

Properties of sub-matrices of Sylvester matrices and triangular toeplitz matrices

Yousong Luo, Robin Hill and Uwe Schwerdtfeger

School of Mathematical and Geospatial Sciences,

RMIT University, GPO Box 2476V

Melbourne, Vic. 3001, AUSTRALIA

email: yluo@rmit.edu.au, r.hill@rmit.edu.au, u.schwerdtfeger@rmit.edu.au

Abstract

In this note we discover and prove some interesting and important relations among sub-matrices of Sylvester matrices and triangular toeplitz matrices. The main result is Hill's identity discovered by R. D. Hill which has an important application in optimal control problems.

1 Introduction

When studying the optimal state evolution of the dual state in a optimal control problem, R. Hill discovered an interesting relation (see Theorem 1.1) among the sub-matrices of Sylvester matrices and triangular toeplitz matrices, see [2] and [3] for details. If these relations holds then we can formulate the exact pattern how the modified states evolve. In such a sense, the result here is not only an interesting result in linear algebra but also has a direct significant impact in control theory.

We would like also to announce that we have an alternative proof for Theorem 1.1 using the tools given in [1] which is an entirely different approach.

We formulate the problems first. Define the following $m \times m$ lower and upper triangular matrices:

$$D_L := \begin{pmatrix} d_1 & 0 & \cdots & \cdots & 0 \\ d_2 & d_1 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ d_{m-1} & \ddots & \ddots & \ddots & 0 \\ d_m & d_{m-1} & \cdots & d_2 & d_1 \end{pmatrix} \quad D_U := \begin{pmatrix} d_{m+1} & d_m & \cdots & d_3 & d_2 \\ 0 & d_{m+1} & d_m & \cdots & d_3 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & d_m \\ 0 & \cdots & \cdots & 0 & d_{m+1} \end{pmatrix}$$

$$N_L := \begin{pmatrix} n_1 & 0 & \cdots & \cdots & 0 \\ n_2 & n_1 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ n_{m-1} & \ddots & \ddots & \ddots & 0 \\ n_m & n_{m-1} & \cdots & n_2 & n_1 \end{pmatrix} \quad N_U := \begin{pmatrix} n_{m+1} & n_m & \cdots & n_3 & n_2 \\ 0 & n_{m+1} & n_m & \cdots & n_3 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & n_m \\ 0 & \cdots & \cdots & 0 & n_{m+1} \end{pmatrix}$$

Consider the Sylvester matrix

$$S := \begin{pmatrix} D_L & N_L \\ D_U & N_U \end{pmatrix}$$

and the lower triangular matrix

$$D := \begin{pmatrix} D_L & 0 \\ D_U & D_L \end{pmatrix}.$$

The entries $d_1, d_2, \dots, d_m, d_{m+1}$ and $n_1, n_2, \dots, n_m, n_{m+1}$ are assumed to be nonzero real numbers such that both S and D are invertible. Under such an assumption we define

$$A := D^{-1} \quad B := S^{-1}.$$

If we use A_T and B_T to denote the matrices consisting of the first m rows of A and B , A_B and B_B the last m rows of A and B respectively, then we can write

$$A = \begin{pmatrix} A_T \\ A_B \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} B_T \\ B_B \end{pmatrix}.$$

The $m \times m$ sub-matrices of A_B consisting of the m consecutive columns of it and starting from the i th column is denoted by A_i . There are $m + 1$ of them:

$$A_1, A_2, \dots, A_m, A_{m+1}. \quad (1)$$

Similarly, the sub-matrices of B_B consisting of m consecutive columns of it and starting from the i th column is denoted by B_i :

$$B_1, B_2, \dots, B_m, B_{m+1}. \quad (2)$$

Our objective of this paper is to prove these relations, as well as discover and prove some other new relations among those sub-matrices. The main result is the following Hill's identity.

Theorem 1.1 *For $1 \leq i < j \leq m + 1$ we have*

$$A_i B_j = A_j B_i. \quad (3)$$

The other results are

Theorem 1.2 Assume that both S and D be invertible. Let A_i and B_j be the sub matrices defined in (1) and (2). Then, for all $i, j = 1, \dots, m + 1$, A_i and B_j are invertible and the following identities hold

$$A_i^{-1}A_j = B_i^{-1}B_j \quad (4)$$

or equivalently

$$A_jB_j^{-1} = A_iB_i^{-1}. \quad (5)$$

and

Theorem 1.3 For $1 \leq i < j \leq m + 1$ we have

$$B_i^{-1}B_j = B_jB_i^{-1}. \quad (6)$$

As we can easily see that Theorem 1.1 is a consequence of the combination of Theorem 1.2 and 1.3.

2 Proofs of the results

Now we introduce an $m \times 3m$ matrix

$$T := \left(\underbrace{-D_U D_L^{-1} \mid I_m}_{\text{augmentation bar}} \mid \overbrace{-D_L D_U^{-1}} \right) \quad (7)$$

where the symbol $|$ stands for an augmentation bar. This matrix T plays a very important role in the following argument through out this paper, so we call it “kernel”. The $m \times 2m$ sub-matrices of T consisting of the $2m$ consecutive columns of it and starting from the i th column is denoted by T_i and we have $m + 1$ such matrices:

$$T_1, T_2, \dots, T_m, T_{m+1}.$$

Obviously $T_1 = (-D_U D_L^{-1}, I_m)$ and $T_{m+1} = (I_m, -D_L D_U^{-1})$. Also, For each $i, j = 1, 2, \dots, m + 1$, the $m \times m$ sub-matrices of T_i consisting of the m consecutive columns of it and starting from the j th column is denoted by T_{ij} .

Lemma 2.1 If $K = \begin{pmatrix} D_L & 0 \\ D_U & D_L \\ 0 & D_U \end{pmatrix}$, then

$$TK = 0. \quad (8)$$

If $D_l = \begin{pmatrix} D_L \\ D_U \end{pmatrix}$, then for $i = 1, 2, \dots, m + 1$ we have

$$T_i D_l = 0. \quad (9)$$

Proof Obviously

$$\begin{aligned} TK &= \begin{pmatrix} -D_U D_L^{-1} & I_m & -D_L D_U^{-1} \end{pmatrix} \begin{pmatrix} D_L & 0 \\ D_U & D_L \\ 0 & D_U \end{pmatrix} \\ &= \begin{pmatrix} -D_U D_L^{-1} D_L + D_U & D_L - D_L D_U^{-1} D_U \end{pmatrix} = \begin{pmatrix} 0 & 0 \end{pmatrix}. \end{aligned}$$

This immediately implies, by considering the first m columns and the last m columns of TK , that

$$T_1 D_l = 0 \quad \text{and} \quad T_{m+1} D_l = 0. \quad (10)$$

For $1 < i < m+1$ let K_i be the m consecutive columns of K starting from the i th column. Then K_i is in the form

$$K_i = \begin{pmatrix} O_i \\ D_l \\ O_{m-i} \end{pmatrix}$$

where O_i is an $i \times m$ zero matrix and O_{m-i} is an $(m-i) \times m$ zero matrix. Therefore

$$T_i D_l = T K_i = 0. \quad (11)$$

QED

Proof of Theorem 1.2 We define

$$D_r := \begin{pmatrix} 0 \\ D_L \end{pmatrix} \quad (12)$$

and hence

$$D = \begin{pmatrix} D_l & D_r \end{pmatrix}.$$

By Lemma (2.1), $T_i D_l = 0$. Then, for $i, j = 1, \dots, m+1$, we have

$$T_i = T_i D A = T_i \begin{pmatrix} D_l & D_r \end{pmatrix} A = \begin{pmatrix} 0 & T_i D_r \end{pmatrix} \begin{pmatrix} A_T \\ A_B \end{pmatrix} = T_i D_r A_B \quad (13)$$

which implies

$$T_{ij} = T_i D_r A_j.$$

From the definition of T we can see that $T_{m-i+2, i} = I$. Then we have

$$I = T_{m-j+2} D_r A_j,$$

that is A_j is invertible and

$$A_j^{-1} = T_{m-j+2} D_r \quad (14)$$

or

$$T_i D_r = (A_{m-i+2})^{-1}. \quad (15)$$

By substituting (15) into (13) we obtain

$$T_i = (A_{m-i+2})^{-1}A_B \quad \text{or} \quad A_i^{-1}A_B = T_{m-i+2}. \quad (16)$$

This implies that

$$A_i^{-1}A_j = T_{m-i+2,j}. \quad (17)$$

On the other hand we perform the same process to B as follows. We define

$$N := \begin{pmatrix} N_L \\ N_U \end{pmatrix}. \quad (18)$$

By Lemma (2.1) we have, for $i, j = 1, \dots, m+1$,

$$T_i = T_i S B = T_i \begin{pmatrix} D_i & N \end{pmatrix} B = \begin{pmatrix} 0 & T_i N \end{pmatrix} \begin{pmatrix} B_T \\ B_B \end{pmatrix} = T_i N B_B \quad (19)$$

which implies

$$T_{ij} = T_i N B_j.$$

From the definition of T we know that $T_{m-i+2,i} = I$. Then we have

$$I = T_{m-j+2} N B_j,$$

that is

$$T_{m-j+2} N = B_j^{-1} \quad (20)$$

or

$$T_i N = (B_{m-i+2})^{-1}. \quad (21)$$

By substituting (21) into (19) we obtain

$$T_i = (B_{m-i+2})^{-1} B_B \quad \text{or} \quad B_i^{-1} B_B = T_{m-i+2}. \quad (22)$$

This implies that

$$B_i^{-1} B_j = T_{m-i+2,j}. \quad (23)$$

Equations (17) and (23) show that

$$A_i^{-1} A_j = B_i^{-1} B_j$$

for each $i, j = 1, 2, \dots, m+1$. This completes the proof. QED

Corollary 2.2 *We define*

$$M := \begin{pmatrix} M_1 & M_2 \end{pmatrix} = \begin{pmatrix} N_L & 0 \\ N_U & N_L \\ 0 & N_U \end{pmatrix}. \quad (24)$$

Let $H = TM$ and H_i be the sub-matrix of H consisting the m consecutive columns of H starting from the i th column. Then

$$H_i = (B_{m-i+2})^{-1} \quad \text{or} \quad H_{m-i+2} = B_i^{-1}.$$

Proof Consider

$$H = TM = T \begin{pmatrix} N_L & 0 \\ N_U & N_L \\ 0 & N_U \end{pmatrix} = (T_1 N \quad T_{m+1} N). \quad (25)$$

This gives immediately

$$H_1 = T_1 N \quad \text{and} \quad H_{m+1} = T_{m+1} N. \quad (26)$$

Equations (21) then implies $H_1 = (B_{m+1})^{-1}$ and $H_{m+1} = B_1^{-1}$. For $1 < i < m + 1$ let M_i be the sub-matrix of M consisting the m consecutive columns of M starting from the i th column. Then M_i is in the form

$$M_i = \begin{pmatrix} O_i \\ N \\ O_{m-i} \end{pmatrix}$$

where O_i is an $i \times m$ zero matrix and O_{m-i} is an $(m - i) \times m$ zero matrix. Therefore

$$H_i = TM_i = T_i N. \quad (27)$$

Again, equations (21) shows $H_i = (B_{m-i+2})^{-1}$. QED

Remark 2.3 *This theorem reveals two remarkable features of A_i 's and B_i 's. First, equation (5) demonstrates the invariance of $A_i B_i^{-1}$ with respect to i . More precisely we have*

$$A_i B_i^{-1} = A_B N.$$

Secondly, equation (4) shows that $B_i^{-1} B_j$ is independent of n_h 's which are the elements defining S . This is quite significant as B_i 's are sub-matrices of B , which is the inverse of S and therefore depends on n_h 's.

Remark 2.4 *The proof of this theorem also demonstrates an interesting feature of those A_i 's and B_i 's. By the definition of T we can see that, for $i, j = 1, 2, \dots, m + 1$ and $1 \leq k \leq \max\{m - i + 1, j\}$ we have*

$$T_{i+k, j-k} = T_{i, j}.$$

This, together with (17) and (23), shows that

$$A_i^{-1} A_j = (A_{i+k})^{-1} A_{j+k} \quad \text{and} \quad B_i^{-1} B_j = (B_{i+k})^{-1} B_{j+k} \quad (28)$$

for such k 's that the right hand sides of the above equations are defined. For example,

$$B_1^{-1} B_2 = B_2^{-1} B_3 = \dots = B_m^{-1} B_{m+1}.$$

Proof of Theorem 1.3 It is well known that B can be represented by

$$B = \begin{pmatrix} N_U B_z & -N_L B_z \\ -D_U B_z & D_L B_z \end{pmatrix} \quad (29)$$

where $B_z = B_T(D, N)^{-1}$ where $B_T(D, N)$ is the Bezoutian matrix generated by D and N in the following manner:

$$B_T(D, N) = D_L N_U - N_L D_U = N_U D_L - D_U N_L. \quad (30)$$

For detailed properties of Bezoutian matrices we refer to the comprehensive article [1]. Using this representation we have $B_1 = -D_U B_z$ and $B_{m+1} = D_L B_z$.

Now, by Corollary 2.2, we have

$$\begin{aligned} B_1 H &= B_1 \begin{pmatrix} (B_{m+1})^{-1} & B_1^{-1} \end{pmatrix} = \begin{pmatrix} B_1 (B_{m+1})^{-1} & I \end{pmatrix} \\ &= \begin{pmatrix} -D_U B_z (B_z^{-1} D_L^{-1}) & I \end{pmatrix} = \begin{pmatrix} -D_U D_L & I \end{pmatrix} \\ &= T_1 \end{aligned}$$

and hence

$$B_1 B_i^{-1} = B_1 H_{m-i+2} = T_{1, m-i+2}.$$

This, together with equation (22), implies

$$B_1 B_i^{-1} = (B_{m+1})^{-1} B_{m-i+2}.$$

Putting $k = m - i + 1$ in (28) gives

$$B_i^{-1} B_1 = (B_{i+k})^{-1} B_{1+k} = (B_{m+1})^{-1} B_{m-i+2}.$$

Therefore $B_1 B_i^{-1} = B_i^{-1} B_1$ for each $i = 1, 2, \dots, m + 1$.

Similarly

$$\begin{aligned} B_{m+1} H &= B_{m+1} \begin{pmatrix} (B_{m+1})^{-1} & B_1^{-1} \end{pmatrix} = \begin{pmatrix} I & B_{m+1} B_1^{-1} \end{pmatrix} \\ &= \begin{pmatrix} I & D_L B_z (-B_z^{-1} D_U^{-1}) \end{pmatrix} = \begin{pmatrix} I & -D_L D_U^{-1} \end{pmatrix} \\ &= T_{m+1}. \end{aligned}$$

This, together with equation (22), proves

$$B_{m+1} B_i^{-1} = T_{m+1, m+2-i} = B_1^{-1} B_{m+2-i}.$$

Equation (28) with $k = i - 1$ gives

$$B_1^{-1} B_{m+2-i} = (B_{1+i-1})^{-1} B_{m+2-i+i-1} = B_i^{-1} B_{m+1},$$

and hence $B_{m+1}B_i^{-1} = B_i^{-1}B_{m+1}$ for each $i = 1, 2, \dots, m + 1$. This is equivalent to

$$B_i(B_{m+1})^{-1} = (B_{m+1})^{-1}B_i. \quad (31)$$

Now for $1 < i < m + 1$, by equation (23)

$$\begin{aligned} B_i H &= B_i \begin{pmatrix} (B_{m+1})^{-1} & B_1^{-1} \end{pmatrix} = \begin{pmatrix} B_i(B_{m+1})^{-1} & B_i B_1^{-1} \end{pmatrix} \\ &= \begin{pmatrix} (B_{m+1})^{-1} B_i & B_1^{-1} B_i \end{pmatrix} \\ &= \begin{pmatrix} T_{1,i} & T_{m+1,i} \end{pmatrix}. \end{aligned}$$

Let t_j denote the j th column of T . The observation

$$T = (t_1, \dots, t_{i-1}, \underbrace{\overbrace{t_i, \dots, t_{m+i-1}}^{T_{1,i}} \overbrace{t_{m+i}, \dots, t_{2m+i-1}}^{T_{m+1,i}}}_{T_i}, t_{2m+i}, \dots, t_{3m}) \quad (32)$$

shows that

$$\begin{pmatrix} T_{1,i} & T_{m+1,i} \end{pmatrix} = T_i,$$

and hence

$$B_i H = T_i. \quad (33)$$

From this we obtain $B_j B_i^{-1} = B_i^{-1} B_j$.

QED

Corollary 2.5 For $i, j = 1, 2, \dots, m + 1$ we have

$$B_i B_j = B_j B_i, \quad (34)$$

and, for all l such that both B_{i+l} and B_{j-l} are meaningful,

$$B_i B_j = B_{i+l} B_{j-l}. \quad (35)$$

Proof The second equation follows from (28) by putting $k = i - j + l$:

$$B_{j-l} B_j^{-1} = B_j^{-1} B_{j-l} = (B_{j+k})^{-1} B_{j-l+k} = (B_{i+l})^{-1} B_i.$$

References

- [1] Georg Heinig and Karla Rost, *Introduction to Bezoutians*, Advances and Applications, Vol. 199, 25 - 118, (2010)
- [2] Robin Hill, Uwe Schwerdtfeger and Michael Baake, *Dynamic programming and duality applied to an optimal control problem*, Proceeding of Australian Control Conference, to appear, (2011)
- [3] Robin D. Hill, *Dual periodicity in l_1 -norm minimisation problems*, Systems & Control Letters, 57, 489 - 496, (2008)