we study soliton-like solutions of the variable coefficients, subcritical gKdV equation $$
u_{t}+\left(u_{x x}-\lambda u+a(\varepsilon x) u^{m}\right)_{x}=0, \quad \text { in } \quad \mathbb{R}_{t} \times \mathbb{R}_{x}, \quad m=2,3 \text { and } 4
$$


with $\lambda \geq 0, a(\cdot) \in(1,2)$ a strictly increasing, positive and asymptotically flat potential, and $\varepsilon$ small enough. In 27 28] it was proved the existence of a pure, global in time, soliton $u(t)$ of the above equation, satisfying

$$
\lim _{t \rightarrow-\infty}\left\|u(t)-Q_{1}(\cdot-(1-\lambda) t)\right\|_{H^{1}(\mathbb{R})}=0, \quad 0 \leq \lambda<1
$$

provided $\varepsilon$ is small enough. Here $R(t, x):=Q_{c}(x-(c-\lambda) t)$ is the soliton of $R_{t}+\left(R_{x x}-\lambda R+\right.$ $\left.R^{m}\right)_{x}=0$. In addition, there exists $\tilde{\lambda} \in(0,1)$ such that, for all $0<\lambda<1$ with $\lambda \neq \tilde{\lambda}$, the solution $u(t)$ satisfies

$$
\sup _{t \gg \frac{1}{\varepsilon}}\left\|u(t)-\kappa(\lambda) Q_{c_{\infty}}(\cdot-\rho(t))\right\|_{H^{1}(\mathbb{R})} \lesssim \varepsilon^{1 / 2}
$$

Here $\rho^{\prime}(t) \sim\left(c_{\infty}(\lambda)-\lambda\right)$, with $\kappa(\lambda)=2^{-1 /(m-1)}$ and $c_{\infty}(\lambda)>\lambda$ in the case $0<\lambda<\tilde{\lambda}$ (refraction), and $\kappa(\lambda)=1$ and $c_{\infty}(\lambda)<\lambda$ in the case $\tilde{\lambda}<\lambda<1$ (reflection).

In this paper we improve our preceding results by proving that the soliton is far from being pure as $t \rightarrow+\infty$. Indeed, we give a lower bound on the defect induced by the potential $a(\cdot)$, for all $0<\lambda<1, \lambda \neq \tilde{\lambda}$. More precisely, one has

$$
\liminf _{t \rightarrow+\infty}\left\|u(t)-\kappa_{m}(\lambda) Q_{c_{\infty}}(\cdot-\rho(t))\right\|_{H^{1}(\mathbb{R})} \gtrsim \varepsilon^{1+\delta}
$$

for any $\delta>0$ fixed. This bound clarifies the existence of a dispersive tail and the difference with the standard solitons of the constant coefficients, gKdV equation.

## 1. Introduction and Main Results

In this work we continue the study of the dynamics of a soliton-like solution for some generalized Korteweg-de Vries equations (gKdV), started in [27, 28. In those papers the objective was the study of the global behavior of a generalized soliton solution for the following subcritical, variable coefficients gKdV equation:

$$
\begin{equation*}
u_{t}+\left(u_{x x}-\lambda u+a(\varepsilon x) u^{m}\right)_{x}=0, \quad \text { in } \quad \mathbb{R}_{t} \times \mathbb{R}_{x}, \quad m=2,3 \text { or } 4 \tag{1.1}
\end{equation*}
$$

Here $u=u(t, x)$ is a real-valued function, $\varepsilon>0$ is a small number, $\lambda \geq 0$ a fixed parameter, and the potential $a(\cdot)$ a smooth, positive function satisfying some specific properties, see (1.4) below.

This equation represents, in some sense, a simplified model of long dispersive waves in a channel with variable bottom, which considers large variations in the shape of the solitary wave. The primary physical model, and the dynamics of a generalized soliton-like solution, was formally described by Karpman-Maslov, Kaup-Newell and Ko-Kuehl [15, 16, 17, with further results by Grimshaw [8, and Lochak [19. See [27, 30] and references therein for a detailed physical introduction to this model. The main novelty in the works above cited was the discovery of a dispersive tail behind the soliton, with small height but large width, as a consequence of the lack of conserved quantities such as mass or energy. However, no mathematical proof of this phenomenon has been given.

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On the other hand, from the mathematical point of view, equation (1.1) is a variable coefficients version of the standard gKdV equation

$$
\begin{equation*}
u_{t}+\left(u_{x x}-\lambda u+u^{m}\right)_{x}=0, \quad \text { in } \mathbb{R}_{t} \times \mathbb{R}_{x} ; \quad m \geq 2 \text { integer, } \quad \lambda \geq 0 \tag{1.2}
\end{equation*}
$$

This last equation is famous due to the existence of localized, exponentially decaying, smooth solutions called solitons. Given real numbers $x_{0}$ and $c>0$, solitons are solutions of (1.2) of the form

$$
\begin{equation*}
u(t, x):=Q_{c}\left(x-x_{0}-(c-\lambda) t\right), \quad \text { with } \quad Q_{c}(s):=c^{\frac{1}{m-1}} Q\left(c^{1 / 2} s\right) \tag{1.3}
\end{equation*}
$$

and where $Q=Q_{1}$ is the unique -up to translations- function satisfying the following, second order, nonlinear ordinary differential equation

$$
Q^{\prime \prime}-Q+Q^{m}=0, \quad Q>0, \quad Q \in H^{1}(\mathbb{R})
$$

In this case, this solution belongs to the Schwartz class and it is explicit [28. For $m=2,3,4$ solitons and the sum of solitons have been showed stable and asymptotically stable [1, 3, 25, 31, 33]. In particular, if $c>\lambda$ the solution (1.3) represents a solitary wave 1 of scaling $c$ and velocity $(c-\lambda)$, defined for all time, moving to the right without any change in shape, velocity, etc. In other words, a soliton represents a pure, traveling wave solution with invariant profile. In addition, this equation has solitons with negative velocity, moving to the left, provided $c<\lambda$. Finally, for the case $c=\lambda$, one has a stationary soliton solution, $Q_{\lambda}\left(x-x_{0}\right)$. These last solutions do not exist in the standard, inviscid model of gKdV (namely when $\lambda=0$ ).

Coming back to (1.1), the corresponding Cauchy problem in $H^{1}(\mathbb{R})$ has been considered in 27. The proof of this result is an adaptation of the fundamental work of Kenig, Ponce and Vega 18, with the introduction of some new monotone quantities, in order to replace the lost conserved ones.

A fundamental question related to (1.2) is how to generalize a soliton-like solution to more complicated models. In [2], the existence of soliton solutions for generalized KdV equations with suitable autonomous nonlinearities has been considered. However, less is known in the case of an inhomogeneous nonlinearity, such as equation (1.1). In a general situation, no elliptic, timeindependent ODE can be associated to the soliton, unlike the standard autonomous case studied in [2]. Therefore, other methods are needed.

The first mathematically rigorous results in the case of time and space dependent KdV and mKdV equations ( $m=2$ and $m=3$ above) were proved by Dejak-Sigal and Dejak-Jonsson 4, 5. They studied the dynamics of a soliton for times of $O\left(\varepsilon^{-1}\right)$, and deduced dynamical laws which characterize the whole soliton dynamics up to some order of accuracy. More recently, Holmer 11] has improved the Dejak-Sigal results in the KdV case, up to the Ehrenfest time $O\left(|\log \varepsilon| \varepsilon^{-1}\right)$, provided the dynamical laws are well defined. In their model, the perturbation is of linear type, which do not allow large variations of the soliton shape, different to the scaling itself.

In [27, 28] it was described the soliton dynamics, for all time, in the case of the time independent, perturbed gKdV equation (1.1). The main novelty was the understanding of the dynamics as a nonlinear interaction between the soliton and the potential, in the spirit of the recent works of Holmer-Zworski [12], and Martel-Merle [22, 23]. In order to state this last result, and our present main results, let us first describe the framework that we have considered for the potential $a(\cdot)$ in (1.1).

Setting and hypotheses on $a(\cdot)$. Concerning the function $a$ in (1.1), we assume that $a \in C^{3}(\mathbb{R})$ and there exist fixed constants $K, \gamma>0$ such that

$$
\left\{\begin{array}{l}
1<a(r)<2, \quad a^{\prime}(r)>0, \quad \text { for all } r \in \mathbb{R}  \tag{1.4}\\
0<a(r)-1 \leq K e^{\gamma r}, \quad \text { for all } r \leq 0, \quad 0<2-a(r) \leq K e^{-\gamma r} \text { for all } r \geq 0, \text { and } \\
\left|a^{(k)}(r)\right| \leq K e^{-\gamma|r|}, \quad \text { for all } r \in \mathbb{R}, k=1,2,3
\end{array}\right.
$$

[^0]In particular, $\lim _{r \rightarrow-\infty} a(r)=1$ and $\lim _{r \rightarrow+\infty} a(r)=2$. The chosen limits (1 and 2$)$ do not imply a loss of generality, it just simplifies the computations. In addition, we assume the following hypothesis: there exists $K>0$ such that for $m=2,3$ and 4,

$$
\begin{equation*}
\left|\left(a^{1 / m}\right)^{(3)}(s)\right| \leq K\left(a^{1 / m}\right)^{\prime}(s), \quad \text { for all } \quad s \in \mathbb{R} . \tag{1.5}
\end{equation*}
$$

This condition is generally satisfied, however $a^{\prime}(\cdot)$ cannot be a compactly supported function.
We remark some important facts about (1.1) (see [27, 28] for more details). Firstly, this equation is not invariant under scaling and spatial translations. Second, a nonzero solution of (1.1) might lose or gain some mass, depending on the sign of $u$, in the sense that, at least formally, the Mass

$$
\begin{equation*}
M[u](t):=\frac{1}{2} \int_{\mathbb{R}} u^{2}(t, x) d x \quad \text { satisfies } \quad \partial_{t} M[u](t)=-\frac{\varepsilon}{m+1} \int_{\mathbb{R}} a^{\prime}(\varepsilon x) u^{m+1}(t, x) d x \tag{1.6}
\end{equation*}
$$

On the other hand, the energy

$$
\begin{equation*}
E_{a}[u](t):=\frac{1}{2} \int_{\mathbb{R}} u_{x}^{2}(t, x) d x+\frac{\lambda}{2} \int_{\mathbb{R}} u^{2}(t, x) d x-\frac{1}{m+1} \int_{\mathbb{R}} a(\varepsilon x) u^{m+1}(t, x) d x \tag{1.7}
\end{equation*}
$$

remains formally constant for all time. Let us recall that this quantity is conserved for local $H^{1}$-solutions of (1.2). Since $a \sim 1$ as $x \rightarrow-\infty$, one should be able to construct a generalized soliton-like solution $u(t)$, satisfying $u(t) \sim Q(\cdot-(1-\lambda) t)$ as $t \rightarrow-\infty{ }^{2}$ Indeed, this scattering result has been proved in [27], but for the sake of completeness, it is briefly described in the following paragraph.
Description of the dynamics. Let us recall the setting of our problem. Let $0<\lambda<1$ be a fixed parameter, consider the equation

$$
\left\{\begin{array}{l}
u_{t}+\left(u_{x x}-\lambda u+a(\varepsilon x) u^{m}\right)_{x}=0 \quad \text { in } \mathbb{R}_{t} \times \mathbb{R}_{x}  \tag{1.8}\\
m=2,3 \text { and } 4 ; \quad 0<\varepsilon \leq \varepsilon_{0} ; \quad a(\varepsilon \cdot) \text { satisfying (1.4)-(1.5) }
\end{array}\right.
$$

Here $\varepsilon_{0}>0$ is a small parameter. Let $\lambda_{0}$ be the following parameter:

$$
\begin{equation*}
\lambda_{0}:=\frac{5-m}{m+3} \in(0,1) \tag{1.9}
\end{equation*}
$$

Assuming the validity of (1.8), one has the following generalization of [20]:
Theorem 1.1 (Existence of solitons for gKdV under variable medium, [27]). Suppose $m=2,3$ and 4. Let $0 \leq \lambda<1$ be a fixed number. There exists a small constant $\varepsilon_{0}>0$ such that for all $0<\varepsilon<\varepsilon_{0}$ the following holds. There exists a solution $u \in C\left(\mathbb{R}, H^{1}(\mathbb{R})\right)$ of (1.1), global in time, such that

$$
\begin{equation*}
\lim _{t \rightarrow-\infty}\|u(t)-Q(\cdot-(1-\lambda) t)\|_{H^{1}(\mathbb{R})}=0 \tag{1.10}
\end{equation*}
$$

Let us remark that (1.10) can be improved in the following way: there exists $K, \gamma>0$ such that

$$
\begin{equation*}
\|u(t)-Q(\cdot-(1-\lambda) t)\|_{H^{1}(\mathbb{R})} \leq K e^{\gamma \varepsilon t}, \quad \text { for all } t \lesssim \varepsilon^{-1-1 / 100} \quad(c f .[27]) \tag{1.11}
\end{equation*}
$$

Next, we have described the dynamics of interaction soliton-potential. Let $\lambda \in(0,1)$, and let $\tilde{\lambda}=\tilde{\lambda}(m)$ be the unique solution of the algebraic equation 28 ]

$$
\begin{equation*}
\tilde{\lambda}\left(\frac{1-\lambda_{0}}{\tilde{\lambda}-\lambda_{0}}\right)^{1-\lambda_{0}}=2^{\frac{4}{m+3}}, \quad \lambda_{0}<\tilde{\lambda}<1 \tag{1.12}
\end{equation*}
$$

with $\lambda_{0}$ given by (1.9). Let $\kappa(\lambda)$ be the parameter defined by

$$
\begin{equation*}
\kappa(\lambda):=2^{-1 /(m-1)}, \quad 0<\lambda<\tilde{\lambda} ; \quad \kappa(\lambda)=1, \quad \tilde{\lambda}<\lambda<1 . \tag{1.13}
\end{equation*}
$$

The above numbers represent a sort of equilibria between the energy of the solitary wave and the strength of the potential. Indeed, let $c_{\infty}=c_{\infty}(\lambda)$ be the unique solution of the algebraic equations [27, 28]

$$
c_{\infty}^{\lambda_{0}}\left(\frac{\lambda-c_{\infty} \lambda_{0}}{\lambda-\lambda_{0}}\right)^{1-\lambda_{0}}= \begin{cases}2^{4 /(m+3)}, & c_{\infty}>\lambda,  \tag{1.14}\\ 1, & c_{\infty}<\lambda, \\ \tilde{\lambda}<\lambda<1\end{cases}
$$

[^1]and $c_{\infty}\left(\lambda_{0}\right)=1$, respectively. We claim that this number represents the final scaling of the soliton. Indeed, one has $c_{\infty}(\lambda) \geq 1$ if $0<\lambda \leq \lambda_{0}, \lambda<c_{\infty}(\lambda)<1$ if $\lambda_{0}<\lambda<\tilde{\lambda}, 0<c_{\infty}(\lambda)<\lambda$ if $\tilde{\lambda}<\lambda<1$, and the following

Theorem 1.2 (Interaction soliton-potential: refraction and reflection, [27, 28]). Suppose $0<\lambda<$ 1 , with $\lambda \neq \tilde{\lambda}$. There exists $K, \varepsilon_{0}>0$ such that for all $0<\varepsilon<\varepsilon_{0}$ the following holds. There exists constants $\tilde{T}, c^{+}>0$, and a smooth $C^{1}$ function $\rho(t)=\rho_{\lambda}(t) \in \mathbb{R}$ such that the function $w^{+}(t):=u(t)-\kappa(\lambda) Q_{c^{+}}(\cdot-\rho(t))$ satisfies, for all $t \gg \varepsilon^{-1}$,

$$
\begin{equation*}
\left\|w^{+}(t)\right\|_{H^{1}(\mathbb{R})}+\left|\rho^{\prime}(t)-c_{\infty}(\lambda)+\lambda\right|+\left|c^{+}-c_{\infty}\right| \leq K \varepsilon^{1 / 2} \tag{1.15}
\end{equation*}
$$

Remark 1.1 (The limiting case $\lambda=\tilde{\lambda}$ ). The behavior of the solution in the case $\lambda=\tilde{\lambda}$ remains an interesting open problem.
Remark 1.2. In addition to (1.15), it is proved in 27, 28, an asymptotic stability property, in the spirit of Martel and Merle 21]. This result gives the existence of the limiting parameter $c^{+}$above mentioned. We believe that the above is the first mathematical proof of the existence of a global, reflected soliton-like solution in a variable coefficients gKdV model.

Finally, by means of a contradiction argument, no pure soliton solutions are present in this regime.

Theorem 1.3 (Non existence of pure-soliton solutions for (1.8), [27, 28]). Let $0<\lambda<1$, with $\lambda \neq \tilde{\lambda}$. Then

$$
\limsup _{t \rightarrow+\infty}\left\|w^{+}(t)\right\|_{H^{1}(\mathbb{R})}>0
$$

Main result. A natural question left open in [27, 28] is to establish a quantitative lower bound on the defect $w^{+}(t)$ as the time goes to infinity, at least in the case $0<\lambda<1, \lambda \neq \tilde{\lambda}$ (the cases $\lambda=0$ and $\lambda=\tilde{\lambda}$ seem harder). In this paper we improve Theorem 1.3 by showing a first lower bound on the defect $w^{+}(t)$ at infinity. In other words, any perturbation of the constant coefficients gKdV equation of the form (1.8) induces non trivial dispersive effects on the soliton solution -they are not pure anymore. This result clarifies the existence of a nontrivial dispersive tail and the inelastic character of generalized solitons for perturbations of some dispersive equations, and moreover, it seems to be the general behavior. In addition, one can see this result as a generalization to the case of interaction soliton-potential of the recent ones proved by Martel and Merle, concerning the inelastic character of the collision of two solitons for non-integrable gKdV equations [22, 24].

However, in order to obtain such a quantitative bound, and compared with the proof in [24, the present analysis requires several new ideas, in particular for the more difficult case, the cubic one. As we will describe below, our lower bounds are related to first and second order corrections to the dynamical parameters of the soliton solution. The main result of this paper is the following
Theorem 1.4 (Inelastic character of the soliton-potential interaction). Let $m=2,3$ and 4, $0<\lambda<1, \lambda \neq \tilde{\lambda}$, and $\delta:=\frac{1}{50}$. There exist constants $K, \varepsilon_{0}>0$ such that, for all $0<\varepsilon<\varepsilon_{0}$, the following holds. Let $w^{+}(t)$ be as in Theorem 1.2. Then

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty}\left\|w^{+}(t)\right\|_{H^{1}(\mathbb{R})} \geq \frac{1}{K} \varepsilon^{1+\delta} \tag{1.16}
\end{equation*}
$$

Remark 1.3 (Meaning of $\delta$ ). The number $\delta$ above is needed in our computations, but it is not essential. It is related to the definition of the time of interaction $T_{\varepsilon}$ (1.21) and estimates (1.11) and (2.26), but it can be replaced by any $\delta>0$ provided $\varepsilon_{0}$ is chosen even smaller. Looking at our proofs, we believe that the best lower bound is given by $\sim \varepsilon|\log \varepsilon|^{-\delta}$, for some $\delta>0$; however, this problem will not be considered in this paper.

Remark 1.4. Similar to the results obtained in [22, 24, we have found a nontrivial gap between the two bounds (1.15) and (1.16). This gap is related to the emergence of infinite mass corrections to the constructed approximate solution [27, 28, and it is not formally present in the NLS model [26]. The understanding of this gap is a very interesting open problem. Additionally, from the above results we do not discard the existence of small solitary waves (note that small solitons
move to the left), at least for the case $m=2$. In the cubic and quartic cases, we believe there are no such soliton solutions.

Ideas of the proof. As we have explained before, the above result is originally based in a recent argument introduced by Martel and Merle in [24], to deal with the interaction of two nearly-equal solitons for the quartic gKdV equation. Roughly speaking, in their paper the interaction was proved to be inelastic because of a small lack of symmetry on the soliton trajectories, contrary to the symmetric integrable case. In this paper, we improve the Martel-Merle idea in two directions: first, we generalize such an argument to the case of the interaction soliton-potential, which is nontrivial since our problem has no evident symmetries to be exploited; and second, we deal, in addition, with a somehow degenerate case, the cubic one, where the original Martel-Merle argument is not longer available. Therefore, we introduce new ideas to recover the same bound as in the other cases.

Let us describe the proof. We consider an approximate solution of (1.8), describing the interaction soliton-potential. This problem was first considered in [27], but in order to find an explicit expression for the defect of the solution, we improved such a construction in [28].

Let us be more precise. The objective of the new approximate solution is to obtain first and second order corrections on the translation and scaling parameters $\rho(t), c(t)$ of the soliton solution. Indeed, in [28] was proved that the solution $u(t)$ behaves along the interaction, at first order, as follows:

$$
u(t, x) \sim a^{-1 /(m-1)}(\varepsilon \rho(t)) Q_{c(t)}(x-\rho(t))+\text { lower order terms in } \varepsilon
$$

with $(c, \rho)$ satisfying the dynamical laws $\mathbb{3}^{3}$

$$
\begin{align*}
& c^{\prime}(t) \sim \varepsilon f_{1}(\varepsilon t)+\varepsilon^{2} f_{3}(\varepsilon t), \quad \text { with } f_{1}(\varepsilon t), f_{3}(\varepsilon t) \neq 0, \quad m=2,3,4  \tag{1.17}\\
& \rho^{\prime}(t) \sim c(t)-\lambda+\varepsilon f_{2}(\varepsilon t)+\varepsilon^{2} f_{4}(\varepsilon t), \quad \text { with } f_{2}(\varepsilon t) \neq 0, \quad m=2,4 \tag{1.18}
\end{align*}
$$

(see Proposition 3.3 for an explicit description of this dynamical system). Moreover, one has $f_{2} \equiv 0$ in the cubic case (cf. Proposition [2.2). Roughly speaking, the parameter $f_{2}(\varepsilon t)\left(f_{3}(\varepsilon t)\right.$ resp.) satisfies

$$
\int_{\mathbb{R}} \varepsilon f_{2}(\varepsilon t) d t<+\infty \quad\left(\int_{\mathbb{R}} \varepsilon f_{3}(\varepsilon t) d t<+\infty \text { resp. }\right)
$$

Therefore, after integration in a time interval of size $O\left(\varepsilon^{-1}\right)$, near $t \sim 0$, these new terms induce a correction of order $O(1)$ (of order $O(\varepsilon)$ resp.) on the trajectory $\rho(t)$ (on the scaling $c(t)$, resp.). These corrections are precisely the quantities that induce lower bounds for the hidden defect.

The next step is to introduce a new function, say $v(t)$, which has the opposite behavior compared to $u(t)$. This solution is pure as $t \rightarrow+\infty$, and therefore, from Theorem 1.2, different from $u(t)$. We can describe the dynamics associated to $v(t)$ for all time, in particular along the interaction region: we construct an approximate solution $\tilde{v}(t)$, with associated dynamical parameters $\tilde{c}(t)$ and $\tilde{\rho}(t)$, which satisfy suitable dynamical laws, as in (1.17)-(1.18). However, since $v(t)$ is pure as $t \rightarrow+\infty$, the respective coefficients $\tilde{f}_{3}(t)$ and $\tilde{f}_{2}(t)$ are of different signs with respect to (1.17)(1.18). This crucial observation was first noticed by Martel and Merle in [24] for the quartic gKdV model, and represents a lack of symmetry in the dynamics.

The purpose for the rest of proof is to profit of this fact. The idea is the following: if (1.16) is not satisfied, then $u(t)$ and $v(t)$ are very close for all time, at some order smaller than $\varepsilon$. This property is nothing but a backward stability result 4 Now, suppose for instance that we are in the quadratic case. From the above stability result, one can prove that the dynamical parameters of $u(t)$ and $v(t)$ are very close, in the sense that

$$
\begin{equation*}
|c(t)-\tilde{c}(t)| \ll \varepsilon, \quad|\rho(t)-\tilde{\rho}(t)| \ll 1 \tag{1.19}
\end{equation*}
$$

[^2]We give a more precise description of these properties in Lemmas 4.1]and 4.2, and (6.3). But from (1.17)-(1.18) one has, after integration in time,

$$
\begin{equation*}
|\rho(t)-\tilde{\rho}(t)| \sim \int_{\mathbb{R}} f_{2}(s) d s \tag{1.20}
\end{equation*}
$$

Note that we have used that $f_{2}(\varepsilon t)$ and $\tilde{f}_{2}(\varepsilon t)$ have opposite signs. Then we have a contradiction with (1.19), provided the integral in (1.20) is not zero, and the bounds in (1.19) are small enough.

The last step above can be performed in a more rigorous way with the following argument. In the case $m=2,4$ the idea is to find a quantity satisfying the following properties: $(i)$ its variation in time is of order $O(\varepsilon),(i i)$ it contains the dynamical laws (1.17)-(1.18), and (iii) now the term $\varepsilon f_{2}(t)$ is relevant for the dynamics. This quantity is given by a suitable modification of a wellknown functional $J(t)$ introduced by Martel and Merle in [24], whereas in the cubic case the defect is in some sense degenerate and therefore $J(t)$ is useless. However, since in this case the variation of $c(t)$ is of second order in $\varepsilon$, we still recover the same lower bound, but we require several sharp estimates. We overcome this difficulty by using improved Virial estimates (cf. Lemmas 2.4, 3.5), with the right signs, which allow to close our arguments. To obtain a suitable lower bound for the defect in the case $\lambda=0$ is probably a more challenging, open problem.

Remark 1.5 (The Schrödinger case). The interaction soliton-potential has be also considered in the case of the nonlinear Schrödinger equation with a slowly varying potential, or a soliton-defect interaction. See e.g. Gustafson et al. [9, 10, Gang and Sigal [6], Gang and Weinstein [7, Holmer, Marzuola and Zworski 12, 13, 14, Perelman 32, and our recent work [26 on the NLS equation. It is relevant to say that the equivalent of Theorem 1.4 for the Schrödinger case considered in [26] is an interesting open question.

Let us explain the organization of this paper. First, in Section 2 we introduce the basic tools for the study of the interaction problem. These results are reminiscent of our previous papers [27, 28], and therefore are stated without proofs. In Section 3 we consider the case of a decreasing potential. We introduce the solution $v(t)$ which satisfies the opposite behavior with respect to $u(t)$. Section 4 is devoted to the rigorous proof of (1.19), and in Section 5 we prove (1.20). In Section 6 we prove the main result in the cases $m=2,4$, and finally in Section 7 we consider the most difficult case, $m=3$.
Notation. We follow most of the notation introduced in [28]. In particular, in this paper both $K, \gamma>0$ will denote fixed constants, independent of $\varepsilon$, and possibly changing from one line to another. Additionally, we introduce, for $\varepsilon>0$ small, the time of interaction

$$
\begin{equation*}
T_{\varepsilon}:=\frac{\varepsilon^{-1-\frac{1}{100}}}{1-\lambda}>0 . \tag{1.21}
\end{equation*}
$$

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## 2. Preliminaries

The purpose of this section is to recall several properties needed along this paper. For more details and the proofs of these results, see Section 2 and 3 in [27, 28].
2.1. Existence of approximate parameters. Denote, for $C>0, P \in \mathbb{R}$ given, and $m=2,3$ or 4,

$$
\begin{equation*}
f_{1}(C, P):=\frac{4}{m+3} C\left(C-\frac{\lambda}{\lambda_{0}}\right) \frac{a^{\prime}(\varepsilon P)}{a(\varepsilon P)} . \tag{2.1}
\end{equation*}
$$

We recall the existence of a unique solution for a dynamical system involving the evolution of the first order scaling and translation parameters of the soliton solution, $(C(t), P(t))$, in the interaction region. The behavior of this solution is essential to understand the dynamics of the soliton inside this region.

Lemma 2.1 (27, 28]). Let $m=2,3$ or 4. Let $\lambda_{0}, a(\cdot)$ and $f_{1}$ be as in (1.9), (1.4) and (2.1). There exists $\varepsilon_{0}>0$ small such that, for all $0<\varepsilon<\varepsilon_{0}$, the following holds.
(1) Existence. Consider $0 \leq \lambda<1$. There exists a unique solution $(C(t), P(t))$, with $C(t)$ bounded, monotone and positive, defined for all $t \geq-T_{\varepsilon}$, of the following nonlinear system

$$
\begin{cases}C^{\prime}(t)=\varepsilon f_{1}(C(t), P(t)), & C\left(-T_{\varepsilon}\right)=1  \tag{2.2}\\ P^{\prime}(t)=C(t)-\lambda, & P\left(-T_{\varepsilon}\right)=-(1-\lambda) T_{\varepsilon}\end{cases}
$$

Moreover, $\lim _{t \rightarrow+\infty} C(t)>0$, for all $0 \leq \lambda<1$, independently of $\varepsilon$.
(2) Asymptotic behavior. Let $\lambda_{0}<\tilde{\lambda}<1$ be the unique number satisfying (1.12). Then,
(a) For all $0 \leq \lambda \leq \tilde{\lambda}$, one has $\lim _{t \rightarrow+\infty} C(t)>\lambda$ and $\lim _{t \rightarrow+\infty} P(t)=+\infty$.
(b) For all $\tilde{\lambda}<\lambda<1$, there exists a unique $t_{0} \in\left(-T_{\varepsilon},+\infty\right)$ such that $C\left(t_{0}\right)=\lambda$, and $\lim _{t \rightarrow+\infty} C(t)<\lambda$. Moreover, $\lim _{t \rightarrow+\infty} P(t)=-\infty$. Finally, one has the bound $-T_{\varepsilon}<t_{0} \leq K(\lambda) T_{\varepsilon}$, for a positive constant $K(\lambda)$, independent of $\varepsilon$.

Remark 2.1. From the above result, one can define a unique time of escape $\tilde{T}_{\varepsilon}>-T_{\varepsilon}$ such that $P(t)$ satisfies

$$
\begin{equation*}
P\left(\tilde{T}_{\varepsilon}\right)=(1-\lambda) T_{\varepsilon}, \text { for } 0<\lambda<\tilde{\lambda}, \quad P\left(\tilde{T}_{\varepsilon}\right)=-(1-\lambda) T_{\varepsilon}, \text { for } \tilde{\lambda}<\lambda<1 \tag{2.3}
\end{equation*}
$$

(See [28, Definition 3.1].) In addition,

$$
\begin{equation*}
\tilde{T}_{\varepsilon} \leq K(\lambda) T_{\varepsilon}, \quad 0<K(\lambda)<+\infty \tag{2.4}
\end{equation*}
$$

provided $\lambda \neq \tilde{\lambda}$. Moreover, one has $C\left(\tilde{T}_{\varepsilon}\right)=c_{\infty}(\lambda)+O\left(\varepsilon^{10}\right)$, with $c_{\infty}(\lambda)$ being the unique solution of the algebraic equation (1.14). See [27, 28] for the proof of these results.
2.2. Construction of an approximate solution describing the interaction [28]. Let $t \in$ $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right], Q_{c}$ given in (1.3), $c=c(t)>0$ and $\rho(t) \in \mathbb{R}$ be bounded functions to be chosen later, and

$$
\begin{equation*}
y:=x-\rho(t), \quad R(t, x):=\tilde{a}^{-1}(\varepsilon \rho(t)) Q_{c(t)}(y) \tag{2.5}
\end{equation*}
$$

where $\tilde{a}(s):=a^{\frac{1}{m-1}}(s)$. The parameter $\tilde{a}$ describes the shape variation of the soliton along the interaction. Concerning the parameters $c(t)$ and $\rho(t)$, it is assumed that, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$,

$$
\begin{equation*}
|c(t)-C(t)|+\left|\rho^{\prime}(t)-P^{\prime}(t)\right| \leq \varepsilon^{1 / 100} \tag{2.6}
\end{equation*}
$$

with $(C(t), P(t))$ from Lemma 2.1. Consider a cut-off function $\eta \in C^{\infty}(\mathbb{R})$ satisfying
$0 \leq \eta(s) \leq 1, \quad 0 \leq \eta^{\prime}(s) \leq 1, \quad$ for any $s \in \mathbb{R} ; \quad \eta(s) \equiv 0$ for $s \leq-1, \quad \eta(s) \equiv 1$ for $s \geq 1$.
Define

$$
\begin{equation*}
\eta_{\varepsilon}(y):=\eta(\varepsilon y+2) \tag{2.7}
\end{equation*}
$$

From [28], the form of $\tilde{u}(t, x)$, the approximate solution, will be the sum of a soliton plus a correction term:

$$
\begin{equation*}
\tilde{u}(t, x):=\eta_{\varepsilon}(y)(R(t, x)+w(t, x)) \tag{2.8}
\end{equation*}
$$

where $w$ is given by

$$
w(t, x):=\left\{\begin{array}{l}
\varepsilon d(t) A_{c}(y), \quad \text { if } m=2,4,  \tag{2.9}\\
\varepsilon d(t) A_{c}(y)+\varepsilon^{2} B_{c}(t, y), \quad \text { if } m=3
\end{array}\right.
$$

and $d(t):=\left(a^{\prime} \tilde{a}^{-m}\right)(\varepsilon \rho(t))$. Here $A_{c}(y)$ and $B_{c}(t, y)$ are unknown functions. Note that, by definition, $\tilde{u}(t, x)=0$ for all $y \leq-3 \varepsilon^{-1}$.

We want to estimate the size of the error obtained by inserting $\tilde{u}$ as defined in (2.8)-(2.9) in the equation (1.8). For this, we define the residual term

$$
\begin{equation*}
S[\tilde{u}](t, x):=\tilde{u}_{t}+\left(\tilde{u}_{x x}-\lambda \tilde{u}+a(\varepsilon x) \tilde{u}^{m}\right)_{x} . \tag{2.10}
\end{equation*}
$$

For this quantity one has the following
Proposition 2.2 ([27, 28). Suppose $(c(t), \rho(t))$ satisfying (2.6). There exists $\gamma>0$ independent of $\varepsilon$ small, and an approximate solution $\tilde{u}$ of the form (2.8)-(2.9), such that for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, one has:
(1) Almost solution. The error associated to the function $\tilde{u}(t)$ satisfies

$$
\begin{aligned}
S[\tilde{u}] & =\left(c^{\prime}(t)-\varepsilon f_{1}(t)-\varepsilon^{2} \delta_{m, 3} f_{3}(t)\right) \partial_{c} \tilde{u} \\
& +\left(\rho^{\prime}(t)-c(t)+\lambda-\varepsilon f_{2}(t)-\varepsilon^{2} \delta_{m, 3} f_{4}(t)\right) \partial_{\rho} \tilde{u}+\tilde{S}[\tilde{u}](t)
\end{aligned}
$$

with $\delta_{m, 3}$ the Kronecker symbol, $\partial_{\rho} \tilde{u}:=\partial_{\rho} R+O_{H^{1}(\mathbb{R})}\left(\varepsilon^{1 / 2} e^{-\varepsilon \gamma|\rho(t)|}\right)$, and

$$
\begin{equation*}
\|\tilde{S}[\tilde{u}](t)\|_{H^{1}(\mathbb{R})} \leq K \varepsilon^{3 / 2} e^{-\gamma \varepsilon|\rho(t)|} \tag{2.11}
\end{equation*}
$$

(2) $A_{c}, B_{c}$ satisfy
$A_{c}, \partial_{c} A_{c} \in L^{\infty}(\mathbb{R}), \quad A_{c}^{\prime} \in \mathcal{Y}, \quad\left|A_{c}(y)\right| \leq K e^{-\gamma y} \quad$ as $y \rightarrow+\infty, \quad \lim _{-\infty} A_{c} \neq 0$,
and for $m=3$,

$$
\left\{\begin{array}{l}
B_{c}^{\prime}(t, \cdot) \in L^{\infty}(\mathbb{R}), \quad\left|B_{c}(t, y)\right| \leq K e^{-\gamma y} e^{-\varepsilon \gamma|\rho(t)|} \quad \text { as } y \rightarrow+\infty  \tag{2.13}\\
\left|B_{c}(t, y)\right|+\left|\partial_{c} B_{c}(t, y)\right| \leq K|y| e^{-\varepsilon \gamma|\rho(t)|}, \quad \text { as } y \rightarrow-\infty
\end{array}\right.
$$

(3) $L^{2}$-solution. For all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right], \eta_{\varepsilon} w(t, \cdot) \in H^{1}(\mathbb{R})$, with

$$
\begin{equation*}
\left\|\eta_{\varepsilon} w(t, \cdot)\right\|_{H^{1}(\mathbb{R})} \leq K \varepsilon^{1 / 2} e^{-\gamma \varepsilon|\rho(t)|} \tag{2.14}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|\int_{\mathbb{R}} \eta_{\varepsilon} w(t, x) Q_{c}(y) d x\right|+\left|\int_{\mathbb{R}} y \eta_{\varepsilon} w(t, x) Q_{c}(y) d x\right| \leq K \varepsilon^{10} \tag{2.15}
\end{equation*}
$$

(4) In addition, $f_{1}(t)=f_{1}(c(t), \rho(t))$ is given by (2.1),

$$
\begin{gather*}
f_{2}(t)=f_{2}(c(t), \rho(t)):=-\frac{\xi_{m}}{\sqrt{c(t)}}\left(\lambda-3 \lambda_{0} c(t)\right) \frac{a^{\prime}}{a}(\varepsilon \rho(t)), \quad \xi_{m}:=\frac{(3-m)}{(5-m)^{2}} \frac{\left(\int_{\mathbb{R}} Q\right)^{2}}{\int_{\mathbb{R}} Q^{2}}  \tag{2.16}\\
f_{3}(t)=f_{3}(c(t), \rho(t)):=\frac{\tilde{\xi}_{3}}{\sqrt{c(t)}}(c(t)-\lambda) \frac{a^{\prime 2}}{a^{2}}(\varepsilon \rho(t)), \quad \tilde{\xi}_{3}:=\frac{\lambda}{2} \frac{\left(\int_{\mathbb{R}} Q\right)^{2}}{\int_{\mathbb{R}} Q^{2}} \tag{2.17}
\end{gather*}
$$

and $f_{4}(t)$ satisfies the decomposition

$$
\begin{equation*}
f_{4}(t):=f_{4}^{1}(t) \frac{a^{\prime 2}}{a^{2}}(\varepsilon \rho(t))+f_{4}^{2}(t) \frac{a^{\prime \prime}}{a}(\varepsilon \rho(t)), \quad\left|f_{4}^{i}(t)\right| \leq K \tag{2.18}
\end{equation*}
$$

(5) Finally, one has the estimates

$$
\begin{equation*}
\left|\int_{\mathbb{R}} Q_{c} \tilde{S}[\tilde{u}]\right|+\left|\int_{\mathbb{R}} y Q_{c} \tilde{S}[\tilde{u}]\right| \leq K \varepsilon^{2} e^{-\varepsilon \gamma|\rho(t)|}+K \varepsilon^{3}, \tag{2.19}
\end{equation*}
$$

for $m=2,4$, and

$$
\begin{equation*}
\left|\int_{\mathbb{R}} Q_{c} \tilde{S}[\tilde{u}]\right|+\left|\int_{\mathbb{R}} y Q_{c} \tilde{S}[\tilde{u}]\right| \leq K \varepsilon^{3} e^{-\varepsilon \gamma|\rho(t)|}+K \varepsilon^{4} \tag{2.20}
\end{equation*}
$$

in the case $m=3$.
Remark 2.2. Note that, even under a correction term of second order, namely $\varepsilon^{2} B_{c}$, one cannot improve the associated error (2.11). We believe that this phenomenon is a consequence of the fact that $A_{c} \notin L^{2}(\mathbb{R})$.
2.3. Decomposition of the solution in the interaction region. The next result summarizes the interaction soliton-potential. Roughly speaking, the solution $u(t)$ behaves as the approximate solution $\tilde{u}(t)$.

Proposition $2.3\left([28)\right.$. Suppose $\lambda \in(0,1), \lambda \neq \tilde{\lambda}$. There exist $K_{0}, \varepsilon_{0}>0$ such that the following holds for any $0<\varepsilon<\varepsilon_{0}$.
(1) There exist unique $C^{1}$ functions $c, \rho:\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right] \rightarrow \mathbb{R}$ such that, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, the function $z(t):=u(t)-\tilde{u}(t, c(t), \rho(t))$ satisfies

$$
\begin{equation*}
\|z(t)\|_{H^{1}(\mathbb{R})} \leq K_{0} \varepsilon^{1 / 2}, \quad \int_{\mathbb{R}} z(t, x) y Q_{c}(y) d x=\int_{\mathbb{R}} z(t, x) Q_{c}(y) d x=0 . \tag{2.21}
\end{equation*}
$$

In addition, $z(t)$ solves the following $g K d V$ equation

$$
\left\{\begin{array}{l}
z_{t}+\left\{z_{x x}-\lambda z+a(\varepsilon x)\left[(\tilde{u}+z)^{m}-\tilde{u}^{m}\right]\right\}_{x}+\tilde{S}[\tilde{u}]+c_{1}^{\prime}(t) \partial_{c} \tilde{u}+\rho_{1}^{\prime}(t) \partial_{\rho} \tilde{u}=0,  \tag{2.22}\\
c_{1}^{\prime}(t):=c^{\prime}(t)-\varepsilon f_{1}(t)-\varepsilon^{2} \delta_{m, 3} f_{3}(t), \quad \rho_{1}^{\prime}(t):=\rho^{\prime}(t)-c(t)+\lambda-\varepsilon f_{2}(t)-\varepsilon^{2} \delta_{m, 3} f_{4}(t) .
\end{array}\right.
$$

(2) There is $\gamma>0$ independent of $K_{0}$ such that for every $t \in\left[-T_{\varepsilon}, T^{*}\right]$,

$$
\begin{gather*}
\left|\rho_{1}^{\prime}(t)\right| \leq K\left(m-3+\varepsilon e^{-\gamma \varepsilon|\rho(t)|}\right)\left[\int_{\mathbb{R}} z^{2} e^{-\gamma \sqrt{c}|y|}\right]^{1 / 2}+K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)+K\left|\int_{\mathbb{R}} y Q_{c} \tilde{S}[\tilde{u}]\right|,  \tag{2.23}\\
\left|c_{1}^{\prime}(t)\right| \leq K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)+K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}\left[\int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)\right]^{1 / 2}+K\left|\int_{\mathbb{R}} Q_{c} \tilde{S}[\tilde{u}]\right| \tag{2.24}
\end{gather*}
$$

and

$$
\begin{equation*}
|c(t)-C(t)|+\left|\rho^{\prime}(t)-P^{\prime}(t)\right| \leq K \varepsilon^{1 / 2} . \tag{2.25}
\end{equation*}
$$

Finally,

$$
\begin{equation*}
\left|c\left(-T_{\varepsilon}\right)-C\left(-T_{\varepsilon}\right)\right|+\left|\rho\left(-T_{\varepsilon}\right)-P\left(-T_{\varepsilon}\right)\right|+\left\|z\left(-T_{\varepsilon}\right)\right\|_{H^{1}(\mathbb{R})} \leq K \varepsilon^{10}, \tag{2.26}
\end{equation*}
$$

with $K>0$ independent of $K_{0}$.
Remark 2.3. Note that estimates (2.25) improve (2.6). In addition, (2.26) are consequences of (1.11) at time $-T_{\varepsilon}$, and (2.2). Moreover, from the proof of the above result, (1.11) and (2.11), one can see that e.g. an estimate of the order $\|z(t)\|_{H^{1}(\mathbb{R})} \leq K_{0} \varepsilon^{10}$ is valid for all sufficiently early times, namely $t \leq-K \varepsilon^{-1}|\log \varepsilon|$, with $K>0$ large enough.
2.4. Virial estimate. A better understanding of the estimate on the scaling parameter (2.24) needs the introduction of a Virial estimate, in the spirit of [27] (see Lemma 6.4). See also [11] for a similar result.

First, we define some auxiliary functions. Let $\phi \in C^{\infty}(\mathbb{R})$ be an even function satisfying the following properties

$$
\left\{\begin{array}{l}
\phi^{\prime} \leq 0 \text { in }[0,+\infty) ; \quad \phi \equiv 1 \text { in }[0,1],  \tag{2.27}\\
\phi(x)=e^{-x} \text { on }[2,+\infty) \quad \text { and } \quad e^{-x} \leq \phi(x) \leq 3 e^{-x} \text { on }[0,+\infty) .
\end{array}\right.
$$

Now, set $\psi(x):=\int_{0}^{x} \phi$. It is clear that $\psi$ is an odd function. Finally, for $A>0$, denote

$$
\begin{equation*}
\psi_{A}(x):=A\left(\psi(+\infty)+\psi\left(\frac{x}{A}\right)\right)>0 \tag{2.28}
\end{equation*}
$$

Note that $\lim _{x \rightarrow-\infty} \psi(x)=0$ and $e^{-|x| / A} \leq \psi_{A}^{\prime}(x) \leq 3 e^{-|x| / A}$. We claim the following
Lemma 2.4 ([28). There exist $K, A_{0}, \delta_{0}>0$ such that for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$ and for some $\gamma=$ $\gamma\left(A_{0}\right)>0$,

$$
\begin{equation*}
\partial_{t} \int_{\mathbb{R}} z^{2}(t, x) \psi_{A_{0}}(y) \leq-\delta_{0} \int_{\mathbb{R}}\left(z_{x}^{2}+z^{2}\right)(t, x) e^{-\frac{1}{A_{0}}|y|}+K A_{0} \varepsilon^{5 / 2} \tag{2.29}
\end{equation*}
$$

A simple but very important conclusion of the last estimate, is the following: one has, from (2.26) and (2.29),

$$
\begin{align*}
\int_{-T_{\varepsilon}}^{t} \int_{\mathbb{R}}\left(z_{x}^{2}+z^{2}\right)(t, x) e^{-\frac{1}{A_{0}}|y|} d x d s & \leq K\left[\int_{\mathbb{R}} z^{2}\left(-T_{\varepsilon}\right) \psi_{A_{0}}(y)-\int_{\mathbb{R}} z^{2}(t) \psi_{A_{0}}(y)\right]+K \varepsilon^{3 / 2-1 / 100} \\
& \leq K \varepsilon^{3 / 2-1 / 100} \tag{2.30}
\end{align*}
$$

for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, by taking $A_{0}$ large enough, independent of $\varepsilon$ and $K^{*}$. In other words, we improve the estimate on the integral of $z^{2}+z_{x}^{2}$ near the soliton (a crude integration of (2.30) gives
a bound $K \varepsilon^{-\frac{1}{100}}$ ). Finally, from (2.24) and (2.19) $-(2.20)$, we improve estimate (4.57) in [28], to obtain

$$
\begin{equation*}
\int_{-T_{\varepsilon}}^{t}\left|c_{1}^{\prime}(s)\right| d s \leq K \varepsilon^{3 / 2-1 / 100} \tag{2.31}
\end{equation*}
$$

(See [28, estimate (4.73)] for the integration of terms of the form $\varepsilon e^{-\gamma \varepsilon|\rho(t)|}$.)

## 3. The case of a decreasing potential

In this section we deal with the problem of existence of a pure soliton-like solution as time goes to $+\infty$. Our objective is to briefly describe the dynamics of such a solution, say $v(t)$, in order to compare its behavior with the solution $u(t)$ described in Theorems 1.1 and 1.2. We sketch some of these results, being straightforward generalizations of the results of Section 4 in [28]. First, we state the following existence result (see also [27, Proposition 7.2]).
Proposition 3.1. Suppose $x_{0} \in \mathbb{R}$ and $0<\lambda<1$ fixed, with $\lambda \neq \tilde{\lambda}$. Let $c^{+}>0$ with $\left|c^{+}-c_{\infty}(\lambda)\right| \leq$ $K \varepsilon^{1 / 2}$, where $c_{\infty}=c_{\infty}(\lambda)>0$ is the scaling given by Theorem 1.2, Let $\kappa(\lambda)$ be the parameter defined in (1.13). For $\varepsilon_{0}>0$ small enough, the following holds for any $0<\varepsilon<\varepsilon_{0}$. There exists $a$ unique solution $v \in C\left(\mathbb{R}, H^{1}(\mathbb{R})\right)$ of (1.8) such that

$$
\begin{equation*}
\lim _{t \rightarrow+\infty}\left\|v(t)-\kappa(\lambda) Q_{c^{+}}\left(\cdot-\left(c^{+}-\lambda\right) t-x_{0}\right)\right\|_{H^{1}(\mathbb{R})}=0 \tag{3.1}
\end{equation*}
$$

Moreover, there are constants $K, \gamma>0$ such that

$$
\begin{equation*}
\left\|v(t)-\kappa(\lambda) Q_{c^{+}}\left(\cdot-\left(c^{+}-\lambda\right) t-x_{0}\right)\right\|_{H^{1}(\mathbb{R})} \leq K e^{-\varepsilon \gamma t} \tag{3.2}
\end{equation*}
$$

provided $0<\varepsilon<\varepsilon_{0}$ small enough.
Remark 3.1. This result has been proved in [27] for all $0<\lambda \leq \lambda_{0}$ (namely, with $\kappa(\lambda)=$ $\left.2^{-1 /(m-1)}\right)$. The key argument in the proof was the introduction of the modified mass $\mathcal{M}[u](t)$, given by

$$
\begin{equation*}
\mathcal{M}[u](t):=\int_{\mathbb{R}} \frac{u^{2}(t, x)}{2 a(\varepsilon x)} d x \tag{3.3}
\end{equation*}
$$

which satisfies [27], for all $t, t^{\prime} \geq \tilde{T}_{\varepsilon}$, with $t^{\prime} \geq t, \mathcal{M}[u](t)-\mathcal{M}[u]\left(t^{\prime}\right) \leq K e^{-\varepsilon \gamma t}$. From the proof of this result, we see that the same conclusion holds for any $\lambda_{0}<\lambda<\tilde{\lambda}$, with no differences in the proof, since one still has $c_{\infty}(\lambda)>\lambda$. However, in the case $\tilde{\lambda}<\lambda<1$, one has $c_{\infty}(\lambda)<\lambda$. Therefore, one needs a modification in the main argument of the proof. It turns out that, instead of considering the modified mass $\mathcal{M}[u]$, one should consider the modified mass $\hat{M}[u]$, introduced in [27], given by

$$
\begin{equation*}
\hat{M}[u](t):=\frac{1}{2} \int_{\mathbb{R}} a^{1 / m}(\varepsilon x) u^{2}(t, x) d x \tag{3.4}
\end{equation*}
$$

Thanks to (1.5) this quantity satisfies, for any $m=2,3$ and 4 , the following property [27]: There exists $\varepsilon_{0}>0$ such that, for all $0<\varepsilon \leq \varepsilon_{0}$, and for all $t^{\prime} \geq t$,

$$
\begin{equation*}
\hat{M}[u](t)-\hat{M}[u]\left(t^{\prime}\right) \geq 0 \tag{3.5}
\end{equation*}
$$

After this modification, the proof of Proposition 3.1 is direct from [27, Proposition 7.2].
Let us come back to the study of the function $v(t)$. A straightforward consequence of Proposition 3.1 is that, for all $\varepsilon>0$ small enough,

$$
\left\|v\left(\tilde{T}_{\varepsilon}\right)-k(\lambda) Q_{c^{+}}\left(\cdot-\left(c^{+}-\lambda\right) \tilde{T}_{\varepsilon}-x_{0}\right)\right\|_{H^{1}(\mathbb{R})} \leq K \varepsilon^{10}
$$

Now, we want to describe the dynamics of this solution in the region $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. The natural step is, following Section 4 in [28], the construction of an approximate solution $\tilde{v}(t)$, with dynamical parameters $\tilde{c}(t)$ and $\tilde{\rho}(t)$, of the form (compare with (2.8))

$$
\begin{equation*}
\tilde{v}(t)=\tilde{v}(t, \tilde{c}(t), \tilde{\rho}(t)):=\tilde{\eta}_{\varepsilon}(\tilde{y})(\tilde{R}(t)+\tilde{w}(t)) \tag{3.6}
\end{equation*}
$$

such that $\tilde{v}\left(\tilde{T}_{\varepsilon}\right)$ is close enough to $v\left(\tilde{T}_{\varepsilon}\right)$. Here $\tilde{y}:=x-\tilde{\rho}(t), \tilde{\eta}_{\varepsilon}(\tilde{y}):=\eta(2-\varepsilon \tilde{y}), \tilde{R}(t)$ is the modulated soliton from (2.5) with parameters $\tilde{c}(t)$ and $\tilde{\rho}(t), \tilde{d}(t):=\frac{a^{\prime}}{\tilde{a}^{m}}(\varepsilon \tilde{\rho}(t))$, and

$$
\tilde{w}(t, x):=\left\{\begin{array}{l}
\varepsilon \tilde{d}(t) \tilde{A}_{\tilde{c}}(\tilde{y}), \quad \text { if } m=2,4,  \tag{3.7}\\
\varepsilon \tilde{d}(t) \tilde{A}_{\tilde{c}}(\tilde{y})+\varepsilon^{2} \tilde{B}_{\tilde{c}}(t, \tilde{y}), \quad \text { if } m=3
\end{array}\right.
$$

Remark 3.2. Note that we have chosen $\tilde{\eta}_{\varepsilon}$ such that $\tilde{\eta}_{\varepsilon}(\tilde{y})=0$ for all $\tilde{y} \geq \frac{3}{\varepsilon}$, and $\tilde{\eta}_{\varepsilon}(\tilde{y})=1$ for $\tilde{y} \leq \frac{1}{\varepsilon}$. This choice is the opposite to the corresponding one associated to $\eta(y)$ (see (2.7)).

Let $\lambda \in(0,1), \lambda \neq \tilde{\lambda}$, and $X_{0} \in \mathbb{R}$ with $\left|X_{0}\right| \leq \varepsilon^{-1 / 2-1 / 100}$. Let $(\tilde{C}(t), \tilde{P}(t))$ be the unique solution of the following backward dynamical system (cf. Lemma 2.1)

$$
\left\{\begin{array}{l}
\tilde{C}^{\prime}(t)=\varepsilon f_{1}(\tilde{C}(t), \tilde{P}(t)), \quad \tilde{C}\left(\tilde{T}_{\varepsilon}\right)=c_{\infty}(\lambda)  \tag{3.8}\\
\tilde{P}^{\prime}(t)=\tilde{C}(t)-\lambda, \quad \tilde{P}\left(\tilde{T}_{\varepsilon}\right)=P\left(\tilde{T}_{\varepsilon}\right)+X_{0}
\end{array}\right.
$$

(note that $\tilde{P}\left(\tilde{T}_{\varepsilon}\right)$ can be negative, as in the case $\tilde{\lambda}<\lambda<1$.) For further purposes, we need the following
Lemma 3.2. Assume $\left|X_{0}\right| \leq \varepsilon^{-1 / 2-1 / 100}$. Let $(C(t), P(t))$ and $(\tilde{C}(t), \tilde{P}(t))$ be the solutions of (2.2) and (3.8) respectively. Then, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$,

$$
\begin{equation*}
\varepsilon|P(t)-\tilde{P}(t)|+|C(t)-\tilde{C}(t)| \leq K \varepsilon^{1 / 2-1 / 100} \tag{3.9}
\end{equation*}
$$

Proof. We prove the most difficult case, namely $\lambda \in(\tilde{\lambda}, 1)$, since the case $\lambda \in(0, \tilde{\lambda})$ is simpler. Suppose $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, with $\left|t-t_{0}\right| \geq \frac{\alpha}{\varepsilon}$, $t_{0}$ from Lemma 2.1] and $\alpha>0$ a small number, independent of $\varepsilon$. From [28, identity (3.2)], one has

$$
C^{\lambda_{0}}(t)\left(\frac{\lambda}{\lambda_{0}}-C(t)\right)^{1-\lambda_{0}}=\left(\frac{\lambda}{\lambda_{0}}-1\right)^{1-\lambda_{0}} \frac{a^{p}(\varepsilon P(t))}{a^{p}\left(\varepsilon P\left(-T_{\varepsilon}\right)\right)}=\left(\frac{\lambda}{\lambda_{0}}-1\right)^{1-\lambda_{0}} a^{p}(\varepsilon P(t))\left(1+O\left(\varepsilon^{10}\right)\right)
$$

Similarly, since $\left|X_{0}\right|$ is small compared with $P\left(\tilde{T}_{\varepsilon}\right)=P\left(-T_{\varepsilon}\right)$, the functions $(\tilde{C}(t), \tilde{P}(t))$ satisfy the identity
$\tilde{C}^{\lambda_{0}}(t)\left(\frac{\lambda}{\lambda_{0}}-\tilde{C}(t)\right)^{1-\lambda_{0}}=c_{\infty}^{\lambda_{0}}\left(\frac{\lambda}{\lambda_{0}}-c_{\infty}\right)^{1-\lambda_{0}} \frac{a^{p}(\varepsilon \tilde{P}(t))}{a^{p}\left(\varepsilon \tilde{P}\left(\tilde{T}_{\varepsilon}\right)\right)}=c_{\infty}^{\lambda_{0}}\left(\frac{\lambda}{\lambda_{0}}-c_{\infty}\right)^{1-\lambda_{0}} a^{p}(\varepsilon \tilde{P}(t))\left(1+O\left(\varepsilon^{10}\right)\right)$. Consider the smooth function $C>0 \mapsto f(C):=C^{\lambda_{0}}\left(\frac{\lambda}{\lambda_{0}}-C\right)^{1-\lambda_{0}}$. Using (1.14), we get

$$
|f(\tilde{C}(t))-f(C(t))| \leq K \varepsilon a^{\prime}(\varepsilon P(t))|\tilde{P}(t)-P(t)|+K \varepsilon^{2}|P(t)-\tilde{P}(t)|^{2}
$$

Note that $f(C)$ has nonzero derivative provided $C \neq \lambda$. Since $|C(t)-\lambda| \geq \kappa \alpha>0, \kappa>0$, uniformly in $\varepsilon$ in the considered time region, we get

$$
|\Delta C(t)| \leq K(\alpha)\left[\varepsilon e^{-\gamma \varepsilon|P(t)|}|\Delta P(t)|+\varepsilon^{2}|\Delta P(t)|^{2}\right]
$$

where $\Delta C(t):=C(t)-\tilde{C}(t)$ and $\Delta P(t):=P(t)-\tilde{P}(t)$. Now we recall that $\Delta C(t)=\Delta P^{\prime}(t)$. Integrating $\left[t, \tilde{T}_{\varepsilon}\right]$, with $t \geq t_{0}+\frac{\alpha}{\varepsilon}$, we get

$$
|\Delta P(t)| \leq\left|\Delta P\left(\tilde{T}_{\varepsilon}\right)\right|+\int_{t}^{\tilde{T}_{\varepsilon}} K \varepsilon e^{-\gamma \varepsilon|P(s)|}|\Delta P(s)| d s+K \varepsilon^{2} \int_{t}^{\tilde{T}_{\varepsilon}}|\Delta P(s)|^{2} d s
$$

By the Gronwall inequality, one has $|\Delta P(t)| \leq K\left|\Delta P\left(\tilde{T}_{\varepsilon}\right)\right|$ and $|\Delta C(t)| \leq K \varepsilon\left|\Delta P\left(\tilde{T}_{\varepsilon}\right)\right|$, as desired. Now we consider the interval $\left[t_{0}-\frac{\alpha}{\varepsilon}, t_{0}+\frac{\alpha}{\varepsilon}\right]$. From (2.2) and (3.8),

$$
|\Delta P(t)| \leq\left|\Delta P\left(t_{0}+\frac{\alpha}{\varepsilon}\right)\right|+\int_{t}^{t_{0}+\frac{\alpha}{\varepsilon}}|\Delta C(s)| d s
$$

and

$$
|\Delta C(t)| \leq\left|\Delta C\left(t_{0}+\frac{\alpha}{\varepsilon}\right)\right|+K \varepsilon \int_{t}^{t_{0}+\frac{\alpha}{\varepsilon}} e^{-\gamma \varepsilon|P(s)|}(|\Delta C(s)|+\varepsilon|\Delta P(s)|) d s
$$

Hence one has $|\Delta C(t)| \leq K\left|\Delta C\left(t_{0}+\frac{\alpha}{\varepsilon}\right)\right|$ and $|\Delta P(t)| \leq K\left|\Delta P\left(t_{0}+\frac{\alpha}{\varepsilon}\right)\right|$. Finally, the proof in the interval $t \in\left[-T_{\varepsilon}, t_{0}-\frac{\alpha}{\varepsilon}\right]$ is similar to the first case. The proof is complete.

[^3]We assume $(\tilde{c}(t), \tilde{\rho}(t))$ and $(\tilde{C}(t), \tilde{P}(t))$ satisfying (2.6). The following is the equivalent to Proposition 2.2 (see also [27]):

Proposition 3.3. Let $(\tilde{c}(t), \tilde{\rho}(t))$ and $(\tilde{C}(t), \tilde{P}(t))$ be satisfying (2.6). There exists a constant $\gamma>0$, independent of $\varepsilon$ small, and an approximate solution $\tilde{v}$ of the form (3.6), such that for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, the following properties are satisfied.
(1) The error term $S[\tilde{v}]$ satisfies the decomposition

$$
\begin{align*}
S[\tilde{v}](t, x)= & \left(\tilde{c}^{\prime}(t)-\varepsilon \tilde{f}_{1}(t)-\varepsilon^{2} \delta_{m, 3} \tilde{f}_{3}(t)\right) \partial_{\tilde{c}} \tilde{v} \\
& +\left(\tilde{\rho}^{\prime}(t)-\tilde{c}(t)+\lambda-\varepsilon \tilde{f}_{2}(t)-\varepsilon^{2} \delta_{m, 3} \tilde{f}_{4}(t)\right) \partial_{\tilde{\rho}} \tilde{v}+\tilde{S}[\tilde{v}](t, x) \tag{3.10}
\end{align*}
$$

(2) The functions $\tilde{A}_{\tilde{c}}, \tilde{B}_{\tilde{c}}$ are as follows:
$\tilde{A}_{\tilde{c}}, \partial_{\tilde{c}} \tilde{A}_{\tilde{c}} \in L^{\infty}(\mathbb{R}), \quad \tilde{A}_{\tilde{c}}^{\prime} \in \mathcal{Y}, \quad\left|\tilde{A}_{\tilde{c}}(\tilde{y})\right| \leq K e^{\gamma \tilde{y}}$ as $\tilde{y} \rightarrow-\infty, \quad \lim _{+\infty} \tilde{A}_{\tilde{c}} \neq 0$,
and for $m=3$,

$$
\left\{\begin{array}{l}
B_{\tilde{c}}^{\prime}(t, \cdot) \in L^{\infty}(\mathbb{R}), \quad\left|B_{\tilde{c}}(t, \tilde{y})\right| \leq K e^{\gamma \tilde{y}} e^{-\varepsilon \gamma|\rho(t)|} \text { as } \tilde{y} \rightarrow-\infty  \tag{3.12}\\
\left|B_{\tilde{c}}(t, \tilde{y})\right|+\left|\partial_{\tilde{c}} B_{\tilde{c}}(t, \tilde{y})\right| \leq K|\tilde{y}| e^{-\varepsilon \gamma|\rho(t)|}, \quad \text { as } \tilde{y} \rightarrow+\infty
\end{array}\right.
$$

(3) The function $\tilde{\eta}_{\varepsilon} \tilde{w}(t)$, with $\tilde{w}(t)$ defined in (3.7), satisfies similar estimates as in (2.14)(2.15).
(4) In addition, $\tilde{f}_{1}(t)=f_{1}(\tilde{c}(t), \tilde{\rho}(t))$, given by (2.1),

$$
\begin{equation*}
\tilde{f}_{2}(t)=-f_{2}(\tilde{c}(t), \tilde{\rho}(t)), \quad \tilde{f}_{3}(t)=-f_{3}(\tilde{c}(t), \tilde{\rho}(t)) \tag{3.13}
\end{equation*}
$$

and $\tilde{f}_{4}(t)$ satisfies a similar decomposition as (2.18).
(5) Finally, $\tilde{S}[\tilde{v}](t, \cdot)$ describes similar estimates as in (2.11), (2.19) and (2.20).

Remark 3.3. Let us emphasize the main differences between Propositions 2.2 and 3.3. Contrary to (2.12) and (2.13), we impose the opposite behavior in (3.11)-(3.12). This last condition is mainly motivated by the fact that the solution $v(t)$ is now pure as $t \rightarrow+\infty$, therefore it should be rapidly decaying on the left hand side of the soliton, instead of the right one. As a consequence, we get that the values of $\tilde{f}_{2}(t)$ and $\tilde{f}_{3}(t)$ are of opposite sign (cf. (3.13).)
Sketch of proof of Proposition [3.3. We follow step by step the proof of Proposition 4.2 in [28] (see also Appendix B in [28]), having in mind the following formal changes:

$$
\begin{aligned}
& (C(t), P(t)) \mapsto(\tilde{C}(t), \tilde{P}(t)), \quad(c(t), \rho(t)) \mapsto(\tilde{c}(t), \tilde{\rho}(t)), \quad \tilde{u}(t) \mapsto \tilde{v}(t) \\
& \left(f_{1}(t), f_{2}(t), f_{3}(t), f_{4}(t)\right) \mapsto\left(\tilde{f}_{1}(t), \tilde{f}_{2}(t), \tilde{f}_{3}(t), \tilde{f}_{4}(t)\right)
\end{aligned}
$$

Steps 0, 1, 2, 3 and 4. In these paragraphs, no significant modifications are needed. Let us recall that $F_{1}$ is given by

$$
\begin{equation*}
F_{1}=\frac{\tilde{f}_{1}(t)}{\tilde{a}(\varepsilon \tilde{\rho})} \Lambda Q_{\tilde{c}}+\frac{a^{\prime}}{\tilde{a}^{m}}(\varepsilon \tilde{\rho})\left[\left(\tilde{y} Q_{\tilde{c}}^{m}\right)_{\tilde{y}}-\frac{1}{m-1}(\tilde{c}-\lambda) Q_{\tilde{c}}\right]-\frac{\tilde{f}_{2}(t)}{\tilde{a}(\varepsilon \tilde{\rho})} Q_{\tilde{c}}^{\prime} \tag{3.14}
\end{equation*}
$$

in particular, $\tilde{f}_{1}(t)=f_{1}(\tilde{c}(t), \tilde{\rho}(t))$. The term $F_{2}$ remains "unchanged".
Step 5. Resolution of the first linear problem. We are looking for a function $\tilde{A}_{\tilde{c}}$ with the opposite behavior with respect to $A_{c}$ (cf. (3.11)). The key difference will be in the computation of $\tilde{f}_{2}(t)$. Indeed, we start from (B.29) in [28]. We have (for the sake of clarity, we drop the variable $t$ and the tilde on each function, if there is no confusion)

$$
\int_{\mathbb{R}}\left(\mathcal{L} A_{c}\right)_{y} \int_{y}^{+\infty} \Lambda Q_{c}=\int_{\mathbb{R}}\left(\tilde{F}_{1}+\lambda F_{2}\right) \int_{y}^{+\infty} \Lambda Q_{c}, \quad \mathcal{L}:=-\partial_{y y}+c-m Q_{c}^{m-1}
$$

and therefore, using that we have chosen $\int_{\mathbb{R}} Q_{c} A_{c}=0[28]$ and $\Lambda Q_{c}:=\partial_{c} Q_{c}$,

$$
\int_{\mathbb{R}}\left(\mathcal{L} A_{c}\right)_{y} \int_{y}^{+\infty} \Lambda Q_{c}=\left.\left(\mathcal{L} A_{c}\right) \int_{y}^{+\infty} \Lambda Q_{c}\right|_{-\infty} ^{+\infty}+\int_{\mathbb{R}} \Lambda Q_{c} \mathcal{L} A_{c}=-\int_{\mathbb{R}} Q_{c} A_{c}=0
$$

Note that, in this case, we have used that $\left.\left(\mathcal{L} A_{c}\right) \int_{y}^{+\infty} \Lambda Q_{c}\right|_{-\infty} ^{+\infty}=0$. Therefore, from (3.14) and [28, B.20],

$$
f_{2} \int_{\mathbb{R}} Q_{c} \Lambda Q_{c}=\frac{a^{\prime}}{a} \int_{\mathbb{R}}\left[p c\left(c-\frac{\lambda}{\lambda_{0}}\right) \Lambda Q_{c}-\frac{1}{m-1}(c-\lambda) Q_{c}+\left(y Q_{c}^{m}\right)^{\prime}\right] \int_{y}^{+\infty} \Lambda Q_{c} .
$$

Using that $\int_{y}^{+\infty} \Lambda Q_{c}=-\int_{0}^{y} \Lambda Q_{c}+\int_{0}^{+\infty} \Lambda Q_{c}=-\int_{0}^{y} \Lambda Q_{c}+\frac{1}{2} \int_{\mathbb{R}} \Lambda Q_{c}$, one has

$$
\theta f_{2} c^{2 \theta-1} \int_{\mathbb{R}} Q^{2}=\frac{a^{\prime}}{2 a}\left[p c\left(c-\frac{\lambda}{\lambda_{0}}\right) \int_{\mathbb{R}} \Lambda Q_{c}-\frac{1}{m-1}(c-\lambda) \int_{\mathbb{R}} Q_{c}\right] \int_{\mathbb{R}} \Lambda Q_{c},
$$

and therefore

$$
f_{2}(t)=-\frac{(3-m)}{(5-m)^{2}}\left(3 \lambda_{0} c-\lambda\right) \frac{a^{\prime}(\varepsilon \rho)}{\sqrt{c} a(\varepsilon \rho)} \frac{\left(\int_{\mathbb{R}} Q\right)^{2}}{\int_{\mathbb{R}} Q^{2}},
$$

as desired (cf. (3.13)).
Step 6. Cubic case. resolution of a second linear system. As above, the main difference here is in the value of $\tilde{f}_{3}(t)$, which is the "opposite" of $f_{3}(t)$. This result is consequence of (3.12).

We start from the equivalent of [28, B.35] in our case. The first big difference is in (B.36). Now we have

$$
\int_{\mathbb{R}} A_{c} \mathcal{L} A_{c}^{\prime}=\left.A_{c} \mathcal{L} A_{c}\right|_{-\infty} ^{+\infty}-\int_{\mathbb{R}} A_{c}\left(\tilde{F}_{1}+\lambda \hat{F}_{1}\right)=c A_{c}^{2}(+\infty)-\int_{\mathbb{R}} A_{c}\left(\tilde{F}_{1}+\lambda \hat{F}_{1}\right),
$$

and therefore,

$$
3 \int_{\mathbb{R}} Q_{c} Q_{c}^{\prime} A_{c}^{2}=\frac{1}{2} c A_{c}^{2}(+\infty)-\int_{\mathbb{R}} A_{c}\left(\tilde{F}_{1}+\lambda \hat{F}_{1}\right) .
$$

In the same way, $\mu_{c}=\frac{1}{2} c A_{c}^{2}(+\infty)-\int_{\mathbb{R}} A_{c} Q_{c}^{3}$. Still following the proof of (B.35), we have that

$$
\begin{aligned}
\mu_{c} & =\frac{1}{2} c A_{c}^{2}(+\infty)+\frac{1}{2} \int_{\mathbb{R}} \mathcal{L} A_{c} Q_{c}=\frac{1}{2} c A_{c}^{2}(+\infty)+\frac{1}{2} \int_{\mathbb{R}} Q_{c} \int_{-\infty}^{y}\left(\tilde{F}_{1}+\lambda \hat{F}_{1}\right) \\
& =\frac{1}{2} c A_{c}^{2}(+\infty)+\frac{1}{4} \int_{\mathbb{R}} Q_{c} \int_{\mathbb{R}}\left(\tilde{F}_{1}+\lambda \hat{F}_{1}\right) .
\end{aligned}
$$

Since $A_{c}(+\infty)=\frac{1}{c} \int_{\mathbb{R}}\left(\tilde{F}_{1}+\lambda \hat{F}_{1}\right)=-\frac{1}{2 c}(c-\lambda) \int_{\mathbb{R}} Q_{c}$, we finally get $\mu_{c}=-\frac{\lambda}{8 c}(c-\lambda)\left(\int_{\mathbb{R}} Q\right)^{2}$. Therefore, $\tilde{f}_{3}(t)=-f_{3}(\tilde{c}(t), \tilde{\rho}(t))$.
Step 7. Final conclusion. No differences, apart from the obvious ones, are present in this paragraph. The sketch of proof of Proposition 3.3 is now complete.

In the following lines, we state without proof the equivalent of Proposition 2.3 for the solution $v(t)$.

Proposition 3.4. Suppose $0<\lambda<1, \lambda \neq \tilde{\lambda}$. There exists a constant $\varepsilon_{0}>0$ such that the following holds for any $0<\varepsilon<\varepsilon_{0}$. There are a constant $K>0$ independent of $\varepsilon$ and unique $C^{1}$ functions $\tilde{c}, \tilde{\rho}:\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right] \rightarrow \mathbb{R}$ such that, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, the function $\tilde{z}(t, x):=v(t)-$ $\tilde{v}(t ; \tilde{c}(t), \tilde{\rho}(t))$ satisfies

$$
\begin{equation*}
\|\tilde{z}(t)\|_{H^{1}(\mathbb{R})} \leq K \varepsilon^{1 / 2}, \quad \int_{\mathbb{R}} \tilde{z}(t, x) Q_{\tilde{c}}(\tilde{y}) d x=\int_{\mathbb{R}} \tilde{y} Q_{\tilde{c}}(\tilde{y}) \tilde{z}(t, x) d x=0 . \tag{3.15}
\end{equation*}
$$

From the proof of this result one can obtain several additional properties, as in Proposition 2.3 We recall some of them, of importance in the following lines. First of all, $\tilde{z}(t)$ satisfies the gKdV equation

$$
\begin{equation*}
\tilde{z}_{t}+\left\{\tilde{z}_{x x}-\lambda \tilde{z}+a(\varepsilon x)\left[(\tilde{v}+\tilde{z})^{m}-\tilde{v}^{m}\right]\right\}_{x}+\tilde{S}[\tilde{v}]+\tilde{c}_{1}^{\prime}(t) \partial_{\tilde{c}} \tilde{v}+\tilde{\rho}_{1}^{\prime}(t) \partial_{\tilde{\rho}} \tilde{v}=0, \tag{3.16}
\end{equation*}
$$

with $\tilde{c}_{1}^{\prime}:=\tilde{c}^{\prime}-\varepsilon \tilde{f}_{1}-\varepsilon^{2} \delta_{m, 3} \tilde{f}_{3}$, and $\tilde{\rho}_{1}^{\prime}:=\tilde{\rho}^{\prime}-\tilde{c}+\lambda-\varepsilon \tilde{f}_{2}-\varepsilon^{2} \delta_{m, 3} \tilde{f}_{4}$. Second, there exists $\gamma>0$ such that, for every $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$,

$$
\begin{equation*}
\left|\tilde{\rho}_{1}^{\prime}(t)\right| \leq K\left(m-3+\varepsilon e^{-\gamma \varepsilon|\tilde{\rho}(t)|}\right)\left[\int_{\mathbb{R}} \tilde{z}^{2}(t) e^{-\gamma|\tilde{y}|}\right]^{1 / 2}+K \int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}(t)+K\left|\int_{\mathbb{R}} \tilde{y} Q_{\tilde{c}} \tilde{S}[\tilde{v}]\right|, \tag{3.17}
\end{equation*}
$$

$$
\begin{equation*}
\left|\tilde{c}_{1}^{\prime}(t)\right| \leq K \int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}(t)+K \varepsilon e^{-\gamma \varepsilon|\tilde{\rho}(t)|}\left[\int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}(t)\right]^{1 / 2}+K\left|\int_{\mathbb{R}} Q_{\tilde{c}} \tilde{S}[\tilde{v}]\right| \tag{3.18}
\end{equation*}
$$

and

$$
\begin{gather*}
|\tilde{c}(t)-\tilde{C}(t)|+\left|\tilde{\rho}^{\prime}(t)-\tilde{P}^{\prime}(t)\right| \leq K \varepsilon^{1 / 2}  \tag{3.19}\\
\left|\tilde{c}\left(\tilde{T}_{\varepsilon}\right)-c^{+}\right|+\left|\tilde{\rho}\left(\tilde{T}_{\varepsilon}\right)-\tilde{P}\left(\tilde{T}_{\varepsilon}\right)\right|+\left\|z\left(\tilde{T}_{\varepsilon}\right)\right\|_{H^{1}(\mathbb{R})} \leq K \varepsilon^{10} \tag{3.20}
\end{gather*}
$$

with $K>0$ independent of $\varepsilon$. This information allows us to prove a Virial identity for $\tilde{z}$, as in Lemma 2.4 (see 28 for the proof).

Lemma 3.5. There exist $K, A_{0}, \delta_{0}>0$ such that for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$ and for some $\gamma=\gamma\left(A_{0}\right)>0$,

$$
\begin{equation*}
\partial_{t} \int_{\mathbb{R}} \tilde{z}^{2}(t, x)\left(1-\psi_{A_{0}}\right)(\tilde{y}) \geq \delta_{0} \int_{\mathbb{R}}\left(\tilde{z}_{x}^{2}+\tilde{z}^{2}\right)(t, x) e^{-\frac{1}{A_{0}}|\tilde{y}|}-K A_{0} \varepsilon^{5 / 2} \tag{3.21}
\end{equation*}
$$

As in (2.30), this last property leads to the estimate

$$
\begin{equation*}
\int_{t}^{\tilde{T}_{\varepsilon}} \int_{\mathbb{R}}\left(\tilde{z}_{x}^{2}+\tilde{z}^{2}\right)(s, x) e^{-\frac{1}{A_{0}}|\tilde{y}|} d x d s+\int_{t}^{\tilde{T}_{\varepsilon}}\left|\tilde{c}_{1}^{\prime}(s)\right| d s \leq K \varepsilon^{3 / 2-1 / 100} \tag{3.22}
\end{equation*}
$$

for $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, and where we have used that $1-\psi_{A_{0}}>0$ and (3.20).

## 4. Backward stability

Let $\delta>0$ a small number, to be chosen below. In this section we will assume that, for $T \geq T_{\varepsilon}$ large enough, one has

$$
\begin{equation*}
\|u(T)-v(T)\|_{H^{1}(\mathbb{R})} \leq K \nu \varepsilon^{1+\delta} \tag{4.1}
\end{equation*}
$$

with $\nu$ a small number, to be specified below, and $K$ a fixed constant. We claim that this smallness condition is preserved for all time below $T$, in particular along the time interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$.
Lemma 4.1. Suppose $\lambda \in(0,1), \lambda \neq \tilde{\lambda}$, and $\delta>0$ small. There exist $K>0$ and a smooth function $\mathcal{T}(t) \in \mathbb{R}$, defined for all $t \in\left[-T_{\varepsilon}, T\right]$, such that

$$
\begin{equation*}
\|u(t+\mathcal{T}(t))-v(t)\|_{H^{1}(\mathbb{R})}+\left|\mathcal{T}^{\prime}(t)\right| \leq K \nu \varepsilon^{1+\delta} \tag{4.2}
\end{equation*}
$$

Remark 4.1. Let us emphasize that the modulation via the function $\mathcal{T}(t)$ is in part consequence of the fact that there is no space invariance for the equation (1.1), and therefore modulation in space is not enough, in particular inside the interaction region. This idea has been previously introduced in [27.

Proof of Lemma 4.1. We sketch the proof of this result, since it is similar to the proof of Proposition 2.5 in [28], and Proposition 5.1 in [27. We proceed in two steps.
First step: From $t=T$ to $t=\tilde{T}_{\varepsilon}$. We claim that for all $t \in\left[\tilde{T}_{\varepsilon}, T\right]$, there exists $\mathcal{T}(t) \in \mathbb{R}$ such that

$$
\|u(t+\mathcal{T}(t))-v(t)\|_{H^{1}(\mathbb{R})}+\left|\mathcal{T}^{\prime}(t)\right| \leq K \nu \varepsilon^{1+\delta}
$$

with $K>0$ independent of $\varepsilon, \nu$ and $t$. Indeed, we define, for $K^{*}>0$ to be fixed later,

$$
\begin{gather*}
T^{*}:=\inf \left\{t \in\left[\tilde{T}_{\varepsilon}, T\right] \text { such that, for all } t^{\prime} \in[t, T]\right. \text {, there exists a smooth } \\
\left.\tilde{T}(t) \in \mathbb{R} \text { satisfying }\|u(t+\tilde{T}(t))-v(t)\|_{H^{1}(\mathbb{R})} \leq K^{*} \nu \varepsilon^{1+\delta}\right\} \tag{4.3}
\end{gather*}
$$

We suppose that $T^{*}>\tilde{T}_{\varepsilon}$. We define, via the implicit function theorem, functions $\mathcal{T}(t)$ and $h(t)$, such that $h(t):=u(t+\mathcal{T}(t))-v(t)$ satisfies, for all $t \in\left[T^{*}, T\right]$,

$$
\begin{equation*}
\int_{\mathbb{R}} h(t, x) v_{x}(t, x) d x=0 \tag{4.4}
\end{equation*}
$$

In addition, one has $\|h(t)\|_{H^{1}(\mathbb{R})}+\left|\mathcal{T}^{\prime}(t)\right| \leq K K^{*} \nu \varepsilon^{1+\delta}$, for some positive constant $K$. Additionally, this estimate at time $t=T$ does not depend on $K^{*}$. Define a mass $\tilde{M}[u](t)$ as follows:

$$
\tilde{M}[u](t):=\left\{\begin{array}{lll}
\hat{M}[u](t) & c_{\infty}(\lambda)<\lambda, & (\text { cf. (3.4) }) \\
\mathcal{M}[u](t) & c_{\infty}(\lambda)>\lambda, & (\text { cf. (3.3) })
\end{array}\right.
$$

Note that this quantity satisfies, for all $t \in\left[T^{*}, T\right]$,

$$
\left\{\begin{array}{lll}
\tilde{M}[u](t)-\tilde{M}[u](T) \geq 0, & c_{\infty}(\lambda)<\lambda, & (\text { cf. (3.4)-(3.5) }),  \tag{4.5}\\
\tilde{M}[u](t)-\tilde{M}[u](T) \leq K e^{-\gamma \varepsilon t}, & c_{\infty}(\lambda)>\lambda, & (\text { cf. Lemma A. } 2[28]) .
\end{array}\right.
$$

Moreover, this result does not vary if we consider instead the translated mass $\tilde{M}[u(\cdot+\mathcal{T}(\cdot))](t)$.
On the one hand, since $\tilde{M}[v](t)=\kappa_{m}(\lambda) M[Q]+O\left(e^{-\varepsilon \gamma t}\right)$, with $\kappa_{m}(\lambda)$ a positive constant (recall that $v(t)$ is a pure soliton solution at $+\infty$ ), and $E_{a}[v](t)=E_{a}[v](T)$, one has

$$
\left|E_{a}[v](T)-E_{a}[v](t)+\left(c_{\infty}(\lambda)-\lambda\right)(\tilde{M}[v](T)-\tilde{M}[v](t))\right| \leq K e^{-\varepsilon \gamma t}
$$

On the other hand, from the decomposition $u(t+\mathcal{T}(t))=v(t)+h(t)$, we get

$$
\begin{equation*}
E_{a}[u(\cdot+\mathcal{T}(\cdot))](t)+\left(c_{\infty}(\lambda)-\lambda\right) \tilde{M}[u(\cdot+\mathcal{T}(\cdot))](t)=E_{a}[v](t)+\left(c_{\infty}(\lambda)-\lambda\right) \tilde{M}[v](t)+\tilde{F}(t) \tag{4.6}
\end{equation*}
$$

with $\tilde{F}(t)$ a coercive Weinstein functional in $h(t)$ (see e.g. [28, Lemma 2.2]), up to a negative direction represented by $v(t)$. This direction can be controlled using the energy conservation law for $E_{a}[u](t)$, as is done in [27, Lemma 5.4]. Indeed, note that

$$
\begin{align*}
E_{a}[u](T) & =E_{a}[u(\cdot+\mathcal{T}(\cdot))](t)=E_{a}[v](t)-\int_{\mathbb{R}} h\left(v_{x x}-\lambda v+a(\varepsilon x) v^{m}\right)+O\left(\|h(t)\|_{H^{1}(\mathbb{R})}^{2}\right) \\
& =E_{a}[v](T)-\left(c_{\infty}-\lambda\right) \int_{\mathbb{R}} v h(t)-\int_{\mathbb{R}} h\left(v_{x x}-c_{\infty} v+a(\varepsilon x) v^{m}\right)+O\left(\|h(t)\|_{H^{1}(\mathbb{R})}^{2}\right) \tag{4.7}
\end{align*}
$$

Since $c_{\infty}(\lambda) \neq \lambda$ for all $\lambda \neq \tilde{\lambda}$, we have

$$
\left|\int_{\mathbb{R}} v h(t)-\int_{\mathbb{R}} v h(T)\right| \leq K(\lambda) K^{*} \nu \varepsilon^{1+\delta}\left(e^{-\gamma \varepsilon t}+K^{*} \nu \varepsilon^{1+\delta}\right)
$$

We evaluate (4.6) at $t=T$ and $t=T^{*}$, and use this last estimate. From the coercivity of $\tilde{F}(t)$ up to the direction $v(t)$ we get, for $\varepsilon_{0}>0$ small enough,

$$
\left\|h\left(T^{*}\right)\right\|_{H^{1}(\mathbb{R})}^{2} \leq K(\lambda) K^{*} \nu^{2} \varepsilon^{2(1+\delta)}+K e^{-\gamma \varepsilon t} \leq \frac{1}{2}\left(K^{*}\right)^{2} \nu^{2} \varepsilon^{2(1+\delta)}
$$

for $K^{*}$ large, independent of $\varepsilon$ and $\nu$, which is a contradiction to the definition of $T^{*}$. This proves the first step of the proof.
Final step. We prove the result inside the interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. The proof is similar to the above case, but in this opportunity we start from the initial estimate

$$
\left\|u\left(\tilde{T}_{\varepsilon}+\hat{T}_{\varepsilon}\right)-v\left(\tilde{T}_{\varepsilon}\right)\right\|_{H^{1}(\mathbb{R})} \leq K \nu \varepsilon^{1+\delta}, \quad \hat{T}_{\varepsilon}:=\mathcal{T}\left(\tilde{T}_{\varepsilon}\right)
$$

Note that $u\left(t+\hat{T}_{\varepsilon}\right)$ is also a solution of (1.1), with same energy and the same pure asymptotics as $t \rightarrow-\infty$. Therefore, in what follows we can assume by simplicity that $\hat{T}_{\varepsilon}=0$. We define (4.3) in the same way, but now we work inside the interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. In a similar fashion, we define $h(t)$ and $\mathcal{T}(t)$, as in (4.4). However, the energy-mass argument above considered is not valid anymore, since the mass variation is too large; we need a different approach.

In order to savage our proof, we follow the argument of [27, Proposition 5.1]. We consider the Weinstein functional

$$
\mathcal{F}(t):=\frac{1}{2} \int_{\mathbb{R}}\left(h_{x}^{2}+\tilde{c}(t) h^{2}\right)-\frac{1}{m+1} \int_{\mathbb{R}} a(\varepsilon x)\left[(v+h)^{m+1}-v^{m+1}-(m+1) v^{m} h\right]
$$

with $\tilde{c}(t)$ being the scaling of the approximate solution $\tilde{v}(t)$, close to $v(t)$. This quantity $\mathcal{F}(t)$ varies slowly, as shows a direct computation, similar to [27, Lemma 5.6]. In particular, the variation of $\tilde{c}(t)$ can be controlled using (3.22). The last step is a sharp control of the quantity

$$
\begin{equation*}
\int_{\mathbb{R}} v h \tag{4.8}
\end{equation*}
$$

better than the standard Cauchy-Schwarz inequality. This can be done using a similar argument as above (see also [27, Lemma 5.4]), as long as $\tilde{c}(t) \neq \lambda$. This is certainly true in the case $0<\lambda<\tilde{\lambda}$, since $\tilde{C}(t)>\lambda\left(\right.$ Lemma 2.1) and $|\tilde{c}(t)-\tilde{C}(t)| \leq K \varepsilon^{1 / 2}$ for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. Therefore, in the case $0<\lambda<\tilde{\lambda}$, we are done.

In order to control this quantity in the case $\tilde{\lambda}<\lambda<1$, we use the following argument. Suppose $t \geq T^{*}>t_{0}+\frac{\alpha}{\varepsilon}$, for $\alpha>0$ small and $t_{0}$ such that $\tilde{C}\left(t_{0}\right)=\lambda$. It is clear that one can control (4.8) inside the interval $\left[T^{*}, \tilde{T}_{\varepsilon}\right]$. Indeed, following (4.7), one has

$$
\begin{equation*}
\left|\int_{\mathbb{R}} v h(t)-\int_{\mathbb{R}} v h\left(\tilde{T}_{\varepsilon}\right)\right| \leq \frac{K}{\alpha} K^{*} \nu \varepsilon^{1+\delta}\left\{\varepsilon e^{-\varepsilon \gamma|\tilde{\rho}(t)|}+K^{*} \nu \varepsilon^{1+\delta}\right\}, \tag{4.9}
\end{equation*}
$$

which improves the standard estimate, provided we take $\varepsilon$ small, depending on $K^{*}$ and $\alpha$. As a conclusion, $T^{*} \leq t_{0}+\frac{\alpha}{\varepsilon}$.

Now we suppose $T^{*}>t_{0}-\frac{\alpha}{\varepsilon}$, and we consider the control of (4.8) inside the interval $\left[T^{*}, t_{0}+\frac{\alpha}{\varepsilon}\right]$. Moreover, we may suppose $T^{*}<t_{0}$, which is the most difficult case, since $\tilde{C}\left(t_{0}\right)=\lambda$ and the usual estimate degenerates. However, since the interval is small, one can use a standard balance of mass. One has, for $t \in\left[T^{*}, t_{0}+\frac{\alpha}{\varepsilon}\right]$,

$$
\begin{equation*}
M[u(\cdot+\mathcal{T}(\cdot))](t)-M[v](t)=\frac{1}{2} \int_{\mathbb{R}}\left[(v+h)^{2}(t)-v^{2}(t)\right]=\int_{\mathbb{R}} v h(t)+\frac{1}{2} \int_{\mathbb{R}} h^{2}(t) \tag{4.10}
\end{equation*}
$$

On the other hand, since $u$ and $v$ are solutions of (1.1), one has from (1.6),

$$
\partial_{t}\left\{M[u(\cdot+\mathcal{T}(\cdot)](t)-M[v](t)\}=\frac{\varepsilon}{m+1} \int_{\mathbb{R}} a^{\prime}\left((v+h)^{m+1}-v^{m+1}\right)+\frac{\varepsilon \mathcal{T}^{\prime}(t)}{m+1} \int_{\mathbb{R}} a^{\prime}(v+h)^{m+1}\right.
$$

Therefore, after integration in $\left[t, t_{0}+\frac{\alpha}{\varepsilon}\right]$, and using (4.10), we get

$$
\begin{equation*}
\left|\int_{\mathbb{R}} v h(t)-\int_{\mathbb{R}} v h\left(t_{0}+\frac{\alpha}{\varepsilon}\right)\right| \leq K K^{*} \nu \varepsilon^{1+\delta}\left(\alpha+K^{*} \nu \varepsilon^{1+\delta}\right) \tag{4.11}
\end{equation*}
$$

which improves the standard estimate, for $\alpha>0$ small enough, depending on $K^{*}$ (take e.g. $\left.\alpha=\left(K^{*}\right)^{-1 / 100}\right)$. Therefore, $T^{*} \leq t_{0}-\frac{\alpha}{\varepsilon}$.

The final estimate inside the interval $\left[-T_{\varepsilon}, t_{0}-\frac{\alpha}{\varepsilon}\right]$ is completely analogous to (4.9). One has, for $t \in\left[T^{*}, t_{0}-\frac{\alpha}{\varepsilon}\right]$,

$$
\begin{equation*}
\left|\int_{\mathbb{R}} v h(t)-\int_{\mathbb{R}} v h\left(t_{0}-\frac{\alpha}{\varepsilon}\right)\right| \leq \frac{K}{\alpha} K^{*} \nu \varepsilon^{1+\delta}\left(\varepsilon e^{-\varepsilon \gamma|\tilde{\rho}(t)|}+K^{*} \nu \varepsilon^{1+\delta}\right) . \tag{4.12}
\end{equation*}
$$

Combining estimates (4.9)-(4.12), taking $K^{*}$ large and $\varepsilon$ small, depending on $K^{*}$, we obtain a contradiction. The proof is complete.

We recall that from Propositions 3.3 and 3.4, there exists a suitable approximate solution $\tilde{v}(t)=\tilde{v}(t ; \tilde{c}(t), \tilde{\rho}(t))$, defined for $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, of the form (3.6), with dynamical parameters $\tilde{c}(t)$ and $\tilde{\rho}(t)$.

The purpose in what follows is to use the smallness condition (6.2) to obtain upper bounds on the variation of parameters $(c, \rho)$ and $(\tilde{c}, \tilde{\rho})$. Define, for $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, the following quantities:

$$
\begin{equation*}
t_{+}:=t+\mathcal{T}(t), \quad \Delta c(t):=c\left(t_{+}\right)-\tilde{c}(t), \quad \text { and } \quad \Delta \rho(t):=\rho\left(t_{+}\right)-\tilde{\rho}(t) \tag{4.13}
\end{equation*}
$$

We have supposed that $|\mathcal{T}(t)| \leq \frac{T_{\varepsilon}}{100}$ in the interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, in such a way that we still can use the decompositions of Propositions 2.3 and 3.4 Later we will improve this result. The next result states that under the condition (6.2) the quantities $\Delta c(t)$ and $\Delta \rho(t)$ are also small, meaning that almost equal solutions have close dynamical parameters.

Lemma 4.2. Assume $|\mathcal{T}(t)| \leq \frac{T_{\varepsilon}}{100}$ in the interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. There exists $K, \varepsilon_{0}>0$ such that for all $0<\varepsilon<\varepsilon_{0}$ the following holds. Suppose that (4.1) is satisfied inside the interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. Then, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$,

$$
\begin{equation*}
|\Delta c(t)|+|\Delta \rho(t)| \leq K \nu \varepsilon^{1+\delta}+K \varepsilon^{10} \tag{4.14}
\end{equation*}
$$

Proof. From Propositions 2.3 and 3.4 we have the following decomposition

$$
\begin{equation*}
u\left(t_{+}, x\right)-v(t, x)=\tilde{u}\left(t_{+}, x\right)-\tilde{v}(t, x)+z\left(t_{+}, x\right)-\tilde{z}(t, x) \tag{4.15}
\end{equation*}
$$

where, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right], z(t, x)$ and $\tilde{z}(t, x)$ satisfy (2.21) and (3.15), respectively. In addition, after a Taylor expansion, we obtain

$$
\begin{align*}
R\left(t_{+}, x\right)-\tilde{R}(t, x)= & \frac{\Delta c(t)}{\tilde{a}(\varepsilon \tilde{\rho}(t))} \Lambda Q_{\tilde{c}(t)}(\tilde{y})-\frac{\Delta \rho(t)}{\tilde{a}(\varepsilon \tilde{\rho}(t))} Q_{\tilde{c}(t)}^{\prime}(\tilde{y}) \\
& +O_{H^{1}(\mathbb{R})}\left(\varepsilon e^{-\varepsilon \gamma|\tilde{\rho}(t)|}|\Delta \rho(t)|+|\Delta c(t)|^{2}+|\Delta \rho(t)|^{2}\right) \tag{4.16}
\end{align*}
$$

On the other hand, from (2.15),

$$
\begin{equation*}
\left|\int_{\mathbb{R}} \eta_{\varepsilon}(y) w\left(t_{+}, x\right) Q_{\tilde{c}}(\tilde{y}) d x\right| \leq K \varepsilon^{10}+K\left\|w\left(t_{+}\right)\right\|_{H^{1}(\mathbb{R})}(|\Delta c(t)|+|\Delta \rho(t)|) \tag{4.17}
\end{equation*}
$$

and from (2.15) and item3in Proposition3.3, similar estimates hold for $\left|\int_{\mathbb{R}} \eta_{\varepsilon}(y) w\left(t_{+}, x\right) \tilde{y} Q_{\tilde{c}}(\tilde{y}) d x\right|$, $\left|\int_{\mathbb{R}} \tilde{\eta}_{\varepsilon}(\tilde{y}) \tilde{w}(t, x) Q_{\tilde{c}}(\tilde{y}) d x\right|$, and $\left|\int_{\mathbb{R}} \tilde{\eta}_{\varepsilon}(\tilde{y}) \tilde{w}(t, x) \tilde{y} Q_{\tilde{c}}(\tilde{y}) d x\right|$. Finally, from (2.21) one has

$$
\begin{equation*}
\left|\int_{\mathbb{R}} z(t, x) Q_{\tilde{c}}(\tilde{y}) d x\right| \leq K\|z(t)\|_{H^{1}(\mathbb{R})}(|\Delta c(t)|+|\Delta \rho(t)|) \tag{4.18}
\end{equation*}
$$

and the same result is valid for the integration against $\tilde{y} Q_{\tilde{c}}$. Now we conclude. Integrating (4.15) against $Q_{\tilde{c}}$ and $\tilde{y} Q_{\tilde{c}}$, and using (4.2), (2.21), (3.15), and (4.16)-(4.18), we finally obtain (4.14).

## 5. Propagation of the defect

Now, we suppose $m=2$ or $m=4$. In the following lines, we introduce two quantities, $J(t)$ and $\tilde{J}(t)$, with small variation in time, and such that the defect clearly appears in the dynamics. Let us define

$$
\begin{array}{ll}
\chi_{c}(t, x):=\int_{-\infty}^{y} \Lambda Q_{c}(s) d s, & e(t):=\left(3 \lambda_{0} c(t)-\lambda\right) \frac{\tilde{a}(\varepsilon \rho(t))}{2 \theta c^{2 \theta-1}(t) M[Q]} \\
\tilde{\chi}_{\tilde{c}}(t, x):=\int_{\tilde{y}}^{+\infty} \Lambda Q_{\tilde{c}}(s) d s, & \tilde{e}(t):=\left(3 \lambda_{0} \tilde{c}(t)-\lambda\right) \frac{\tilde{a}(\varepsilon \tilde{\rho}(t))}{2 \theta \tilde{c}^{2 \theta-1}(t) M[Q]} . \tag{5.2}
\end{array}
$$

It is clear that $\chi_{c}$ remains bounded as $y \rightarrow+\infty$, and it is exponentially decreasing as $y \rightarrow-\infty$. Similarly, $\tilde{\chi}_{\tilde{c}}$ has the opposite behavior as $\tilde{y} \rightarrow \pm \infty$. Finally, let us recall the notation introduced in (3.6) and Proposition 3.4. Consider the functionals

$$
J(t):=e(t) \int_{\mathbb{R}} \chi_{c}(t, x) z(t, x) d x, \quad \text { and } \quad \tilde{J}(t):=\tilde{e}(t) \int_{\mathbb{R}} \tilde{\chi}_{\tilde{c}}(t, x) \tilde{z}(t, x) d x
$$

Lemma 5.1. The functionals $J(t)$ and $\tilde{J}(t)$ are well defined for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, and they satisfy

$$
\begin{equation*}
|J(t)|+|\tilde{J}(t)| \leq K \varepsilon^{1 / 4} \tag{5.3}
\end{equation*}
$$

Proof. We only prove the estimate for $J(t)$, being the estimate for $\tilde{J}(t)$ similar (see Remark 5.1 below).

Let $y_{0}>0$ be a large number, independent of $\varepsilon$, to be chosen later. Note that $\chi_{c}(y)$, with $y=x-\rho(t)$, is an exponentially decreasing function as $y \rightarrow-\infty$. From (2.21) and the CauchySchwarz inequality, one has

$$
\left|\int_{y \leq y_{0}} \chi_{c}(y) z(t, x) d x\right| \leq K y_{0} \varepsilon^{1 / 2}
$$

On the other hand, the region $\left\{y>y_{0}\right\}$ requires more care since $\chi_{c}$ does not converge to zero as $y \rightarrow+\infty$. Let us suppose by now that, for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right], z(t, x)$ enjoys the following exponential decay property:

$$
\begin{equation*}
|z(t, x)| \leq K \varepsilon^{1 / 4} e^{-\gamma(x-\rho(t))}, \quad x \geq \rho(t)+y_{0} \tag{5.4}
\end{equation*}
$$

for some $K, \gamma>0$, independent of $\varepsilon$. This implies that

$$
\left|\int_{y>y_{0}} \chi_{c}(y) z(t, x) d x\right| \leq K e^{-\gamma y_{0}} \varepsilon^{1 / 4}
$$

These two inequalities imply (5.3), since $y_{0}>0$ does not depend on $\varepsilon$ small.

Note that (5.4) is consequence of (2.21), the following Gagliardo-Nirenberg inequality

$$
|z(t, y+\rho(t))| \leq\|z(t, \cdot+\rho(t))\|_{L^{2}(\cdot \geq y)}^{1 / 2}\left\|z_{x}(t, \cdot+\rho(t))\right\|_{L^{2}(\mathbb{R})}^{1 / 2} \leq K \varepsilon^{1 / 4}\|z(t, \cdot+\rho(t))\|_{L^{2}(\cdot \geq y)}^{1 / 2}
$$

and provided we prove that, for some $K, \gamma>0$, and for all $y \geq y_{0}$,

$$
\begin{equation*}
\|z(t, \cdot+\rho(t))\|_{L^{2}(\cdot \geq y)}^{1 / 2} \leq K e^{-\gamma y} \tag{5.5}
\end{equation*}
$$

The proof of this last estimate is a consequence of the following estimate (see e.g. [27, Lemma 7.3] for a similar result):

Lemma 5.2. There exist $K, \gamma, y_{0}>0$, independent of $\varepsilon$, such that for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, and for all $y \geq y_{0}$,

$$
\begin{equation*}
\|u(t, \cdot+\rho(t))\|_{L^{2}(\cdot \geq y)}^{2} \leq K e^{-\gamma y} \tag{5.6}
\end{equation*}
$$

Proof. The proof of this result can be divided in two steps.
Step one. Reduction to the case $\left(-\infty,-T_{\varepsilon}\right)$. From (2.23), there exists $\sigma_{1}, \sigma_{2}, \sigma_{3} \in \mathbb{R}$ such that $-\lambda<\sigma_{1}<\sigma_{2}<\sigma_{3}<\inf _{t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]} \rho^{\prime}(t)$, independent of $\varepsilon$. Indeed, using (2.6) and the fact that $C(t)>0$ uniformly in $\varepsilon$,

$$
\begin{equation*}
\rho^{\prime}(t)=c(t)-\lambda+O(\varepsilon)>0.9 \inf _{t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]} C(t)-\lambda>-\lambda . \tag{5.7}
\end{equation*}
$$

Then it is clear that we can find such numbers. Suppose $y_{0}>0$ large, but fixed, to be chosen later, $s, t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, with $s \leq t$. Consider the modified mass

$$
\begin{equation*}
\tilde{I}_{t, y_{0}}(s):=\frac{1}{2} \int_{\mathbb{R}} a^{1 / m}(\varepsilon x) u^{2}(s, x) \phi(\ell) d x \tag{5.8}
\end{equation*}
$$

with $\ell=\ell(s, t):=x-\left(\rho(t)+\sigma_{1}(s-t)+y_{0}\right)$ and $\phi(\ell):=\frac{2}{\pi} \arctan \left(e^{\ell / K_{0}}\right)$, with $K_{0}>0$ large to be chosen below. From the definition of $\sigma_{3}$, we have

$$
\begin{equation*}
\rho(t)-\rho(s)-\sigma_{3}(t-s) \geq 0 \tag{5.9}
\end{equation*}
$$

Let us consider now (5.8). We claim that for $y_{0}>0$ large but arbitrary,

$$
\begin{equation*}
\tilde{I}_{t, y_{0}}(t)-\tilde{I}_{t, y_{0}}\left(-T_{\varepsilon}\right) \leq K e^{-y_{0} / K}\left(1-e^{-\left(T_{\varepsilon}+t\right) / K}\right) . \tag{5.10}
\end{equation*}
$$

Indeed, a direct computation gives

$$
\begin{aligned}
\frac{1}{2} \partial_{s} \int_{\mathbb{R}} a^{1 / m}(\varepsilon x) \phi u^{2}= & -\frac{3}{2} \int_{\mathbb{R}} a^{1 / m} \phi^{\prime} u_{x}^{2}+\frac{m}{m+1} \int_{\mathbb{R}} a^{1 / m+1}(\varepsilon x) \phi^{\prime} u^{m+1} \\
& +\frac{1}{2} \int_{\mathbb{R}} u^{2} a^{1 / m}(\varepsilon x)\left[-(\sigma+\lambda) \phi^{\prime}+\phi^{(3)}\right] \\
& -\frac{3}{2} \varepsilon \int_{\mathbb{R}}\left(a^{1 / m}\right)^{\prime}(\varepsilon x) \phi u_{x}^{2}-\frac{\varepsilon}{2} \int_{\mathbb{R}} u^{2}\left[\lambda\left(a^{1 / m}\right)^{\prime}-\varepsilon^{2}\left(a^{1 / m}\right)^{(3)}\right](\varepsilon x) \phi \\
& +\frac{3}{2} \varepsilon \int_{\mathbb{R}} u^{2}\left[\varepsilon\left(a^{1 / m}\right)^{(2)}(\varepsilon x) \phi^{\prime}+\left(a^{1 / m}\right)^{\prime}(\varepsilon x) \phi^{\prime \prime}\right]
\end{aligned}
$$

In the last computation we have clearly defined six terms. Let us study in detail each one. In what follows we use the decomposition $u=\tilde{u}+z$, given by Proposition 2.3,

First of all, one has

$$
\int_{\mathbb{R}} \phi^{\prime} a^{1 / m} u_{x}^{2}=\int_{\mathbb{R}} \phi^{\prime} a^{1 / m}\left(\tilde{u}_{x}^{2}+2 \tilde{u}_{x} z_{x}+z_{x}^{2}\right)
$$

Recall from Proposition 2.2 that $\tilde{u}(s, x)$ is exponentially decreasing in the region $x \geq \rho(s)$, independent of $\varepsilon$. Moreover, it is zero for $x \leq \rho(s)-\frac{3}{\varepsilon}$. On the other hand, $\phi^{\prime}$ is exponentially decreasing away from zero. Therefore, one has e.g.

$$
\begin{aligned}
\left|\int_{\mathbb{R}} a^{1 / m} \phi^{\prime} \tilde{u}_{x}^{2}\right| & \leq K \int_{\rho(s)-\frac{3}{\varepsilon}}^{\rho(t)+\sigma_{2}(s-t)+\frac{1}{2} y_{0}} e^{\ell / K} d x+K \int_{\rho(t)+\sigma_{2}(s-t)+\frac{1}{2} y_{0}}^{\infty} e^{-\frac{1}{K}(x-\rho(s))} d x \\
& \leq K e^{-\frac{1}{K}\left(\left(\sigma_{2}-\sigma_{1}\right)(t-s)+\frac{1}{2} y_{0}\right)}+K e^{-\frac{1}{K}\left(\rho(t)-\rho(s)-\sigma_{2}(t-s)+\frac{1}{2} y_{0}\right)} \\
& \leq K e^{-y_{0} / K} e^{-(t-s) / K}+K e^{-\frac{1}{K}\left(\left(\sigma_{3}-\sigma_{2}\right)(t-s)+\frac{1}{2} y_{0}\right)} \leq K e^{-y_{0} / K} e^{-(t-s) / K}
\end{aligned}
$$

for some $K>0$, and where we have used (5.9). The same method con be applied to the term $\int_{\mathbb{R}} \phi^{\prime} \tilde{u}_{x} z_{x}$. Hence, one has

$$
\int_{\mathbb{R}} a^{1 / m} \phi^{\prime} u_{x}^{2}=\int_{\mathbb{R}} a^{1 / m} \phi^{\prime} z_{x}^{2}+O\left(e^{-y_{0} / K} e^{-(t-s) / K}\right)
$$

Similarly, since $u=\tilde{u}+z$,

$$
\begin{aligned}
\left|\int_{\mathbb{R}} a^{1 / m+1} \phi^{\prime} u^{m+1}\right| & \leq K\left|\int_{\mathbb{R}} \phi^{\prime} \tilde{u}^{m+1}\right|+K \varepsilon^{(m-1) / 2} \int_{\mathbb{R}} a^{1 / m} \phi^{\prime} z^{2} \\
& \leq K e^{-(t-s) / K} e^{-x_{0} / K}+K \varepsilon^{(m-1) / 2} \int_{\mathbb{R}} a^{1 / m} \phi^{\prime} z^{2}
\end{aligned}
$$

On the other hand, since $\sigma+\lambda>0$, taking $K_{0}>0$ large if necessary,

$$
\int_{\mathbb{R}} a^{1 / m} u^{2}\left[-(\sigma+\lambda) \phi^{\prime}+\phi^{(3)}\right]=-\frac{1}{2}(\sigma+\lambda) \int_{\mathbb{R}} a^{1 / m} \phi^{\prime} z^{2}+O\left(e^{-y_{0} / K} e^{-(t-s) / K}\right)
$$

and

$$
-\frac{3}{2} \varepsilon \int_{\mathbb{R}}\left(a^{1 / m}\right)^{\prime}(\varepsilon x) \phi u_{x}^{2}-\frac{\varepsilon}{2} \int_{\mathbb{R}} u^{2}\left[\lambda\left(a^{1 / m}\right)^{\prime}-\varepsilon^{2}\left(a^{1 / m}\right)^{(3)}\right](\varepsilon x) \phi \leq 0
$$

provided $\varepsilon$ is small. Finally,

$$
\left|\frac{3}{2} \varepsilon \int_{\mathbb{R}}\left[\varepsilon\left(a^{1 / m}\right)^{(2)}(\varepsilon x) \phi^{\prime}+\left(a^{1 / m}\right)^{\prime}(\varepsilon x) \phi^{\prime \prime}\right] u^{2}\right| \leq K \varepsilon e^{-(t-s) / K} e^{-y_{0} / K}+K \varepsilon \int_{\mathbb{R}} a^{1 / m} \phi^{\prime} z^{2}
$$

After these estimates, it is easy to conclude that

$$
\frac{1}{2} \partial_{t} \int_{\mathbb{R}} a^{1 / m}(\varepsilon x) \phi(y) u^{2} \leq K e^{-y_{0} / K} e^{-(t-s) / K}
$$

Therefore, estimate (5.10) follows after integration in time.
Step two. Estimate in $\left(-\infty,-T_{\varepsilon}\right)$. Now we perform the same computation as above, but now inside the interval $\left(-\infty,-T_{\varepsilon}\right)$. Indeed, it is not difficult to show that, for $t_{0} \leq-T_{\varepsilon} \leq t$,

$$
\begin{equation*}
\tilde{I}_{t, y_{0}}\left(-T_{\varepsilon}\right)-\tilde{I}_{t, y_{0}}\left(t_{0}\right) \leq K e^{-y_{0} / K}\left(1-e^{-\left(t-t_{0}\right) / K}\right) \tag{5.11}
\end{equation*}
$$

The final conclusion comes from the fact that $\lim _{t_{0} \rightarrow-\infty} \tilde{I}_{t, y_{0}}\left(t_{0}\right)=0$, as a consequence of (1.10). Collecting (5.10) and (5.11), we get

$$
\tilde{I}_{t, y_{0}}(t) \leq K e^{-y_{0} / K}
$$

The proof of (5.6) is complete.
Let us conclude the proof of (5.5). From (2.21) and (5.6) one has

$$
\int_{y+\rho(t)}^{+\infty}\left[\tilde{u}^{2}+2 \tilde{u} z+z^{2}\right](t, x) d x \leq K e^{-\gamma y}
$$

Now we use the main properties of the decomposition of the function $\tilde{u}$, sated in Proposition 2.2, One has, for $x \geq y+\rho(t), y \geq y_{0}>0$ large,

$$
\begin{equation*}
|\tilde{u}(t, x)| \leq K\left|Q_{c}(x-\rho(t))+\varepsilon d(t) A_{c}(x-\rho(t))\right| \leq K e^{-\gamma(x-\rho(t))} \tag{5.12}
\end{equation*}
$$

for some constants $K, \gamma>0$, independent of $\varepsilon$. Note that the fact that $A_{c}$ is exponentially decreasing for $x \geq \rho(t)+y_{0}$ is essential. Therefore, we finally get (5.5):

$$
\int_{y+\rho(t)}^{+\infty} z^{2}(t, x) d x \leq K e^{-\gamma y}
$$

Remark 5.1. Let us remark that the proof in the case of $\tilde{J}(t)$ is quite similar, with some basic changes. We need exponential decay of $\tilde{z}(t, x)$ on the left side. Second, instead of $\phi$ one has to consider the function $1-\phi$, supported on the left side of the soliton, and since $\tilde{A}_{\tilde{c}}$ is exponentially decreasing for $x<\tilde{\rho}(t)$, estimate (5.12) holds for $\tilde{v}(t, x)$ in the region $x \leq y+\tilde{\rho}(t), y \leq-y_{0}<0$ large.

Since $J(t)$ and $\tilde{J}(t)$ are well-defined, we can compute and estimate its variation in time.
Lemma 5.3. The functionals $J(t)$ and $\tilde{J}(t)$ satisfy, for some constants $K, \gamma>0$, and for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$,

$$
\begin{equation*}
\left|J^{\prime}(t)+\rho_{1}^{\prime}(t)\left(3 \lambda_{0} c(t)-\lambda\right)\right| \leq K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)+K \varepsilon^{5 / 4}+K\left|c_{1}^{\prime}(t)\right| \tag{5.13}
\end{equation*}
$$

and similarly for $\tilde{J}^{\prime}(t)$ :

$$
\begin{equation*}
\left|\tilde{J}^{\prime}(t)-\tilde{\rho}_{1}^{\prime}(t)\left(3 \lambda_{0} \tilde{c}(t)-\lambda\right)\right| \leq K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|\tilde{y}|} \tilde{z}^{2}(t)+K \varepsilon^{5 / 4}+K\left|\tilde{c}_{1}^{\prime}(t)\right| \tag{5.14}
\end{equation*}
$$

Proof. Let us prove (5.13). We compute:

$$
\begin{aligned}
J^{\prime}(t)= & e^{\prime} \int_{\mathbb{R}} \chi_{c} z+e \int_{\mathbb{R}} \chi_{c} z_{t}-\rho^{\prime} e \int_{\mathbb{R}} \Lambda Q_{c} z+c^{\prime} e \int_{\mathbb{R}} \partial_{c} \chi_{c} z \\
= & e^{\prime} \int_{\mathbb{R}} \chi_{c} z+e \int_{\mathbb{R}} \Lambda Q_{c}\left\{z_{x x}-c z+a(\varepsilon x)\left[(\tilde{u}+z)^{m}-\tilde{u}^{m}\right]\right\}-\rho_{1}^{\prime} e \int_{\mathbb{R}} \Lambda Q_{c} z+c_{1}^{\prime} e \int_{\mathbb{R}} \partial_{c} \chi_{c} z \\
& +\varepsilon f_{1} e \int_{\mathbb{R}} \partial_{c} \chi_{c} z-\varepsilon f_{2} e \int_{\mathbb{R}} \Lambda Q_{c} z-c_{1}^{\prime} e \int_{\mathbb{R}} \chi_{c} \partial_{c} \tilde{u}-e \int_{\mathbb{R}} \chi_{c} \tilde{S}[\tilde{u}]-\rho_{1}^{\prime} e \int_{\mathbb{R}} \chi_{c} \partial_{\rho} \tilde{u} .
\end{aligned}
$$

Notice that we have used (2.22). In the following lines, we estimate each term above. First of all, from (5.1), (2.21) and (2.24),

$$
\left|e^{\prime}(t)\right| \leq K\left|c^{\prime}(t)\right|+K\left|a^{\prime}(\varepsilon \rho) \varepsilon \rho^{\prime}(t)\right| \leq K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}+K\left|c_{1}^{\prime}(t)\right| \leq K \varepsilon
$$

From here, we get $\left|e^{\prime} \int_{\mathbb{R}} \chi_{c} z\right| \leq K \varepsilon^{5 / 4}$. Using (2.21) and the identity $\mathcal{L} \Lambda Q_{c}:=-\left(\Lambda Q_{c}\right)^{\prime \prime}+c \Lambda Q_{c}-$ $m Q_{c}^{m-1} \Lambda Q_{c}=-Q_{c}$, we have

$$
\begin{aligned}
& \left|e \int_{\mathbb{R}} \Lambda Q_{c}\left\{z_{x x}-c z+a(\varepsilon x)\left[(\tilde{u}+z)^{m}-\tilde{u}^{m}\right]\right\}\right| \leq \\
& \quad \leq\left|e \int_{\mathbb{R}} \Lambda Q_{c}\left\{\mathcal{L} z+m\left[a(\varepsilon x) \tilde{u}^{m-1}-Q_{c}^{m-1}\right] z\right\}\right|+\left|e \int_{\mathbb{R}} \Lambda Q_{c} a(\varepsilon x)\left[(\tilde{u}+z)^{m}-\tilde{u}^{m}-m \tilde{u}^{m-1} z\right]\right| \\
& \quad \leq K \varepsilon\|z(t)\|_{H^{1}(\mathbb{R})}+K \int_{\mathbb{R}} e^{-\sqrt{c}|y|} z^{2}(t) \leq K \varepsilon^{3 / 2}+K \int_{\mathbb{R}} e^{-\sqrt{c}|y|} z^{2}(t) .
\end{aligned}
$$

On the other hand, from (2.23),

$$
\begin{aligned}
\left|\rho_{1}^{\prime} e \int_{\mathbb{R}} \Lambda Q_{c} z\right| & \leq K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)+K\left(\varepsilon e^{-\varepsilon \gamma|\rho(t)|}+\|z(t)\|_{H^{1}(\mathbb{R})}^{2}+\|\tilde{S}[\tilde{u}](t)\|_{L^{2}(\mathbb{R})}\right)\|z(t)\|_{H^{1}(\mathbb{R})} \\
& \leq K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)+K \varepsilon^{3 / 2}
\end{aligned}
$$

Note that $\partial_{c} \chi_{c}=\int_{-\infty}^{y} \partial_{c} \Lambda Q_{c}$ has a similar asymptotic behavior as $\chi_{c}$. Therefore, from the first part,

$$
\left|\varepsilon f_{1} e \int_{\mathbb{R}} \partial_{c} \chi_{c} z\right|+\left|c_{1}^{\prime} e \int_{\mathbb{R}} \partial_{c} \chi_{c} z\right| \leq K \varepsilon^{5 / 4}
$$

Similarly, $\left|\varepsilon f_{2} e \int_{\mathbb{R}} \Lambda Q_{c} z\right| \leq K \varepsilon^{3 / 2}$. Let us recall that, from Proposition 2.2, $\tilde{u}$ is exponentially decreasing in $y$ as $y \rightarrow+\infty$, moreover $\tilde{u} \equiv 0$ for $y \leq-\frac{3}{\varepsilon}$. Since $\chi_{c}(y)$ is exponentially decreasing as $y \rightarrow-\infty$, one has, for some constant $\gamma>0$,

$$
\begin{aligned}
\left|c_{1}^{\prime} \int_{\mathbb{R}} \chi_{c} \partial_{c} \tilde{u}\right| & =\left|c_{1}^{\prime}\right|\left|\int_{y \geq-\frac{3}{\varepsilon}} \chi_{c}\left(\frac{1}{\tilde{a}} \Lambda Q_{c}+\varepsilon d(t) \partial_{c} A_{c}\right)\right| \\
& \leq K\left|c_{1}^{\prime}\right|\left|\int_{\mathbb{R}} \chi_{c} \chi_{c}^{\prime}\right|+K \varepsilon\left|c_{1}^{\prime}\right| \int_{-\frac{3}{\varepsilon}}^{0} e^{\gamma y}\left|\partial_{c} A_{c}(y)\right| d y+K \varepsilon\left|c_{1}^{\prime}\right| \int_{0}^{+\infty} e^{-\gamma y} d y+K \varepsilon^{10} \\
& \leq K\left|c_{1}^{\prime}\right|+K \varepsilon^{10}
\end{aligned}
$$

The term $\int_{\mathbb{R}} \chi_{c} \tilde{S}[\tilde{u}]$ can be treated similarly. Indeed, since $\chi_{c}$ is exponentially decreasing as $y \rightarrow-\infty$, one has from Step 7 in Appendix B of [28],

$$
\begin{aligned}
\left|\int_{\mathbb{R}} \chi_{c} \tilde{S}[\tilde{u}]\right| & \leq K \int_{-\frac{3}{\varepsilon}}^{0} e^{\gamma y}|\tilde{S}[\tilde{u}]|+K \int_{y \geq 0}|\tilde{S}[\tilde{u}]| \\
& \leq K e^{-\gamma / \varepsilon} e^{-\varepsilon \gamma|\rho(t)|}+K \varepsilon^{2} e^{-\varepsilon \gamma|\rho(t)|}+K \varepsilon^{3} \leq K \varepsilon^{2} e^{-\varepsilon \gamma|\rho(t)|}+K \varepsilon^{3} \leq K \varepsilon^{2} .
\end{aligned}
$$

The last estimate concerns the nonzero term $\rho_{1}^{\prime} e \int_{\mathbb{R}} \chi_{c} \partial_{\rho} \tilde{u}$. Here one has

$$
\begin{aligned}
\rho_{1}^{\prime} e \int_{\mathbb{R}} \chi_{c} \partial_{\rho} \tilde{u} & =\frac{\rho_{1}^{\prime} e}{\tilde{a}(\varepsilon \rho)} \int_{\mathbb{R}} \Lambda Q_{c} Q_{c}+\varepsilon \rho_{1}^{\prime} e \partial_{\rho} d(t) \int_{\mathbb{R}} \chi_{c} A_{c}(y)-\varepsilon \rho_{1}^{\prime} e d(t) \int_{\mathbb{R}} \chi_{c} A_{c}^{\prime}(y) \\
& =\rho_{1}^{\prime}\left(3 \lambda_{0} c-\lambda\right) c^{2 \theta}(2 \theta M[Q])^{-1} \int_{\mathbb{R}} \Lambda Q_{c} Q_{c}+O\left(\left|\rho_{1}^{\prime}\right| \varepsilon e^{-\varepsilon \gamma|\rho(t)|}\right) \\
& =\rho_{1}^{\prime}\left(3 \lambda_{0} c-\lambda\right)+O\left(\varepsilon^{3 / 2}\right)
\end{aligned}
$$

Finally, collecting the above estimates, we get, for some $\gamma>0$ independent of $\varepsilon>0$ small,

$$
\left|J^{\prime}(t)+\rho_{1}^{\prime}\left(3 \lambda_{0} c-\lambda\right)\right| \leq K \varepsilon^{5 / 4}+K \int_{\mathbb{R}} e^{-\gamma \sqrt{c}|y|} z^{2}(t)+K\left|c_{1}^{\prime}(t)\right|
$$

as desired. The proof of (5.14) is analogous, the minus sign is a consequence of (5.2).

## 6. Proof of Theorem 1.4, cases $m=2,4$

In this section we prove Theorem 1.4 in the non degenerate cases $m=2$ and 4 . For the sake of clarity, we divide the proof into several steps.
Step 1. Preliminaries. We will follow an argument by contradiction. Suppose that (1.16) do not hold; therefore for $\nu>0$ arbitrarily small, there is $T>T_{\varepsilon}$ arbitrarily large such that

$$
\begin{equation*}
\left\|w^{+}(T)\right\|_{H^{1}(\mathbb{R})} \leq \nu \varepsilon^{1+1 / 50} \tag{6.1}
\end{equation*}
$$

(cf. Theorem 1.2 for the definition of $w^{+}$and $\rho(t)$ ). Let us define $x_{0}=x_{0}(T):=\rho(T)-\left(c^{+}-\lambda\right) T$. From Proposition 3.1 we know that there exists a unique solution $v=v_{x_{0}}$ of (1.8) such that (3.1) is satisfied. Moreover, from (3.2), by taking $T$ larger if necessary, one has

$$
\|u(T)-v(T)\|_{H^{1}(\mathbb{R})} \leq 2 \nu \varepsilon^{1+1 / 50}
$$

Thanks to Lemma 4.1 with $\delta:=\frac{1}{50}$, there are a constant $K>0$ and a smooth function $\mathcal{T}(t) \in \mathbb{R}$, defined for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, such that

$$
\begin{equation*}
\|u(t+\mathcal{T}(t))-v(t)\|_{H^{1}(\mathbb{R})}+\left|\mathcal{T}^{\prime}(t)\right| \leq K \nu \varepsilon^{1+1 / 50} \tag{6.2}
\end{equation*}
$$

Now we assume that $\mathcal{T}(t)$ is a small perturbation of $T_{\varepsilon}$ inside the interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, in the sense that

$$
|\mathcal{T}(t)| \leq K^{*} \varepsilon^{-1 / 2-1 / 100}, \quad\left|\mathcal{T}\left(\tilde{T}_{\varepsilon}\right)\right| \leq K \varepsilon^{-1 / 2-1 / 100}
$$

where $K^{*}>0$ is a large constant, to be chosen later, and $0<K<K^{*}$ is independent of $K^{*}$. Therefore Lemma 4.2 makes sense with no modifications. Moreover, from Propositions 2.3 and 3.4) and (2.25), one has for $X_{0}:=\left(c^{+}-\lambda\right) \tilde{T}_{\varepsilon}+x_{0}(T)-P\left(\tilde{T}_{\varepsilon}\right)$,

$$
\left|X_{0}\right| \leq K\left|P^{\prime}\left(\tilde{T}_{\varepsilon}\right)\right|\left|\mathcal{T}\left(\tilde{T}_{\varepsilon}\right)\right|+\left|P\left(\tilde{T}_{\varepsilon}+\mathcal{T}\left(\tilde{T}_{\varepsilon}\right)\right)-\left(c^{+}-\lambda\right) \tilde{T}_{\varepsilon}-x_{0}(T)\right| \leq K \varepsilon^{-1 / 2-1 / 100}
$$

Note that we can apply Lemma 3.2. As a consequence, we improve our previous assumption:
Lemma 6.1 (Bootstrap). For all $\varepsilon>0$ small, the function $\mathcal{T}(t)$ satisfies $|\mathcal{T}(t)| \leq \frac{1}{2} K^{*} \varepsilon^{-1 / 2-1 / 100}$ in the interval $\left[-T_{\varepsilon}, T_{\varepsilon}\right]$.

Proof. We prove this result in the most difficult case, namely $\tilde{\lambda}<\lambda<1$. The case $0<\lambda<\tilde{\lambda}$ follows easily. Suppose that $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, but $\left|t-t_{0}\right| \geq \frac{\alpha}{\varepsilon}$, with $t_{0}$ given by Lemma 2.1] and $\alpha>0$ small, independent of $\varepsilon$. Then, from (4.14), (2.25), (3.19) and (3.9),

$$
\begin{aligned}
|\rho(t+\mathcal{T}(t))-\rho(t)| & \leq|\Delta \rho(t)|+|\tilde{\rho}(t)-\tilde{P}(t)|+|\tilde{P}(t)-P(t)|+|P(t)-\rho(t)| \\
& \leq K \nu \varepsilon^{1+1 / 50}+K \varepsilon^{-1 / 2-1 / 100}+|P(t)-\tilde{P}(t)| \leq K \varepsilon^{1 / 2-1 / 100}
\end{aligned}
$$

A direct computation shows that, outside the interval $\left[t_{0}-\frac{\alpha}{\varepsilon}, t_{0}+\frac{\alpha}{\varepsilon}\right]$, one has $|C(t)-\lambda|>\kappa \alpha$, for some $\kappa>0$ independent of $\varepsilon$. Therefore, from (2.23) and (2.25),

$$
\left|\rho^{\prime}(t)\right| \geq|c(t)-\lambda|-K \varepsilon^{1 / 2} \geq|C(t)-\lambda|-K \varepsilon^{1 / 2} \geq \kappa \alpha / 2
$$

Finally, from the lower bound $|\rho(t+\mathcal{T}(t))-\rho(t)| \geq \frac{1}{2} \kappa \alpha|\mathcal{T}(t)|$, we get $|\mathcal{T}(t)| \leq K(\alpha) \varepsilon^{1 / 2-1 / 100}$. Now we consider the estimate of $\mathcal{T}(t)$ inside the interval $\left[t_{0}-\frac{\alpha}{\varepsilon}, t_{0}+\frac{\alpha}{\varepsilon}\right]$. Since $\left|\mathcal{T}\left(t_{0}-\frac{\alpha}{\varepsilon}\right)\right| \leq$ $K \varepsilon^{-1 / 2-1 / 100}$, integrating (6.2), we get

$$
|\mathcal{T}(t)| \leq K \nu \varepsilon^{1 / 100}+K \varepsilon^{-1 / 2-1 / 100} \leq K \varepsilon^{-1 / 2-1 / 100}
$$

By taking $K^{*}>2 K$, we can conclude. We are done.
We have proved that $|\mathcal{T}(t)|$ is small, compared with $T_{\varepsilon}$, in the interaction region. This means that, by performing a suitable translation in time, we can assume, without loss of generality, that $\mathcal{T}\left(-T_{\varepsilon}\right)=0$, and the arguments below do not change.
Step 2. Integration in time. Using (6.2) and (2.4), we get, for $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$,

$$
|\mathcal{T}(t)| \leq \int_{-T_{\varepsilon}}^{t}\left|\mathcal{T}^{\prime}(s)\right| d s \leq K \nu \varepsilon^{1 / 100}
$$

and thus from (4.13), (4.14), (2.23) and (2.24),

$$
\left\{\begin{array}{l}
|c(t)-\tilde{c}(t)| \leq|c(t)-c(t+\mathcal{T}(t))|+|c(t+\mathcal{T}(t))-\tilde{c}(t)| \leq K \nu \varepsilon^{1+1 / 100}  \tag{6.3}\\
|\rho(t)-\tilde{\rho}(t)| \leq|\rho(t)-\rho(t+\mathcal{T}(t))|+|\rho(t+\mathcal{T}(t))-\tilde{\rho}(t)| \leq K \nu \varepsilon^{1 / 100}
\end{array}\right.
$$

Now we consider (5.13) and (5.14). Adding both inequalities, we have

$$
\begin{align*}
& \left|J^{\prime}(t)+\tilde{J}^{\prime}(t)+\rho_{1}^{\prime}(t)\left(3 \lambda_{0} c(t)-\lambda\right)-\tilde{\rho}_{1}^{\prime}(t)\left(3 \lambda_{0} \tilde{c}(t)-\lambda\right)\right| \\
& \quad \leq K \int_{\mathbb{R}}\left(e^{-\gamma \sqrt{c}|y|} z^{2}(t)+e^{-\gamma \sqrt{c}|\tilde{c}|} \tilde{z}^{2}(t)\right)+K \varepsilon^{5 / 4}+K\left(\left|c_{1}^{\prime}(t)\right|+\left|\tilde{c}_{1}^{\prime}(t)\right|\right) \tag{6.4}
\end{align*}
$$

Now we integrate between $-T_{\varepsilon}$ and $\tilde{T}_{\varepsilon}$. Using the Virial estimates (2.29) and (3.21) for $A_{0}$ large enough, one obtains

$$
\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \int_{\mathbb{R}}\left(e^{-\gamma \sqrt{c}|y|} z^{2}(t)+e^{-\gamma \sqrt{\tilde{c}}|\tilde{y}|} \tilde{z}^{2}(t)\right) d x d t \leq K \varepsilon^{3 / 2-1 / 100}
$$

and similarly $\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}}\left(\left|c_{1}^{\prime}(t)\right|+\left|\tilde{c}_{1}^{\prime}(t)\right|\right) d t \leq K \varepsilon^{3 / 2-1 / 100}$ (see e.g. (2.31)). On the other hand, from (5.3),

$$
\left|\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}}\left(J^{\prime}(t)+\tilde{J}^{\prime}(t)\right) d t\right| \leq|J(t)|+\left|J\left(-T_{\varepsilon}\right)\right|+|\tilde{J}(t)|+\left|\tilde{J}\left(-T_{\varepsilon}\right)\right| \leq K \varepsilon^{1 / 4}
$$

Hence, from (6.4), (6.3) and (2.23),

$$
\left|\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}}\left(\rho_{1}^{\prime}(t)-\tilde{\rho}_{1}^{\prime}(t)\right)\left(3 \lambda_{0} c(t)-\lambda\right) d t\right| \leq K \varepsilon^{1 / 4-1 / 100}+K \nu \varepsilon^{1 / 2}
$$

In addition, using (6.3),

$$
\left|\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}}\left(\rho_{1}^{\prime}(t)-\tilde{\rho}_{1}^{\prime}(t)\right)\left(3 \lambda_{0} c(t)-\lambda\right) d t\right| \geq c_{m}\left|\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \varepsilon\left(f_{2}(t)-\tilde{f}_{2}(t)\right)\left(3 \lambda_{0} c(t)-\lambda\right) d t\right|-K \nu
$$

We use (2.16), (3.13), and (6.3) to obtain

$$
\varepsilon\left|\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\left(3 \lambda_{0} c(t)-\lambda\right)^{2}}{c^{1 / 2}(t)} \frac{a^{\prime}(\varepsilon \rho(t))}{a(\varepsilon \rho(t))} d t\right| \leq K \varepsilon^{1 / 4-1 / 100}+K \nu
$$

Now we claim that the quantity in the left side is bounded below independent of $\nu$ and $\varepsilon$, which gives the contradiction, for $\varepsilon$ and $\nu$ small enough. Indeed, from (2.25), one has

$$
\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\left(3 \lambda_{0} c(t)-\lambda\right)^{2}}{c^{1 / 2}(t)} \frac{a^{\prime}(\varepsilon \rho(t))}{a(\varepsilon \rho(t))} d t=\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\left(3 \lambda_{0} C(t)-\lambda\right)^{2}}{C^{1 / 2}(t)} \frac{a^{\prime}(\varepsilon P(t))}{a(\varepsilon P(t))} d t+o_{\varepsilon}(\varepsilon) .
$$

First, we consider the case $\lambda=\lambda_{0}$. In this case, from Lemma 2.1 we have $C(t) \equiv 1$ and $P(t)=$ $\left(1-\lambda_{0}\right) t$. Then

$$
\begin{aligned}
\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\left(3 \lambda_{0} C(t)-\lambda\right)^{2}}{C^{1 / 2}(t)} \frac{a^{\prime}(\varepsilon P(t))}{a(\varepsilon P(t))} d t & =4 \lambda_{0}^{2} \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{a^{\prime}\left(\varepsilon\left(1-\lambda_{0}\right) t\right)}{a\left(\varepsilon\left(1-\lambda_{0}\right) t\right)} \varepsilon d t \\
& =\left.\frac{4 \lambda_{0}^{2}}{1-\lambda_{0}} \log a\left(\varepsilon\left(1-\lambda_{0}\right) t\right)\right|_{-T_{\varepsilon}} ^{\tilde{T}_{\varepsilon}}=\frac{4 \lambda_{0}^{2}}{1-\lambda_{0}} \log 2+o_{\varepsilon}(1) .
\end{aligned}
$$

It is clear that the last quantity is positive. Now we consider the general case, $\lambda \neq \lambda_{0}$. We have, from (2.2),

$$
\begin{align*}
\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\left(3 \lambda_{0} C(t)-\lambda\right)^{2}}{C^{1 / 2}(t)} \frac{a^{\prime}(\varepsilon P(t))}{a(\varepsilon P(t))} d t & =\frac{(5-m)}{4} \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\left(3 \lambda_{0} C(t)-\lambda\right)^{2}}{C^{3 / 2}(t)\left(\lambda_{0} C(t)-\lambda\right)} C^{\prime}(t) d t \\
& =\frac{(5-m)}{4} \int_{1}^{c_{\infty}} \frac{\left(3 \lambda_{0} c-\lambda\right)^{2}}{c^{3 / 2}\left(\lambda_{0} c-\lambda\right)} d c \tag{6.5}
\end{align*}
$$

Note that the term inside the integral has always the same sign, and it is not identically zero for $0<\lambda<1, \lambda \neq \lambda_{0}$. Since (6.5) is always non zero, independent of $\nu$ and $\varepsilon$, we get the final conclusion. The proof is complete.

## 7. The cubic case

Consider now the proof of Theorem 1.4 in the case $m=3$. This case is in some sense degenerate since $f_{2} \equiv 0$ in (2.16). Moreover, in this case $\chi_{c}(y)=\frac{1}{2} y Q_{c} \in \mathcal{S}(\mathbb{R})$ and from (2.21)-(3.15), one has that the functionals $J(t)$ and $\tilde{J}(t)$ are identically zero. This is the reason why we needed to improve the approximate solution $\tilde{u}(t)$ (cf. Proposition 2.2 and [28]) to obtain a nonzero defect in the solution. In this opportunity, a defect is given by the term $f_{3}(t) \neq 0$ in (2.17).

So, in order to prove the main result, instead of using the functionals $J(t)$ and $\tilde{J}(t)$, we consider the scaling laws (2.24) and (3.18). Indeed, we start out following the Step 1 as in the previous section. Then we arrive to the estimate

$$
\begin{equation*}
\|u(t+\mathcal{T}(t))-v(t)\|_{H^{1}(\mathbb{R})}+\left|\mathcal{T}^{\prime}(t)\right| \leq K \nu \varepsilon^{1+1 / 100} \tag{7.1}
\end{equation*}
$$

valid for all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$. Similarly, one has

$$
\begin{equation*}
|c(t)-\tilde{c}(t)| \leq K \nu \varepsilon^{1+1 / 100}, \quad|\rho(t)-\tilde{\rho}(t)| \leq K \nu \varepsilon^{1 / 100} \tag{7.2}
\end{equation*}
$$

Lemma 7.1. For all $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, one has

$$
\begin{gather*}
\left|c_{1}^{\prime}(t)-\tilde{c}_{1}^{\prime}(t)\right| \leq K \varepsilon^{5 / 2}+K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}\left[\int_{\mathbb{R}} e^{-\gamma|y|} z^{2}\right]^{1 / 2}+K \varepsilon e^{-\gamma \varepsilon|\tilde{\rho}(t)|}\left[\int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}\right]^{1 / 2} \\
+K \int_{\mathbb{R}} e^{-\gamma|y|} z^{2}+K \int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2} \tag{7.3}
\end{gather*}
$$

Let us assume the validity of this result and let us conclude the proof of Theorem 1.4 for the cubic case. From (7.3), (2.30) and (3.22) one has, after integration and using the Cauchy-Schwarz inequality,

$$
\left|\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}}\left(c_{1}^{\prime}(t)-\tilde{c}_{1}^{\prime}(t)\right) d t\right| \leq o_{\varepsilon}(\varepsilon) .
$$

Therefore, from (2.22), (3.16) and (7.2),

$$
\begin{equation*}
\left|\varepsilon^{2} \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} f_{3}(t) d t\right| \leq K \nu \varepsilon+o_{\varepsilon}(\varepsilon) \tag{7.4}
\end{equation*}
$$

Note that we have used (2.1) and (7.2) to obtain

$$
\left|\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}}\left(f_{1}(t)-\tilde{f}_{1}(t)\right) d t\right| \leq K \nu \varepsilon
$$

Coming back to (7.4), and using (2.17), one has

$$
\begin{equation*}
\left|\varepsilon^{2} \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{1}{\sqrt{c(t)}}(c(t)-\lambda) \frac{a^{\prime 2}(\varepsilon \rho(t))}{a^{2}(\varepsilon \rho(t))} d t\right| \leq K \nu \varepsilon+o_{\varepsilon}(\varepsilon) . \tag{7.5}
\end{equation*}
$$

In what follows, we split the proof in two cases.
First case: $0<\lambda<\tilde{\lambda}$. From (2.23)-(2.24),

$$
\begin{equation*}
\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{(c(t)-\lambda)}{\sqrt{c(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon \rho(t)) d t \geq \frac{9}{10 \sqrt{c_{\infty}(\lambda)}} \int_{-1}^{1} \frac{a^{\prime 2}}{a^{2}}(s) d s=: \kappa \tag{7.6}
\end{equation*}
$$

with $\kappa>0$ independent of $\varepsilon$. We get then $\tilde{\kappa} \varepsilon \leq K \nu \varepsilon+K \varepsilon^{3 / 2}$, for some positive constants $K, \tilde{\kappa}$. By taking $\nu$ small enough, we obtain the desired contradiction. This proves the result in the case $0<\lambda<\tilde{\lambda}$.
Second case: $\tilde{\lambda}<\lambda<1$. First of all, note that from (2.25), one has

$$
\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{(c(t)-\lambda)}{\sqrt{c(t)}} \frac{a^{2}}{a^{2}}(\varepsilon \rho(t)) d t=\varepsilon \int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{(C(t)-\lambda)}{\sqrt{C(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon P(t)) d t+o_{\varepsilon}(\varepsilon) .
$$

Now we split the time interval $\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$ into three disjoints subintervals, as in the proof of [28, Lemma 3.3]. Let $t_{0}$ be as in Lemma 2.1. We have, for $\alpha>0$ small, independent of $\varepsilon$,

$$
\begin{equation*}
\int_{-T_{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\varepsilon(C(t)-\lambda)}{\sqrt{C(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon P(t)) d t=\left[\int_{-T_{\varepsilon}}^{t_{0}-\frac{\alpha}{\varepsilon}}+\int_{t_{0}-\frac{\alpha}{\varepsilon}}^{t_{0}+\frac{\alpha}{\varepsilon}}+\int_{t_{0}+\frac{\alpha}{\varepsilon}}^{\tilde{T}_{\varepsilon}}\right] \frac{\varepsilon(C(t)-\lambda)}{\sqrt{C(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon P(t)) d t \tag{7.7}
\end{equation*}
$$

A simple computation shows that, inside the interval $\left[t_{0}-\frac{\alpha}{\varepsilon}, t_{0}+\frac{\alpha}{\varepsilon}\right]$,

$$
C(t)-\lambda=C\left(t_{0}\right)-\lambda+C^{\prime}\left(t_{0}\right)\left(t-t_{0}\right)+O\left(\varepsilon^{2}\left(t-t_{0}\right)^{2}\right)=O(\alpha)
$$

and thus,

$$
\left|\int_{t_{0}-\frac{\alpha}{\varepsilon}}^{t_{0}+\frac{\alpha}{\varepsilon}} \frac{\varepsilon(C(t)-\lambda)}{\sqrt{C(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon P(t)) d t\right| \leq \frac{K \alpha^{2}}{\sqrt{\lambda}} .
$$

Note that $\lambda>\tilde{\lambda}>0$. On the other hand,

$$
\int_{-T_{\varepsilon}}^{t_{0}-\frac{\alpha}{\varepsilon}} \frac{\varepsilon(C(t)-\lambda)}{\sqrt{C(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon P(t)) d t \leq \frac{1}{\sqrt{C\left(t_{0}-\frac{\alpha}{\varepsilon}\right)}} \int_{\varepsilon P\left(-T_{\varepsilon}\right)}^{\varepsilon P\left(t_{0}-\frac{\alpha}{\varepsilon}\right)} \frac{a^{\prime 2}}{a^{2}}(s) d s
$$

and

$$
\int_{t_{0}+\frac{\alpha}{\varepsilon}}^{\tilde{T}_{\varepsilon}} \frac{\varepsilon(C(t)-\lambda)}{\sqrt{C(t)}} \frac{a^{\prime 2}}{a^{2}}(\varepsilon P(t)) d t \leq-\frac{1}{\sqrt{C\left(t_{0}+\frac{\alpha}{\varepsilon}\right)}} \int_{\varepsilon P\left(\tilde{T}_{\varepsilon}\right)}^{\varepsilon P\left(t_{0}+\frac{\alpha}{\varepsilon}\right)} \frac{a^{\prime 2}}{a^{2}}(s) d s
$$

Recall that, by definition of $\tilde{T}_{\varepsilon}(\sqrt{2.3})$, one has $P\left(\tilde{T}_{\varepsilon}\right)=P\left(-T_{\varepsilon}\right)$. Moreover,

$$
\left|\int_{\varepsilon P\left(t_{0}+\frac{\alpha}{\varepsilon}\right)}^{\varepsilon P\left(t_{0}-\frac{\alpha}{\varepsilon}\right)} \frac{a^{\prime 2}}{a^{2}}(s) d s\right| \leq K \varepsilon\left[P\left(t_{0}-\frac{\alpha}{\varepsilon}\right)-P\left(t_{0}+\frac{\alpha}{\varepsilon}\right)\right] \leq K \alpha^{3},
$$

since $P^{\prime}\left(t_{0}\right)=C\left(t_{0}\right)-\lambda=0$ and $P^{(3)}(t)=C^{\prime \prime}(t)=O\left(\varepsilon^{2}\right)$. Therefore, we have for some $K>0$,

$$
\begin{aligned}
(7.7) & \leq-\left[\frac{1}{\sqrt{C\left(t_{0}+\frac{\alpha}{\varepsilon}\right)}}-\frac{1}{\sqrt{C\left(t_{0}-\frac{\alpha}{\varepsilon}\right)}}\right] \int_{\varepsilon P\left(-T_{\varepsilon}\right)}^{\varepsilon P\left(t_{0}-\frac{\alpha}{\varepsilon}\right)} \frac{a^{\prime 2}}{a^{2}}(s) d s+K \alpha^{2}+K \alpha^{3} \\
& \leq-K \alpha \int_{\varepsilon P\left(-T_{\varepsilon}\right)}^{\varepsilon P\left(t_{0}\right)} \frac{a^{\prime 2}}{a^{2}}(s) d s+K \alpha^{2}+K \alpha^{3} .
\end{aligned}
$$

Since $\left|\varepsilon P\left(t_{0}\right)\right| \leq K(\lambda)$ [28, estimate (3.7)], and $\varepsilon P\left(-T_{\varepsilon}\right)=-\varepsilon^{-1 / 100} \ll-K(\lambda)$, one has

$$
\text { (7.7) } \leq-K \alpha \int_{-K(\lambda)-1}^{-K(\lambda)} \frac{a^{\prime 2}}{a^{2}}(s) d s+K \alpha^{2}+K \alpha^{3} \leq-\tilde{K}(\lambda) \alpha<0,
$$

for some $\tilde{K}(\lambda)>0$, and $\alpha>0$ small, but independent of $\varepsilon$ and $\nu$. Replacing in (7.5), we get the desired contradiction, provided $\nu$ and $\varepsilon$ are small enough. The proof is complete.
Proof of Lemma 7.1. We start from the proof of [28, identity (4.47)], where, for each $t \in\left[-T_{\varepsilon}, \tilde{T}_{\varepsilon}\right]$, one has

$$
\begin{aligned}
c_{1}^{\prime} \int_{\mathbb{R}} Q_{c} \partial_{c} \tilde{u}= & -\int_{\mathbb{R}} Q_{c} \tilde{S}[\tilde{u}]-\rho_{1}^{\prime} \int_{\mathbb{R}} Q_{c} \partial_{\rho} \tilde{u}-\rho_{1}^{\prime} \int_{\mathbb{R}} Q_{c}^{\prime} z+c_{1}^{\prime} \int_{\mathbb{R}} \Lambda Q_{c} z-\varepsilon^{2} f_{4} \int_{\mathbb{R}} Q_{c}^{\prime} z \\
& +\varepsilon\left(f_{1}+\varepsilon f_{3}\right) \int_{\mathbb{R}} \Lambda Q_{c} z+\int_{\mathbb{R}} Q_{c}^{\prime} a(\varepsilon x)\left[3 \tilde{u} z^{2}+z^{3}\right]+3 \int_{\mathbb{R}} Q_{c}^{\prime}\left[a(\varepsilon x) \tilde{u}^{2}-Q_{c}^{2}\right] z .
\end{aligned}
$$

This expression leads to the bound (2.24) above. We also recall that a completely similar expression holds for $\tilde{c}_{1}(t)$. On the one hand, from (2.23) with $m=3$, and (2.20),

$$
\begin{equation*}
\left|\rho_{1}^{\prime}\right| \leq K \int_{\mathbb{R}} e^{-\gamma|y|} z^{2}(t)+K \varepsilon e^{-\varepsilon \gamma|\rho(t)|}\left[\int_{\mathbb{R}} e^{-\gamma|y|} z^{2}(t)\right]^{1 / 2}+K \varepsilon^{3}, \tag{7.8}
\end{equation*}
$$

and similarly for $\left|\tilde{\rho}_{1}^{\prime}\right|$. Now we compare both identities, using (7.8), to obtain,

$$
\begin{align*}
& c_{1}^{\prime}\left[\int_{\mathbb{R}} Q_{c} \partial_{c} \tilde{u}-\int_{\mathbb{R}} \Lambda Q_{c} z\right]-\tilde{c}_{1}^{\prime}\left[\int_{\mathbb{R}} Q_{\tilde{c}} \partial_{\tilde{c}} \tilde{v}-\int_{\mathbb{R}} \Lambda Q_{\tilde{c}} \tilde{z}\right]=-\int_{\mathbb{R}} Q_{c} \tilde{S}[\tilde{u}]+\int_{\mathbb{R}} Q_{\tilde{c}} \tilde{S}[\tilde{v}]  \tag{7.9}\\
&-\rho_{1}^{\prime}\left[\int_{\mathbb{R}} Q_{c} \partial_{\rho} \tilde{u}+\int_{\mathbb{R}} Q_{c}^{\prime} z\right]+\tilde{\rho}_{1}^{\prime}\left[\int_{\mathbb{R}} Q_{\tilde{c}} \partial_{\tilde{\rho}} \tilde{v}+\int_{\mathbb{R}} Q_{\tilde{c}}^{\prime} \tilde{z}\right]  \tag{7.10}\\
&+\varepsilon f_{1} \int_{\mathbb{R}} \Lambda Q_{c} z-\varepsilon \tilde{f}_{1} \int_{\mathbb{R}} \Lambda Q_{\tilde{c}} \tilde{z}  \tag{7.11}\\
&-\varepsilon^{2} f_{4} \int_{\mathbb{R}} Q_{c}^{\prime} z+\varepsilon^{2} \tilde{f}_{4} \int_{\mathbb{R}} Q_{\tilde{c}}^{\prime} \tilde{z}+\varepsilon^{2} f_{3} \int_{\mathbb{R}} \Lambda Q_{c} z-\varepsilon^{2} \tilde{f}_{3} \int_{\mathbb{R}} \Lambda Q_{\tilde{c}} \tilde{z}  \tag{7.12}\\
&+\int_{\mathbb{R}} Q_{c}^{\prime} a(\varepsilon x)\left[3 \tilde{u} z^{2}+z^{3}\right]-\int_{\mathbb{R}} Q_{\tilde{c}}^{\prime} a(\varepsilon x)\left[3 \tilde{v} \tilde{z}^{2}+\tilde{z}^{3}\right]  \tag{7.13}\\
&+3 \int_{\mathbb{R}} Q_{c}^{\prime}\left[a(\varepsilon x) \tilde{u}^{2}-Q_{c}^{2}\right] z-3 \int_{\mathbb{R}} Q_{\tilde{c}}^{\prime}\left[a(\varepsilon x) \tilde{v}^{2}-Q_{\tilde{c}]}^{2} \tilde{z} .\right. \tag{7.14}
\end{align*}
$$

We first deal with the right hand side of (7.9). Since $Q_{c}$ and $Q_{\tilde{c}}$ are Schwartz functions, we have from (2.20),

$$
\left|\int_{\mathbb{R}} Q_{c} \tilde{S}[\tilde{u}]-\int_{\mathbb{R}} Q_{\tilde{c}} \tilde{S}[\tilde{v}]\right| \leq K \varepsilon^{3} e^{-\varepsilon \gamma|\rho(t)|}+K \varepsilon^{4} .
$$

On the other hand,

$$
\begin{aligned}
\int_{\mathbb{R}} Q_{c} \partial_{\rho} \tilde{u} & =\int_{\mathbb{R}} Q_{c} \partial_{\rho}\left[\eta_{\varepsilon}(y)\left(\frac{Q_{c}(y)}{a^{1 / 2}(\varepsilon \rho)}+\varepsilon d(t) A_{c}(y)+\varepsilon^{2} B_{c}(t, y)\right)\right] \\
& =-\int_{\mathbb{R}} \eta_{\varepsilon} Q_{c}\left[\varepsilon a^{\prime}(\varepsilon \rho) \frac{Q_{c}(y)}{2 a^{3 / 2}(\varepsilon \rho)}+\frac{Q_{c}^{\prime}(y)}{a^{1 / 2}(\varepsilon \rho)}+\varepsilon d(t) A_{c}^{\prime}(y)\right]+O\left(\varepsilon^{2}\right)=O\left(\varepsilon e^{-\varepsilon \gamma|\rho(t)|}\right)+O\left(\varepsilon^{2}\right),
\end{aligned}
$$

and similarly with the term $\int_{\mathbb{R}} Q_{\tilde{c}} \partial_{\tilde{\rho}} \tilde{v}$. Therefore, from (7.8), we get

$$
|(\overline{7.10})| \leq K \varepsilon^{1 / 2} \int_{\mathbb{R}} e^{-\gamma|y|} z^{2}(t)+K \varepsilon^{1 / 2} \int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}(t)+K \varepsilon^{5 / 2}
$$

Now we deal with (7.11). We have

$$
\left|\varepsilon f_{1} \int_{\mathbb{R}} \Lambda Q_{c} z-\varepsilon \tilde{f}_{1} \int_{\mathbb{R}} \Lambda Q_{\tilde{c}} \tilde{z}\right| \leq K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}\left[\int_{\mathbb{R}} z^{2} e^{-\gamma|y|}\right]^{1 / 2}+K \varepsilon e^{-\gamma \varepsilon|\tilde{\rho}(t)|}\left[\int_{\mathbb{R}} \tilde{z}^{2} e^{-\gamma|\tilde{y}|}\right]^{1 / 2}
$$

The estimate of (7.12) is easy: from (2.21) and (3.15), one has $|(7.12)| \leq K \varepsilon^{5 / 2}$. Now we consider the terms in (7.13). We have

$$
\left|\int_{\mathbb{R}} Q_{c}^{\prime} a(\varepsilon x)\left[3 \tilde{u} z^{2}+z^{3}\right]-\int_{\mathbb{R}} Q_{\tilde{c}}^{\prime} a(\varepsilon x)\left[3 \tilde{v} \tilde{z}^{2}+\tilde{z}^{3}\right]\right| \leq K\left[\int_{\mathbb{R}} e^{-\gamma|y|} z^{2}+\int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}\right] .
$$

Since $\left\|a(\varepsilon x) \tilde{u}^{2}-Q_{c}^{2}\right\|_{L^{\infty}(\mathbb{R})} \leq K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}+K \varepsilon^{2}$, and similarly in the case of $\tilde{v}$, one has

$$
|(\overline{7.14})| \leq K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}\left[\int_{\mathbb{R}} e^{-\gamma|y|} z^{2}\right]^{1 / 2}+K \varepsilon e^{-\gamma \varepsilon|\rho(t)|}\left[\int_{\mathbb{R}} e^{-\gamma|\tilde{y}|} \tilde{z}^{2}\right]^{1 / 2}+K \varepsilon^{5 / 2}
$$

Finally, we deal with the left hand side of (17.9):

$$
\int_{\mathbb{R}} Q_{c} \partial_{c} \tilde{u}-\int_{\mathbb{R}} \Lambda Q_{c} z=2 \theta \frac{c^{2 \theta-1}(t)}{\tilde{a}(\varepsilon \rho(t))} \int_{\mathbb{R}} Q^{2}+O\left(\varepsilon^{1 / 2}\right) \geq k_{0}>0, \quad\left(\theta=\frac{1}{m-1}-\frac{1}{4}>0\right)
$$

Gathering the above estimates, we get finally (7.3).

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[^0]:    ${ }^{1}$ In this paper we will not do any distinction between soliton and solitary wave, unlike in the mathematicalphysics literature.

[^1]:    ${ }^{2}$ Note that, with no loss of generality, we have chosen the scaling parameter equals one.

[^2]:    ${ }^{3}$ We write $f_{j}=f_{j}(\varepsilon t)$ in order to emphasize the fact that we are working with slowly varying functions, but in the rigorous proof below we only use the notation $f_{j}(t)$.
    ${ }^{4}$ The existence of this property in the NLS case is an open problem, see [26].

[^3]:    ${ }^{5}$ More specifically, $f^{\prime}(C)=-(C-\lambda) C^{\lambda_{0}-1}\left(\frac{\lambda}{\lambda_{0}}-C\right)^{-\lambda_{0}}$.

