

Convergence Analysis of Discrete Differential Geometry Operators over Surfaces [★]

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Abstract

In this paper, we study the convergence property of several discrete schemes of the surface normal. We show that the arithmetic mean, the area-weighted averaging, and the angle-weighted averaging schemes have quadratic convergence rate for a special triangulation scenario of the surfaces. By constructing a counterexample, we also show that it is impossible to find a discrete scheme of normals that has quadratic convergence rate over any triangulated surface and give a negative answer for the open question raised by D.S.Meek and D.J. Walton. Moreover, we point out that one cannot build a discrete scheme for Gaussian curvature, mean curvature and Laplace-Beltrami operator that converges over any triangulated surface.

Key words: Normal estimation, Surface triangulation, Convergence

1 Introduction

Estimation of normal vectors and curvatures on discrete surfaces are often required in Computer Aided Geometric Design and Computer Graphics. In the past decades, many discretized approaches for normal vectors, Gaussian curvature, mean curvature and Laplace-Beltrami operator have been proposed

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and used. The convergence of the discretized approaches has also been studied. In [3], the authors analyzed the convergence of the normal vector and Gaussian curvature. For normal vectors, they obtained the following result: *For non-uniform data, the unit vector parallel to the arithmetic mean of unit normals of the triangular faces around a point approximates the unit normal of the surface at that point to accuracy $O(h)$.* Furthermore, by the numerical test, they found that the accuracy of arithmetic mean, the area-weighted averaging, and the angle-weighted averaging are not higher than $O(h)$. As pointed out in [3], normal estimation methods with accuracy $O(h^2)$ are very useful for the spherical image method of Gaussian curvature approximation. Hence, they raised an open question: *Find a linear combination of the normals of the triangular faces, based on geometric considerations, that approximates the normal of the surface to $O(h^2)$.* In this paper, we prove that under certain conditions, the approximation accuracy of normal vectors can be $O(h^2)$, meaning the approximation converges with a quadratic rate. Moreover, we show that it is impossible to find a discretization scheme of normals that has quadratic convergence rate over any triangulated surface. Hence, the answer to the above mentioned open question is negative.

In [4], Meyer et al. proposed some discrete schemes to approximate several important geometric attributes, including normal vectors and curvatures on arbitrary triangular meshes. In [9], G. Xu proved that a well know discretized scheme of Gaussian curvature, derived from Gauss-Bonnet theorem, has quadratic convergence rate under certain conditions. In [10] and [11], he also studied the convergence of Laplace-Beltrami operators and mean curvature, include Taubin et al's discretization [5], Mayer et al's discretization [8], Desbrun et al's discretization[1], Meyer et al 's discretization[4], and proposed several simple discretization schemes of Laplace-Beltrami operator over triangulated surfaces. In [3], the author proposes an asymptotic analysis of Gaussian curvature for three methods: quadratic fit method, angular defect and spherical image method. A review of these schemes is given in [7]. However, none of these discretizations of Gaussian curvature and mean curvature has been proved to be convergent over any non-degenerate triangulated surface. Therefore, a natural questions is raised: *can we build a discrete scheme of Gaussian curvature and mean curvature which involves one-ring vertices and converges over any non-degenerate triangle surface?* In this paper, we will give a negative answer to this question. Hence, we have to accept the fact that the discretization scheme for curvature only convergent over special triangular surface.

The rest of the paper is organized as follows. In section 2, we introduce some definitions and formulations. In section 3, we discuss the convergence property of discrete schemes of normals. In section 4, by giving a counterexample, we show that one cannot construct a scheme of Gaussian curvature and mean curvature that converges over any non-degenerate triangle surface. Moreover,

we also give a negative answer to the open question raised in [3].

2 Preliminaries

Let $\mathbf{S}(u, v) = (x(u, v), y(u, v), z(u, v)) \in \mathbf{R}^3$ be a regular parametric surface. By inverse function theorem, we may assume that the surface near the point (x_0, y_0, z_0) can be expressed in the form $z = f(x, y)$. We further assume that the point where the normal and curvature need to be approximated is $(0, 0, f(0, 0))^T$. Similar to [3], we can select an appropriate coordinate system so that $f(x, y)$ can be expanded into a Maclaurin series as

$$f(x, y) = \frac{f_{xx}(0, 0)}{2}x^2 + f_{xy}(0, 0)xy + \frac{f_{yy}(0, 0)}{2}y^2 + \dots, \quad (1)$$

Hence, for the convergence analysis, we assume that $f(x, y)$ is of the form

$$f(x, y) = \frac{B_{20}}{2}x^2 + B_{11}xy + \frac{B_{02}}{2}y^2 + \frac{B_{30}}{6}x^3 + \frac{B_{21}}{2}x^2y + \frac{B_{12}}{2}xy^2 + \frac{B_{03}}{6}y^3 + \dots,$$

and the parametric form of the surface is given by

$$\mathbf{S}(x, y) = \begin{pmatrix} x \\ y \\ f(x, y) \end{pmatrix}.$$

Using this expression of $f(x, y)$, we can see that the point where the normal and curvature needs to be approximated is the origin $(0, 0, 0)$. Then from differential geometry, the normal vector, Gaussian curvature and mean curvature of $\mathbf{S}(x, y)$ at the origin are $(0, 0, 1)^T$, $B_{20}B_{02} - B_{11}^2$ and $\frac{B_{20}+B_{02}}{2}$, respectively.

Let $\mathbf{P}_i = \mathbf{S}(\mathbf{q}_i)$ be n distinct points on $\mathbf{S}(x, y)$ near the origin \mathbf{O} and $\mathbf{q}_i = (r_i \cos(\theta_i)h, r_i \sin(\theta_i)h)$, i.e.

$$\mathbf{P}_i = r_i \begin{pmatrix} \cos(\theta_i)h \\ \sin(\theta_i)h \\ w_i h^2 + O(h^3) \end{pmatrix}, i = 1, 2, \dots, n, \quad (2)$$

where $w_i = r_i(B_{20}/2 \cos^2 \theta_i + B_{11} \cos \theta_i \sin \theta_i + B_{02}/2 \sin^2 \theta_i)$. The indices arithmetic modulo n so index $n+1$ is the same as index 1. Without loss of generality, we assume $0 \leq \theta_1 \leq \theta_2 \leq \dots \leq \theta_n < 2\pi$. Denoting the normal to the triangle $\mathbf{P}_i \mathbf{O} \mathbf{P}_{i+1}$ as $\mathbf{n}_{i,i+1}$, by (2),

$$\begin{aligned}
\mathbf{n}_{i,i+1} &= (\mathbf{P}_i - \mathbf{O}) \times (\mathbf{P}_{i+1} - \mathbf{O}) \\
&= r_i r_{i+1} h^2 \begin{pmatrix} (w_{i+1} \sin(\theta_i) - w_i \sin(\theta_{i+1}))h + O(h^2) \\ (-w_{i+1} \cos(\theta_i) + w_i \cos(\theta_{i+1}))h + O(h^2) \\ \sin(\theta_{i+1} - \theta_i) \end{pmatrix}.
\end{aligned} \tag{3}$$

Obviously,

$$\|\mathbf{n}_{i,i+1}\| = r_i r_{i+1} \sin(\theta_{i+1} - \theta_i) h^2 (1 + A_i h^2 + O(h^3)), \tag{4}$$

where $A_i = \frac{w_i^2 - 2w_i w_{i+1} \cos(\theta_{i+1} - \theta_i) + w_{i+1}^2}{2 \sin^2(\theta_{i+1} - \theta_i)}$. In fact, (3) and (4) are also derived in [3]. Denote the unit normal vector on triangle surfaces $\mathbf{P}_i \mathbf{O} \mathbf{P}_{i+1}$ as $\bar{\mathbf{n}}_{i,i+1}$. By (3) and (4), we have

$$\bar{\mathbf{n}}_{i,i+1} = \begin{pmatrix} \frac{w_{i+1} \sin \theta_i - w_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)(1 + A_i h^2 + O(h^3))} h + O(h^2) \\ \frac{-w_{i+1} \cos \theta_i + w_i \cos \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)(1 + A_i h^2 + O(h^3))} h + O(h^2) \\ \frac{1}{1 + A_i h^2 + O(h^3)} \end{pmatrix}. \tag{5}$$

In general, the unit normal vector at \mathbf{O} is approximated by

$$\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1}, \tag{6}$$

where λ_i is weight and $\sum_{i=1}^n \lambda_i = 1$.

There are several ways to determine the weights. A simple way is to take arithmetic mean, i.e., $\lambda_i = \frac{1}{n}$. Other ways include take an area-weighted average and an angle-weighted average.

Using discretization normals, the spherical image method for Gaussian curvature approximation is built in [3], and moreover, the following lemma is proved

Lemma 1 (see [3]) *When unit normals are known to accuracy $O(h^2)$, the spherical image method approximates the Gaussian curvature to accuracy $O(h)$.*

Hence, $O(h^2)$ accuracy normals are very useful for computing the Gaussian curvature.

3 Convergence of normal vectors

In [3], the authors showed that the accuracy of the arithmetic mean, the area-weighted averaging, and the angle-weighted averaging are not higher than

$O(h)$. However, we shall prove that under certain conditions, the approximation accuracy of the three ways can be $O(h^2)$.

Theorem 1 *Let p_0 be a vertex of M with valence n , and $p_i, i = 1, \dots, n$ be its neighbor vertices. Suppose p_0 and $p_i, i = 1, \dots, n$ are on a sufficiently smooth regular parametric surface $\mathbf{S}(x, y) \in \mathbf{R}^3$ and there exist $q_0, q_i \in \mathbf{R}^2$ such that $p_0 = \mathbf{S}(q_0), p_i = \mathbf{S}(q_i)$. Then in the following two cases*

(1). $n = 2m, m > 1, q_{i+m} = q_0 - (q_i - q_0), \sum_{i=1}^m \lambda_i = 1, \lambda_{i+m} = \lambda_i,$

(2). $n = 2m + 1, m > 1, \angle q_i q_0 q_{i+1} = \frac{2i\pi}{2m+1}, \|q_i - q_0\| = \|q_{i+1} - q_0\|, \sum_{i=1}^m \lambda_i = 1, \lambda_{i+1} = \lambda_i,$

$\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1}$ approximates the unit normal of the surface at the point p_0 to the accuracy $O(h^2)$.

Proof: Without loss of generality, we may assume $q_0 = (0, 0)$ and $q_i = (r_i \cos(\theta_i)h, r_i \sin(\theta_i)h)$. Since $\mathbf{S}(x, y)$ is a regular surface, we can use the notations and formulas proposed in Section 2.

It follows from (5) that,

$$\bar{\mathbf{n}}_{i,i+1} = \begin{pmatrix} \frac{w_{i+1} \sin \theta_i - w_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)(1 + A_i h^2 + O(h^3))} h + O(h^2) \\ \frac{-w_{i+1} \cos \theta_i + w_i \cos \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)(1 + A_i h^2 + O(h^3))} h + O(h^2) \\ \frac{1}{1 + A_i h^2 + O(h^3)} \end{pmatrix}.$$

Consider $\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1}$. By Taylor expansion, $\frac{1}{1 + A_i h^2 + O(h^3)} = 1 - A_i h^2 + O(h^3)$.

We have

$$\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1} = \begin{pmatrix} \sum_{i=1}^n \lambda_i \frac{w_{i+1} \sin \theta_i - w_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} h + O(h^2) \\ \sum_{i=1}^n \lambda_i \frac{-w_{i+1} \cos \theta_i + w_i \cos \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} h + O(h^2) \\ 1 + O(h^2) \end{pmatrix}.$$

To prove the theorem, we merely need to prove $\sum_{i=1}^n \lambda_i \frac{w_{i+1} \sin \theta_i - w_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0$ and $\sum_{i=1}^n \lambda_i \frac{-w_{i+1} \cos \theta_i + w_i \cos \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0$.

We firstly consider

$$\sum_{i=1}^n \lambda_i \frac{w_{i+1} \sin \theta_i - w_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} = \sum_{i=1}^n \lambda_i \frac{B_{20} H_{1i}/2 + B_{11} H_{2i} + B_{02} H_{3i}/2}{\sin(\theta_{i+1} - \theta_i)} \quad (7)$$

where,

$$\begin{aligned} H_{1i} &= r_{i+1} \cos^2 \theta_{i+1} \sin \theta_i - r_i \cos^2 \theta_i \sin \theta_{i+1}, \\ H_{2i} &= r_{i+1} \cos \theta_{i+1} \sin \theta_{i+1} \sin \theta_i - r_i \cos \theta_i \sin \theta_i \sin \theta_{i+1}, \\ H_{3i} &= r_{i+1} \sin^2 \theta_{i+1} \sin \theta_i - r_i \sin^2 \theta_i \sin \theta_{i+1}. \end{aligned}$$

We shall prove that

$$\sum_{i=1}^n \lambda_i \frac{H_{1i}}{\sin(\theta_{i+1} - \theta_i)} \equiv \sum_{i=1}^n \lambda_i \frac{H_{2i}}{\sin(\theta_{i+1} - \theta_i)} \equiv \sum_{i=1}^n \lambda_i \frac{H_{3i}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0.$$

Firstly, we consider the case where $n = 2m$. Since $q_{i+m} = q_0 - (q_i - q_0)$, we have $\theta_{i+m} = \pi + \theta_i, r_{i+m} = r_i$. Hence,

$$\begin{aligned} \sum_{i=1}^n \lambda_i \frac{H_{1i}}{\sin(\theta_{i+1} - \theta_i)} &= \sum_{i=1}^n \lambda_i \frac{r_{i+1} \cos^2 \theta_{i+1} \sin \theta_i - r_i \cos^2 \theta_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \\ &= \sum_{i=1}^m \lambda_i \frac{r_{i+1} \cos^2 \theta_{i+1} \sin \theta_i - r_i \cos^2 \theta_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \\ &\quad + \sum_{i=m+1}^n \lambda_{i-m} \frac{r_{i+1-m} \cos^2(\pi + \theta_{i+1-m}) \sin(\pi + \theta_{i-m}) - r_{i-m} \cos^2(\pi + \theta_{i-m}) \sin(\pi + \theta_{i+1+m})}{\sin(\theta_{i+1-m} - \theta_{i-m})} \\ &= \sum_{i=1}^m \lambda_i \frac{r_{i+1} \cos^2 \theta_{i+1} \sin \theta_i - r_i \cos^2 \theta_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \\ &\quad + \sum_{i=1}^m \lambda_i \frac{-r_{i+1} \cos^2 \theta_{i+1} \sin \theta_i + r_i \cos^2 \theta_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \\ &\equiv 0. \end{aligned}$$

Secondly, we consider the case where $n = 2m + 1$. In this case, λ_i, r_i and $\theta_{i+1} - \theta_i$ are all constant. Hence, to prove $\sum_{i=1}^n \lambda_i \frac{H_{1i}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0$, we only need prove $\sum_{i=1}^n \cos^2 \theta_{i+1} \sin \theta_i = 0$ and $\sum_{i=1}^n \cos^2 \theta_i \sin \theta_{i+1} = 0$. Consider

$$\begin{aligned} \sum_{i=1}^n \cos^2 \theta_{i+1} \sin \theta_i &= \sum_{i=1}^{2m+1} \cos^2 \frac{i}{2m+1} 2\pi \sin \frac{i-1}{2m+1} 2\pi \\ &= 2 \sum_{i=1}^{2m} \sin \frac{i}{2m+1} 2\pi \cos \frac{2(i+1)}{2m+1} 2\pi - \sum_{i=1}^{2m} \sin \frac{i}{2m+1} 2\pi. \end{aligned}$$

Using the equality $\sum_{k=1}^{2m} \sin(a_0 + kd) = \frac{\cos(d/2+a_0) - \cos(a_0+2md+d/2)}{2 \sin d/2}$, we have

$$\begin{aligned}
& 2 \sum_{i=1}^{2m} \sin \frac{i}{2m+1} 2\pi \cos \frac{2(i+1)}{2m+1} 2\pi - \sum_{i=1}^{2m} \sin \frac{i}{2m+1} 2\pi \\
&= \sum_{i=1}^{2m} \left(\sin \frac{3i+2}{2m+1} 2\pi + \sin \frac{-i-2}{2m+1} 2\pi \right) - \sum_{i=1}^{2m} \sin \frac{i}{2m+1} 2\pi \\
&= \frac{\cos\left(\frac{3\pi}{2m+1} + \frac{4\pi}{2m+1}\right) - \cos\left(-\frac{3\pi}{2m+1} + \frac{4\pi}{2m+1}\right)}{2 \sin\left(\frac{3\pi}{2m+1}\right)} \\
&\quad - \frac{\cos\left(\frac{\pi}{2m+1} + \frac{4\pi}{2m+1}\right) - \cos\left(-\frac{\pi}{2m+1} + \frac{4\pi}{2m+1}\right)}{2 \sin\left(\frac{\pi}{2m+1}\right)} \\
&= 0.
\end{aligned}$$

Using the similar derivation above, we can prove

$$\sum_{i=1}^n \lambda_i \frac{H_{2i}}{\sin(\theta_{i+1} - \theta_i)} \equiv \sum_{i=1}^n \lambda_i \frac{H_{3i}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0.$$

Hence, under the condition (1) or (2), we have

$$\sum_{i=1}^n \lambda_i \frac{w_{i+1} \sin \theta_i - w_i \sin \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0.$$

Similarly, under the condition (1) or (2), we can obtain

$$\sum_{i=1}^n \lambda_i \frac{-w_{i+1} \cos \theta_i + w_i \cos \theta_{i+1}}{\sin(\theta_{i+1} - \theta_i)} \equiv 0.$$

Hence, under the condition (1) or (2), $\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1} = (O(h^2), O(h^2), 1+O(h^2))^T$. The theorem is proved. \square

Corollary 1 *Under the condition of Theorem 1, if the weight λ_i is defined as the arithmetic mean, the area-weighted averaging or the angle-weighted averaging, $\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1}$ approximates the unit normal of the surface at the point p_0 to accuracy $O(h^2)$.*

Proof: When λ_i is selected as arithmetic mean, $\lambda_i = \frac{1}{n}$. Obviously, in this case $\lambda_i = \lambda_j, \forall i, j$. By Theorem 1, the Corollary holds.

Denote the area of $\triangle p_i p_0 p_{i+1}$ and $\triangle q_i q_0 q_{i+1}$ as $A(p_i p_0 p_{i+1})$ and $A(q_i q_0 q_{i+1})$ respectively. When λ_i is selected as the area-weight, $\lambda_i = \frac{A(p_i p_0 p_{i+1})}{\sum_i A(p_i p_0 p_{i+1})}$. By [3], $A(p_i p_0 p_{i+1}) = A(q_i q_0 q_{i+1}) h^2 + O(h^4)$. Hence,

$$\lambda_i = \frac{A(q_i q_0 q_{i+1}) + O(h^2)}{\sum_i A(q_i q_0 q_{i+1}) + O(h^2)} = \frac{A(q_i q_0 q_{i+1})}{\sum_i A(q_i q_0 q_{i+1})} + O(h^2).$$

Denote $\frac{A(q_i q_0 q_{i+1})}{\sum_i A(q_i q_0 q_{i+1})}$ as $\widehat{\lambda}_i$. Since $\widehat{\lambda}_i$ satisfy the weight condition in Theorem 1,

$$\lambda_i \bar{\mathbf{n}}_{i,i+1} = \widehat{\lambda}_i \bar{\mathbf{n}}_{i,i+1} + O(h^2)(0, 0, 1)^T = (O(h^2), O(h^2), 1 + O(h^2))^T.$$

Hence, $\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1}$ approximates the unit normal of the surface at the point p_0 to accuracy $O(h^2)$.

Let $\theta_{i,i+1}$ be the planar angle $p_i p_0 p_{i+1}$ and let it be positive by convention. By [3], $\theta_{i,i+1} = \theta_{i+1} - \theta_i + O(h^2)$. Hence, by using the same method with the above, we can show when $\lambda_i = \frac{\theta_{i,i+1}}{\sum_i \theta_{i,i+1}}$, $\sum_{i=1}^n \lambda_i \bar{\mathbf{n}}_{i,i+1}$ approximates the unit normal of the surface at the point p_0 to accuracy $O(h^2)$. \square

Remark 1 *The convergence results are established under particular conditions. As pointed out in [11], these special cases are very useful and important. A number of numerical simulations of geometric partial differential equations are conducted over a triangulated domain formed by a uniform three-directional or four-directional partitions. The both partitions satisfy the condition in Theorem 1.*

Remark 2 *An interesting observation is that the condition of the discretization scheme of normals having quadratic convergence is exactly the same as the condition of a discretization of gradient having quadratic convergence proposed in [11]. (Theorem 4.1 in [11] only present the condition (1). In fact, by using similar method with [11], under the condition (2), the discretization of gradient has also quadratic convergence.)*

4 The counterexamples about the convergence of curvature and normals

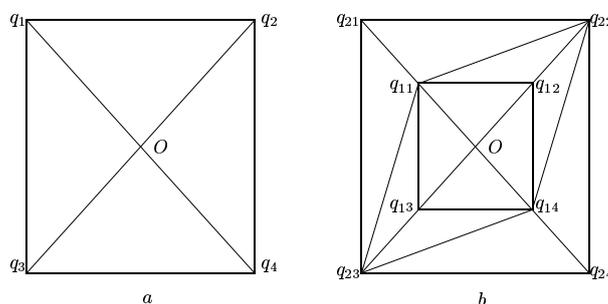


Fig.1: a counterexample

In the previous section, we have studied the convergence of the discrete unit normal. The convergence property of the discrete Gaussian curvature and mean curvature has been considered in [9],[10],[11] and [3]. But none of dis-

cretization schemes has been proved to be convergent over any non-degenerate triangle surfaces. A natural question is raised: *can we build a discretization scheme of Gaussian curvature and mean curvature converging over any non-degenerate triangle surfaces?* In this section, by a counterexample we shall give a negative answer for the question.

Let p_0 be a vertex of M where the Gaussian curvature is to be approximated and $p_i, i = 1, \dots, n$ be its neighbor vertices. We make a hypothesis that the discretization scheme of Gaussian curvature involving one-ring neighbor vertices of p_0 , denoted as $H(M, p_0; p_1, \dots, p_n)$, is convergent for any triangle mesh surface M . Suppose M is a given triangle surface approximating the surface $\mathbf{S}(x, y) = (x, y, f(x, y))^T$, $f(x, y) = B_{02}x^2 + B_{11}xy + B_{02}y^2$ and the origin $p_0 = (0, 0, 0)$ is a vertex of M . Assume the valence of the origin point is 4 and the neighbor points are $p_i = \mathbf{S}(\mathbf{q}_i), i = 1, \dots, 4$, where $\mathbf{q}_1 = h(1, 2), \mathbf{q}_2 = h(-1, -2), \mathbf{q}_3 = h(-1, 2)$ and $\mathbf{q}_4 = h(1, -2)$ (see fig.1.a). Since Gaussian curvature of $\mathbf{S}(x, y, z)$ at p_0 equals to $4B_{02}B_{20} - B_{11}^2$, by the convergence property of $H(M, p_0; p_1, \dots, p_n)$, we have $\lim_{h \rightarrow 0} H(M, p_0; p_1, p_2, p_3, p_4) = 4B_{02}B_{20} - B_{11}^2$.

Suppose \widehat{M} is another given mesh surface approximating the surface $\widehat{\mathbf{S}}(x, y) = (x, y, \widehat{f}(x, y))^T$, $\widehat{f}(x, y) = (4B_{02} + B_{20})x^2 + B_{11}xy$, and the origin $(0, 0, 0)$ is a vertex of \widehat{M} where the curvature needs to be approximated. The neighbor points of the origin are $\widehat{p}_i = \widehat{\mathbf{S}}(\mathbf{q}_i), i = 1, \dots, 4$, where $\mathbf{q}_1 = h(1, 2), \mathbf{q}_2 = h(-1, -2), \mathbf{q}_3 = h(-1, 2)$ and $\mathbf{q}_4 = h(1, -2)$. The Gaussian curvature of $\widehat{\mathbf{S}}$ at O is $-B_{11}^2$. By the convergence property of H , we have $\lim_{h \rightarrow 0} H(\widehat{M}, p_0; \widehat{p}_1, \widehat{p}_2, \widehat{p}_3, \widehat{p}_4) = -B_{11}^2$. Obviously, by the formulation of $f(x, y)$ and $\widehat{f}(x, y)$, for any h , $p_i = \widehat{p}_i, i = 1, \dots, 4$. Since the discretization scheme H merely involves one-ring neighbor vertices of p_0 , by $p_i = \widehat{p}_i$, $H(\widehat{M}, p_0; \widehat{p}_1, \widehat{p}_2, \widehat{p}_3, \widehat{p}_4) = H(M, p_0; p_1, p_2, p_3, p_4)$ for any h . Hence, $\lim_{h \rightarrow 0} H(\widehat{M}, p_0; \widehat{p}_1, \widehat{p}_2, \widehat{p}_3, \widehat{p}_4) = \lim_{h \rightarrow 0} H(M, p_0; p_1, p_2, p_3, p_4)$. But $-B_{11}^2$ is not always equal to $4B_{02}B_{20} - B_{11}^2$. Therefore, a contradiction appears. So, the hypothesis with $H(M, p_0; p_1, \dots, p_n)$ being convergent for any mesh surface does not hold.

Since the mean curvature of $\mathbf{S}(x, y)$ and $\widehat{\mathbf{S}}(x, y)$ at the origin equals to $B_{02} + B_{20}$ and $4B_{02} + B_{20}$ respectively, we can show that one can not construct a discretization scheme of mean curvature converging over any mesh surface by using the similar method with the above,

From above, if merely using one-ring vertices, we can not build discretization schemes of Gaussian curvature and mean curvature converging over any mesh surface. For fixed integer k , using k -ring vertices, can we construct a discretization scheme of Gaussian and mean curvature converging over any mesh surface?

Suppose the j -th ring vertices around p_0 is $p_{j,i} = \mathbf{S}(\mathbf{q}_{j,i})$, where $j \leq k, \mathbf{q}_{j,i} = j\mathbf{q}_i, i = 1, \dots, 4$ (Fig.1.b shows the case where $k = 2$). Obviously, for any h ,

$S(\mathbf{q}_{j,i}) = \widehat{S}(\mathbf{q}_{j,i}), j \leq k, i = 1, \dots, 4$. Hence, by using similar method with the above, we can show that for fixed integer k , if only use k -ring vertices, we can not build discretization schemes of mean curvature converging over any mesh surface. It is well known that Laplace-Beltrami operators relates closely to the mean curvature normal. Let p be a surface point on two-dimensional manifold \mathcal{M} . Then $\|\Delta_{\mathcal{M}}p\| = 2H(p)$, where $\Delta_{\mathcal{M}}p$ is the Laplace-Beltrami operator and $H(p)$ is the mean curvature at p . Hence, by above results, for fixed integer k , if only k -ring vertices are used, we can not build discretization schemes of Laplace-Beltrami operators converging over any mesh surface.

In [3], a open question is raised: *Find a linear combination of the normals of the triangular faces, based on geometric considerations, that approximates the normal of the surface to $O(h^2)$.* We shall give a negative answer for the open question. Suppose that the vertexes $\mathbf{S}(q_{1i}), i = 1, \dots, 4$ (see Fig.1.b) are the vertexes of M where the unit normals are to be approximated. We make a hypothesis that there exists a linear combination of the normal of the triangular faces that approximates the normal at $\mathbf{S}(q_{1i})$ to $O(h^2)$. By Lemma 1, under the hypothesis, we can build a discretization schemes involving 2-ring vertexes which approximates the Gaussian curvature at O to accuracy $O(h)$. The conclusion contradicts to the above results. Hence, the hypothesis does not hold. For any mesh surface, we can not find a linear combination of the normals of the triangular faces that approximates the normal of the surface to $O(h^2)$.

Remark 3 *In this counterexample, the valence of p_0 and p_{11} is 4 and 6 respectively. In fact, by using similar method, we can show one can not build a discretization schemes of Gauss and mean curvature which convergent at p_{11} . Hence, even the valence of vertexes in mesh surface is bigger than 4, we also can not build convergencing discretization schemes of Gauss and mean curvature for any mesh surface.*

Remark 4 *The points p_i or p_{ji} in this counterexample are under-determined for quadratic fit. As pointed out in [3] and [11], if the quadratic fit method has a unique solution, we can approximate the Gaussian and mean curvature to accuracy $O(h)$ and the unit normal to accuracy $O(h^2)$. Then, when the quadratic fit method has a unique solution, can we find a convergence discretization scheme of Gaussian and mean curvature depending only on edge length, angles, and areas of triangle faces? We conjecture that the answer to the question is negative. If the conjecture holds, quadratic fit methods can be the most general method for finding convergence discretization scheme of geometry operators.*

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